



ZASTOSOWANIE MODELU TILE2VEC DLA DANYCH EUROSAT W WARIANCIE MULTISPEKTRALNYM

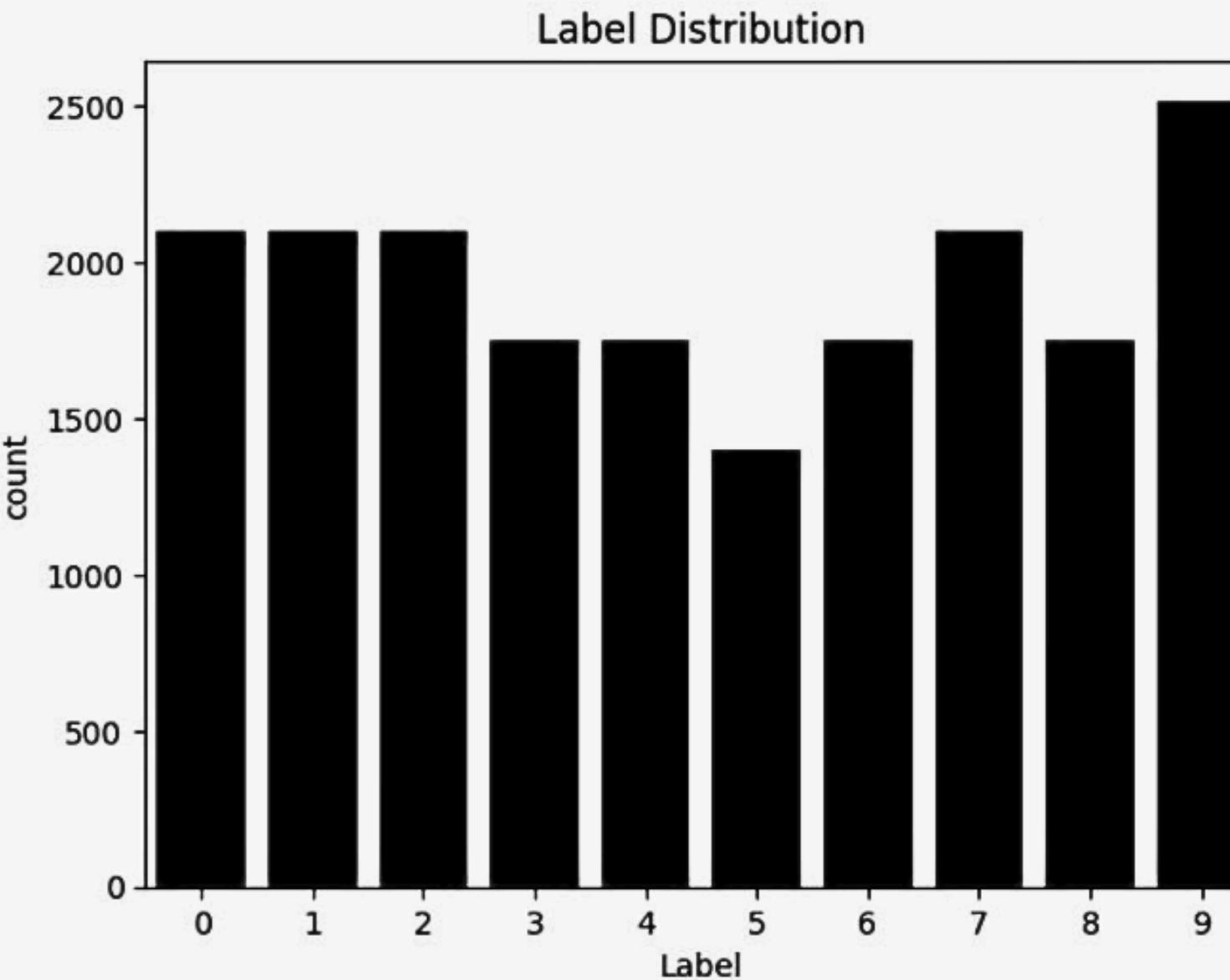
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ŁUKASZ LEPIANKA, MACIEJ MOMOT**

ZBIÓR DANYCH

EuroSAT multispectral

<https://www.kaggle.com/datasets/apollo2506/eurosat-dataset>

Dane satelitarne pochodzące z satelity Sentinel-2 w wariantie wielospektralnym. Dane zawierają etykiety opisujące jakiego rodzaju jest obiekt na zdjęciu.



Annual Crop	0
Forest	1
Herbaceous Vegetation	2
Highway	3
Industrial	4
Pasture	5
Permanent Crop	6
Residential	7
River	8
Sea Lake	9

MODEL TILE2VEC

- Analogia do metod NLP, gdzie słowa o podobnym brzmieniu mają podobne znaczenie, tutaj obrazy geograficznie sąsiednie są do siebie podobne
- Unsupervised
- Trenujemy sieć na trójkach płytak: podstawowa (anchor), sąsiadująca (neighbor) i odległa (distant)
- Działa nie tylko dla danych obrazowych

HIPOTEZY

HIPOTEZA 1

CONTRASTIVE LEARNING

TRIPLET LOSS

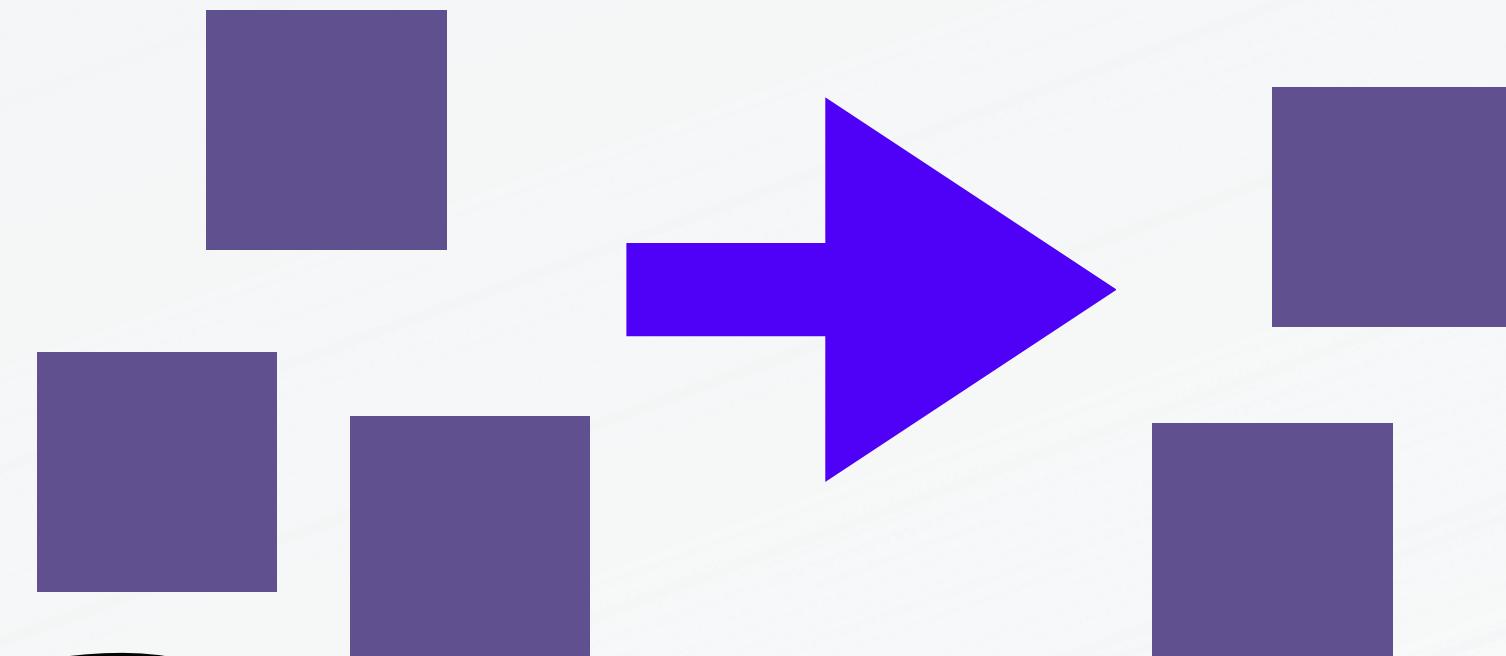


CONTRASTIVE LOSS

MODYFIKACJE TILE2VEC

L2 DISTANCE

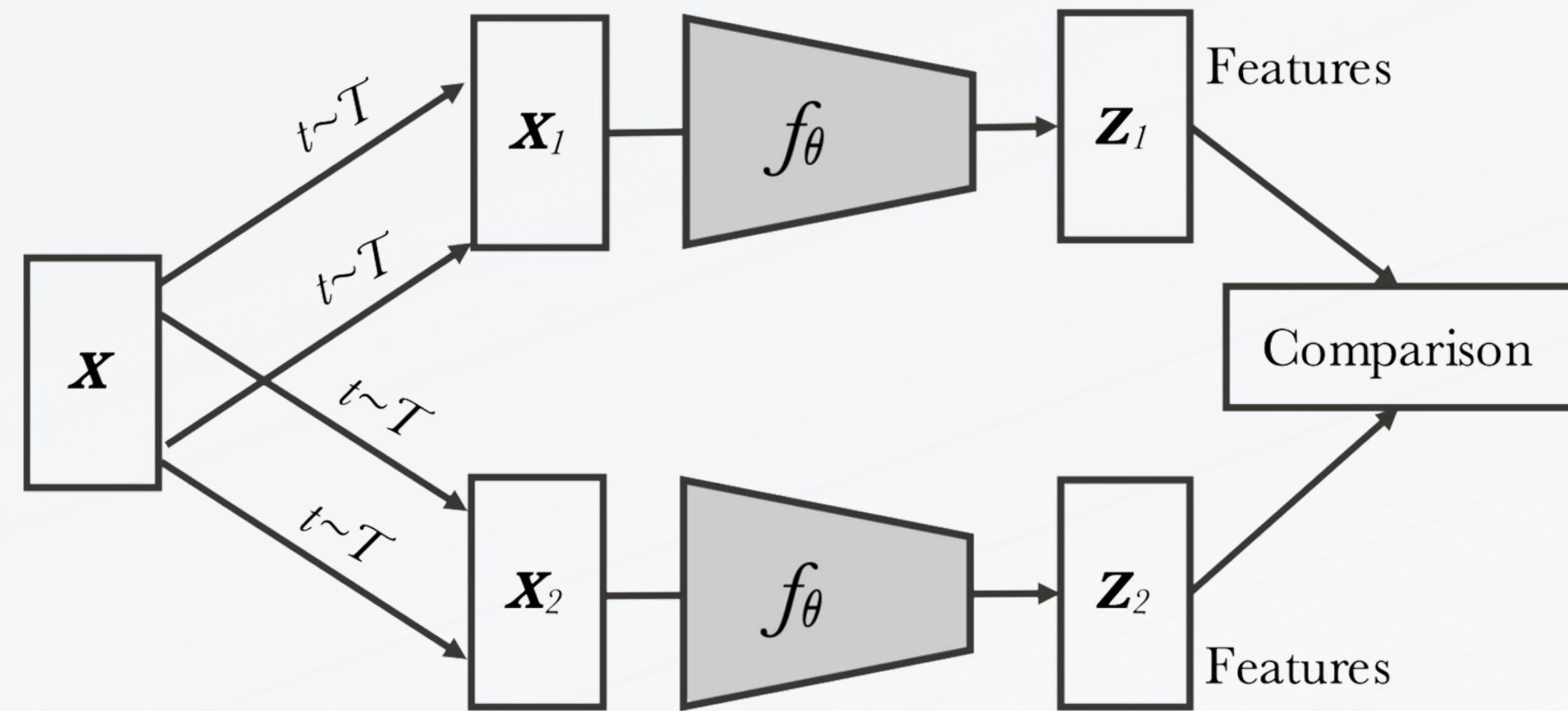
$$\|x - y\|_2 = \sqrt{\sum_{i=1}^n (x_i - y_i)^2} = \sqrt{(x_1 - y_1)^2 + (x_2 - y_2)^2 + \dots + (x_n - y_n)^2}$$



COSINE SIMILARITY

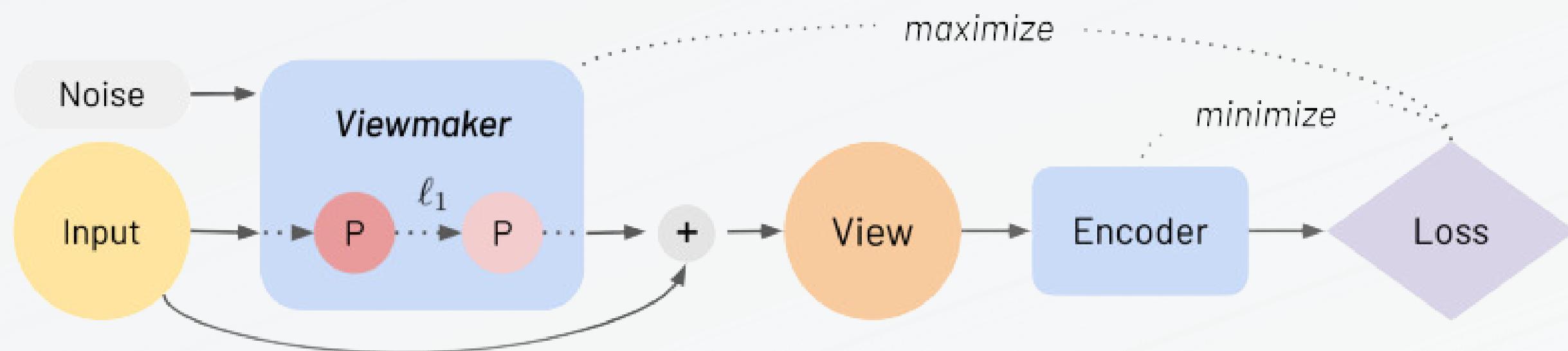
$$\cos(\theta) = \frac{x \cdot y}{\|x\| \cdot \|y\|}$$

SIMPLIFIED SIMCLR



THE MOST BASIC CONTRASTIVE LEARNING
FRAMEWORK WITH ROBUST IMPLEMENTATION

VIEWMAKER

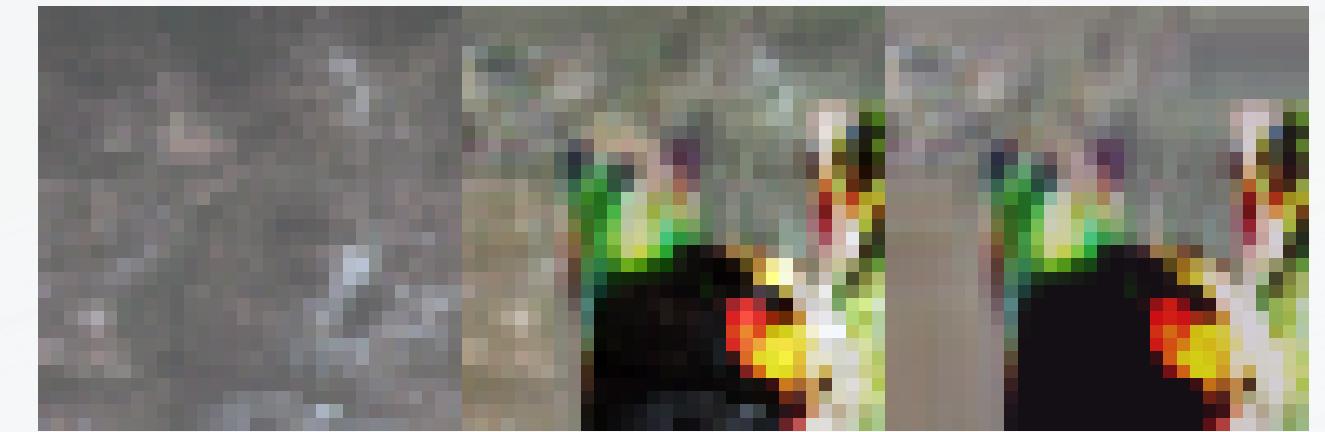


STOCHASTIC ADVERSARIAL VIEWS RESTRICTED TO L1 SPHERE AROUND THE INPUT

DIVMAKER VS VIEWMAKER



VIEWMAKER
ADVERSARIAL VIEW GENERATION

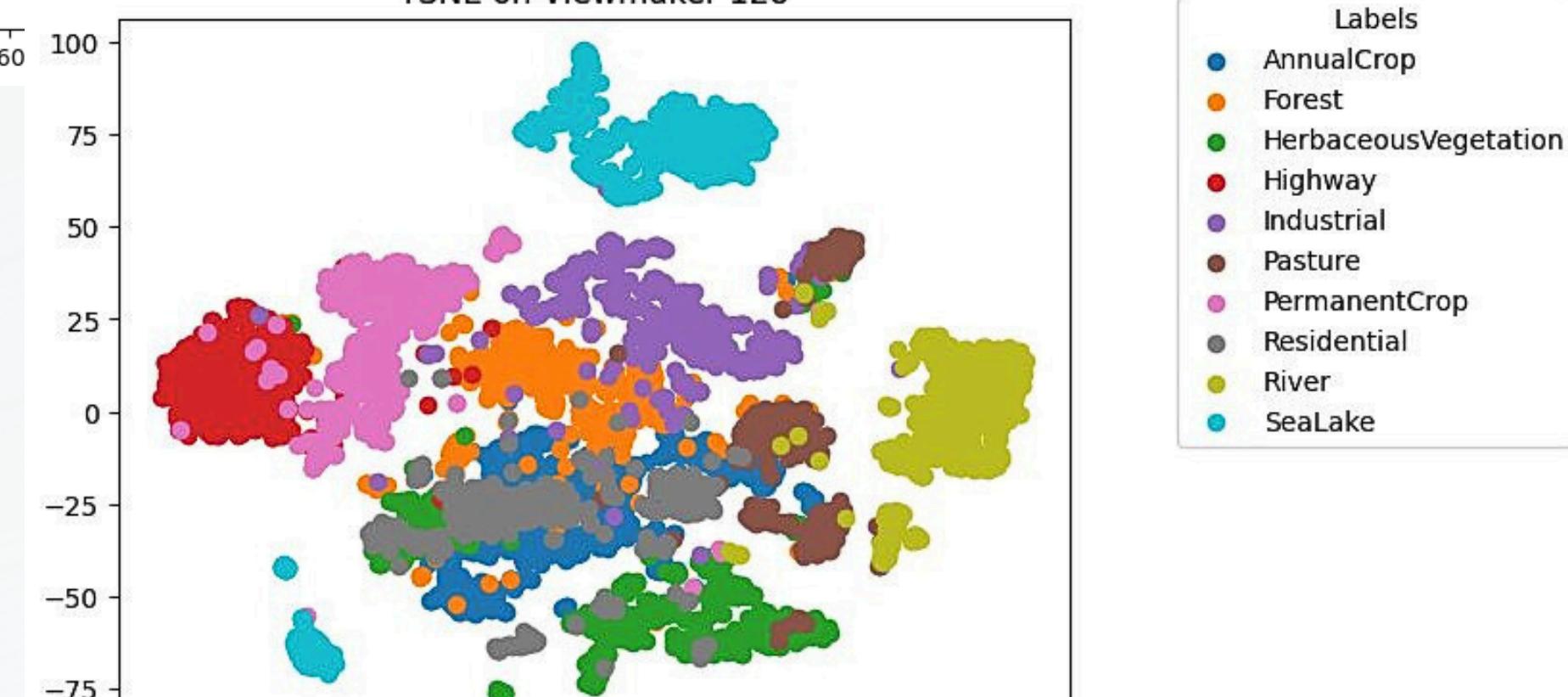
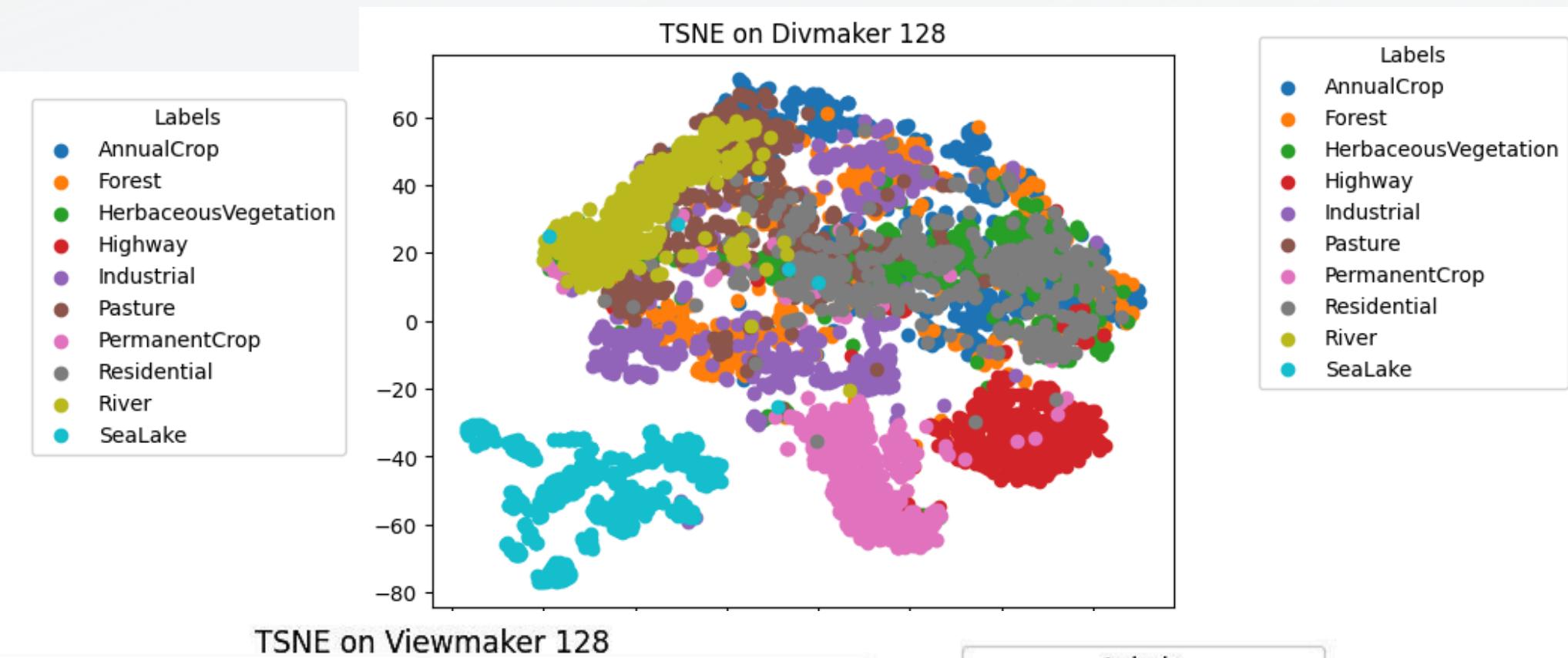
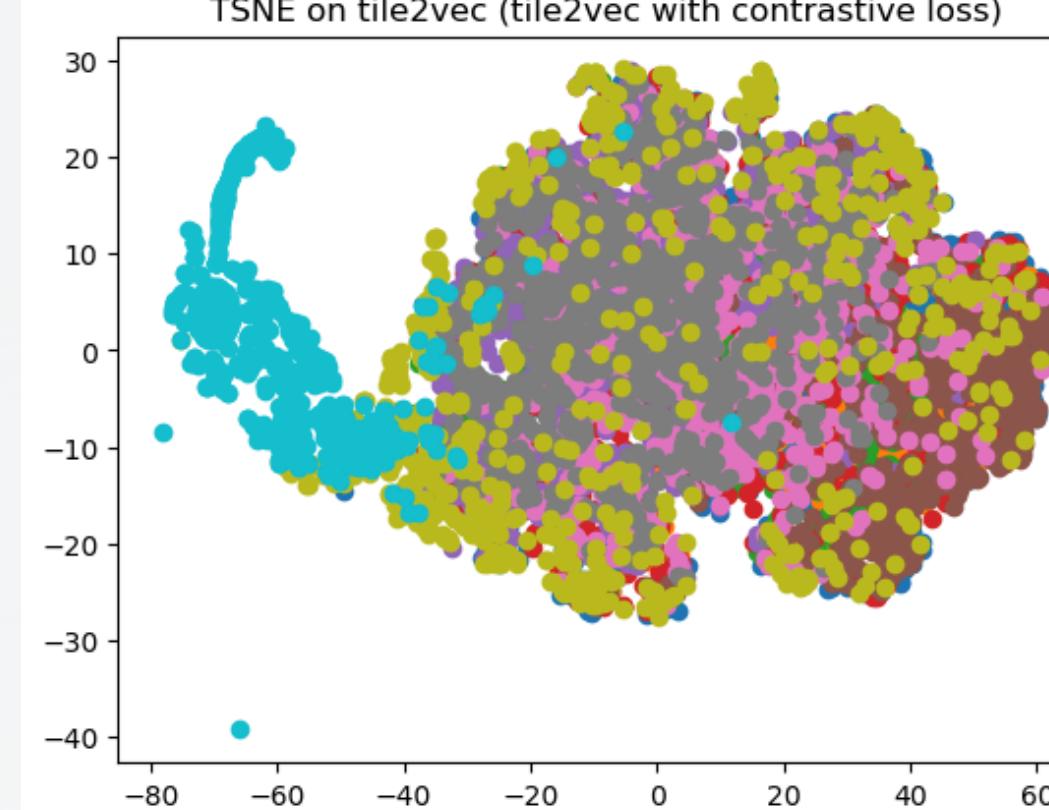


DIVMAKER
**VIEW GENERATION FOR DIVERSITY OF AUGMENTED
VIEWS**

SIMCLR, DIVMAKER, VIEWMAKER

Typ modelu	accuracy	v-measure	silhouette
contrastive tile2vec	44.79±0.98%	0.26±0.01	0.30±0.01
contrastive tile2vec (cos)	44.41±0.77%	0.26±0.01	0.33±0.01
SimCLR	86.09±0.50%	0.15±0.01	0.03±0.01
Viewmaker 512	92.83±0.60%	0.54±0.02	0.10±0.01
Viewmaker 128	94.08±0.35%	0.51±0.01	0.10±0.01
Divmaker 512	62.16±1.74%	0.32±0.01	0.29±0.01
Divmaker 128	84.57±1.79%	0.50±0.01	0.19±0.01

WYNIKI UCZENIA KONTRASTOWEGO



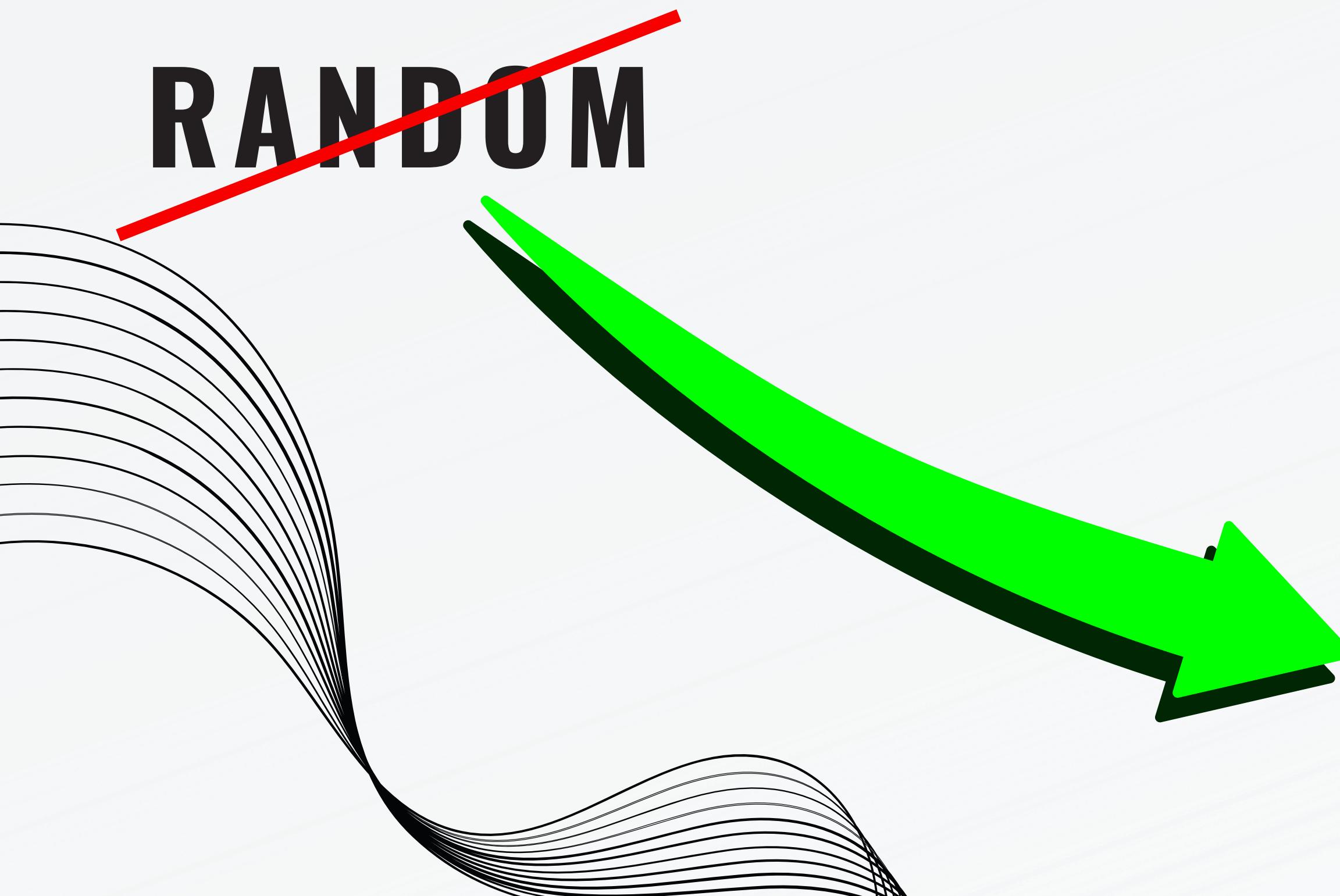
HIPOTEZA 2

HARD NEGATIVE MINING

WYBÓR PŁYTEK

RANDOM

LABELS



WYNIKI HARD MINING

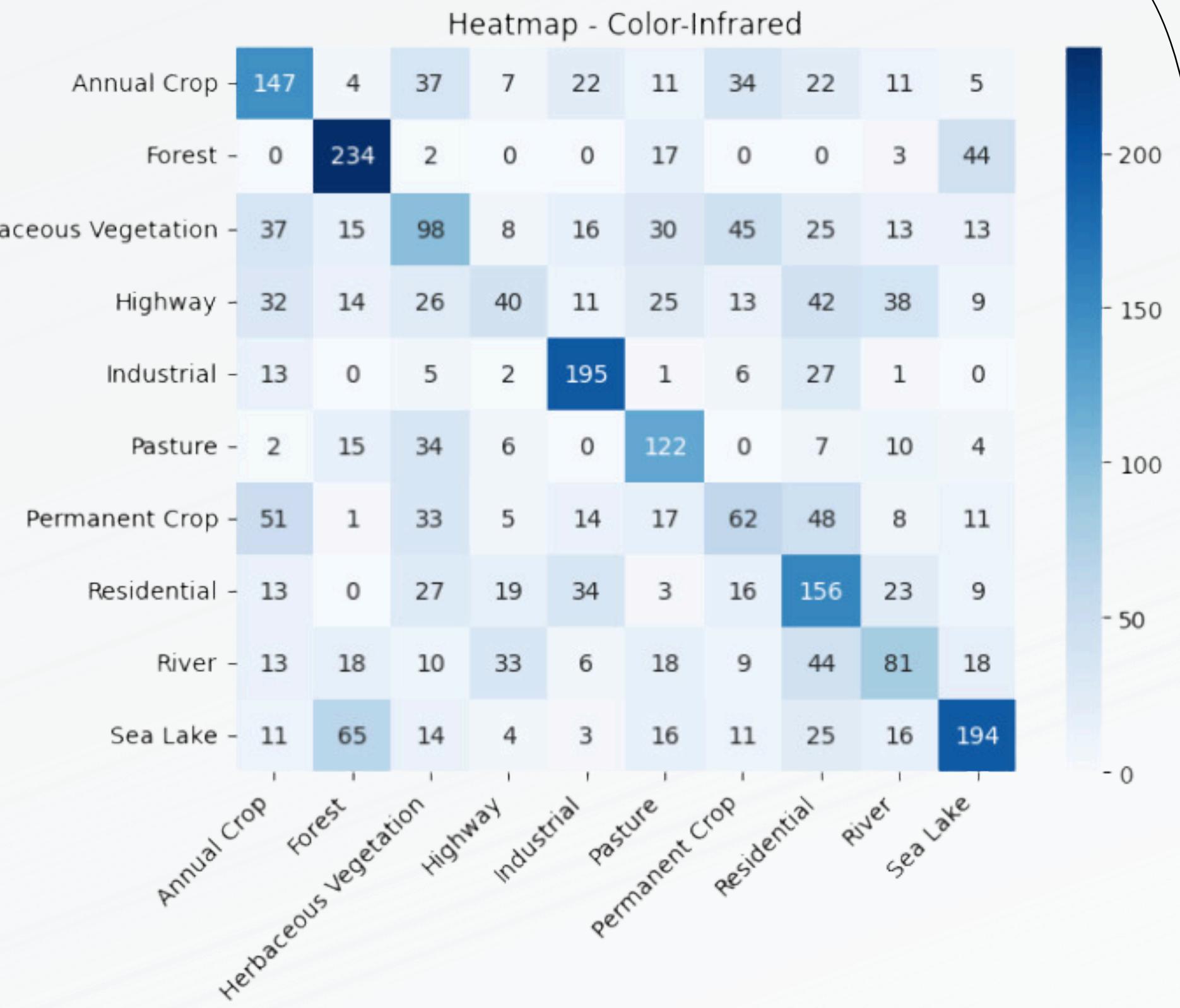
Model Name	Accuracy
Our tile2vec	55.88 ± 0.73
Hard Negative Mining	65.92 ± 0.71

HIPOTEZA 3

PRACTICAL APPLICATION

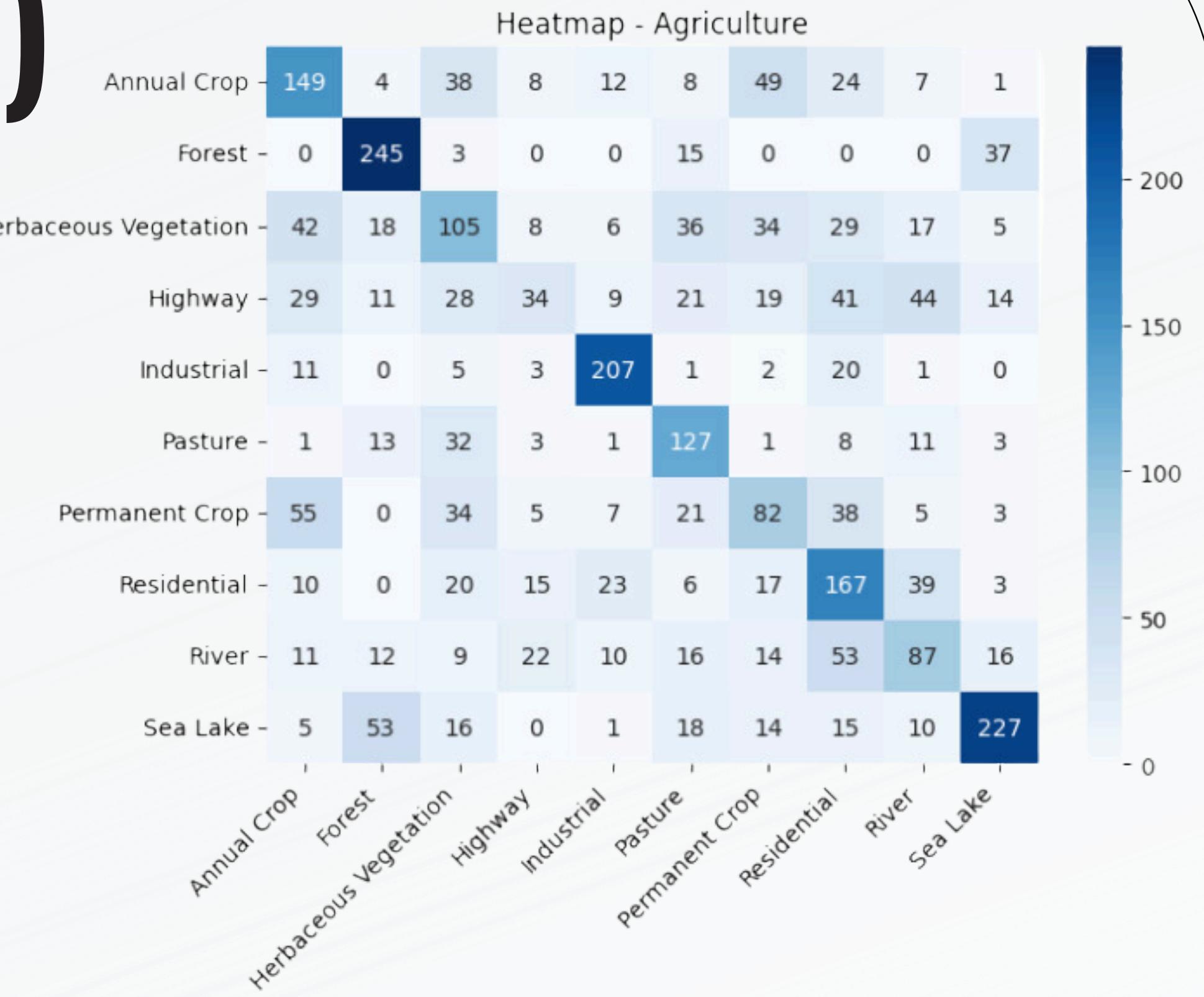
COLOR INFRARED

(B8, B4, B3)



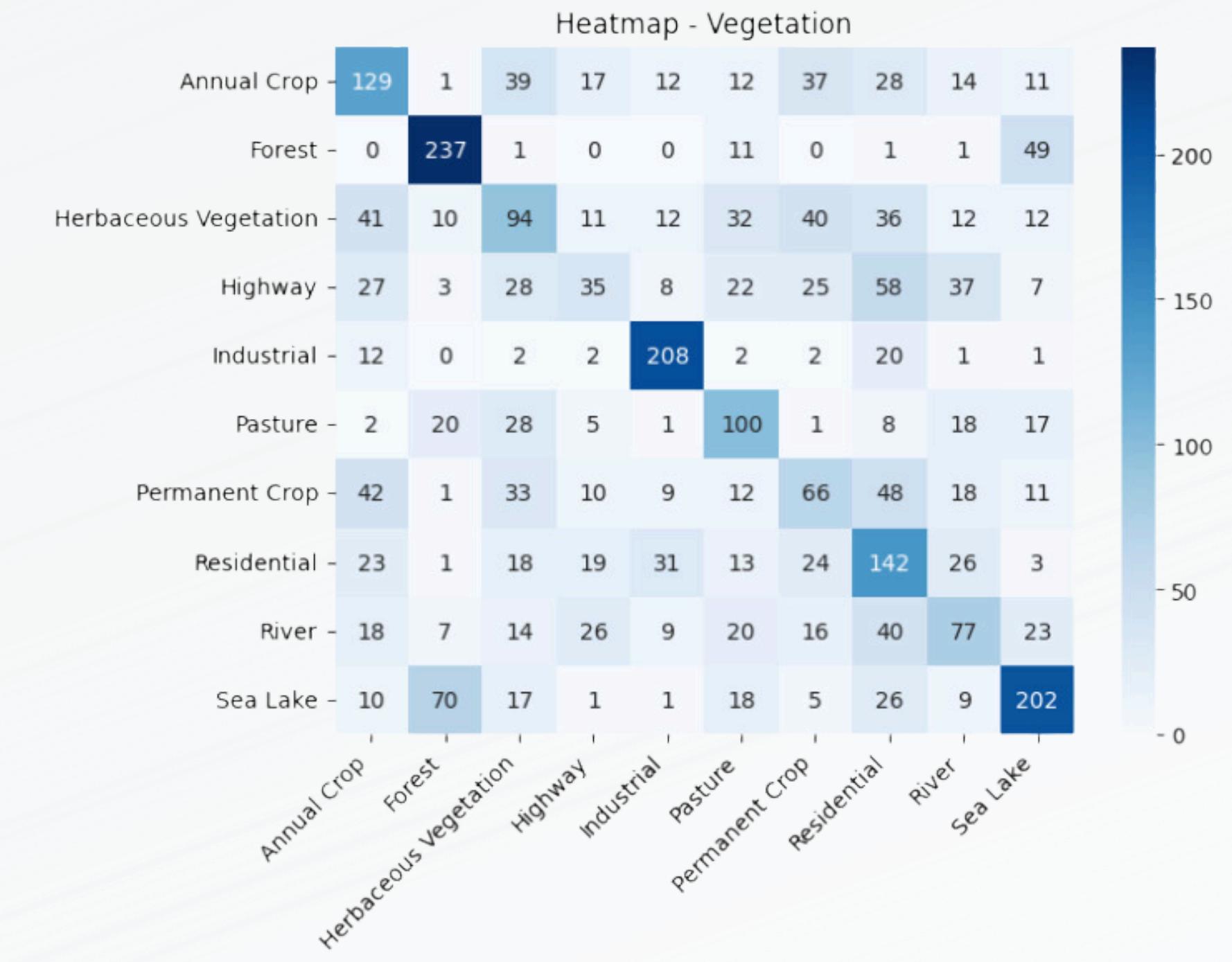
AGRICULTURE

(B11, B8, B2)



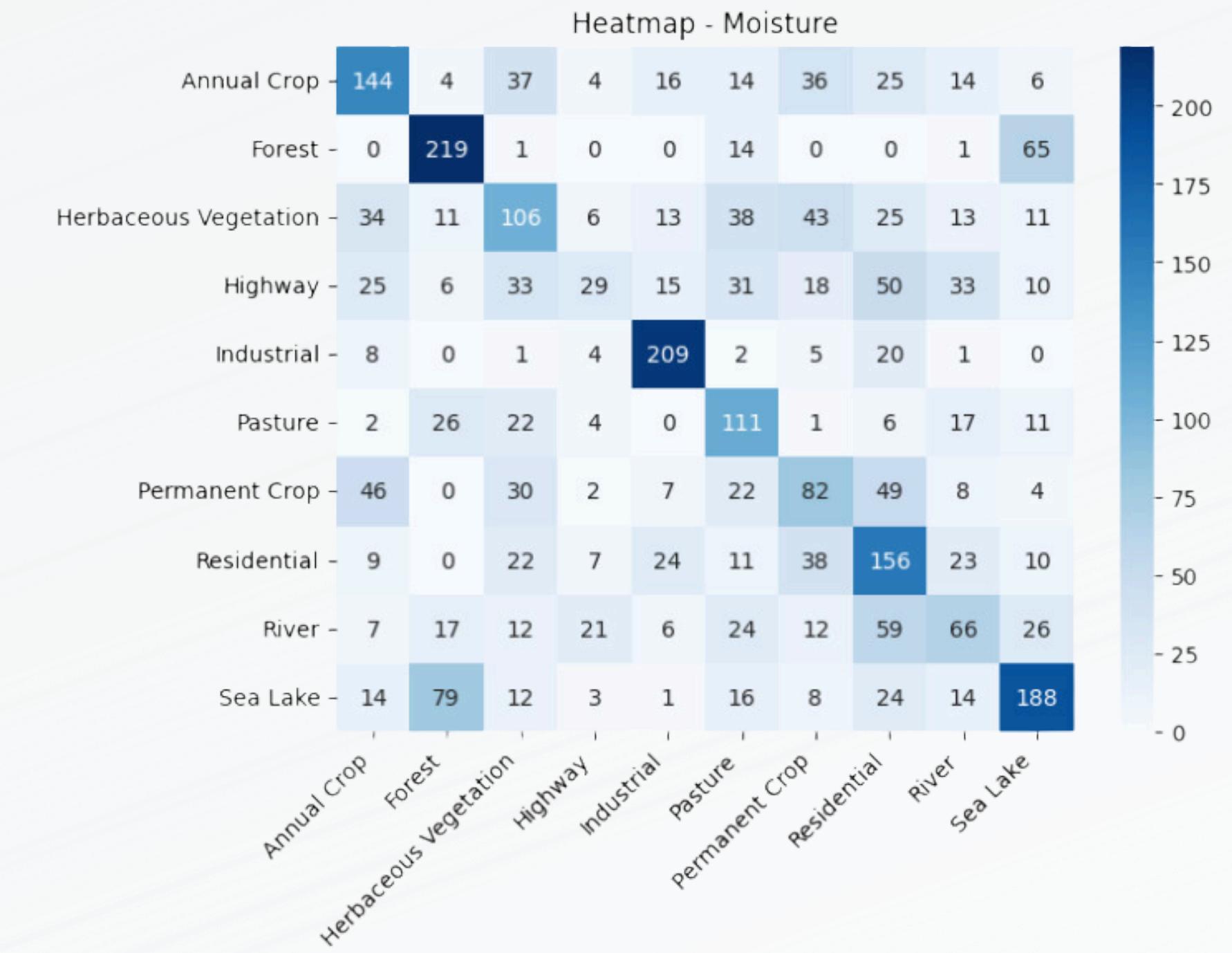
VEGETATION INDEX

$(B8 - B4) / (B8 + B4)$



MOISTURE INDEX

$(B8A - B11) / (B8A + B11)$



PORÓWNANIE WYNIKÓW

		wszystkie bandy	color-infrated	agriculture	vegetation	moisture
0	Annual Crop	57.39%	47.61%	48.31%	44.04%	44.77%
1	Forest	89.38%	77.94%	80.88%	79.21%	77.83%
2	Herb. Vegetation	41.42%	35.19%	36.15%	32.77%	33.79%
3	Highway	17.39%	11.66%	14.35%	16.30%	10.45%
4	Industrial	37.77%	78.99%	86.29%	84.26%	83.83%
5	Pasture	57.52%	62.68%	63.97%	53.66%	58.30%
6	Permanent Crop	39.72%	26.36%	29.65%	28.46%	29.55%
7	Residential	49.49%	53.02%	53.57%	45.92%	52.29%
8	River	75.63%	32.16%	31.94%	28.40%	26.93%
9	Sea Lake	99.26%	57.46%	64.10%	58.91%	55.67%

WNIOSKI

VIEWMAKER:



HARD NEGATIVE MINING:

7%



DOSTOSOWANE MODELE

- zauważalne są drobne zależności między dostosowanymi modelami, a wynikami
- zależności te jednak nie są mocno zauważalne
- wpływ różnych modeli na wyniki nie jest jednoznaczny
- model agriculture ma najlepsze wyniki na większości labeli
- na 3 labelach dostosowane modele działają lepiej niż podstawowy model

**DZIĘKUJEMY ZA
UWAGĘ**

LITERATURA

[1] <https://github.com/ermongroup/tile2vec>.

[2] <https://www.kaggle.com/datasets/apollo2506/eurosat-dataset>.

[3] **Jasmine Bayrooti, Noah Goodman, and Alex Tamkin.** **Multispectral contrastive learning with viewmaker networks**, 2023.

[4] **Alex Tamkin, Mike Wu, and Noah Goodman.** **Viewmaker networks: Learning views for unsupervised representation learning**, 2021.