

Continuum Mechanics

Design of a Gravity Dam

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- Algebra Recap
- Recap Lecture 3
Failure Criteria
- Hands on session
3.1 Gravity Dam

Algebra Recap

Tensor/Vector product

- Scalar product :

$$\underline{a}, \underline{b} \in \mathbb{R}^a \quad \langle \underline{a}, \underline{b} \rangle = \sum_{m=1}^a a_m b_m$$

- Tensors and tensor product :

$$\underline{\underline{A}} \in \mathbb{R}^a \rightarrow \mathbb{R}^b \quad \underline{\underline{A}} = \underline{a} \otimes \underline{b}, \underline{a} \in \mathbb{R}^a, \underline{b} \in \mathbb{R}^b$$

- Tensor application to vector :

$$\underline{\underline{A}} = \underline{a} \otimes \underline{b} \in \mathbb{R}^a \rightarrow \mathbb{R}^b, \underline{c} \in \mathbb{R}^b \quad \underline{\underline{A}}.\underline{c} = \underline{a} \langle \underline{b}, \underline{c} \rangle$$

- Tensor/Tensor product :

$$\underline{\underline{A}} = \underline{a} \otimes \underline{b} \in \mathbb{R}^a \rightarrow \mathbb{R}^b, \underline{\underline{B}} = \underline{c} \otimes \underline{d} \in \mathbb{R}^b \otimes \mathbb{R}^c \quad \underline{\underline{A}}.\underline{\underline{B}} = \underline{a} \otimes \underline{d} \langle \underline{b}, \underline{c} \rangle$$

Some algebra (cont'd)

Tensor/Vector product

- Vector gradient :

$$\underline{a} \in \mathbb{R}^a \quad \underline{\underline{\mathbb{D}_x a}} = \sum_{m=1}^a \frac{\partial \underline{a}}{\partial x_m} \otimes \underline{e}_m$$

- Vector divergence :

$$\underline{a} \in \mathbb{R}^a \quad \text{div}_x (\underline{a}) = \text{Tr} \left(\underline{\underline{\mathbb{D}_x a}} \right) = \langle \underline{\nabla}_x, \underline{a} \rangle = \sum_{m=1}^a \frac{\partial a_m}{\partial x_m}$$

- Tensor divergence :

$$\underline{\underline{A}} \in \mathbb{R}^a \rightarrow \mathbb{R}^b \quad \text{div}_x (\underline{\underline{A}}) = \sum_{m=1}^b \frac{\partial \underline{A}}{\partial x_m} \cdot \underline{e}_m$$

Some algebra (cont'd)

Tensor/Vector product in cylindrical coordinates

- Vector gradient :

$$\underline{a} \in \mathbb{R}^3 \quad \underline{\underline{\mathbb{D}_x a}} = \frac{\partial \underline{a}}{\partial r} \otimes \underline{i}_r(\theta) + \frac{\partial \underline{a}}{\partial \theta} \otimes \frac{\underline{i}_\theta}{r}(\theta) + \frac{\partial \underline{a}}{\partial z} \otimes \underline{i}_z$$

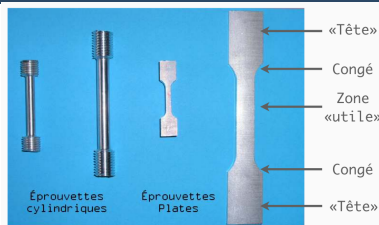
- Vector divergence :

$$\underline{a} \in \mathbb{R}^3 \quad \text{div}_x(\underline{a}) = \text{Tr} \left(\underline{\underline{\mathbb{D}_x a}} \right) = \langle \underline{\nabla}_x, \underline{a} \rangle = \left\langle \frac{\partial \underline{a}}{\partial r}, \underline{i}_r \right\rangle + \left\langle \frac{\partial \underline{a}}{\partial \theta}, \frac{\underline{i}_\theta}{r} \right\rangle + \left\langle \frac{\partial \underline{a}}{\partial z}, \underline{i}_z \right\rangle$$

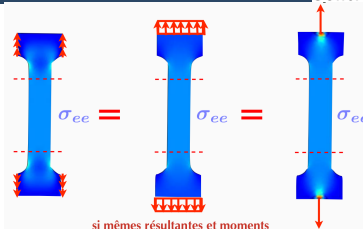
- Tensor divergence :

$$\underline{\underline{A}} \in \mathbb{R}^3 \rightarrow \mathbb{R}^3 \quad \text{div}_x(\underline{\underline{A}}) = \frac{\partial \underline{\underline{A}}}{\partial r} \cdot \underline{i}_r(\theta) + \frac{\partial \underline{\underline{A}}}{\partial \theta} \cdot \frac{\underline{i}_\theta}{r} + \frac{\partial \underline{\underline{A}}}{\partial z} \cdot \underline{i}_z$$

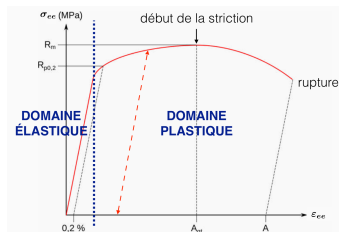
Failure Criteria



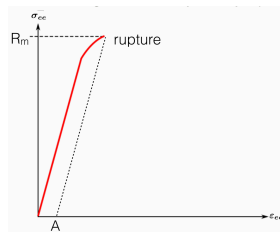
a



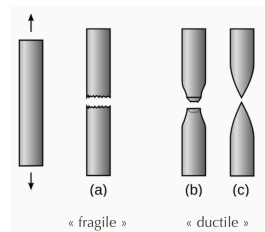
b



c ductile



d fragile



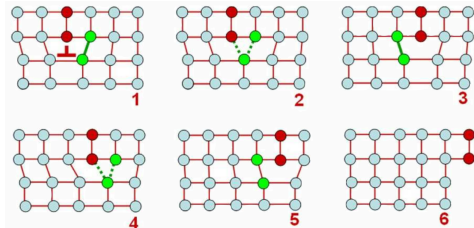
e

Figure – Credits G. Puel

...at atomistic level



a



b

Figure – Credits G. Puel

Splitting failure

- Separation of two atomic planes
- Driven by normal stress component σ_{nn}
- Random atomic planes
 → orientation that maximizes σ_{nn}

$$f\left(\frac{\underline{\sigma}}{\underline{n}}\right) = \max_{\|\underline{n}\|=1} \sigma_{nn}(\underline{x}; t) - \sigma_r \leq 0 \quad (1)$$

- for fragile materials (concrete)

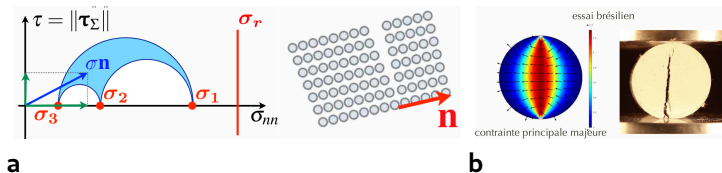


Figure – Credits G. Puel

Shear failure

- plastic shearing along a certain plane
- induced by shearing stress overruns the threshold (Schmidt's law) σ_{nn}
- ① maximum tangent traction component \rightarrow Tresca's criterion

$$f(\underline{\underline{\sigma}}) = \max_{\|\underline{n}\|=1} \|\underline{\tau}_{\Sigma}\|(\underline{x}; t) - \tau_0 \leq 0 \quad (2)$$

$$\underline{n} = \frac{1}{\sqrt{2}} (\underline{n}_I + \underline{n}_{III})$$

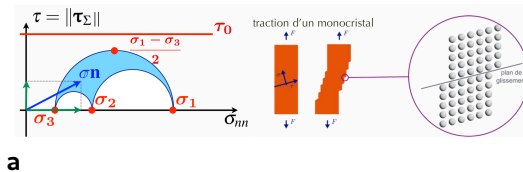


Figure – Credits G. Puel

Shear failure

- plastic shearing along a certain plane
- induced by shearing stress overruns the threshold (Schmidt's law) σ_{nn}
- ① Potential energy of elastic distortion \rightarrow Von Mises criterion

$$f(\underline{\underline{\sigma}}) = \sigma_{eq} - \tau_0 \leq 0, \quad \sigma_{eq} = \sqrt{3J_2(\underline{\underline{s}}^\sigma)} \quad (2)$$

$$\underline{\underline{\sigma}} = \sigma_{ee} \underline{\underline{e}} \otimes \underline{\underline{e}} \rightarrow \sigma_{eq} = \sigma_{ee}$$

$$\underline{\underline{\sigma}} = \tau_{em} \underline{\underline{e}} \otimes_s \underline{\underline{m}} \rightarrow \sigma_{eq} = \sqrt{3}\tau_{em}$$

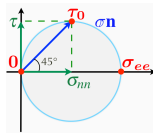
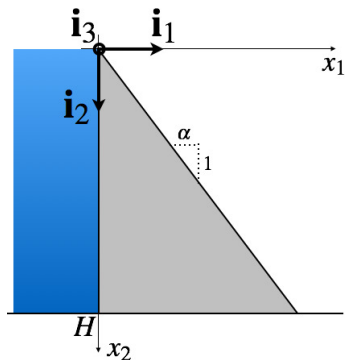


Figure – Credits G. Puel

3.1 Gravity Dam



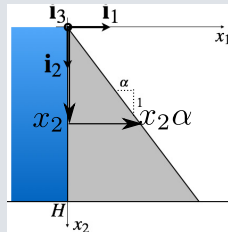
Barrage de Willow Creek (Oregon, USA)

Figure – Set up [Credits : G. Puel]

Set up

Stress description

- $\underline{x} = x_1 \underline{i}_1 + x_2 \underline{i}_2 + x_3 \underline{i}_3$, $(x_1, x_2, x_3) \in \Omega_t =]0, x_2 \alpha[\times]0, H[\times]0, L[$
- $\underline{\sigma}(\underline{x}) = b_1 x_2 \underline{i}_1 \otimes \underline{i}_1 + (a_2 x_1 + b_2 x_2) \underline{i}_2 \otimes \underline{i}_2 - 2(\rho_b g + b_2) x_1 \underline{i}_1 \otimes \underline{i}_2, \forall \underline{x} \in \Omega_t$
- $\rho_e = 1000 \text{ kg/m}^3, \rho_b = 2200 \text{ kg/m}^3, g = 9.81 \text{ m/s}^2$
- $b_1 = -\rho_e g, \quad a_2 = \frac{\rho_b g}{\alpha} - \frac{2\rho_e g}{\alpha^3}, \quad b_2 = -\rho_b g + \frac{\rho_e g}{\alpha^2} = -\alpha a_2 - \frac{\rho_e g}{\alpha^2}$



Check equilibrium

Question 1 : $div_x \left(\underline{\underline{\sigma}}(\underline{x}) \right) + \underline{f}_v = 0$ (static)?

- $\underline{f}_v(\underline{x}; t) = \rho_b g \underline{i}_2$

$$\square \frac{\partial \underline{\underline{\sigma}}}{\partial x_1} = a_2 \underline{i}_2 \otimes \underline{i}_2 - 2(\rho_b g + b_2) \underline{i}_1 \otimes_S \underline{i}_2$$

$$\boxtimes \frac{\partial \underline{\underline{\sigma}}}{\partial x_2} = b_1 \underline{i}_1 \otimes \underline{i}_1 + b_2 \underline{i}_2 \otimes \underline{i}_2$$

$$\boxplus \frac{\partial \underline{\underline{\sigma}}}{\partial x_3} = 0$$

$$\begin{aligned} \rightarrow div_x \left(\underline{\underline{\sigma}} \right) + \underline{f}_v &= \square \cdot \underline{i}_1 + \boxtimes \cdot \underline{i}_2 + \boxplus \cdot \underline{i}_3 + \rho_b g \underline{i}_2 = \\ &= -(\rho_b g + b_2) \underline{i}_2 + b_2 \underline{i}_2 + 0 + \rho_b g \underline{i}_2 = 0 \end{aligned}$$

Boundary Conditions

Question 2 : $\underline{\underline{\sigma}} \cdot \underline{n}|_{\Gamma_{\text{downstream}}} = 0$?

- $\Gamma_{\text{downstream}} : x_1 - \alpha x_2 = 0$
 - ① $\underline{n}(\alpha) = \frac{1}{\sqrt{1+\alpha^2}} (\underline{i}_1 - \alpha \underline{i}_2)$, $\underline{n}(\alpha \rightarrow 0) = \underline{i}_1$, $\underline{n}(\alpha \rightarrow \infty) = -\frac{\alpha}{|\alpha|} \underline{i}_2$
 - ② $\underline{\underline{\sigma}}|_{\Gamma_{\text{downstream}}} = -\rho_e g x_2 \underline{i}_1 \otimes \underline{i}_1 - \frac{\rho_e g x_2}{\alpha^2} \underline{i}_2 \otimes \underline{i}_2 - 2 \frac{\rho_e g x_2}{\alpha} \underline{i}_1 \otimes_S \underline{i}_2$
 - ③ $\underline{\underline{\sigma}} \cdot \underline{n}|_{\Gamma_{\text{downstream}}} = -\frac{\rho_e g x_2}{\sqrt{1+\alpha^2}} \left(\underline{i}_1 - \frac{1}{\alpha} \underline{i}_2 + \frac{1}{\alpha} \underline{i}_2 - \underline{i}_1 \right) = 0$

Question 3 : $\underline{\underline{\sigma}} \cdot \underline{n}|_{\Gamma_{\text{upstream}}} = -p \underline{i}_1$?

- $\Gamma_{\text{upstream}} : x_1 = 0$
 - ① $\underline{n} = -\underline{i}_1$, $\underline{f}_s|_{\Gamma_{\text{upstream}}} = -p \underline{i}_1 (p < 0)$
 - ② $\underline{\underline{\sigma}}|_{\Gamma_{\text{upstream}}} = b_1 x_2 \underline{i}_1 \otimes \underline{i}_1 + b_2 x_2 \underline{i}_2 \otimes \underline{i}_2 \rightarrow \text{NO SHEAR STRESS !}$
 - ③ $\underline{\underline{\sigma}} \cdot \underline{n}|_{\Gamma_{\text{upstream}}} = -b_1 x_2 \underline{i}_1 = \rho_e g x_2 \underline{i}_1 = -p \underline{i}_1 \Rightarrow p = -\rho_e g x_2 < 0$
 - ④ $\max_{x_2 \in [0, H]} \underline{\underline{\sigma}} \cdot \underline{n}|_{\Gamma_{\text{upstream}}} = \rho_e g H$

Question 4 : $\max_{\|\underline{n}\|=1} \sigma_{nn} \leq \sigma_r$?

- $\Gamma_{\text{upstream}} : x_1 = 0$
 - ① $\underline{\underline{\sigma}}|_{\Gamma_{\text{upstream}}} = b_1 x_2 \underline{i}_1 \otimes \underline{i}_1 + b_2 x_2 \underline{i}_2 \otimes \underline{i}_2 \rightarrow \text{NO SHEAR STRESS !}$
 - ② $\sigma_I = \max \sigma_{11}, \sigma_{22} = x_2 \max b_1(\alpha), b_2(\alpha)$
 - ③ $\sigma_{nn}|_{\Gamma_{\text{upstream}}} = \left\langle \underline{\underline{\sigma}}|_{\Gamma_{\text{upstream}}} \cdot \underline{n}, \underline{n} \right\rangle = b_1 x_2 n_1^2 + b_2 x_2 n_2^2 =$

$$x_2 \left(-\rho_e g + \rho_b g - \frac{\rho_e g}{\alpha^2} \right) n_1^2 + \left(\frac{\rho_e g}{\alpha^2} - \rho_b g \right) x_2$$