



Applied Electronics

E2 – Linear Voltage Regulators

- Parameters and structure
- Zener and parallel regulators
- Series regulators
- Integrated regulators



Lecture E2: Linear Voltage Regulators

- Power supply types and their parameters
- Parallel regulators: Zener diodes
- Series regulators
 - ◆ Transistor circuits
 - ◆ Circuits with operational amplifiers (and transistors)
- Integrated voltage regulators
 - ◆ Low Dropout Regulators (LDO)
- References
 - ◆ F. Maloberti: Understanding Microelectronics..., Chap. 13



Electrical energy converters

- Electrical energy: different forms
 - ◆ Ac (Alternate Current): alternating voltage (sinusoidal)
 - Supplied by alternators, distribution network, inverters, ...
 - ◆ Dc (Direct Current): direct voltage (constant voltage)
 - Supplied by batteries, solar cells, fuel-cells, **dc power supplies**
- Electrical energy converter
 - ◆ Transform one form of (electrical) energy into another, or into the same with other parameters
 - ◆ Objectives
 - Low losses / high yield
 - Well controlled output parameters (voltage, frequency, ...)
 - Protections (no damage to the load or the source)



Overall converter picture

- $Ac \rightarrow ac$
 - ◆ Transformers
 - ◆ Converters ($ac \rightarrow dc \rightarrow ac$)
- $Ac \rightarrow dc$
 - ◆ Power Supplies
- $Dc \rightarrow ac$
 - ◆ Inverter
- $Dc \rightarrow dc$
 - ◆ Regulators
 - ◆ Converters ($dc \rightarrow ac \rightarrow dc$)



Power systems

- Specifications
 - ◆ Input voltage/current, type, ...
 - ◆ **Output voltage and current** (maximum ranges allowed)
 - ◆ Adjustment, stability, performance, ...
 - ◆ Special needs (precision, fail-safe, ...)
- Functional units
 - ◆ Input protections
 - ◆ Galvanic isolation (if required)
 - ◆ Ac-dc conversion (may have a filter)
 - ◆ Regulator
 - ◆ Output protection



Input parameters

- Type
 - ◆ Ac, dc, battery, dynamo, solar panel, ...
- Nominal value and range
 - ◆ 100–240 Vac, 12 Vdc \pm 10 %, ...
- Frequency (if ac)
 - ◆ 50 Hz, 45–65 Hz, 400 Hz, ...
- Noise and spurious
 - ◆ Harmonics
 - ◆ Transients
 - ◆ ...

Output parameters

- Nominal values (are on label) and tolerances
 - ◆ Output voltage V_O : 12 V, 5 V \pm 10 %, ...
 - ◆ Current I_O (min, max, ...): 0.1 A, 0–50 A, ...
 - ◆ Ripple (periodic changes) and noise (random changes)

- Stability

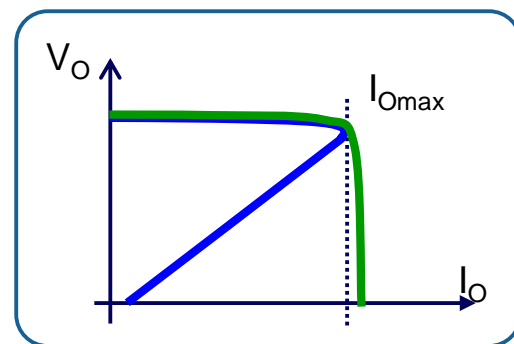
- ◆ Stabilization as the load varies:
- ◆ Stabilization for input variations (line):

$$R_O = \Delta V_O / \Delta I_O$$

$$S_V = \Delta V_O / \Delta V_I$$

- Other parameters

- ◆ Foldback, fail safe, protections, ...
- ◆ Temperature: max, min, derating, ...
- ◆ Early power-off signal



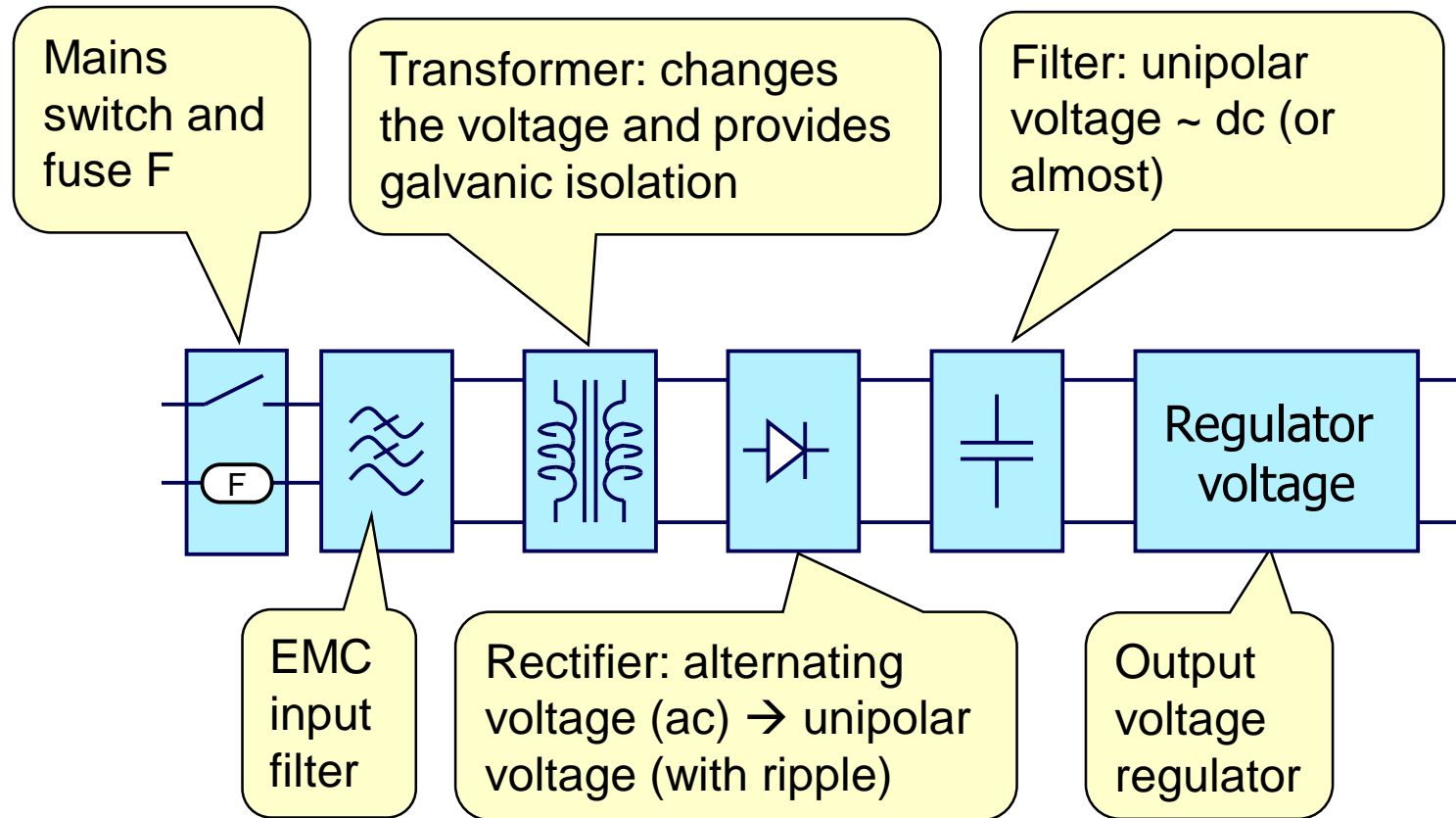


Safety and protections

- Prevent damage other parts of the system
 - ◆ User (safety) No electric shock! → galvanic isolation
 - ◆ Load Avoid output overvoltage
 - ◆ Input source
(mains or battery) Input current limiter (fuse)
 - ◆ EMC Do not generate external noise
 - ◆ Fail-safe Do no harm in case of failure
- Power system protection
 - ◆ Output current limiter (in case of faults or shorts)
 - ◆ Protect from input overvoltage
 - ◆ Temperature (ambient and heat dissipation)
 - ◆ ...



Block diagram of “classic” PSU





Input loop

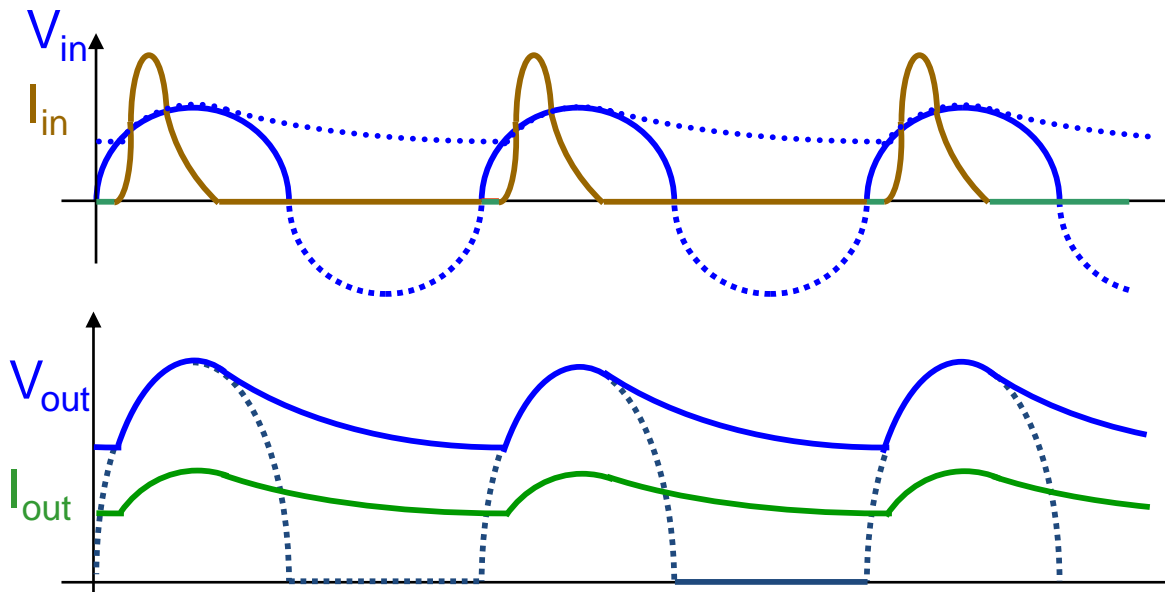
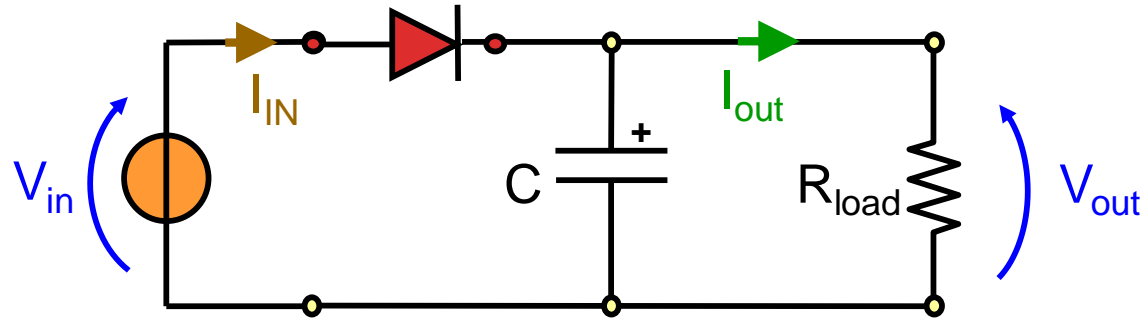
- The mains ON/OFF **switch** isolate the supply
 - ◆ Not always present; often OFF is a standby
- Input **filter**
 - ◆ Blocks conducted interferences
 - ◆ Passive filter
- **Fuse**: disconnects excessive currents, fault protection
- **Transformer**
 - ◆ Brings the voltage to desired value, with good yield (η)
 - ◆ Guarantees **galvanic isolation** – safety!
 - ◆ **Big, heavy, expensive, ...**
 - Move to **switching power supplies**



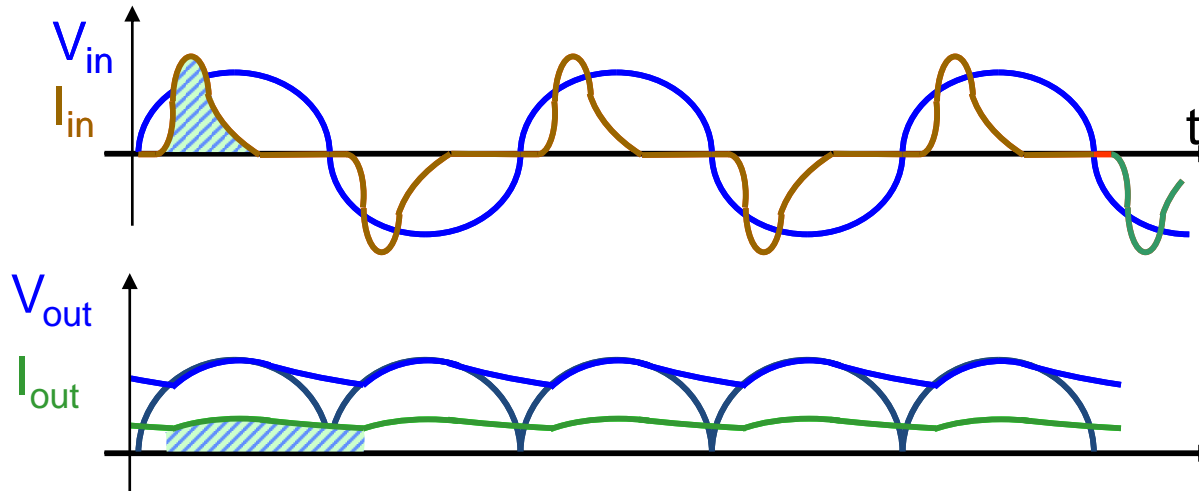
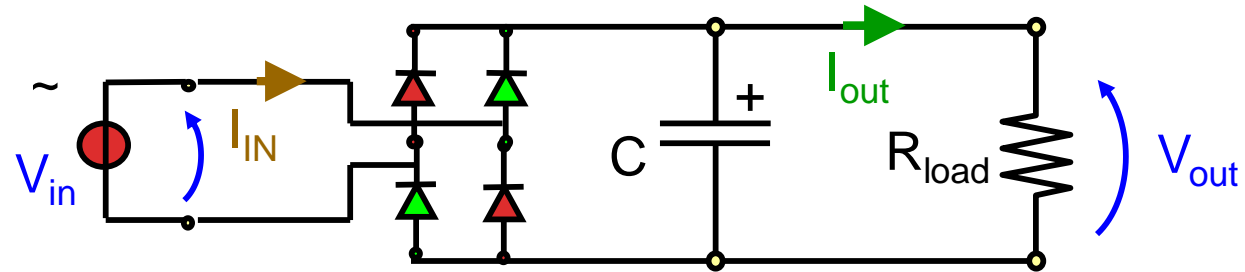
Ac–dc conversion

- Ac–dc conversion requires two basic elements
- Rectifier
 - ◆ Transforms bipolar ac voltage into unipolar voltage
 - ◆ Use standard diodes (or controlled diodes for high power)
 - ◆ The rectified voltage has a dc component and many ac components (harmonics of the mains ac)
- Hum filter
 - ◆ Transfers the dc component without attenuation
 - ◆ Removes or reduces the ac components
 - ◆ **Passive** circuit: low-pass filter **RC, LC**

Half-wave rectifier



Full-wave rectifier



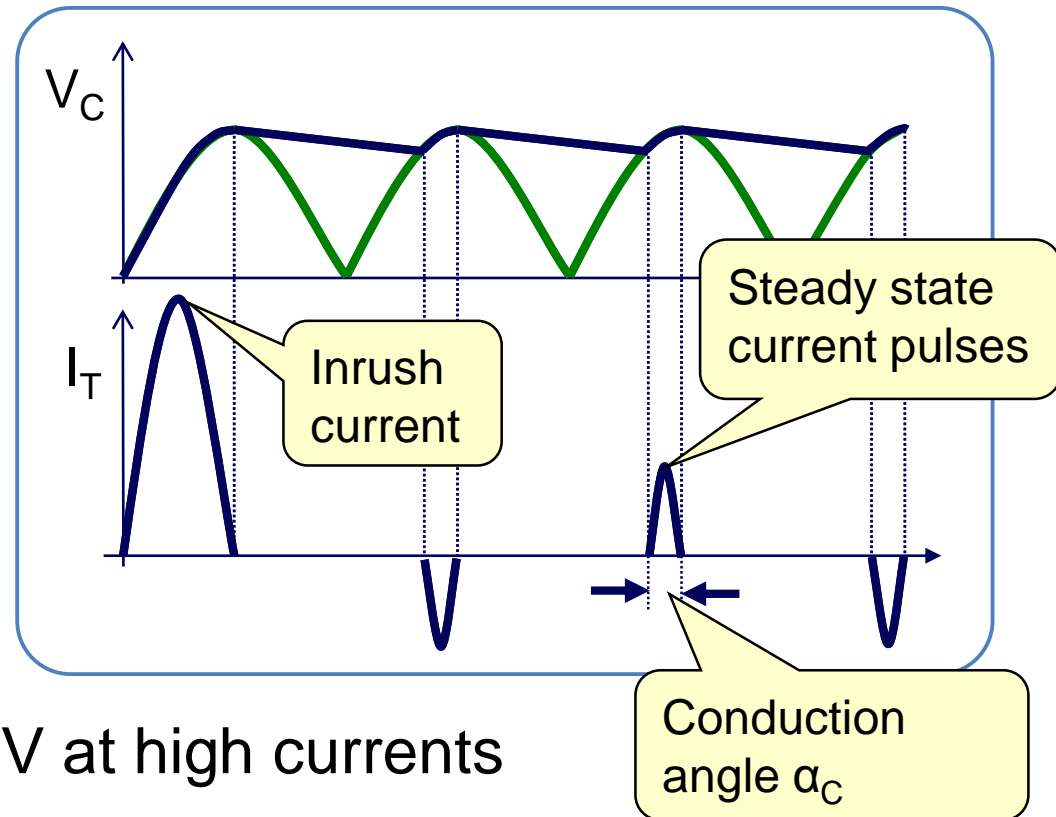
Current flow

- First cycle

- ◆ Fully charge the filter capacitor
- ◆ High current, "inrush"

- Steady state

- ◆ Peak current much higher than the output average current ($\approx \times 5$ if the diode conducts 20 % of the time)
- ◆ Voltage drop on diodes ≈ 1 V at high currents
- ◆ Non-sinusoidal current
 - Harmonics, noise emission



Output ripple

- Simplifying hypotheses

- ◆ Linear C discharge, i.e., constant load current
- ◆ Sawtooth ripple, i.e., C fully charges at
 - Half-wave rectifier: $K \cdot T$
 - Full-wave rectifier: $K \cdot T/2$

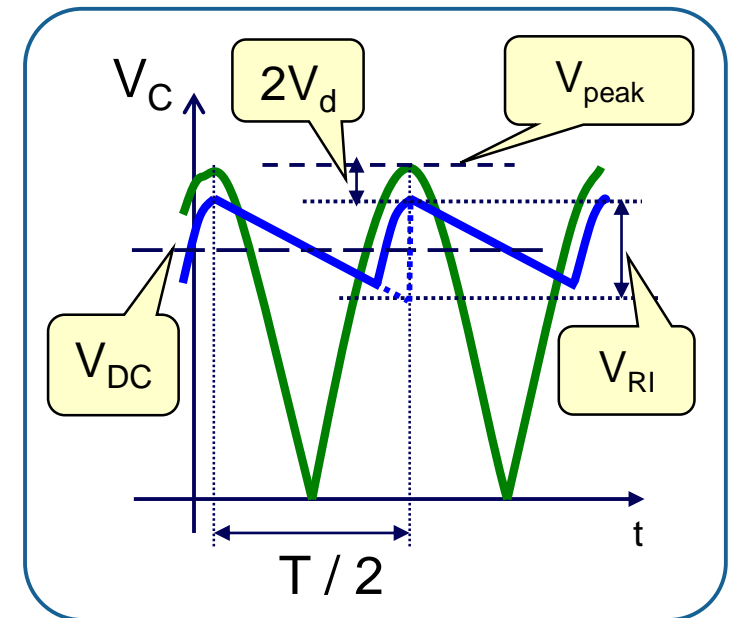
- Full-wave rectifier ripple voltage

- ◆ $V_{RI} = (I_O T/2) / C = I_O / (2 f C)$
- ◆ Half-wave rectifier: T instead of $T/2$

- Output voltage V_{DC}

- ◆ $V_{DC} = V_{peak} - V_{RI} / 2$
- ◆ With a V_d drop on the diode

$$V_{DC} = V_{peak} - 2 V_d - V_{RI} / 2$$



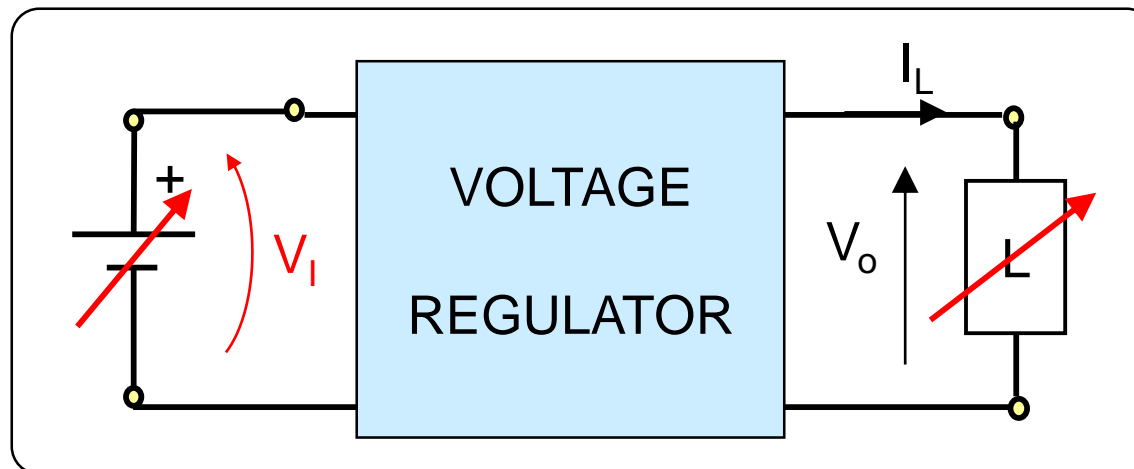


Disadvantages of the “classic” structure

- Transformer works at mains frequency (50/60 Hz)
 - ◆ Bulky, heavy, expensive
- For low ripple
 - ◆ Large filter capacitors → bulky and expensive
 - ◆ Strong impulsive currents → diode losses, interferences (EMI)
 - Forbidden by EC rules for powers $> 10\text{ W}$
- Alternative structures
 - ◆ Active regulators to reduce the ripple
 - ◆ Switching Power Supplies
 - Move the transformer to high frequencies
 - High efficiency, small size
 - Mandatory by EC rules for $P > 10\text{ W}$

Output voltage regulator

- The voltage regulator supplies constant V_O
 - ◆ Stabilization for load variations $S_L = \Delta V_O / \Delta I_L$
 - Equivalent output resistance $R_O = S_L$
 - ◆ Stabilization for input voltage V_I variations
 - Input / output regulation $S_I = \Delta V_O / \Delta V_I$
 - Reduction of ripple (seen as a V_I change)





Active (linear) regulator

- Parallel regulators (shunt)
 - ◆ Zener diode
 - ◆ Voltage references
- Series regulators
 - ◆ Circuits with transistors and operational amplifiers
 - ◆ Can limit the current
- Integrated regulators
 - ◆ Standard
 - ◆ 3-terminals
 - ◆ Low-DropOut (LDO)

Series and parallel regulators

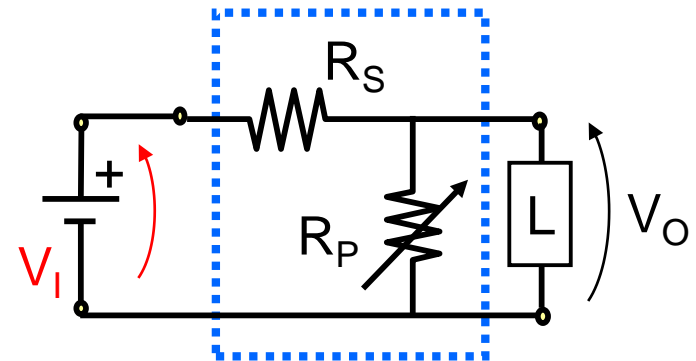
- Objective

- ◆ V_O constant for variations of V_I , L

- Two basic techniques

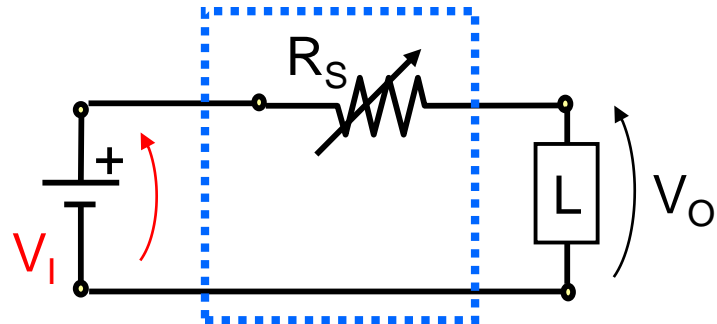
- ◆ *Current divider*

- Change the split ratio acting on the parallel branch R_P
- **Parallel** regulator



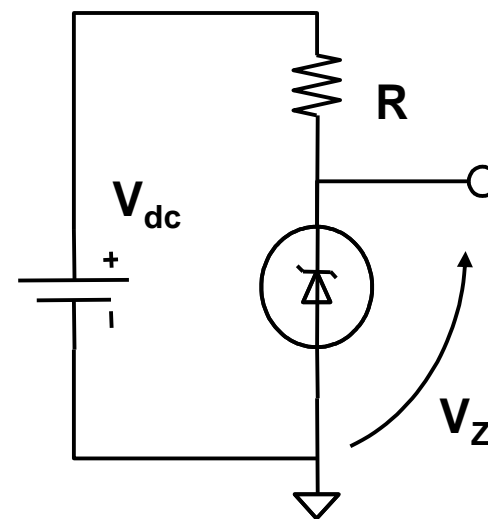
- ◆ *Voltage divider*

- Change the ratio by acting on the series branch R_S
- **Series** regulator



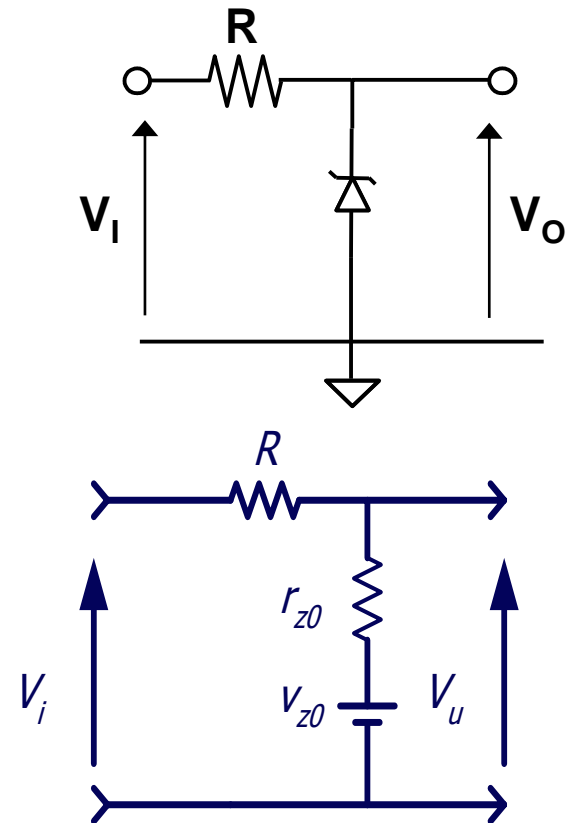
Parallel regulator (Zener diode)

- Basic parallel controller: **Zener diode**
 - ◆ Very simple
 - ◆ Low efficiency, suitable for low power
 - ◆ Voltage references are parallel regulators (low current)
- Currents in Zener diodes
 - ◆ Higher than I_{Zmin} (~5 mA)
 - ◆ Lower than I_{Zmax}
 - To limit the dissipated power



Exercise E2.1: Zener regulator

- Design a parallel regulator with
 - ◆ $V_I = 10\text{ V} \rightarrow 20\text{ V}$
 - ◆ $V_O = 5\text{ V}$ (as close as possible)
 - ◆ $I_O = 0\text{ mA} \rightarrow 100\text{ mA}$
- Available Zener diode
 - ◆ $V_{ZO} = 5\text{ V}$, $R_Z = 1\text{ }\Omega$, $I_{Zmin} = 5\text{ mA}$
 - ◆ $P_{Zmax} = 2\text{ W}$
- Calculate
 - ◆ Drop resistance R (min/max)
 - ◆ V_O min/max (various combinations of V_I , I_O , R)
 - ◆ P_{Rmax} for R





Exercise E2.1: Zener regulator: R_{\min}

$$V_I = V_R + V_O = R I_R + V_O = R(I_O + I_Z) + V_O$$

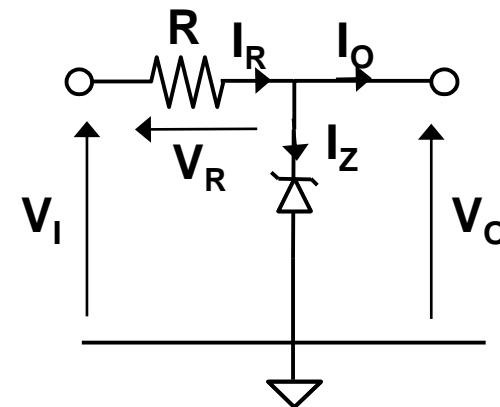
$$R = \frac{V_I - V_O}{I_O + I_Z}$$

The minimum R value should limit the power dissipation on the Zener diode when through it flows the maximum current, i.e.:

$$V_{I\max} = 20 \text{ V}, I_{O\min} = 0 \text{ A}$$

$$I_{Z\max} = P_{Z\max} / V_{ZO} = 2 \text{ W} / 5 \text{ V} = 400 \text{ mA}$$

$$R_{\min} = \frac{20 \text{ V} - 5 \text{ V}}{0 \text{ A} + 0.4 \text{ A}} = 37.5 \Omega$$





Exercise E2.1: Zener regulator: R_{\max}

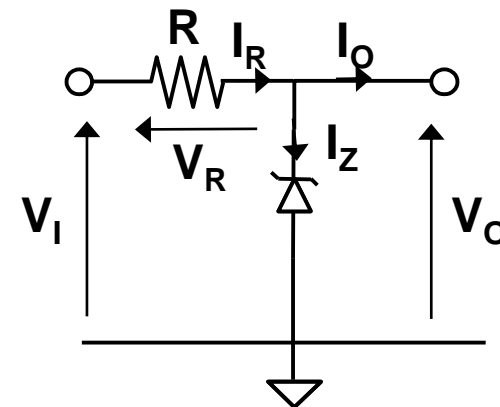
$$V_I = V_R + V_O = R I_R + V_O = R(I_O + I_Z) + V_O$$

$$R = \frac{V_I - V_O}{I_O + I_Z}$$

The voltage drop on the maximum R should allow the Zener diode to regulate (i.e., $I_Z \geq I_{Z\min}$) when V_I is minimum and output (load) current I_O is maximum

$$V_{I\min} = 10 \text{ V}, I_{O\max} = 100 \text{ mA}, I_{Z\min} = 5 \text{ mA}$$

$$R_{\max} = \frac{10 \text{ V} - 5 \text{ V}}{0.1 \text{ A} + 0.005 \text{ A}} = 47.62 \Omega$$





Exercise E2.1: Zener regulator: $V_{Omin/max}$

$$V_O = I_Z R_Z + V_Z$$

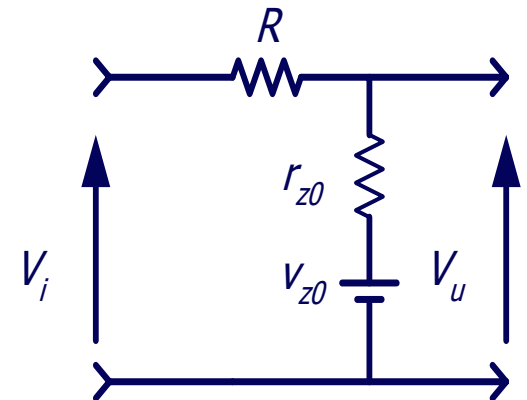
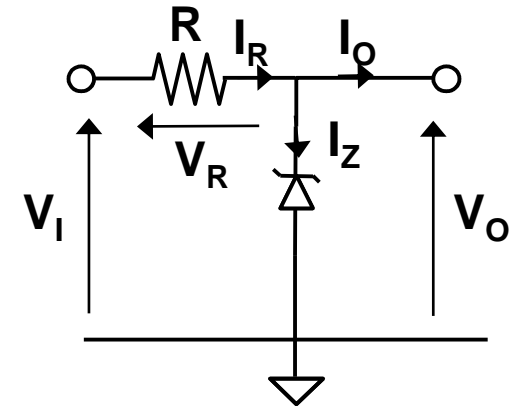
$$V_{Omin} = I_{Zmin} R_Z + V_Z$$

$$V_{Omin} = 5 \text{ mA} \cdot 1 \Omega + 5 \text{ V} = 5.005 \text{ V}$$

$$V_{Omax} = I_{Zmax} R_Z + V_Z$$

$$I_{Zmax} = \frac{P_{Zmax}}{V_Z} = \frac{2 \text{ W}}{5 \text{ V}} = 0.4 \text{ A}$$

$$V_{Omax} = 0.4 \text{ A} \cdot 1 \Omega + 5 \text{ V} = 5.4 \text{ V}$$



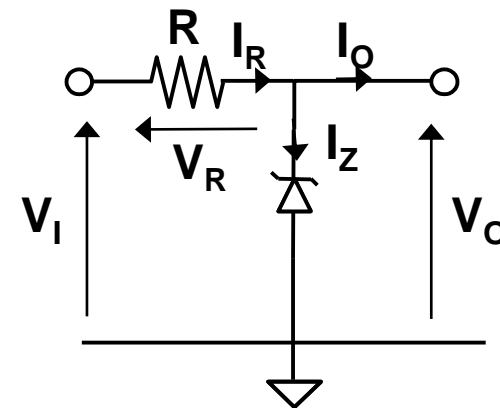
Exercise E2.1: Zener regulator: P_{Rmax}

The power dissipated in R

$$P_R = \frac{V_R^2}{R}$$

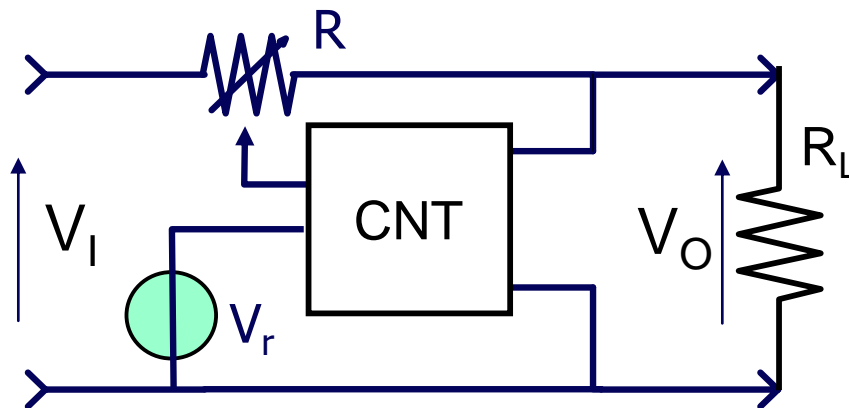
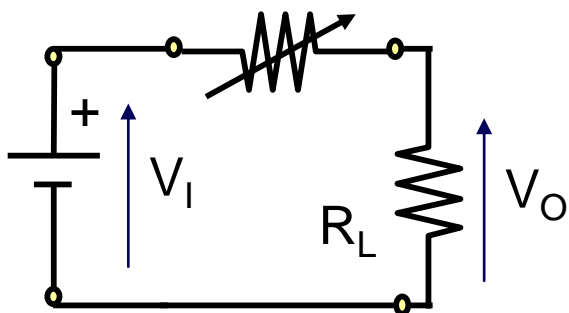
Maximum dissipated power in R
is for maximum V_R and minimum R

$$P_{Rmax} = \frac{V_{Rmax}^2}{R_{min}} = \frac{(20\text{ V} - 5\text{ V})^2}{37.5\ \Omega} = 6\text{ W}$$



Series regulator – basic schematic

- The series regulator acts as a variable resistor to reduce power consumption
 - ◆ The variable resistor is a BJT or MOS
 - ◆ The CNT controller compares the V_O output with a reference V_r



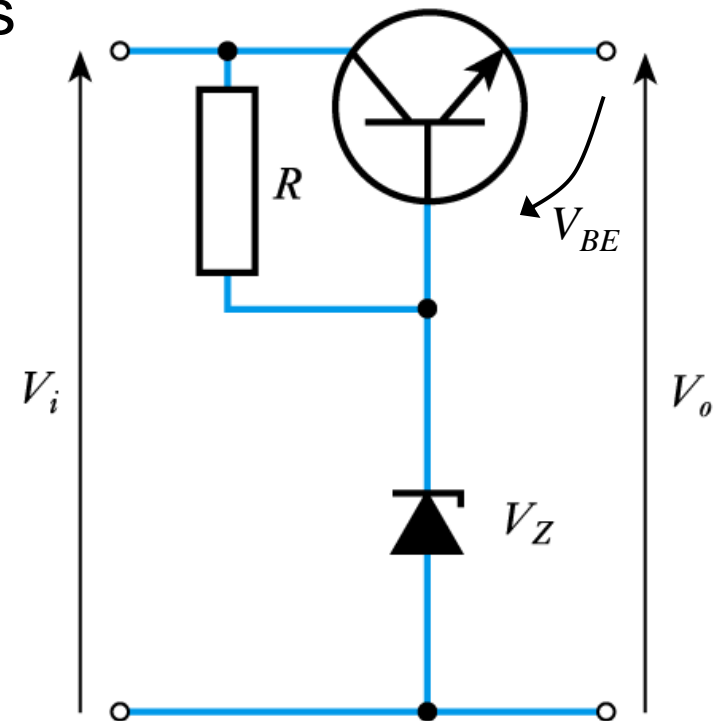


Series Regulators

- Require a controlled “variable resistor”
 - ◆ Can use BJT or MOS
 - ◆ Current amplifier controlled by the voltage reference
 - ◆ Implemented with voltage reference and op-amp
- Always $V_O < V_I$
 - ◆ All regulators require a minimum voltage drop (V_{drop})
 - Losses, reduces efficiency
 - ◆ Low Drop Out (LDO) low drop / high efficiency regulators
- Available as standard integrated circuits (commodity)
 - ◆ Fixed voltage (5 V, 6 V, 9 V, 12 V, ...)
 - ◆ Variable voltage

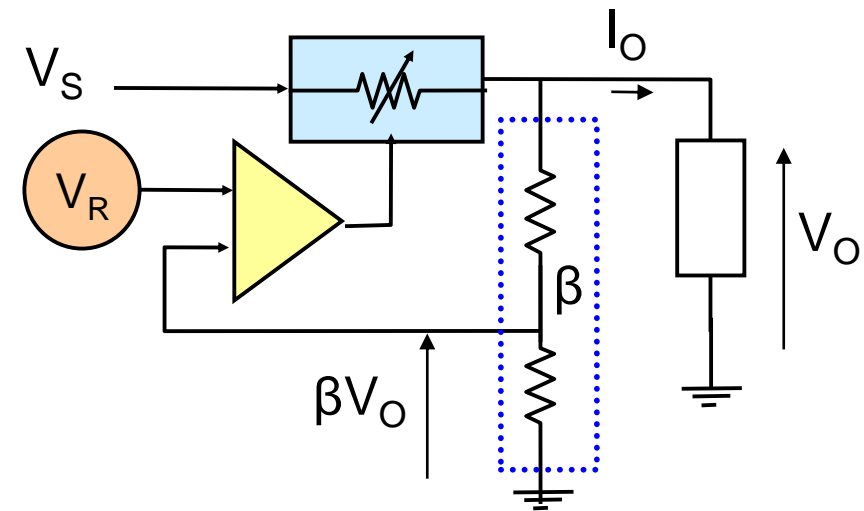
Example of series regulator

- Resistance-Zener base regulator
 - ◆ Regulates by splitting the current between the Zener and load
 - ◆ Low efficiency, can manage low currents
- V_Z and current amplifier with emitter follower (CC)
 - ◆ Output voltage
$$V_O = V_Z - V_{BE} \rightarrow \text{same } S_i \text{ of the Zener}$$
 - ◆ Load current can vary widely
$$\Delta I_O = \Delta I_Z \beta \rightarrow \text{lower } R_O (S_L)$$



Reaction regulator

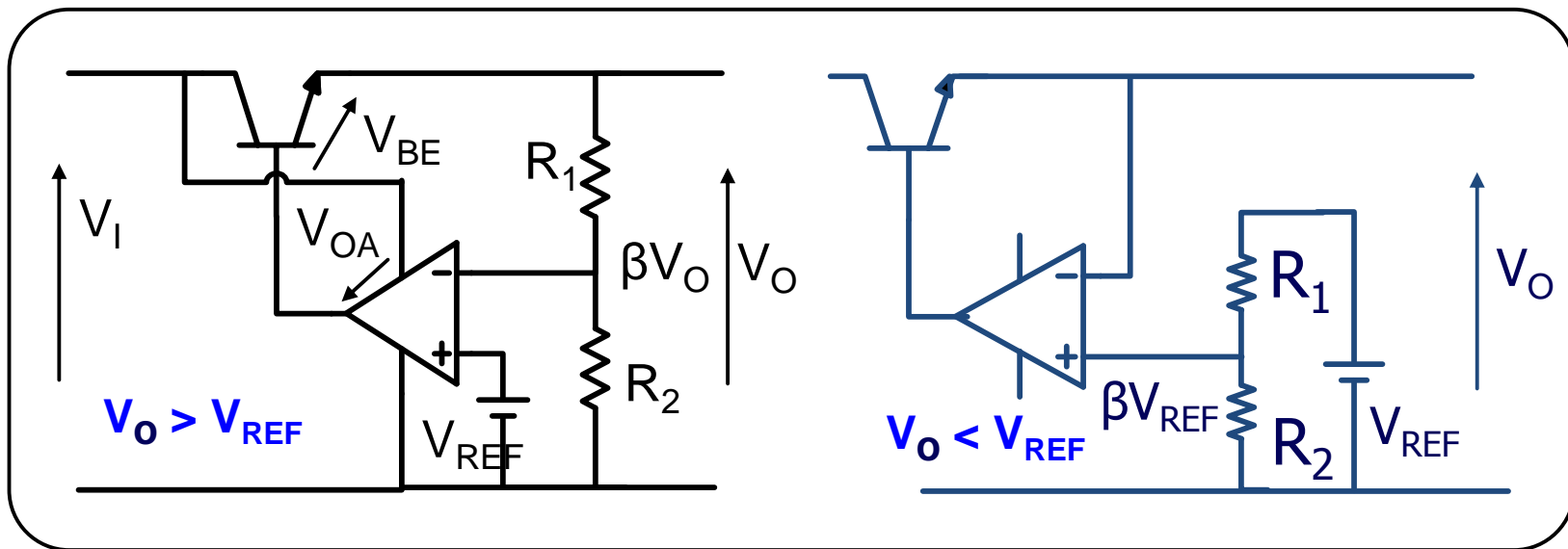
- Reference generator and amplifier
 - ◆ Compare a fraction β of the output voltage V_O with the reference voltage V_R
- Drive the control element to keep
$$\beta V_O = V_R$$
- We need a **voltage reference** (V_R , generated with a Zener diode or other means)



Regulator with op-amp and BJT

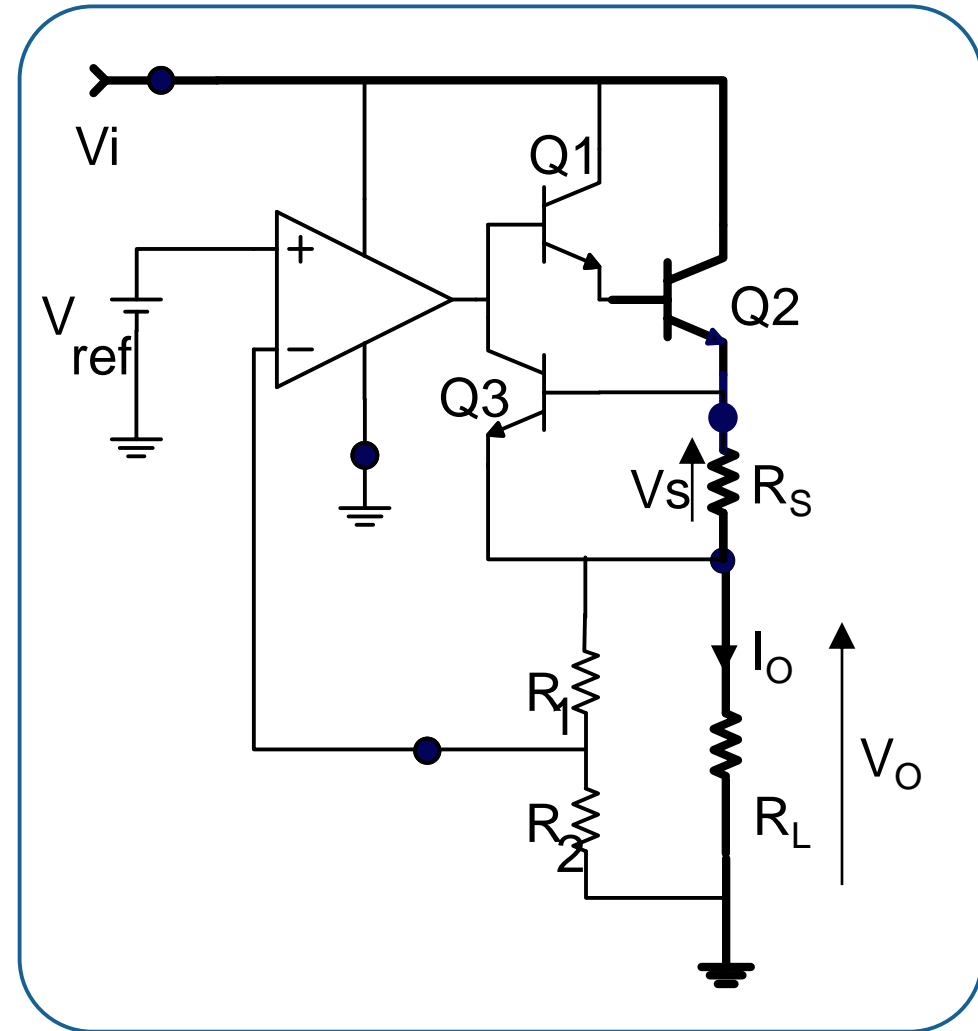
- BJT used as Common Collector power stage

- ◆ If $V_O > V_{REF} \rightarrow \beta V_O = V_{REF}$
- ◆ If $V_O < V_{REF} \rightarrow V_O = \beta V_{REF}$
- ◆ Voltage drop from V_I to V_O is V_{OA} (within the op-amp) + V_{BE}



Current limiter

- Power transistors Q1 + Q2 (Darlington configuration)
- Current sense: R_S
 - ◆ If V_S exceeds 0.7 V, Q3 draws current from Q1 base
 - ◆ Reduced current in Q1 and Q2
- $I_{Omax} = 0.7 / R_S$





Efficiency of series regulators

- Losses from voltage drops and “leakage” currents, I_{LEAK} (or quiescent currents, I_Q)
 - ◆ Includes the supply of the op-amp, the Zener diode, etc.
 - ◆ Normally, $I_{LEAK} \ll I_{OUT}$

$$\eta = \frac{P_{OUT}}{P_{IN}} = \frac{V_{OUT} \times (I_{IN} - I_{LEAK})}{V_{IN} \times I_{IN}} \cong \frac{V_{OUT}}{V_{IN}}$$

- To improve performance
 - ◆ Reduce voltage drop \rightarrow regulators Low-DropOut (LDO)
 - ◆ Reduce leakage currents, $I_{LEAK} \rightarrow$ low power ref. voltage, V_R
 - ◆ Use **switching regulators**



Commercial voltage regulators

- Are available many integrated regulators
- Linear regulators: 78xx family (positive voltages)
 - ◆ XX = output voltage
 - ◆ High power cases
 - ◆ Max current depends on package and heatsink
 - 50 mA ... 5 A
- Other devices
 - ◆ 79xx family: negative voltages
 - ◆ 317 Family: variable output voltages
 - ◆ LM9076: LDO
 - ◆



78xx data sheet

KA78XXE / KA78XXAE

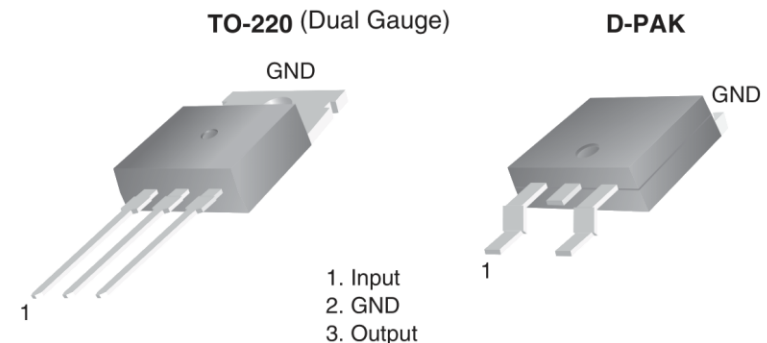
3-Terminal 1 A Positive Voltage Regulator

Features

- Output Current up to 1 A
- Output Voltages of 5, 6, 8, 9, 10, 12, 15, 18, 24 V
- Thermal Overload Protection
- Short-Circuit Protection
- Output Transistor Safe Operating Area Protection

Description

The KA78XXE / KA78XXAE series of three-terminal positive regulators is available in the TO-220 / D-PAK package with several fixed-output voltages, making them useful in a wide range of applications. Each type employs internal current limiting, thermal shut-down, and safe operating area. If adequate heat sinking is provided, they can deliver over 1 A output current. Although designed primarily as fixed-voltage regulators, these devices can be used with external components for adjustable voltages and currents.





78xx data sheet

Electrical Characteristics (KA7805E / KA7805ER)

Refer to test circuit, $-40^{\circ}\text{C} < T_J < 125^{\circ}\text{C}$, $I_O = 500 \text{ mA}$, $V_I = 10 \text{ V}$, $C_I = 0.33 \mu\text{F}$, $C_O = 0.1 \mu\text{F}$, unless otherwise specified.

Symbol	Parameter	Conditions	Min.	Typ.	Max.	Unit
V_O	Output Voltage	$T_J = +25^{\circ}\text{C}$	4.80	5.00	5.20	V
		$5.0 \text{ mA} \leq I_O \leq 1.0 \text{ A}$, $P_O \leq 15 \text{ W}$, $V_I = 7 \text{ V to } 20 \text{ V}$	4.75	5.00	5.25	
Regline	Line Regulation ⁽³⁾	$T_J = +25^{\circ}\text{C}$	$V_I = 7 \text{ V to } 25 \text{ V}$	4.0	100.0	mV
			$V_I = 8 \text{ V to } 12 \text{ V}$	1.6	50.0	
Regload	Load Regulation ⁽³⁾	$T_J = +25^{\circ}\text{C}$	$I_O = 5.0 \text{ mA to } 1.5 \text{ A}$	9	100	mV
			$I_O = 250 \text{ mA to } 750 \text{ mA}$	4	50	
I_Q	Quiescent Current	$T_J = +25^{\circ}\text{C}$		5	8	mA
ΔI_Q	Quiescent Current Change	$I_O = 5 \text{ mA to } 1.0 \text{ A}$		0.03	0.50	mA
		$V_I = 7 \text{ V to } 25 \text{ V}$		0.30	1.30	
$\Delta V_O / \Delta T$	Output Voltage Drift ⁽⁴⁾	$I_O = 5 \text{ mA}$		-0.8		mV/ $^{\circ}\text{C}$
V_N	Output Noise Voltage	$f = 10 \text{ Hz to } 100 \text{ kHz}$, $T_A = +25^{\circ}\text{C}$		42		μV
RR	Ripple Rejection ⁽⁴⁾	$f = 120 \text{ Hz}$, $V_I = 8 \text{ V to } 18 \text{ V}$	62	73		dB
V_{Drop}	Dropout Voltage	$I_O = 1 \text{ A}$, $T_J = +25^{\circ}\text{C}$		2		V
R_O	Output Resistance ⁽⁴⁾	$f = 1 \text{ kHz}$		15		m Ω
I_{SC}	Short-Circuit Current	$V_I = 35 \text{ V}$, $T_A = +25^{\circ}\text{C}$		230		mA
I_{PK}	Peak Current ⁽⁴⁾	$T_J = +25^{\circ}\text{C}$		2.2		A

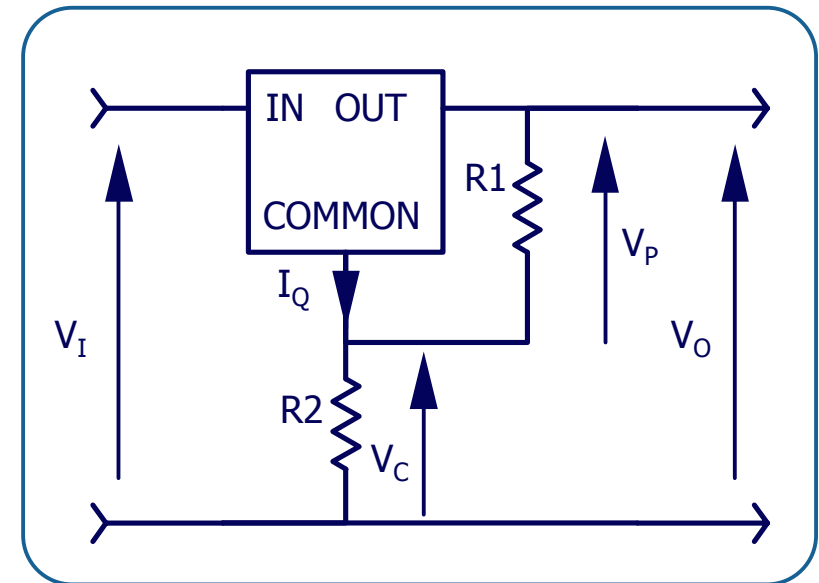
Notes:

3. Load and line regulation are specified at constant junction temperature. Changes in V_O due to heating effects must be taken into account separately. Pulse testing with low duty is used.

4. These parameters, although guaranteed, are not 100% tested in production.

Variable voltages with 3-pin regulators

- 3-pin regulators maintain a predetermined voltage V_P between the OUT and COMMON pins
 - ◆ We ignore the quiescent current I_Q
 - ◆ $V_P = V_O R1 / (R1 + R2)$
 - ◆ $V_O = V_P (R1 + R2) / R1$
- Replacing $I_Q R2$ with its Thevenin equivalent, we add $I_Q R2$ to the output loop
 - ◆ $V_O = V_P (R1 + R2) / R1 + I_Q R2$





Exercise E2.2: voltage regulator design

- Specifications: PSU with linear regulator for 5 V, 1 A load
 - ◆ Draw the block diagram with and without regulator
 - ◆ Define the characteristics of the transformer, diodes, capacitor
 - ◆ Evaluate S_V (stabilization) and R_O (output resistance)
- Add a Zener diode regulator
 - ◆ Define the Zener diode parameters
 - ◆ Evaluate the new S_V and R_O
- Add a power transistor (CC)
 - ◆ Evaluate the new S_V and R_O
- Find (from catalog) a suitable 3-pin regulator
 - ◆ Compare the S_V and R_O with the previous results



Lecture E2 – final check

- What parameters define the characteristics of a regulator?
- Draw the block diagram of a power supply with regulator, describing the functions of each module.
- Plot the waveforms of voltages and currents for a double half-wave (loaded) rectifier.
- Describe how to calculate and measure the output ripple of an unstabilized power supply.
- Describe the differences between parallel and series regulators.
- What are the benefits of feedback voltage regulators?
- Explain how to obtain from a three-terminal (fixed voltage) regulator a different voltage than the one set.