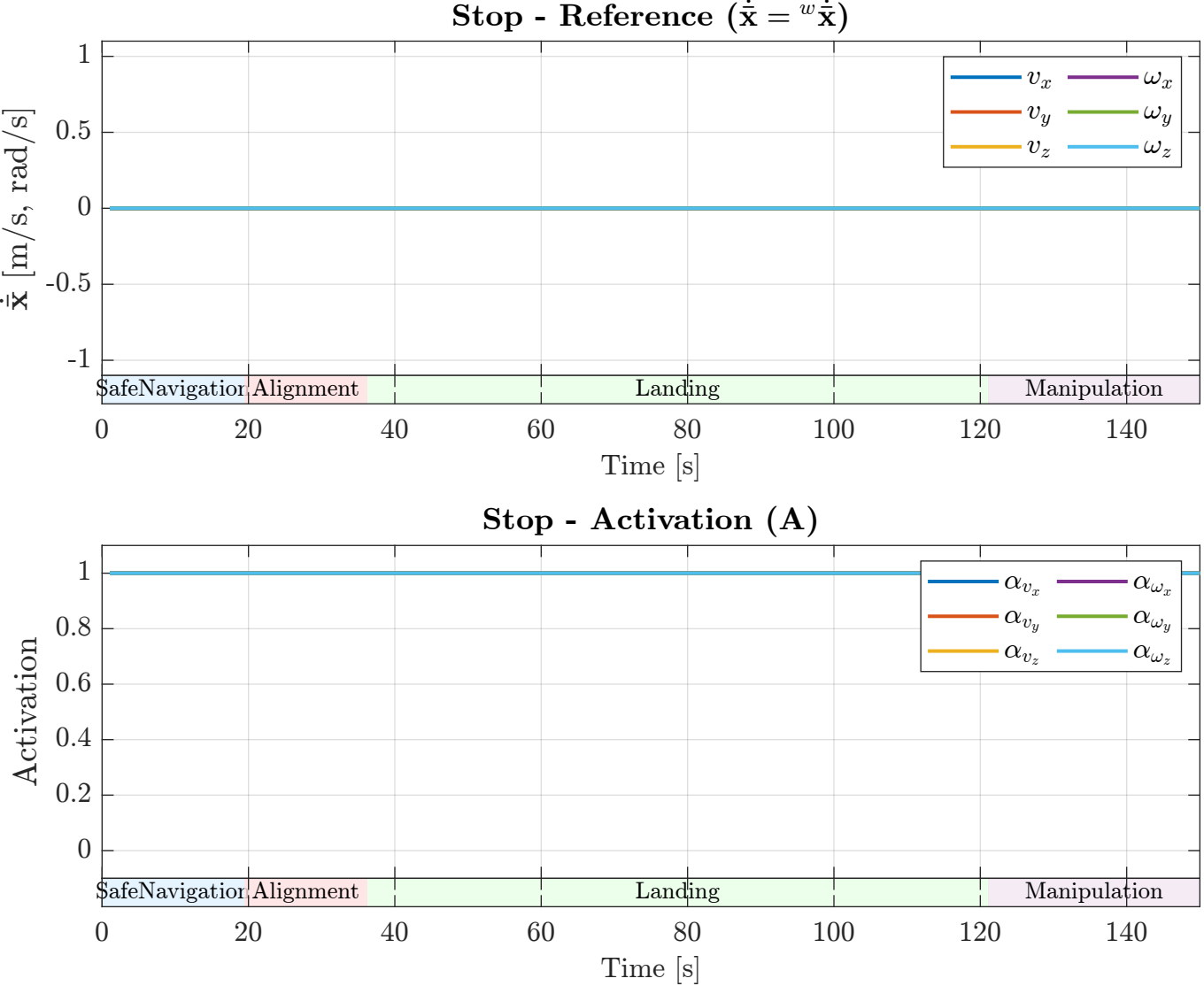
Stop - Reference ($\dot{\bar{\mathbf{x}}} = {}^{w}\dot{\bar{\mathbf{x}}}$)
$\dot{\bar{\mathbf{x}}}$ [m/s, rad/s]
1
0.5
0
-0.5
-1
$v_x$
$v_y$
$v_z$
$\omega_x$
$\omega_y$
$\omega_z$
SafeNavigation
Alignment
Landing
Manipulation
0
20
40
60
80
100
120
140
Time [s]
Stop - Activation (A)
Activation
1
0.8
0.6
0.4
0.2
0
$\alpha_{v_x}$
$\alpha_{v_y}$
$\alpha_{v_z}$
$\alpha_{\omega_x}$
$\alpha_{\omega_y}$
$\alpha_{\omega_z}$
SafeNavigation
Alignment
Landing
Manipulation
0
20
40
60
80
100
120
140
Time [s]