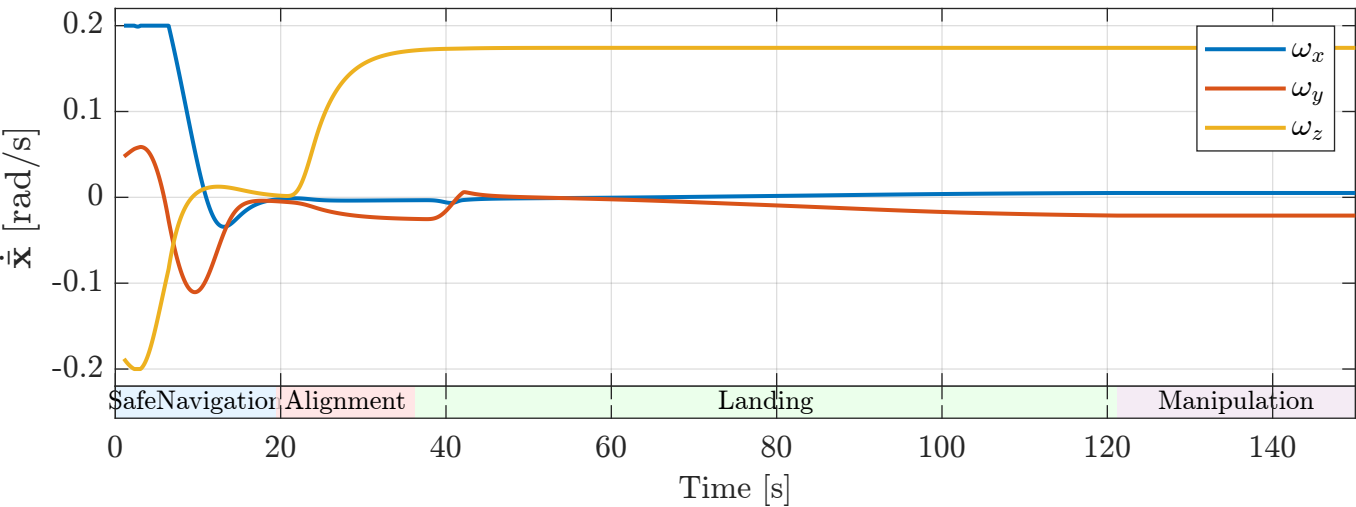


Vehicle Orientation - Reference ($\ddot{\mathbf{x}} = {}^w \ddot{\mathbf{x}}$)



Vehicle Orientation - Activation (A)

