



# Uncertainty evaluation Basics



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## Terms and definitions



## Terms and definitions

- Many terms are used ...
  - Error
  - Precision
  - Accuracy
  - Uncertainty
  - Resolution
  - Sensitivity
  - Systematic effect
  - ...
- ... for historical reasons, but not only!



## Terms and definitions

### ● Error

- Used in the past, distinguishing between:
  - ✓ **systematic**: errors that affects a measurement always in the same way (same sign and same value)
  - ✓ **random**: errors due to phenomenon not under the operator's control
- Today used as **measurement error** to indicate the difference between a measurement and a reference value
  - ✓ Example: difference between the nominal value of a standard resistor and its measured value



## Terms and definitions

- (measurement) **Precision**

- It expresses the capability of a measurement system to provide similar measurements in specified conditions

- ✓ **Repeatability conditions**

- Same procedure, operator, instruments and conditions

- ✓ **Reproducibility conditions**

- Different procedures (inter-procedure reproducibility), or operators (inter-operator reproducibility), or instruments ...

- Commonly used parameters: variance or standard deviation



## Terms and definitions

- (measurement) **Accuracy**

- It expresses the capability of a measurement system to provide measurements close to the «true» value of the parameter under measurement
  - ✓ Qualitative concept: the instrument **X** is more accurate than instrument **Y** if **X** provides lower errors
  - ✓ It is often confused with the term «uncertainty»
    - Manufacturers prefer to state «accuracy specifications» instead of «uncertainty specifications»



## Terms and definitions

- (measurement) **Uncertainty**
  - It expresses the not perfect knowledge of the parameter under measurement (**measurand**)
    - ✓ It includes all the uncertainty contributions
    - ✓ It is stated by means of an interval of values
      - The meaning of this interval depends on the model (deterministic or probabilistic)



## Terms and definitions

- (measurement) **Resolution**

- Smallest change in the input measurand of an instrument that causes a perceptible change in the output indication
  - ✓ The measurement unit is the same as the measurand
  - ✓ It is the capability of the instrument in detecting small changes in the measurand
    - The resolution is an uncertainty contribution
    - Small resolution can be required regardless of the uncertainty



## Terms and definitions

### ● Sensitivity

- Ratio between the output indication of a measuring device and the corresponding change in the input measurand
  - ✓ The measurement unit (m.u.) is the m.u. of the output divided by the m.u. of the input (e.g., mm/V or div/V for an oscilloscope)
  - ✓ For non-linear devices it depends on the measurand value
  - ✓ It is a constant value for linear devices
    - The reciprocal value represents the calibration constant



## Terms and definitions

### ● Systematic effect

- Effect due to different sources that affects repeated measurements in the same way or changes in a predictable manner
  - ✓ If the systematic error can be evaluated, a correction is applied
  - ✓ The evaluation of a systematic effect is always affected by uncertainty

## Terms and definitions

### ● Systematic effect

#### 👉 Main sources

- Interaction between instruments and system under measurement (load effect)
- Effects of the influence quantities
- Instrument errors
  - ✓ Offset
  - ✓ Gain
  - ✓ ...

## Terms and definitions

### ● Systematic effect

- 👉 Its evaluation is not always possible (not enough information) or convenient (time/cost constraints)
  - The load-effect evaluation is related to parameters of instrument and system under measurement, which could be unknown
  - Instrument-error evaluation requires known measurands
    - ✓ Null input for offset evaluation
    - ✓ Known inputs for gain-error evaluation

## Terms and definitions

### ● Systematic effect

- 👉 Two possible strategies
  - i. Correction of the systematic effect
    - ✓ If it can be evaluated and if it is significative compared to the uncertainty
    - ✓ A residual uncertainty-contribution is related to this correction
  - ii. Considering the systematic effect as an uncertainty contribution
    - ✓ Suitable assumption has to be made according to the available information



## Uncertainty contributions



## Uncertainty contributions

### ● Instrumentation

- The **calibration function** of an instrument is not perfectly known
  - ✓ It suffers from several errors, such as offset, gain error and non linearity
- The **calibration function** is affected by quantities different than the measurand (**influence quantities**)
  - ✓ Temperature, humidity, value and frequency of the supply voltage, vibration, electromagnetic fields, ...



## Uncertainty contributions

### ● Instrumentation

- The instrument output (**indication**) is available with a finite **resolution** (quantization)
- The interaction between an instrument and the system under measurement always modify the system
  - ✓ The obtained measurement is different than the measurand in unloaded conditions
  - ✓ **Load effect**, which depends both on the instrument and the system under measurement



## Uncertainty contributions

### ● Measurand

- The definition of the measurand is provided by means of a finite amount of detail (**definitional uncertainty**)
  - ✓ It sets the minimum uncertainty achievable
  - ✓ The reduction of this contribution requires a more complex definition to be provided
  - ✓ A more complex definition makes the realization of the measurand more difficult



## Uncertainty contributions

### ● Measurand

- The way the measurand is defined identifies the quantities that describe the state of the system under measurement
  - ✓ Quantities that have to be specified when a measurement is provided
  - ✓ These quantities are not perfectly known (they are affected by uncertainty)



## Uncertainty contributions

### ● Method

- Different procedures can be used to measure the same parameter
- Different instruments can be used to implement the same procedure
- Different operator can implement the same procedure (with the same or with different instruments)
  - ✓ This contribution represents the **measurement reproducibility**
  - ✓ It is usually evaluated through specific experiments



## Uncertainty contributions

### ● Method

- The repetition of the same procedure, with the same instruments, with the same operator and in the same nominal conditions does not provide the same results
  - ✓ This contribution represents the **measurement repeatability**
  - ✓ It is due to random effects (e.g., influence quantities variation or electronic noise)
  - ✓ It is usually evaluated through specific experiments



## Classification of measurement methods



# Uncertainty evaluation - Basics

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## Classification of measurement methods

- According to our aim
  - Direct vs indirect methods
  - Single-reading vs multiple-readings methods



## Classification of measurement methods

- According to our aim
  - **Direct** vs **indirect** methods

### Direct method

→ The measurement is obtained from the reading of one instrument (direct reading) or from the value of one or more standards (comparison methods)



## Classification of measurement methods

- According to our aim
  - **Direct** vs **indirect** methods

### Indirect method

- ↳ A **measurement model** is used that relates the measurand to other quantities, which are measured using direct methods
- ↳ Often used when a direct measurement is not convenient
  - Volumetric mass density of a substance ( $\text{kg/m}^3$ )
  - Electrical resistance ( $\Omega$ )

## Classification of measurement methods

- According to our aim
  - Direct vs indirect methods

Indirect method

⇒ The measurement model is often expressed in explicit form

$$Y = f(X_1, X_2, \dots, X_N)$$

- $Y$  is the measurand
- $X_1, \dots, X_N$  are the quantities measured through direct methods
- $f$  is the measurement function



## Classification of measurement methods

- According to our aim
  - Direct vs indirect methods

### Indirect method

- A further uncertainty contribution has to be taken into account
  - The measurement model could not perfectly describe the measurand
  - Often indicated as model uncertainty
    - Volume of a cube obtained as  $V = L^3$
    - Sound speed in air obtained as a function of temperature and relative humidity ...



## Classification of measurement methods

- According to our aim
  - Direct vs indirect methods
  - Single-reading vs multiple-readings methods

### Single-reading methods

➤ The measurement is obtained starting from a single reading of one or more instruments

### Multiple-readings methods

➤ A set of measurements is collected from one or more instruments in specified conditions

- Repeatability conditions
- Reproducibility conditions



## Deterministic approach



## Deterministic approach

- When it is used
  - In the past (before the definition of the probabilistic approach)
  - Today
    - ✓ Uncertainty specifications of many commercial instruments
    - ✓ Industrial field
    - ✓ In worst-case design applications

## Deterministic approach

### ● Uncertainty interpretation

- A measurement is stated as a closed interval of values, which is usually centered around the value assigned to the measurand
- Example of measurement statement:

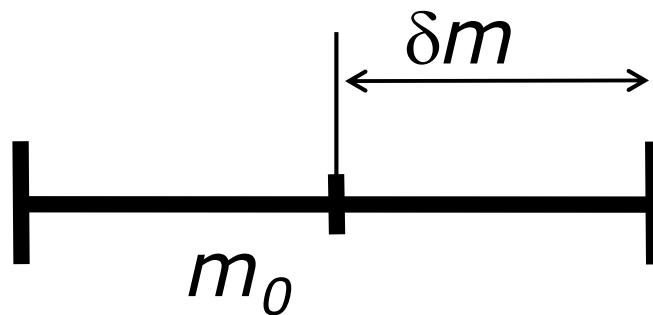
$$m = (m_0 \pm \delta m) \text{ U}$$

- ✓  $\delta m$  is the absolute uncertainty (half-width of the interval), which is expressed in the same measuring unit U of the measurand  $m_0$

## Deterministic approach

- Uncertainty interpretation
  - According to the deterministic approach:

- The measurand is included in the assigned interval of values
- All the values of the assigned interval are equally representative of the measurand



## Deterministic approach

- Uncertainty interpretation

- Example of measurements:

$$r = (113 \pm 1) \Omega$$

$$m = (1.45 \pm 0.02) \text{ g}$$

- The absolute uncertainty does not highlight the «quality/cost» of a measurement

$$l_1 = (13.6 \pm 0.01) \text{ m}$$

$$l_2 = (2320.1 \pm 0.01) \text{ m}$$

- ✓ Same absolute uncertainty, but very different cost!



## Deterministic approach

- Uncertainty interpretation
  - Alternative uncertainty statements
    - Relative uncertainty or relative percentage uncertainty:
$$\varepsilon m = \delta m / m_0 ; \varepsilon m \% = 100 \cdot \delta m / m_0$$
    - Measurement statement
$$m = m_0 U, \pm \varepsilon m$$
    - For the previous example:
$$l_1 = 13.6 \text{ m}, \pm 0.07 \%$$
$$l_2 = 2320.1 \text{ m}, \pm 0.0004 \%$$

## Deterministic approach

### ● Uncertainty interpretation

- Often manufacturers state relative uncertainty with respect to a conventional value  $m_C$  of the measurand

$$\varepsilon m = \delta m/m_C ; \varepsilon m \% = 100 \cdot \delta m/m_C$$

➤ **WARNING:** same symbol but different meaning

- Voltmeter 1: range 50 V; relative uncertainty: 1 %  
Votmeter 2: range 100 V; relative uncertainty 0.5 %  
(with respect to the range)

✓ Voltage to be measured = 30 V

- $V_1 \rightarrow v = (30 \pm 0.3) \text{ V}$
- $V_2 \rightarrow v = (30 \pm 0.5) \text{ V}$



## Deterministic approach

- Uncertainty propagation
  - The way the different uncertainty contributions are combined depends on the measurement method
    - Direct vs indirect methods
  - Direct measurement methods: sum of the contributions
    - ✓ Instrumental uncertainty
    - ✓ Measurement repeatability/reproducibility
    - ✓ Residual uncertainty of corrected systematic errors
    - ✓ Definitional uncertainty
    - ✓ ...

## Deterministic approach

- Uncertainty propagation
  - Indirect measurement methods

$$Y = f(X_1, X_2, \dots, X_N)$$

- ✓  $x_1 = (x_{10} \pm \delta x_1) U_1$
- ✓ ...
- ✓  $x_N = (x_{N0} \pm \delta x_N) U_N$

- Measurand evaluation

$$y_0 = f(x_{10}, x_{20}, \dots, x_{N0})$$

## Deterministic approach

- Uncertainty propagation
  - Indirect measurement methods
    - Absolute uncertainty evaluation

$$\delta y = \left| \frac{\partial f}{\partial x_1} \right|_{(x_1, \dots, x_N)} \cdot \delta x_1 + \dots + \left| \frac{\partial f}{\partial x_N} \right|_{(x_1, \dots, x_N)} \cdot \delta x_N$$

- Taylor series of the measurement function  $f$  estimated in the point  $(x_1, \dots, x_N)$
- Approximation: only the first-order partial derivatives are used in the series

## Deterministic approach

- Uncertainty propagation
  - Indirect measurement methods
    - Absolute uncertainty evaluation

$$\delta y = \sum_{i=1}^N \left| \frac{\partial f}{\partial x_i} \right|_{(x_1, \dots, x_N)} \cdot \delta x_i = \sum_{i=1}^N |c_i| \cdot \delta x_i$$

- $c_i$ : sensitivity coefficients of the measurement function  $f$

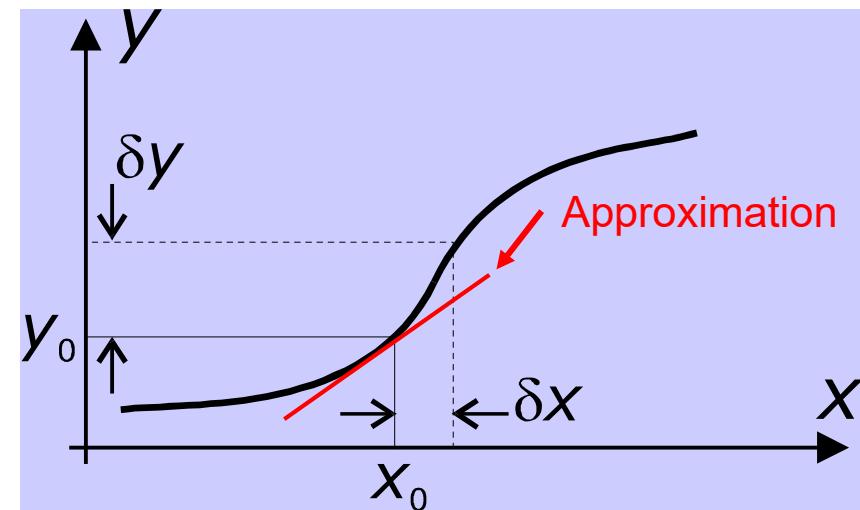
## Deterministic approach

- Uncertainty propagation

- Indirect measurement methods

- Absolute uncertainty evaluation

- ↳ The absolute uncertainty  $\delta x$  is considered as a deviation with respect to the nominal value  $x_0$ , which corresponds to a deviation  $\delta y$  with respect to the nominal value  $y_0$



## Deterministic approach

- Uncertainty propagation
  - Indirect measurement methods
    - Absolute uncertainty evaluation
    - **WORST-CASE MODEL**

$$\delta y = \sum_{i=1}^N \left| \frac{\partial f}{\partial x_i} \right|_{(x_1, \dots, x_N)} \cdot \delta x_i$$

The “absolute value” operator prevents any possible uncertainty compensation

## Deterministic approach

- Uncertainty propagation
  - Indirect measurement methods
    - Absolute uncertainty evaluation
    - **WORST-CASE MODEL**

$$\delta y = \sum_{i=1}^N \left| \frac{\partial f}{\partial x_i} \right|_{(x_1, \dots, x_N)} \cdot \delta x_i$$

The maximum deviation  $\delta x$  from the nominal value  $x_0$  is considered for each involved quantity



# Uncertainty evaluation - Basics

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## Example

$$Y = X_1 + X_2 - X_3$$

$$x_1 = (x_{10} \pm \delta x_1) U$$

$$x_2 = (x_{20} \pm \delta x_2) U$$

$$x_3 = (x_{30} \pm \delta x_3) U$$

**Measurand  
evaluation**

$$y_0 = x_{10} + x_{20} - x_{30}$$

## Example

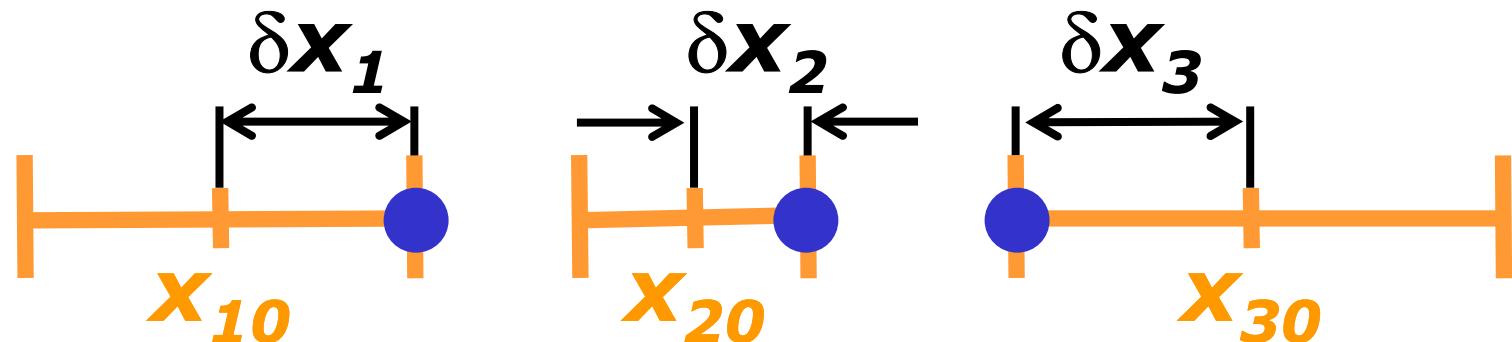
$$Y = X_1 + X_2 - X_3$$

Uncertainty  
evaluation

$$\delta Y = \delta X_1 + \delta X_2 + \delta X_3$$



WORST  
CASE





## General rules

$$Y = a \cdot X_1 - b \cdot X_2 \quad a \text{ and } b \text{ constants} > 0$$

$$\left| \frac{\partial f}{\partial x_1} \right| = a; \quad \left| \frac{\partial f}{\partial x_2} \right| = b$$

$$\delta y = a \cdot \delta x_1 + b \cdot \delta x_2$$

## General rules

$$Y = \frac{a \cdot X_1 \cdot X_2}{b \cdot X_3}$$

*a and b constants > 0*

$$\left| \frac{\partial f}{\partial x_1} \right| = \frac{a \cdot x_2}{b \cdot x_3}; \quad \left| \frac{\partial f}{\partial x_2} \right| = \frac{a \cdot x_1}{b \cdot x_3}; \quad \left| \frac{\partial f}{\partial x_3} \right| = \frac{a \cdot x_1 \cdot x_2}{b \cdot x_3^2}$$

## General rules

$$Y = \frac{a \cdot X_1 \cdot X_2}{b \cdot X_3}$$

$a$  and  $b$  constants  $> 0$

$$\delta y = \frac{a \cdot x_1 \cdot x_2}{b \cdot x_3} \cdot \left( \frac{\delta x_1}{x_1} + \frac{\delta x_2}{x_2} + \frac{\delta x_3}{x_3} \right)$$

$$\varepsilon y = \frac{\delta y}{y} = \varepsilon x_1 + \varepsilon x_2 + \varepsilon x_3$$



## General rules

$$Y = a \cdot X^n \quad a \text{ constant} > 0$$

$$Y = a \cdot \prod_{i=1}^n X_i$$

The rule of the product can be used

$$\varepsilon_y = N \cdot \varepsilon_x$$



## General rules

$$Y = a \cdot \sqrt[n]{X} \quad a \text{ constant} > 0$$

$$Y = a \cdot X^{\frac{1}{n}}$$

The rule of the power can be used

$$\varepsilon_y = \frac{1}{N} \cdot \varepsilon_x$$