# beamz.sty

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#### Abstract

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## 1 Beam

The basic command is \beam{<length>}{<height>} which needs to be encapsulated within a tikzpicture environment.

#### Example:

```
\begin{tikzpicture}
\beam{5}{0.2}
\end{tikzpicture}
```

All other objects (eg supports and loads) need the beam as a reference so the command \beam should be provided before anything else is drawn.

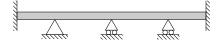
## 2 Supports

The following supports are implemented:

- Triangle supports: \triangleSupport<rel.pos.>
- Roller supports: \rollerSupport<rel.pos.>
- Clamped supports:
  - \clampedLeft<height><thickness>
  - \clampedRight<height><thickness>

The height of \triangleSupport and \rollerSupport are set by the command \setSupportHeight{<height} which needs to be given before any support is drawn.

#### Example:



\begin{tikzpicture}
% beam
\beam{5}{0.2}

% supports
\setSupportHeight{0.4}
\triangleSupport{0.2}
\rollerSupport{0.5}
\rollerSupport{0.8}
\clampedLeft{0.4}{0.1}
\clampedRight{0.4}{0.1}
\end{tikzpicture}

## 3 Joint

A joint can be added to the beam using the command \joint{<rel. pos.>}. The joint's size is proportional to the beam's thickness.

## Example:



\begin{tikzpicture}
%beam
\beam{5}{0.2}

% joint
\joint{0.5}

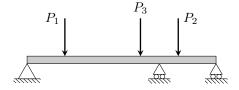
%supports
\setSupportHeight{0.4}
\clampedLeft{0.4}{0.1}
\rollerSupport{1.0}
\end{tikzpicture}

## 4 Loads

#### 4.1 Point loads

The command \pointLoad takes 5 arguments: \pointLoad{<rel.pos.>}{<height>}{<annotation>}{<annotations pos.>}{<vertical offset>}

## Example:



\begin{tikzpicture}
% beam
\beam{5}{0.2}

% loads

```
\pointLoad{0.2}{1.0}{$P_1$}{left}{0}
\pointLoad{0.8}{1.0}{$P_2$}{right}{0}
\pointLoad{0.6}{1.0}{$P_3$}{above}{0}

% supports
\setSupportHeight{0.4}
\triangleSupport{0.0}
\rollerSupport{0.7}
```

\rollerSupport{1.0}

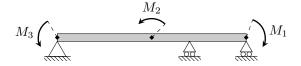
\end{tikzpicture}

### 4.2 Point moment

The commands  $\mbox{momentClockwise}$  and  $\mbox{momentCounterclockwise}$  both take the same 6 arguments:

 $\label{lockwise} $$\operatorname{\colored}_{\colored} (\colored) < \colored_{\colored}_{\colored} (\colored_{\colored}_{$ 

## Example:



\begin{tikzpicture}
% beam
\beam{5}{0.2}

#### % loads

 $\label{lockwise} $$ \mathbf{1.0}_{0.5}_{-30}_{100}_{M_1$}{\mathbf m}_{1$}{\mathbf m}_{0.5}_{120}_{90}_{M_3$}_{\mathbf m}_{3$}_{\mathbf m}_{0.5}_{0.5}_{45}_{90}_{M_2$}_{above}$$$ 

### % supports

\setSupportHeight{0.4}

\triangleSupport{0.0}

\rollerSupport{0.7}

\rollerSupport{1.0}

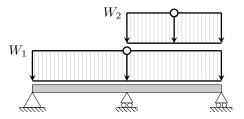
\end{tikzpicture}

## 4.3 Distributed loads

#### 4.3.1 Rectangle loads

The command \distributedload takes 6 arguments: \distributedload{<start pos.>}{<end pos.>}{<annotation left>}{<annotation right>}{<height>}{<vertical offset>}

#### Example:



```
\begin{tikzpicture}
% beam
\beam{5}{0.2}
```

#### % loads

 $\label{load} $$ \distributedLoad\{0.0\}_{1.0}_{W_1$}_{0.8}_{0.8}_{0.8}_{1}$$ $$ \distributedLoad\{0.5\}_{1.0}_{W_2$}_{0.8}_{1}$$$ 

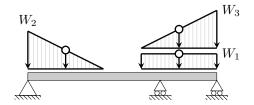
## % supports

\setSupportHeight{0.4}
\triangleSupport{0.0}
\rollerSupport{0.5}
\rollerSupport{1.0}
\end{tikzpicture}

#### 4.3.2 Triangle loads

The commands  $\triangleloadLeft$  and  $\triangleloadRight$  both take the same 6 arguments:

#### Example:



\begin{tikzpicture}
% beam
\beam{5}{0.2}

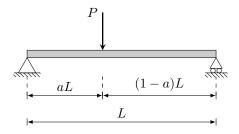
% loads

% supports
\setSupportHeight{0.4}
\triangleSupport{0.0}
\rollerSupport{0.7}
\rollerSupport{1.0}
\end{tikzpicture}

## 5 Annotation

## 5.1 Dimension annotations

## Example:



\begin{tikzpicture}
% beam
\beam{5}{0.2}

% loads
\pointLoad{0.4}{1.0}{\$P\$}{left}{0}

% supports
\setSupportHeight{0.4}
\triangleSupport{0.0}
\rollerSupport{1.0}

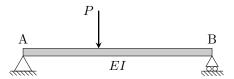
% dimensions \dimension{0.0}{0.4}{1.0}{\$aL\$}{0.5} \dimension{0.4}{1.0}{1.0}{\$(1-a)L\$}{0.5} \dimension{0.0}{1.0}{1.7}{\$L\$}{0.0} \end{tikzpicture}

## 5.2 Beam annotation

Beam annotations can be added using the commands:

- \beamAnnotationBelow{<rel.pos.>}{<annotation>}
- \beamAnnotationAbove{<rel.pos.>}{<annotation>}

#### Example:



\begin{tikzpicture}
% beam
\beam{5}{0.2}

% loads
\pointLoad{0.4}{1.0}{\$P\$}{left}{0}

% supports
\setSupportHeight{0.4}
\triangleSupport{0.0}
\rollerSupport{1.0}

% annotation
\beamAnnotationAbove{0}{A}
\beamAnnotationAbove{1}{B}

```
\beamAnnotationBelow{0.5}{$EI$}
\end{tikzpicture}
```

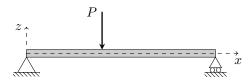
## 6 Coordinate axes

Coordinate axes for a beam can be drawn using the two commands:

- \horizontalAxis (draws x axis)
- \verticalAxis (draws z axis (positive direction upwards))

The coordinate axes' lengths are proportional to the beam's length and height, respectively.

#### Example:



\begin{tikzpicture}
% beam
\beam{5}{0.2}

% loads
\pointLoad{0.4}{1.0}{\$P\$}{left}{0}

% supports
\setSupportHeight{0.4}
\triangleSupport{0.0}
\rollerSupport{1.0}

% axes
\horizontalAxis
\verticalAxis
\end{tikzpicture}

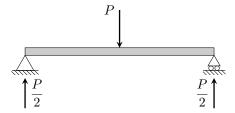
## 7 Reaction forces

Reaction forces can be drawn using the command \reactionForce which takes 3 arguments:

\reactionForce{<position>}{<annotation>}{<annotation pos.>} The arrow's offset distance from the support is proportional to the support's height so the supports need to be drawn before the reaction forces. The hight of the

reaction force is set by the command
\setReactionForceHeight{<height>}

#### Example:



```
\begin{tikzpicture}
% beam
\beam{5}{0.2}
```

% loads
\pointLoad{0.5}{1.0}{\$P\$}{left}{0}

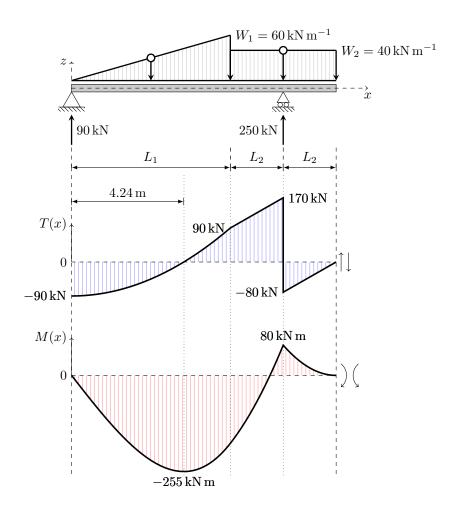
% supports
\setSupportHeight{0.4}
\triangleSupport{0.0}
\rollerSupport{1.0}

% reaction forces
\setReactionForceheight{0.8}
\reactionForce{0.0}{\$\displaystyle\frac{P}{2}\$}{right}
\reactionForce{1.0}{\$\displaystyle\frac{P}{2}\$}{left}
\end{tikzpicture}

## 8 Cross-sectional force diagrams

The commands Tofx and Mofx both take the same 3 arguments:  $\texttt{Tofx}{\texttt{T(x)}}{\texttt{cvertical shift}}{\texttt{cscale factor}}$  where T(x) is T(x) (or M(x)) given as a path of either coordinates or analytical functions, or a combination of both (see example below). When analytical expressions are given in T(x), the true length of the beam needs to be declared for correct scaling of the graph, which is done using the command setTrueBeamLength length.

**Example** In the example below  $L_1 = 6 \,\text{m}$  and  $L_2 = 2 \,\text{m}$ . The example needs \usepackage{siunitx} in the preamble.



\begin{tikzpicture}

# % Beam

 $\begin{tabular}{l} \begin{tabular}{l} \begin{tabu$ 

## % Force

 $$$ \triangleloadRight{0}{0.6}{$W_1 = SI{60}{\kappa \rho^{0}}{1.2}{0} distributedLoad{6/10}{1}{}{$W_2 = SI{40}{\kappa \rho^{0}}{0.8}{0}}$ 

## % Supports

\setSupportHeight{0.4} \triangleSupport{0}

\rollerSupport{8/10}

#### % Dimension

```
\dim(0){6/10}{2}{L_1}{0.3}
\label{local_condition} $$\dim(6/10)_{8/10}_{2}_{L_2}_{0.3}$
\dim(8/10){1.0}{2}{L_2}{0.3}
\horizontalAxis
\verticalAxis
% Support reactions
\setReactionForceheight{0.8}
\reactionForce{0}{$\SI{90}{\kilo\newton}$}{right}
\colored{8/10}{\$\SI{250}{\tilde{\colored}}}{left}
\setTrueBeamLength{10}
% T(x)
\Tofx{
(0,-90) node [left] {SI{-90}{\kappa in \newton}}
plot[domain=0:6] (\x, {5*\x^2-90})
(6,90) node [left] {\$SI\{90\}{\tilde{n}\in\mathbb{S}}}
plot[domain=6:8] (\x, {40*(\x-6)+90})
(8,170) node[right] {\$SI\{170\}}\{\tilde{s}\}
(8,-80) node[left] {\$SI{-80}{\tilde{s}}}
plot[domain=8:10] (\x, {40*(\x-6)-160})
}{4.5}{0.01}
% M(x)
\Mofx{}
(0,0)
plot[domain=0:4.24] (\x, \{-90*\x+5/3*\x^3\})
(4.24,-255) node[below] {\$SI\{-255\}\{\tilde \infty\}}
plot[domain=4.24:6] (\x, {-90*\x+5/3*\x^3})
plot[domain=6:8] (\x, {20*(\x-6)^2+90*\x-720})
(8,80) node [above] {\$SI\{80\}{\tilde{newton}}}
```

% dimenstions
\setVerticalLineOffset{2.2}
\verticalLine{0}{8}{dashed}
\verticalLine{4.25/10}{8}{dotted}
\verticalLine{6/10}{8}{dotted}
\verticalLine{8/10}{8}{dotted}
\verticalLine{1}{8}{dashed}
\end{tikzpicture}