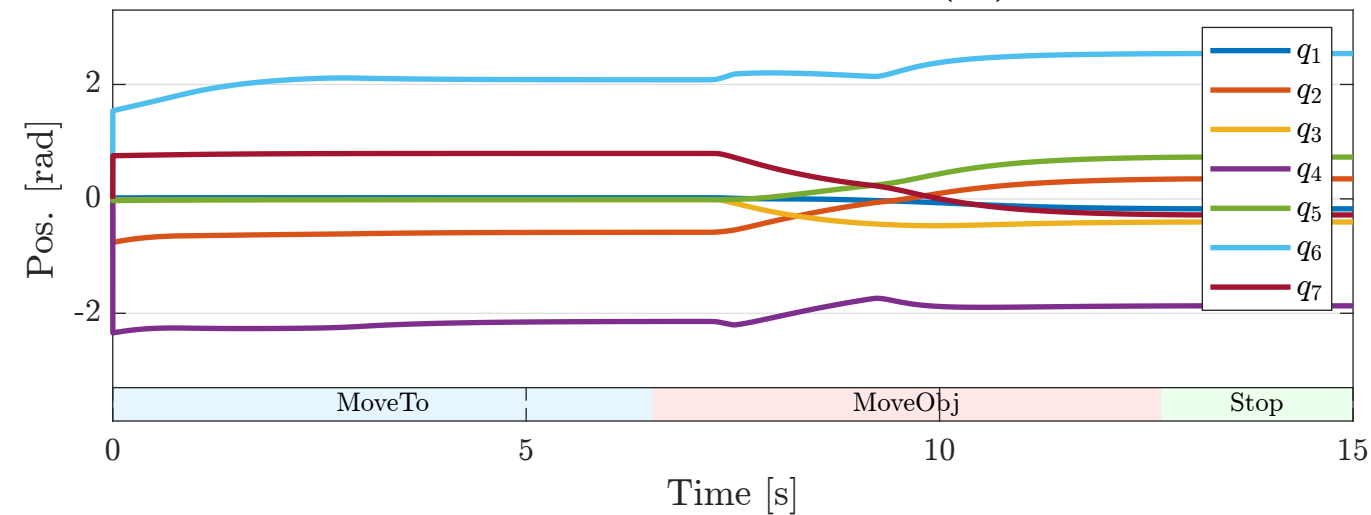


Left Arm - Joint Positions (q_L)



Left Arm - Joint Velocities (\dot{q}_L)

