Joint Limits - Reference ($\dot{\bar{\mathbf{x}}} = \dot{\bar{\mathbf{q}}}$)

$\dot{q}_{1,L}$ $\dot{q}_{1,R}$
$\dot{q}_{2,L}$ $\dot{q}_{2,R}$
$\dot{q}_{3,L}$ $\dot{q}_{3,R}$
$\dot{q}_{4,L}$ $\dot{q}_{4,R}$
$\dot{q}_{5,L}$ $\dot{q}_{5,R}$
$\dot{q}_{6,L}$ $\dot{q}_{6,R}$
$\dot{q}_{7,L}$ $\dot{q}_{7,R}$

$\dot{\bar{\mathbf{x}}}$ [rad/s]

MoveTo   MoveObj   Stop

Time [s]
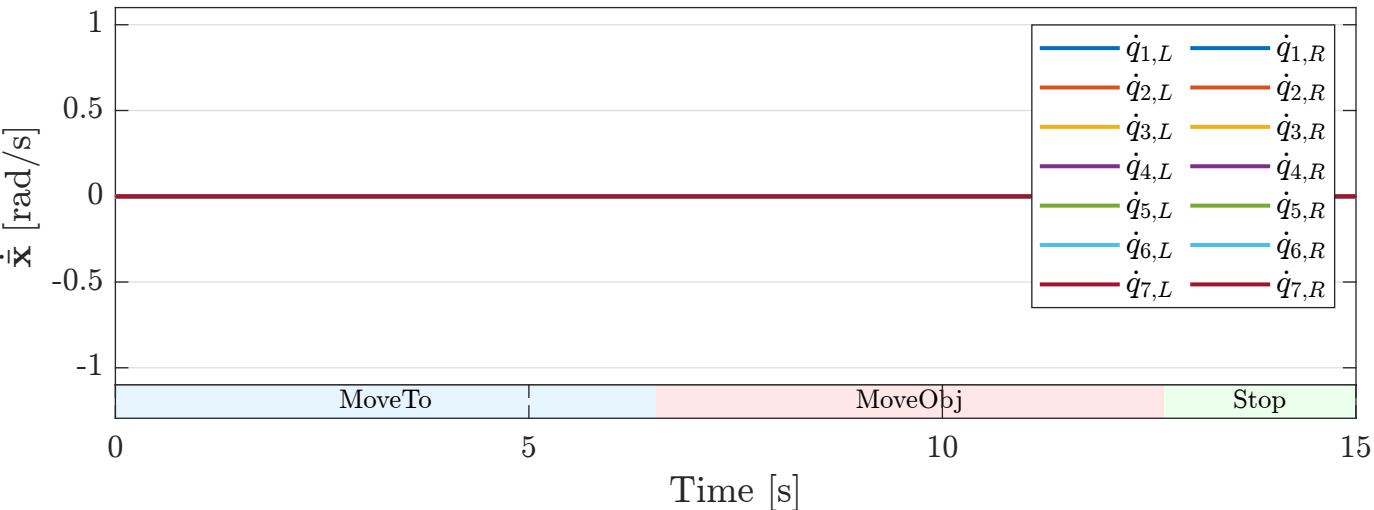
Joint Limits - Activation (A)

$\alpha_{1,L}$ $\alpha_{1,R}$
$\alpha_{2,L}$ $\alpha_{2,R}$
$\alpha_{3,L}$ $\alpha_{3,R}$
$\alpha_{4,L}$ $\alpha_{4,R}$
$\alpha_{5,L}$ $\alpha_{5,R}$
$\alpha_{6,L}$ $\alpha_{6,R}$
$\alpha_{7,L}$ $\alpha_{7,R}$

Activation

MoveTo   MoveObj   Stop

Time [s]