kennisplatform CROW

SPaT Data

Dutch Profile version 2.2.0

Over deze publicatie

De internationale ontwikkeling van Smart Mobility zorgt voor flinke vernieuwingen in verkeer, vervoer en mobiliteit. Dit raakt direct ook de verkeersregelinstallaties in de Nederlandse steden en provincies en op rijkswegen. Als verkeersregelinstallaties kunnen communiceren met voertuigen en weggebruikers kunnen weggebruikers worden geïnformeerd over actuele fasewisselingen van verkeersregelinstallaties en hierop hun rijgedrag vroegtijdig aanpassen, kunnen doelgroepen als openbaar vervoer, nood- en hulpdiensten en vrachtwagens conform beleidswensen van overheden worden geprioriteerd en kan data van voertuigen zelf worden gebruikt voor betere netwerkregelingen. Dit bevordert doorstroming, bereikbaarheid, verkeersveiligheid en duurzaamheid, legt de basis voor connected en automated driving en speelt in op een digitale samenleving waarin data en connectiviteit bijdragen aan economisch aantrekkelijke en duurzame steden.

Voor het effectief, veilig en leveranciers- en overheidsonafhankelijk communiceren van intelligente verkeersregelinstallaties (iVRI's) met voertuigen en weggebruikers hebben bedrijven en overheden in het Innovatiepartnership Talking Traffic binnen internationale standaarden gezamenlijk specificaties en koppelvlakken voor iVRI's vastgelegd. Eenduidig gebruik door alle overheden en betrokken bedrijven van deze uniforme afspraken binnen internationale standaarden is noodzakelijk voor interoperabiliteit en een goede en betrouwbare werking. Deze standaarden zijn daarom vastgesteld door de landelijke publiek private Strategic Committee 'Borgen en beheren iVRI standaarden en producten'. Na vaststelling gelden deze standaarden voor alle bedrijven en overheden die in Nederland (willen gaan) werken aan iVRI's t.b.v. intelligente mobiliteit. Vanuit de rol van onafhankelijk en landelijk kennisinstituut verzamelt CROW deze landelijk vastgestelde standaarden en stelt deze transparant ter beschikking aan overheden, adviesbureaus en leveranciers.

About this publication

The international developments in Smart Mobility technology are boosting innovations for traffic, transportation and mobility. This has a direct effect on traffic control systems in Dutch cities and provinces, as well as national highways. When traffic controllers are able to communicate with vehicles and road users, the latter can be informed about real-time phase changes in traffic lights, enabling them to anticipate and adjust driving behaviour accordingly. Also, special interest groups, such as emergency services, public transport and freight carriers, can be prioritized in line with public policy guidelines. The data provided by vehicles themselves can be utilised to improve network-based traffic control programmes. This has a positive effect on flow, accessibility, traffic safety and sustainability, laying out the fundamentals for connected and automated driving and preparing for a digital society in which data and connectivity contribute to economically viable and sustainable cities.

In order to let intelligent traffic controllers (iVRI) communicate with vehicles and road users in an effective, safe and platform independent way, businesses and governments have created and recorded common specifications and interfaces for iVRI technology. These are compliant to international standards and developed within the framework of the Talking Traffic Innovation partnership. The unambiguous use of these uniform agreements, within international standards, by all governmental bodies and businesses is necessary for interoperability and a good and reliable operation. These standards are adopted by the national public-private Strategic Committee 'Ensuring and maintaining iVRI standards and products'. After adoption, these standards apply to all businesses and governmental bodies in the Netherlands that work, or plan to work, on iVRI technology for intelligent mobility purposes. Being an independent national knowledge institute, CROW collects these national standards and provides them to governments, consultants and suppliers in a transparent way.

Praktische kennis direct toepasbaar

SPaT Data

Contents

1 Introduction

1.1 Purpose of this Document

This document provides the Dutch Profile for the SPAT message. It offers an interpretation of data elements and describes the use of them as extension to the standards.

1.2 SPAT Message

The Signal Phase and Timing (SPAT) message is used to convey the current status of one or more signalized intersections. Along with the MapData message (which describes a full geometric layout of an intersection) the receiver of this message can determine the state of the signal phasing and when the next expected phase will occur.

The SPAT message sends the current movement state of each active phase in the system as needed (such as values of what states are active and values at what time a state has begun/does begin earliest, is expected to begin most likely and will end latest). The state of inactive movements is not normally transmitted. Movements are mapped to specific approaches and connections of ingress to egress lanes and by use of the SignalGroupID in the MapData message.

The current signal pre-emption and priority status values (when present or active) are also sent. A more complete summary of any pending priority or pre-emption events can be found in the Signal Status message.

1.3 Assumptions

The following standards have been used to prepare this profile.

- SAE J2735, Dedicated Short Range Communications (DSRC) Message Set Dictionary, March 2016
- ISO TS19091, Intelligent transport systems – Cooperative ITS – Using V2I and I2V communications for applications related to signalized intersections, 2016(E)
- ETSI 103 301, Intelligent Transport Systems (ITS); Vehicular Communications; Basic Set of Applications; Facilities layer protocols and communication requirements for infrastructure services, V1.1.1 (2016-11)
- ETSI TS102 894-2, Intelligent Transport Systems (ITS); Users and applications requirements; Part 2: Applications and facilities layer common data dictionary, V1.2.1 (2014-09)

1.4 Legend

Chapter 2 contains the actual profile describing how the data frames (DFs) and data elements (DEs) shall be used for the implementation of the SPAT message.

The description of the DFs and DEs can be found in aforementioned standards. The description of the DEs and DFs in this document build upon the descriptions in these standards.

The font style of the name of DEs and DFs indicates the status as defined in the standards:

- **Bold**: required by the standard;
- *Italic*: these are optional in the standard;
- Underlined: one of these can be chosen (OR);

The status in the profile is indicated in a separate column by means of one of the following labels:

- Mandatory. This DF or DE is mandatory in the standard and is thus always provided.
- Profiled. This DF or DE is mandatory in the profile although optional in the standard. It is therefore assumed that this DF or DE will always be provided.
- Conditional. This DF or DE is mandatory in specific conditions and not used in other conditions. The conditions are provided in the profile.
- Optional. This DF or DE is optional in the standard as well as in the profile.
- Used. This DF or DE is a choice in the standard and used in the profile. It is therefore assumed that this DF or DE can be provided.

- Not used. This DF or DE is optional or a choice in the standard but not used in the profile. A response to the use of this DF or DE is therefore not guaranteed, but as the message is compliant with the ASN.1 specification, the message is valid.
- Future use. This DF or DE is not relevant for use cases currently in scope and therefore not profiled in the current version of the profile.
- Bold. Applies to attributes in an enumeration or bitstring and indicates the attribute shall be assigned if applicable. All non-bold attributes are optional.

1.5 Document history

Version	Date	Protocol Version	Changes
0.1	22-03-2017		Document and table structure (Martijn Harmenzon)
0.2	27-03-2017		Contribution from Eric Koenders
0.3	04-04-2017		Review and contributions from Jaap Vreeswijk. First draft
0.5	11-04-2017		Version including new comments from subWG
0.6	01-05-2017		Version including comments WG meeting 21st of April
0.7	12-05-2017		Version with new comments, input WG meeting 12th of May
1.0	18-05-2017		Final version for broader review
1.1	15-06-2017		Minor revisions which are tracked in Annex B + summary of SPAT profile added in Annex A.
1.2	29-06-2017		Final revised version for approval
1.8	02-11-2017		Revised version for approval
2.0	16-11-2017		Version approved by WG Techniek on 16th of November '17
2.1	22-03-2018		Added: corrections, clarifications and interpretation.
2.1.a	21-06-2019		Revised version based on Change Orders CAB-Work-item4-CO4 and CAB-Work-item4-CO5
2.2.0	26-06-2020	1.0.0	Revision based on 'Werkgroep UC4'.

2 Signal Phase and Timing (SPAT) Profile

Standard				Profile		
Level	Field	Meaning		Status	Content	Value
Header container (ItsPduHeader - ETSI TS 102 894-2 V1.2.1)						
	protocol-Version	Version of the protocol.		Fixed	Current version is 1.	Set to 1
	messageID	Indicates the type of message.		Fixed	Examples are denm(1), cam(2), spat(4) etc.	Set to 4.
	stationID	This is the ID of the station broadcasting the message.		Mandatory	The numerical presentation of the combination of the hexadecimal representation of the RoadRegulatorID and the IntersectionID (which is a multiple of ten).	Set by application.

Standard				Profile		
Level	Field	Meaning		Status	Content	Value
Level 0: SPAT						
0.1	*timeStamp [MinuteOfTheYear]*	The MinuteOfTheYear data element expresses the number of elapsed minutes of the current year in the time system being used (typically UTC time).		Not used	The time stamp used for the IntersectionStateList data frame makes this data element redundant.	-
0.2	*name [DescriptiveName]*	The DescriptiveName data element is used to provide a human readable and recognizable name for the feature that follows.		Mandatory	Mandatory as opposed to standard and used to provide information of the applicable SPaT-profile-version. Semantic versioning (SemVer) is used, the current version of the profile is: 2.2.0.	2.2.0
0.3	**intersections [Intersection-StateList] (1..32)**	The IntersectionStateList data frame consists of a list data IntersectionState entries.	**IntersectionState** The IntersectionState data frame is used to convey all the SPAT information for a single intersection.	Mandatory	One IntersectionState for each independent conflict area.	See level 1
0.4	*regional [REGION.Reg-SPAT]*	The element is used for additional "regional information", as defined in ISO/PDTS 19091.		Not used	-	-

Level 1: IntersectionStateList → IntersectionState						
1.1	*name [DescriptiveName]*	The DescriptiveName data element is used to provide a human readable and recognizable name for the feature that follows.		Profiled	Mandatory in Dutch profile as opposed to standard. Human readable and recognizable for road authority. Maximum 63 characters. Shorter is better.	Set by application
1.2	**id [Intersection-ReferenceID]**	The IntersectionReference-ID is a globally unique value set, consisting of an optional	*region [RoadRegulatorID]*	Profiled	Mandatory in Dutch profile as opposed to standard. For each road operator a RoadRegulatorID is provided in the document	Set by application

		RoadRegulatorID and a required IntersectionID assignment, providing an unique mapping to the intersection MAP.	The RoadRegulatorID data element is a globally unique identifier assigned to a regional authority.		'Addendum VRA en geregeld Kruisingsvlak Identificatie 20170728'.	
			id [IntersectionID] The IntersectionID is used within a region to uniquely define an intersection within that country or region.	Mandatory	The identifier shall be defined by the road operator.	Set by application
1.3	**Revision [MsgCount]**	The MsgCount data element is used to provide a sequence number within a stream of messages with the same DSRCmsgID and from the same sender. Depending on the application the sequence number may change with every message or may remain fixed during a stream of messages when the content within each message has not changed from the prior message sent.		Mandatory	The revision number must be increased by 1 each time the MapData of this intersection changes. The revision numbers of SPAT and MAP must be the same as an indication that the right MAP version is used.	Set by application
1.4	**status [Intersection-StatusObject]**	The IntersectionStatusObject data element contains Advanced Traffic Controller (ATC) status information.		Mandatory	Types: • **manualControlIsEnabled (0),** • stopTimeIsActivated (1), • **failureFlash (2),** • **preemptIsActive (3),** • signalPriorityIsActive (4), • **fixedTimeOperation (5),** • **trafficDependentOperation (6),** • **standbyOperation (7),** • failureMode (8), • **off (9),** • recentMAPmessageUpdate (10), • recentChangeInMAPassignedLanesIDsUsed (11), • **noValidMAPisAvailableAtThisTime (12),** • **noValidSPATisAvailableAtThisTime (13)** Bits 14,15 reserved at this time and shall be zero	Set by application
1.5	*moy [MinuteOfTheYear]*	The MinuteOfTheYear data element expresses the number of elapsed minutes of the current year in the time system being used (typically UTC time).		Profiled	Mandatory in profile as opposed to standard. To indicate when this message was constructed.	Set by application

1.6	*timeStamp [Dsecond]*	The DSRC second expressed in this data element represents the milliseconds within the current UTC minute.		Profiled	Mandatory in profile as opposed to standard. To indicate when this message was constructed.	-
1.7	*enabledLanes [EnabledLaneList]*	The Enabled Lane List data frame is a sequence of lane IDs for lane objects that are *activated* in the current map configuration. These lanes, unlike most lanes, have their *RevocableLane* bit set to one (asserted). Such lanes are not considered to be part of the current map unless they are in the Enabled Lane List.	LaneID The LaneID data element conveys an assigned index that is unique within an intersection. It is used to refer to that lane by other objects in the intersection map data structure. Lanes may be ingress (inbound traffic) or egress (outbound traffic) in nature, as well as barriers and other types of specialty lanes.	Conditional	Mandatory in profile for specific situations with dynamic lane configurations, e.g. a lane that is used for different manoeuvres at different times of the day. Otherwise not used. The valid configuration can be derived from the active variant as indicated by the intersection controller (e.g. VlogIndicator).	Set by application
1.8	**states [MovementList] (1..255)**	The MovementList data frame consists of a list of MovementState entries. Each Movement is given in turn and contains its signal phase state, mapping to the lanes it applies to, and point in time it will end, and it may contain both active and future states	MovementState The MovementState data frame is used to convey various information about the current or future movement state of a designated collection of one or more lanes of a common type. It is used in the SPAT message to convey every active movement in a given intersection so that vehicles, when combined with certain map information, can determine the state of the signal phases.	Conditional	Mandatory in case the status (see 1.4) indicates normal operation, i.e. IntersectionStatusObject bit 3 to 6. Otherwise states are not used. The states shall be updated and a new SPAT message shall be transmitted when: - The MovementPhaseState of one of the signal groups changes. - The confidence of one of the signal groups changes. - The minEndTime of one of the signal groups changes with 1 second or more. - The maxEndTime of one of the signal groups changes with 1 second or more. - exceptionalCondition is used for one of the signal groups.	See level 2
1.9	*maneuverAssistList [Maneuver-AssistList] (1..6)*	The ManeuverAssistList data frame consists of a list of ConnectionManeuver-Assist entries.	ConnectionManeuverAssist The ConnectionManeuver-Assist data frame contains information about the the dynamic flow of traffic for the lane(s) and maneuvers in question (as determined by the LaneConnectionID). Note that this information can be sent regarding any lane-to-	Not used	At this level the values apply to all movements of the intersection. In the Dutch profile this data frame is only used in level 2, where values are assigned to individual movements.	See level 6

			lane movement; it need not be limited to the lanes with active (non-red) phases when sent.			
1.10	*regional [REGION.Reg-IntersectionState]*	The element is used for additional "regional information", as defined in ISO/PDTS 19091.		Not used	Extension allow to transmit activePrioritizations which consists of a sequence of stationID, priorState and signalGroup. Offers an alternative to the SSM message.	-

Level 2: MovementList → MovementState						
2.1	*movementName [DescriptiveName]*	The DescriptiveName data element is used to provide a human readable and recognizable name for the MovementState data frame.		Profiled	Mandatory in profile as opposed to standard. The DescriptiveName data element is set to human readable and recognizable SignalGroupID. For example, fc02, fc21, SG31, SG41, etc.	Set by application
2.2	**signalGroup [SignalGroupID]**	The SignalGroupID data element is an *index* used to map between the internal state of one or more signal controllers and a common numbering system that can represent all possible combinations of active states (movements and phases). All possible movement variations are assigned a unique value within the intersection.		Mandatory	The SignalGroupID data element is used to map to lists of lanes (and their descriptions) to which this MovementState data applies to. Please note that the range for the SignalGroupID is such that the common Dutch number scheme could contain too high numbers. Therefore SignalGroupIDs must be numbered starting at 1 (0 = unknown, 255 = permanent green movement state) and is unique within the intersection. The signalGroupID used in SPAT and MAP must be identical when they refer to the same signalGroup.	Set by the application
2.3	**state-time-speed [Movement-EventList] (1..16)**	The MovementEventList data frame consists of a list of MovementEvent entries.	MovementEvent The MovementEvent data frame contains details about a single movement. It is used by the movement state to convey one of number of movements (typically occurring over a sequence of times) for a SignalGroupID.	Mandatory	At least one MovementEvent must be provided, i.e. the current MovementPhaseState. Provision of additional MovementEvents is optional.	See level 3
2.4	*maneuverAssistList [Maneuver-AssistList] (1..6)*	The ManeuverAssistList data frame consists of a list of ConnectionManeuverAssist entries. -- This information may also be placed in the IntersectionState	ConnectionManeuverAssist The ConnectionManeuver-Assist data frame contains information about the the dynamic flow of traffic for the lane(s) and maneuvers in question (as determined by the	Profiled	Mandatory in profile as opposed to standard unless the data is not available. Used to convey the queue length.	See level 6

		when common information applies to different lanes in the same way	LaneConnectionID). Note that this information can be sent regarding any lane-to-lane movement; it need not be limited to the lanes with active (non-red) phases when sent.			
2.5	*regional [REGION.Reg-MovementState]*	The element is used for additional "regional information", as defined in ISO/PDTS 19091.		Not used	-	-

Level 3: MovementEventList → MovementEvent					
3.1	**eventState [Movement-PhaseState]**	The MovementPhaseState data element provides the overall current state of the movement (in many cases a signal state), including its core phase state and an indication of whether this state is permissive or protected. It is expected that the allowed transitions from one state to another will be defined by regional deployments. Not all regions will use all states; however, no new states are to be defined. Permissive is typically referred to as a "round ball", while protected implies it has a directional arrow associated with it. A diagram of the above states is included in Annex C.	Mandatory	The MovementPhaseState data element can be set to: Unlit (dark): 0. unavailable e.g. power outage 1. dark e.g. outside of operating hours Reds: 2. stop-Then-Proceed 3. stop-And-Remain Greens: 4. pre-Movement 5. permissive-Movement-Allowed 6. protected-Movement-Allowed Yellows / Ambers: 7. permissive-clearance 8. protected-clearance 9. caution-Conflicting-Traffic e.g. outside of operating hours	Set by application
3.2	*timing [TimeChange-Details]*	The TimeChangeDetails data frame conveys details about the timing of a phase within a movement. The core data concept expressed is the time stamp (time mark) at which the related phase will change to the next state. This is often found in the *MinEndTime* element, but the other elements may be needed to convey the full concept when adaptive timing is employed. The data Element "DE_TimeMark" is defined as an offset to the UTC full hour with a resolution of 36 000 in units of 1/10th of	Conditional	Mandatory when the iVRI (ITS-CLA, TLC, RIS) is fully operational and an ITS-CLA is in control of the intersection, otherwise not used. Mandatory for the current MovementPhaseState , and optional for the next MovementPhaseState(s), for MovementPhaseStates 0, 1 or 9, or when the data is not available (e.g. for specific movements).	See level 4

		second. For proper calculation, be aware of time periods beyond the full hour ("TimeMark" value > 36 000) to avoid negative values. For a calculation of the duration of a traffic light signal phase change, the limited range of the "TimeMark" has to be considered. See the example in TS19091, section G.9.2.3.				
3.3	*speeds [AdvisorySpeedList] (1..16)*	The AdvisorySpeedList data frame consists of a list of AdvisorySpeed entries.	AdvisorySpeed The AdvisorySpeed data frame is used to convey a recommended traveling approach speed to an intersection from the message issuer for different distances to the stop line and various traveller and vehicle types.	Profiled	Mandatory in profile as opposed to standard in case of physical roadside signage displaying dynamic advisory speeds. Recommended to be used in other cases. AdvisorySpeed is a general recommendation for the particular SignalGroupID and not tied to one specific MovementPhaseState. Therefore, it is provided only one time, with the first MovementEvent.	See level 5
3.4	*regional [REGION.Reg-MovementEvent]*	The element is used for additional "regional information", as defined in ISO/PDTS 19091.		Conditional	One extension was defined for this data frame: exceptionalCondition [ExceptionalCondition] Mandatory in case of exceptional waiting, priority green or sudden increases and decreases in waiting time, types: 0. unknown 1. publicTransportPriority 2. emergencyVehiclePriority 3. trainPriority 4. bridgeOpen 5. vehicleHeight 6. weather 7. trafficJam 8. tunnelClosure 9. meteringActive 10. truckPriority 11. bicyclePlatoonPriority 12. vehiclePlatoonPriority 13. ... The signal (ITS) application sets this DE and deactivates it.	Set by application

Level 4: MovementEvent → TimeChangeDetails					
4.1	*startTime [TimeMark]*	The StartTime element is used to relate when the phase itself started or is expected to start. This in turn allows the indication that a set of time change details refers to a future phase, rather than a currently active phase. By this method, timing information about "pre" phase events (which are the short transitional phase used to alert OBEs to an impending green/go or yellow/caution phase) and the longer yellow-caution phase data is supported in the same form as various green/go phases. In theory, the time change details could be sent for a large sequence of phases if the signal timing was not adaptive and the operator wished to do so. In practice, it is expected only the "next" future phase will commonly be sent.	Not used	-	-
4.2	**minEndTime [TimeMark]**	The element MinEndTime is used to convey the earliest time possible at which the phase could change, except when unpredictable events relating to a pre-emption or priority call disrupt a currently active timing plan.	Mandatory	The minEndTime shall not decrease with more than 500ms without provision of a valid exceptionalCondition (the use of exceptionalCondition 'unknown' should be minimised). The difference between the minEndTime and maxEndTime is a measure for the reliability of the prediction. 36001 = undefined or unknown (e.g. 'wachtstand').	Set by application
4.3	*maxEndTime [TimeMark]*	The element MaxEndTime is used to convey the latest time possible which the phase could change, except when unpredictable events relating to a pre-emption or priority call come into play and disrupt a currently active timing plan.	Mandatory	The maxEndTime shall not increase with more than 500ms without provision of a valid exceptionalCondition (the use of exceptionalCondition 'unknown' should be minimised). The difference between the minEndTime and maxEndTime is a measure for the reliability of the prediction. 36001 = undefined or unknown (e.g. 'wachtstand'.	Set by application
4.4	*likelyTime [TimeMark]*	The element likelyTime is used to convey the most likely time the phase changes. This occurs between MinEndTime and MaxEndTime and is only relevant for traffic-actuated control programs.	Optional	Indicates the expected / predicted end time of the phase. Unknown = 36001.	Set by application

4.5	*confidence [TimeIntervalConfidence]*	The element confidence is used to convey basic confidence data about the likelyTime. In this profile an alternative meaning for the confidence values is defined compared to the original standard.	Conditional	These values only apply for MovementPhaseStates 2 and 3. For these states they are mandatory, for other states *confidence* shall not be used. For MovementPhaseStates 2 and 3 (i.e. 'red') the *confidence* value refers to a stage of the control cycle: 1.No demands. 3.Traffic present, time to green unknown. 6.Other conflicting directions may become green first. 9.Signal group is next in line to get green. 12.No conflicting direction is green, signal group will become green, conflicting priority with indication of exceptionalCondition is still possible. 15.Signal group will become green, conflicting priority is not possible. The confidence value shall not decrease unless the eventState changes or an exceptionalCondition is given.	Set by application
4.6	*nextTime [TimeMark]*	The element nextTime is used to express a general (and presumably less precise) value regarding when this phase will next occur. This is intended to be used to alert the OBE when the next green/go may occur so that various ECO driving applications can better manage the vehicle during the intervening stopped time.	Optional	The data element nextTime typically equals likelyTime + the cycle time. Since most signal controllers in the Netherlands use inputs, such as detectors, to dynamically adjust signal timing and phasing, the 'cycle time' is not constant and most likely not available. Therefore, this data element is optional. Unknown = 36001. This data element is mandatory in case the control programs have a constant cycle time. For example, fixed time or semi-fixed time ("half star") control programs.	Set by application

Level 5: MovementEvent → AdvisorySpeed					
5.1	**type [Advisory-SpeedType]**	The AdvisorySpeedType data element relates the type of travel to which a given speed refers. This element is typically used as part of an AdvisorySpeed data frame for signal phase and timing data.	Mandatory	As the main purpose is (dynamic) green wave the value shall be set to 1.	1

5.2	*speed [SpeedAdvice]*	This data element represents the recommended velocity of an object, typically a vehicle speed along a roadway, expressed in unsigned units of 0.1 meters per second.	Profiled	Mandatory in profile as opposed to standard. If the AdvisorySpeed DF is used this is the primary value. Typically the SpeedAdvice considers one intersection, however, the application may have computed the speed advice considering multiple intersections.	Set by application
5.3	*confidence [SpeedConfidence]*	The SpeedConfidence data element is used to provide the 95% confidence level for the currently reported value of DE_Speed, taking into account the current calibration and precision of the sensor(s) used to measure and/or calculate the value.	Not used	As the SpeedAdvice is already described as bandwidth for specific road segments, a confidence value is redundant.	-
5.4	*distance [ZoneLength]*	The ZoneLength data element is used to provide an estimated distance from the stop bar, along the lane centreline back in the lane to which it pertains. It is used in various ways to relate this distance value. When used with clearance zones, it represents the point at which the driver can successfully execute the connection maneuver. It is used in the Clearance Maneuver Assist data frame to relate dynamic data about the lane. It is also used to relate the distance from the stop bar to the rear edge of any queue. It is further used within the context of a vehicle's traveling speed to advise on preferred dynamic approach speeds. -- Unit = 1 meter, -- The distance indicates the region for which the advised speed is recommended, it is specified upstream from the stop bar along the connected egressing lane	Profiled	Mandatory in profile as opposed to standards. The distance indicates the region for which the advised speed is recommended, it is specified upstream from the stop bar in units of 1 meter. The first zone starts at the stop line and ends at the indicated distance.	Set by application
5.5	*class [RestrictionClassID]*	The RestrictionClass data element defines an intersection-unique value to convey data about classes of users. The typical use of this element is to map additional movement restrictions or rights (in both the MAP and SPAT messages) to special classes of users (trucks, high sided vehicles, special vehicles etc.).	Not used	Absent implies that the AdvisorySpeed applies to all users of the Movement, or in case of a shared lane to all motor vehicle types.	-
5.6	*regional [REGION.Reg-AdvisorySpeed]*	The element is used for additional "regional information", as defined in ISO/PDTS 19091.	Not used	-	-

Level 6: ManeuverAssistList → ConnectionManeuverAssist					
6.1	**connectionID [Lane-ConnectionID]**	The LaneConnectionID data entry is used to state a connection index for a lane to lane connection (defined in MAP). It is used to relate this connection and any dynamic clearance data sent in the SPAT.	Mandatory	Unique index value.	Set by application

6.2	*queueLength [ZoneLength]*	The queueLength data entry is used to state the distance from the stop line to the back edge of the last vehicle in the queue as measured along the lane centre line.	Optional	Highly recommended as queue information can improve the quality of service considerably. To be considered mandatory if available. Unit = 1 meter, 0 = no queue. Used to improve the in-vehicle calculation of the SpeedAdvice.	Set by application
6.3	*available-StorageLength [ZoneLength]*	Distance (e.g. beginning from the downstream stop-line up to a given distance) with a high probability for successfully executing the connecting manoeuvre between the two lanes during the current cycle. Used for enhancing the awareness of vehicles to anticipate if they can pass the stop line of the lane. Used for optimizing the green wave, due to knowledge of vehicles waiting in front of a red light (downstream).	Not used	Out of scope of current use cases.	-
6.4	*waitOnStop [WaitOnStopline]*	The WaitOnStopline data element is used to indicate to the vehicle that it must stop at the stop line and not move past.	Not used	Out of scope of current use cases.	-
6.5	*pedBicycleDetect [Pedestrian-BicycleDetect]*	The PedestrianBicycleDetect data element is used to provide an indication of whether Pedestrians and/or Bicyclists have been detected in the crossing lane.	Not used	Out of scope of current use cases.	-
6.6	*regional [REGION.RegConnec-tionManeuverAssist]*	The element is used for additional "regional information", as defined in ISO/PDTS 19091.	Not used	Extensions allow to transmit vehicleToLanePositions and rsuGNSSOffset.	-

Annex A: Summary of SPaT profile

bold = mandatory/used

bold-italic = conditional

italic = optional

~~strikethrough~~ = not used

red = desired extensions

~~timestamp [MinuteOfTheYear]~~
name [DescriptiveName]
intersections [Intersection-StateList]
IntersectionState
name [DescriptiveName]
id [Intersection-ReferenceID]
region [RoadRegulatorID]
id [IntersectionID]
Revision [MsgCount]
Status [IntersectionStatusObject]
moy [MinuteOfTheYear]
timestamp [Dsecond]
enabledLanes [EnabledLaneList]
LaneID
states [MovementList]
MovementState
movementName [DescriptiveName]
signalGroup [SignalGroupID]
state-time-speed [MovementEventList]
MovementEvent
eventState [MovementPhaseState]
timing [TimeChangeDetails]
~~*startTime [TimeMark]*~~
minEndTime [TimeMark]
maxEndTime [TimeMark]

likelyTime [TimeMark]

confidence [TimeIntervalConfidence]

nextTime [TimeMark]

speeds [AdvisorySpeedList]

AdvisorySpeed

type [AdvisorySpeedType]

speed [SpeedAdvice]

~~confidence [SpeedConfidence]~~

distance [ZoneLength]

~~class [Restriction-ClassID]~~

~~regional [REGION.Reg-AdvisorySpeed]~~

~~regional [REGION.Reg-MovementEvent]~~

~~addGrpC [MovementEvent-addGrpC]~~

exceptionalCondition [ExceptionalCondition]

maneuverAssistList [ManeuverAssistList]

ConnectionManeuverAssist

connectionID [LaneConnectionID]

queueLength [ZoneLength]

~~availableStorageLength [ZoneLength]~~

~~waitOnStop [WaitOnStopline]~~

~~pedBicycleDetect [PedestrianBicycleDetect]~~

~~regional [REGION.Reg-ConnectionManeuverAssist]~~

regional [REGION.Reg-MovementState]

~~maneuverAssistList [ManeuverAssistList]~~

~~ConnectionManeuverAssist~~

~~connectionID [LaneConnectionID]~~

~~queueLength [ZoneLength]~~

~~availableStorageLength [ZoneLength]~~

~~waitOnStop [WaitOnStopline]~~

~~pedBicycleDetect [PedestrianBicycleDetect]~~

~~regional [REGION.Reg-ConnectionManeuverAssist]~~

~~regional [REGION.Reg-IntersectionState]~~

~~regional [REGION.Reg-SPAT]~~

Annex B: Bit string example

A bit string is an arbitrarily long array of bits. Specific bits can be identified by parenthesized integers and assigned names. As an example, the bit string for the data element LaneSharing is shown in **Figure 1**.

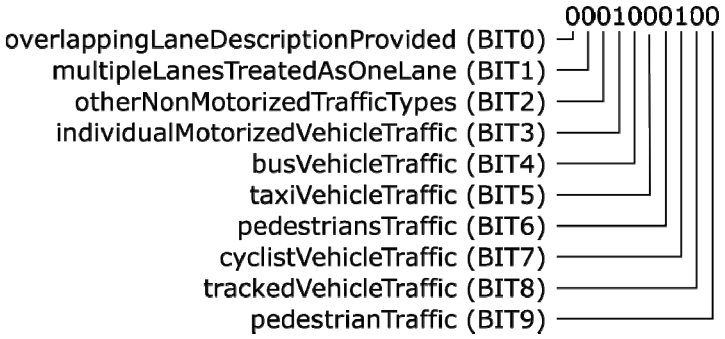

Figure 1 Bit string example

The example shows the 10 bit sting '0001000100', where BIT3and BIT7 are set from left to right. This indicates that user types individualMotorizedVehicleTraffic and cyclistVehicleTraffic can access and use the respective lane.

Annex C: State Diagram

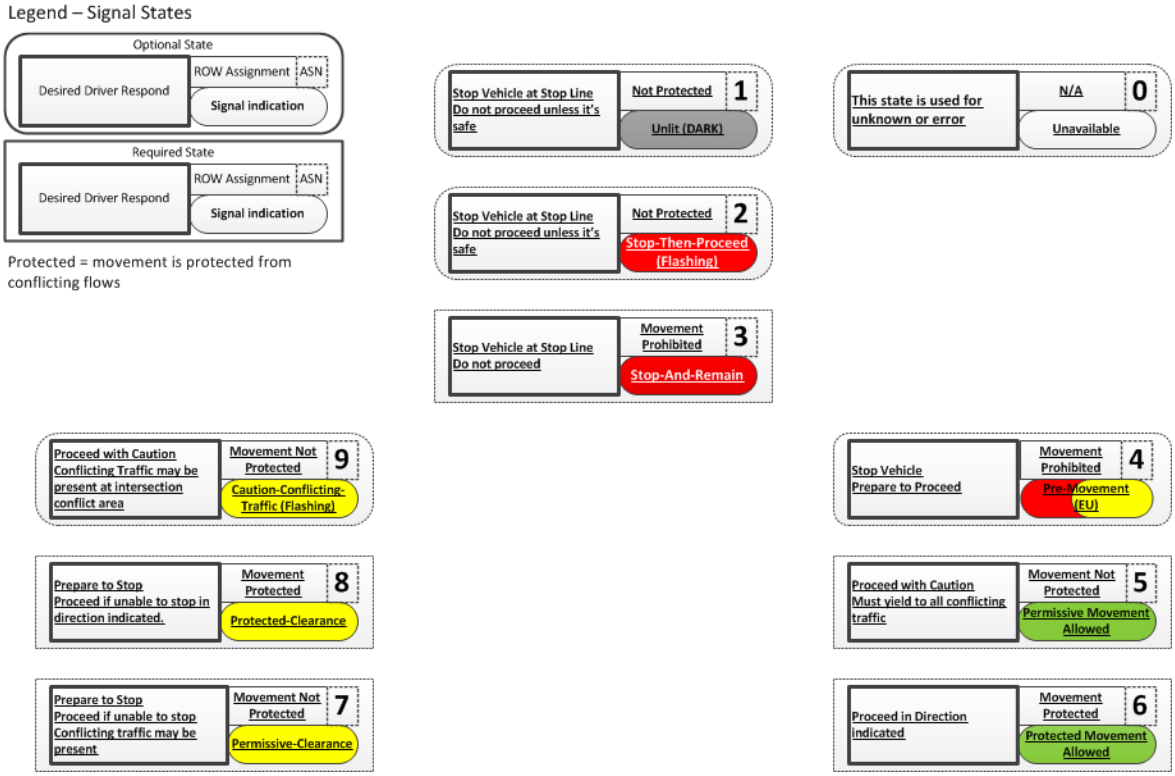

Figure 1 State Diagram

Colophon

SPaT Data

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