Right Joint Limits - Reference ($\dot{\bar{\mathbf{x}}} = \dot{\bar{\mathbf{q}}}$)

Legend: $\dot{q}_{1,R}$, $\dot{q}_{2,R}$, $\dot{q}_{3,R}$, $\dot{q}_{4,R}$, $\dot{q}_{5,R}$, $\dot{q}_{6,R}$, $\dot{q}_{7,R}$

$\dot{\bar{\mathbf{x}}}$ [rad/s] vs Time [s]

MoveTo, MoveObj, Stop
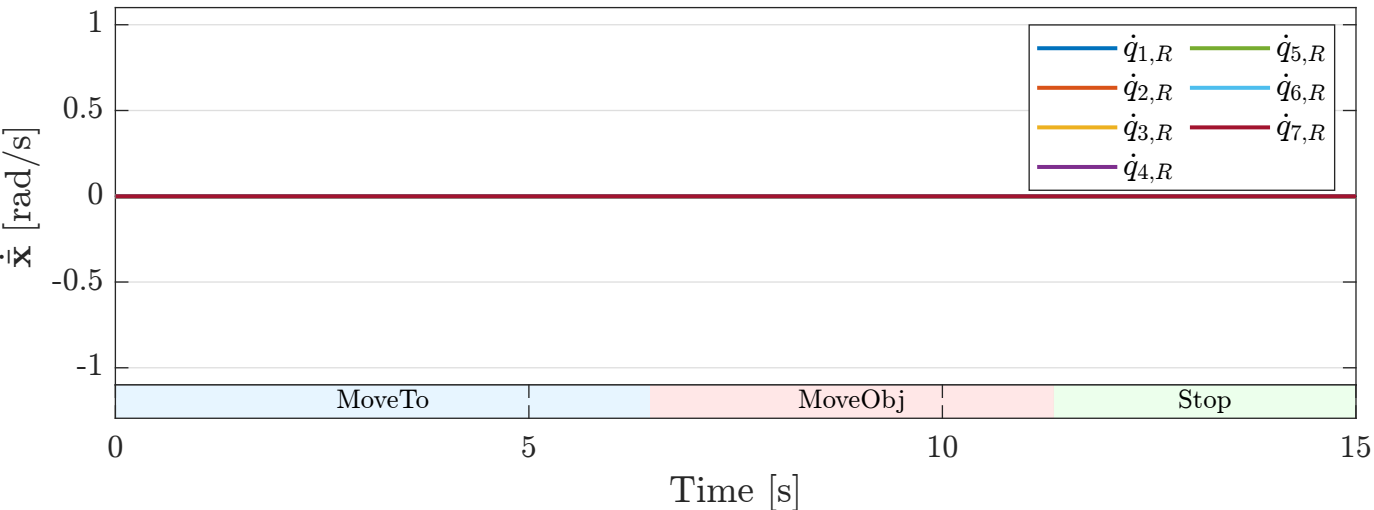
Right Joint Limits - Activation (A)

Legend: $\alpha_{1,R}$, $\alpha_{2,R}$, $\alpha_{3,R}$, $\alpha_{4,R}$, $\alpha_{5,R}$, $\alpha_{6,R}$, $\alpha_{7,R}$

Activation vs Time [s]

MoveTo, MoveObj, Stop