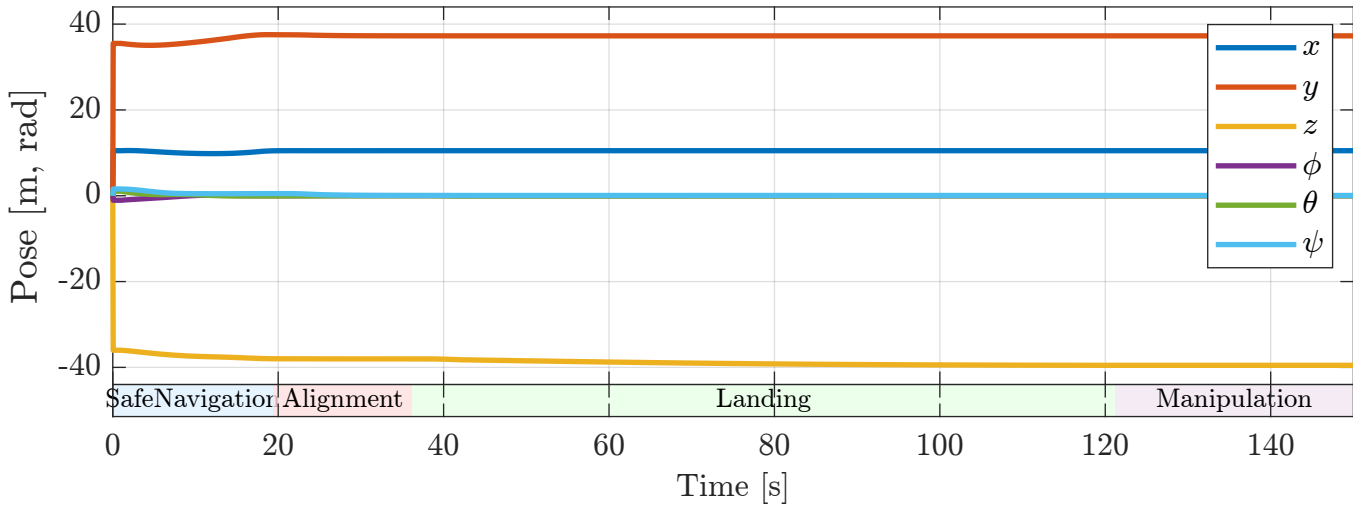


Vehicle Pose (η)



Vehicle Velocity (ν)

