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CSE 351 #1

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linearity condition,

$$i) f_1(t) \rightarrow \boxed{\quad} \rightarrow y_1(t)$$

$$f_2(t) \rightarrow \boxed{\quad} \rightarrow y_2(t)$$

$$ii) k_1 f_1(t) + k_2 f_2(t) \rightarrow \boxed{\quad} \rightarrow k_1 y_1(t) + k_2 y_2(t)$$

a)

$$\frac{dy(t)}{dt} + 2y(t) = f^2(t)$$

$$i) \frac{dy_1}{dt} + 2y_1(t) = f_1^2(t) \rightarrow \frac{dk_1 y_1(t)}{dt} + 2k_1 y_1(t) = k_1 f_1^2(t)$$

$$\frac{dy_2}{dt} + 2y_2(t) = f_2^2(t) \rightarrow \frac{dk_2 y_2(t)}{dt} + 2k_2 y_2(t) = k_2 f_2^2(t)$$

$$\frac{d}{dt} \left[\underbrace{k_1 y_1(t) + k_2 y_2(t)}_{y(t)} \right] + 2 \left[\underbrace{k_1 y_1(t) + k_2 y_2(t)}_{y(t)} \right] = \underbrace{k_1 f_1^2(t) + k_2 f_2^2(t)}_{f_i(t)}$$

$$f_i(t) = k_1 f_1^2(t) + k_2 f_2^2(t)$$

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$$ii) \frac{d}{dt} \left[\underbrace{k_1 y_1(t) + k_2 y_2(t)}_{y(t)} \right] + 2 \left[\underbrace{k_1 y_1(t) + k_2 y_2(t)}_{y(t)} \right] = \underbrace{[k_1 f_1(t) + k_2 f_2(t)]^2}_{f_{ii}(t)}$$

Since $f_1(t) \neq f_{ii}(t)$, this system is non-linear. ~~\times~~

b) $\frac{dy(t)}{dt} + 3ty(t) = t^2 f(t)$

i) $\frac{dy_1(t)}{dt} + 3ty_1(t) = t^2 f_1(t) \rightarrow \frac{dk_1 y_1(t)}{dt} + 3fk_1 y_1(t) = t^2 k_1 f_1(t)$

$$\frac{dy_2(t)}{dt} + 3ty_2(t) = t^2 f_2(t) \rightarrow \frac{dk_2 y_2(t)}{dt} + 3tk_2 y_2(t) = t^2 k_2 f_2(t)$$

$$\frac{d}{dt} \left[\underbrace{k_1 y_1(t) + k_2 y_2(t)}_{y(t)} \right] + 3t \left[\underbrace{k_1 y_1(t) + k_2 y_2(t)}_{y(t)} \right] = t^2 \left[\underbrace{k_1 f_1(t) + k_2 f_2(t)}_{f_{ii}(t)} \right]$$

ii) $\frac{d}{dt} \left[\underbrace{k_1 y_1(t) + k_2 y_2(t)}_{y(t)} \right] + 3t \left[\underbrace{k_1 y_1(t) + k_2 y_2(t)}_{y(t)} \right] = t^2 \left[\underbrace{k_1 f_1(t) + k_2 f_2(t)}_{f_{ii}(t)} \right]$

Since $f_1(t) = f_{ii}(t)$, this system is linear.

2)

a) Characteristic Equation: $(\lambda^2 + 5\lambda + 6) = 0$

$$(\lambda+2)(\lambda+3) = 0$$

$$\lambda_1 = -2 \quad \lambda_2 = -3$$

$$y_0(t) = c_1 e^{\lambda_1 t} + c_2 e^{\lambda_2 t} = c_1 e^{-2t} + c_2 e^{-3t}$$

$$y_0'(t) = -2c_1 e^{-2t} - 3c_2 e^{-3t}$$

Set $t=0$ using $y_0(0)=2, y_0'(0)=-1$

$$\begin{aligned} c_1 + c_2 &= 2 \\ -2c_1 - 3c_2 &= -1 \end{aligned} \quad \left. \begin{array}{l} c_1 = 5 \\ c_2 = -3 \end{array} \right\}$$

$y_0(t) = 5e^{-2t} - 3e^{-3t}$

b)

$$f(t) = u(t) \rightarrow h(t) = e^{-t}u(t) \rightarrow y(t) = ?$$

$$\begin{aligned} y(t) &= h(t) * f(t) \\ &= e^{-t}u(t) * u(t) \\ &= (1 - e^{-t})u(t) \end{aligned}$$

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3)

$$a) \quad y(k+1) + 2y(k) = f(k) \rightarrow (E+2)y(k) = f(k)$$

$$h(k) = \frac{b_0}{a_0} \delta(k) + y_0(k) u(k)$$

Characteristic Equation $(Y+2) = 0 \Rightarrow Y = -2$

$$y_0(k) = c(Y)^k = c(-2)^k$$

$$\text{Also, } a_0 = 2, b_0 = 1$$

Therefore

$$h(k) = \frac{1}{2} \delta(k) + c(-2)^k$$

Use iterative solution to determine c .

$$(E+2)h(k) = \delta(k)$$

$$h(k+1) + 2h(k) = \delta(k)$$

Set $k = -1$ and substitute $h(-1) = \delta(-1) = 0$

$$h(0) = 0$$

For $k=0$ and use $h(0) = 0$

$$0 = \frac{1}{2} + c(-2)^0 \Rightarrow c = -\frac{1}{2}$$

As a result,

$$h(k) = \frac{1}{2} \delta(k) - \frac{1}{2} (-2)^k u(k)$$

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$$b) h(k) = (-2)^k u(k), f(k) = e^{-k} u(k) \rightarrow y(k) = f(k) \neq h(k)$$

$$f_1(k) = \gamma^k u(k), f_2(k) = \gamma_2^k u(k), \gamma_1 \neq \gamma_2$$

$$f_1(k) * f_2(k) = \left[\frac{\gamma_1^{k+1} - \gamma_2^{k+1}}{\gamma_1 - \gamma_2} \right] u(k)$$

$$y(k) = e^{-k} u(k) * (-2)^k u(k)$$

$$= \left(\frac{1}{e} \right)^k u(k) * (-2)^k \cdot u(k)$$

$$= \left[\frac{(1/e)^{k+1} - (-2)^{k+1}}{(1/e) + 2} \right] u(k)$$

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