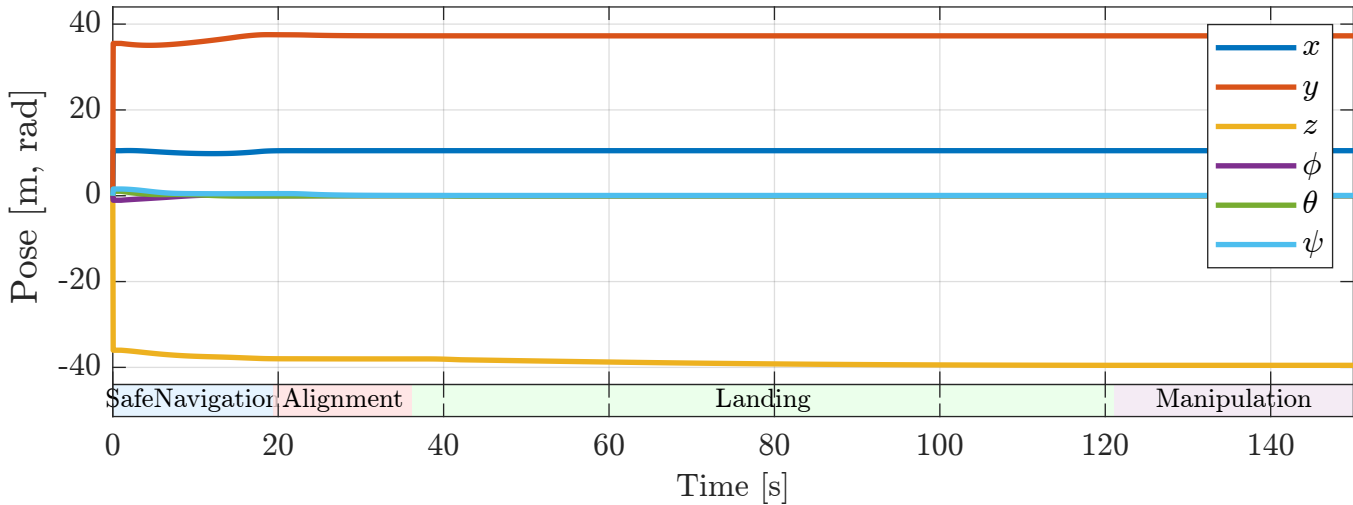


# Vehicle Pose ( $\eta$ )



# Vehicle Velocity ( $\nu$ )

