Left Joint Limits - Reference ($\dot{\bar{x}} = \dot{\bar{q}}$)

Legend: $\dot{q}_{1,L}$, $\dot{q}_{2,L}$, $\dot{q}_{3,L}$, $\dot{q}_{4,L}$, $\dot{q}_{5,L}$, $\dot{q}_{6,L}$, $\dot{q}_{7,L}$

$\dot{\bar{x}}$ [rad/s] vs Time [s]

MoveTo — MoveObj — Stop
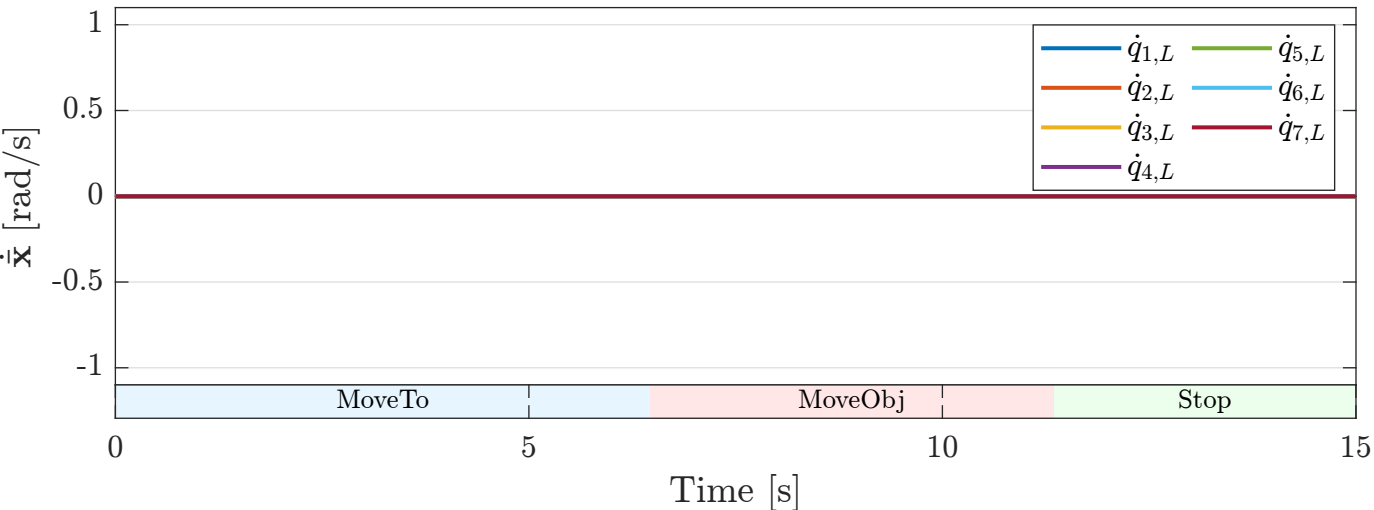
Left Joint Limits - Activation (A)

Legend: $\alpha_{1,L}$, $\alpha_{2,L}$, $\alpha_{3,L}$, $\alpha_{4,L}$, $\alpha_{5,L}$, $\alpha_{6,L}$, $\alpha_{7,L}$

Activation vs Time [s]

MoveTo — MoveObj — Stop