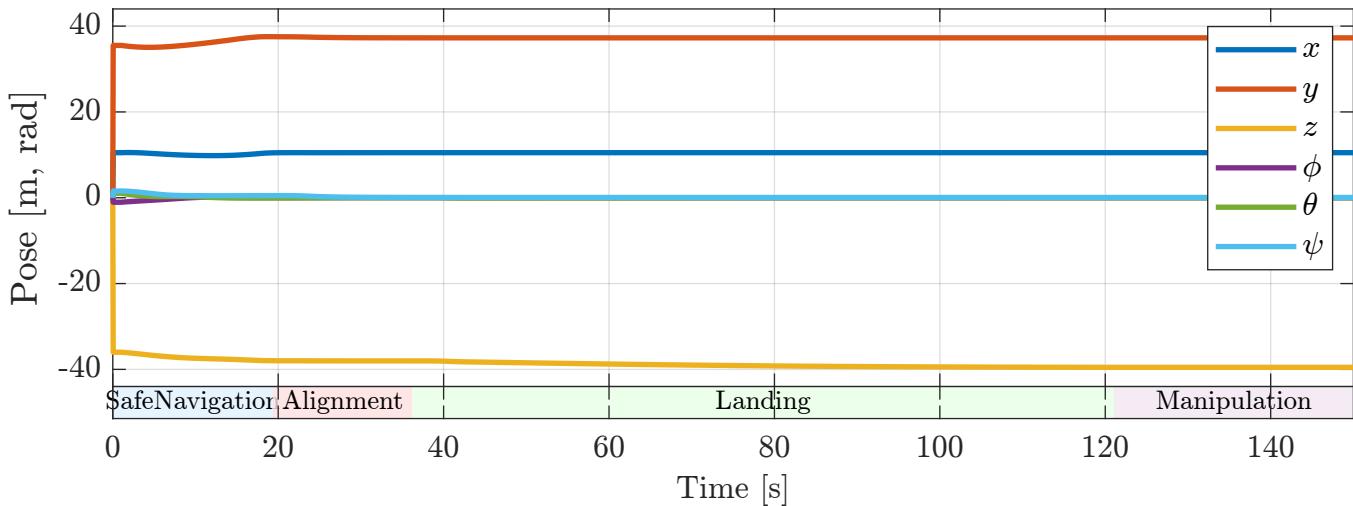


## Vehicle Pose ( $\eta$ )



## Vehicle Velocity ( $\nu$ )

