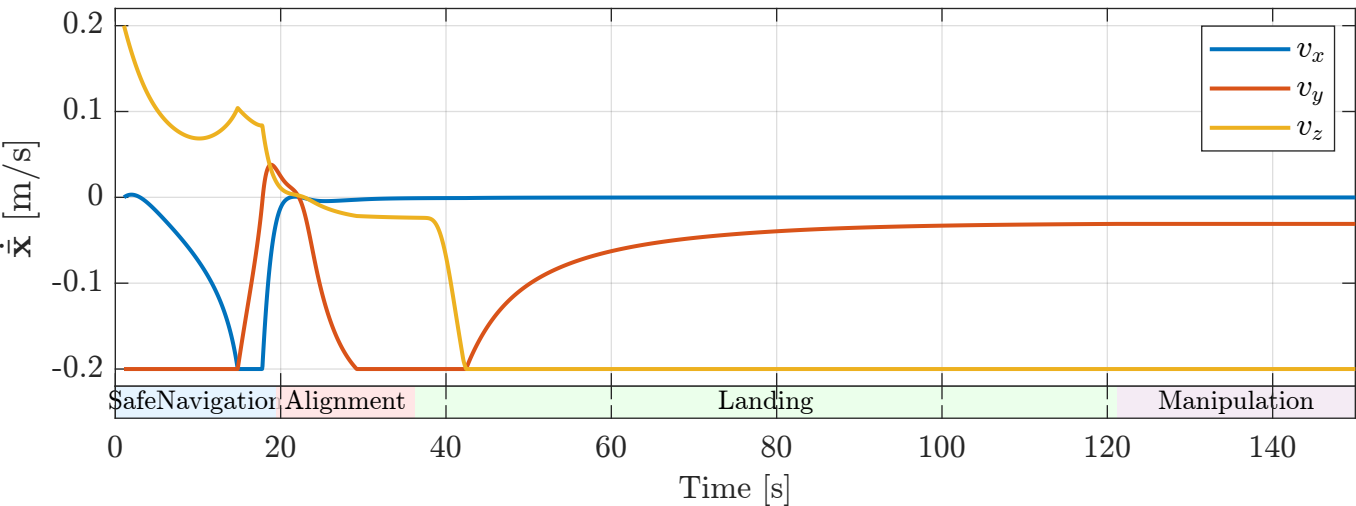


Vehicle Position - Reference ( $\dot{\vec{x}} = {}^w\dot{\vec{x}}$ )



Vehicle Position - Activation (A)

