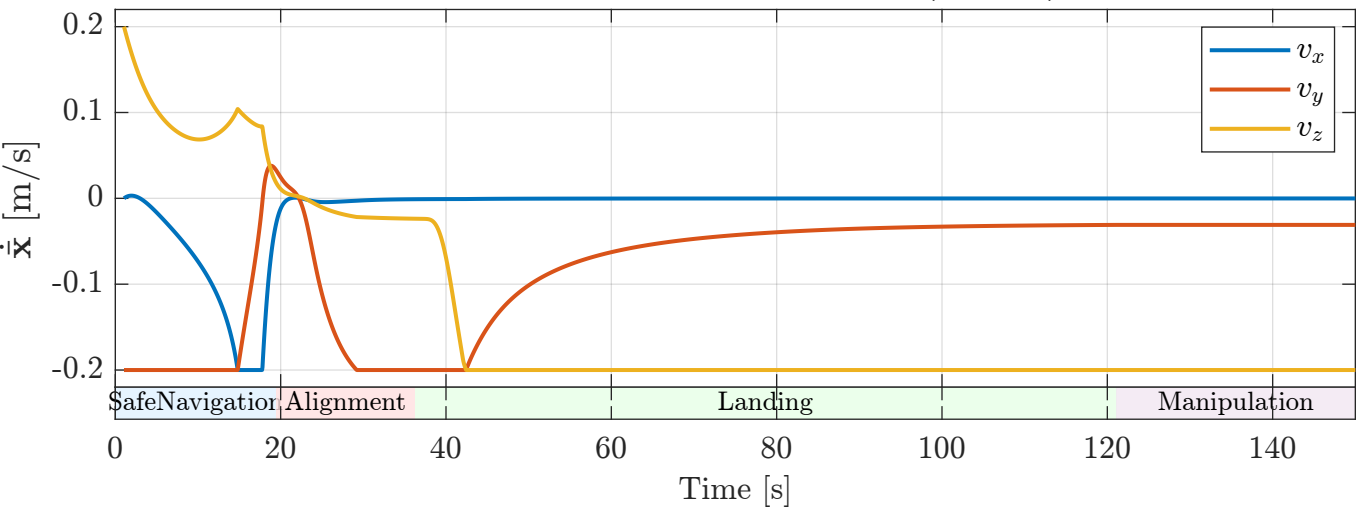


Vehicle Position - Reference ($\dot{\bar{\mathbf{x}}} = {}^w\dot{\bar{\mathbf{x}}}$)



Vehicle Position - Activation (A)

