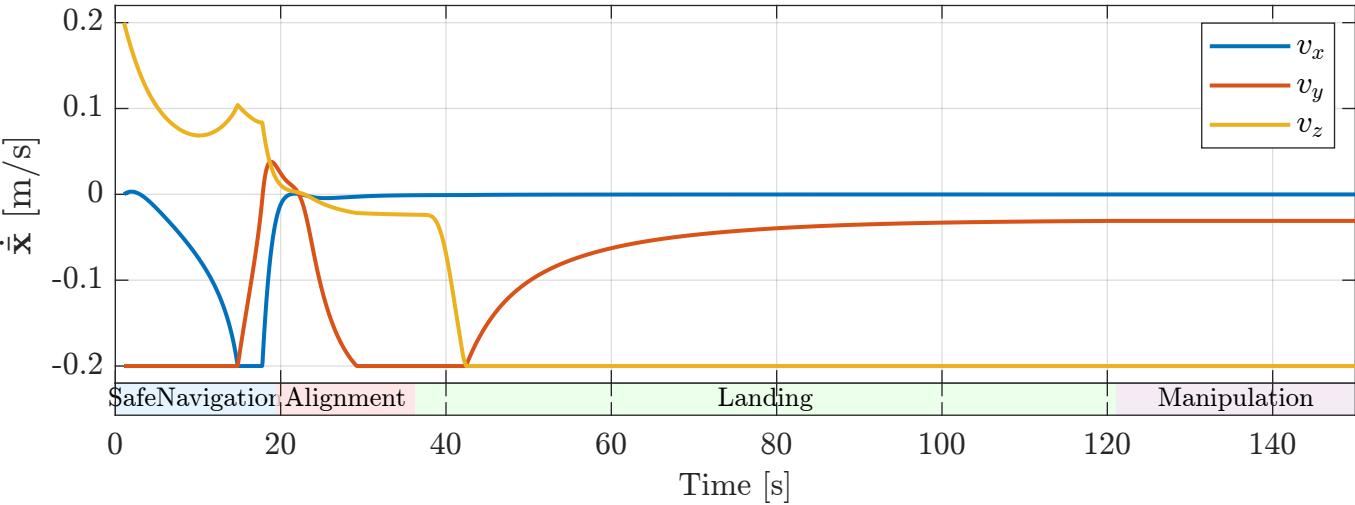


## Vehicle Position - Reference ( $\dot{\bar{x}} = {}^w\dot{\bar{x}}$ )



## Vehicle Position - Activation (A)

