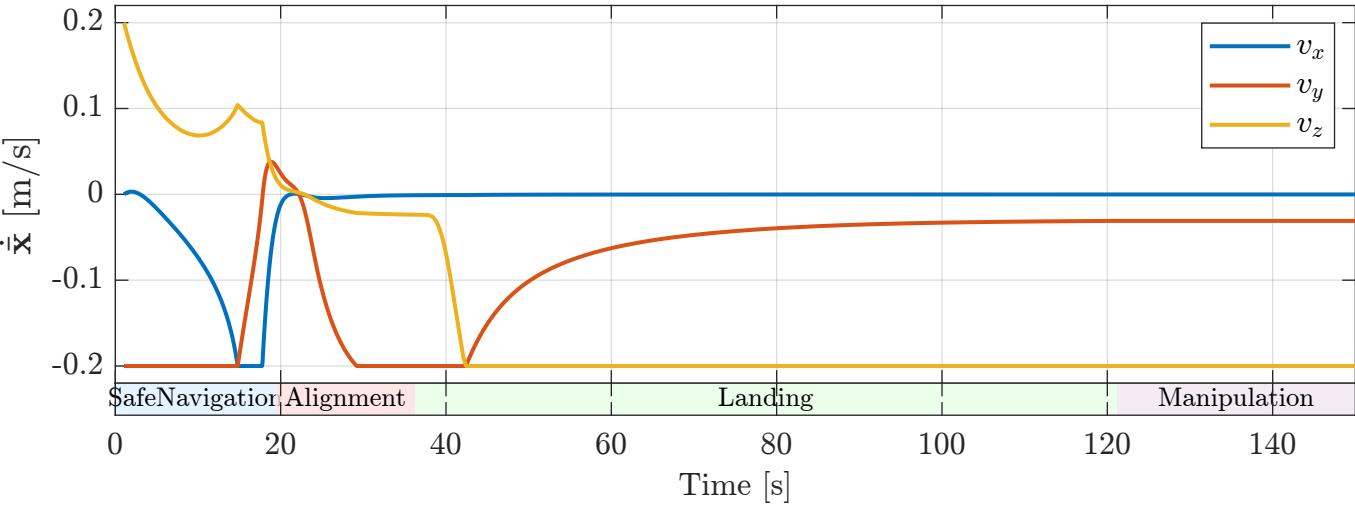


Vehicle Position - Reference ($\dot{\bar{x}} = {}^w\dot{\bar{x}}$)



Vehicle Position - Activation (A)

