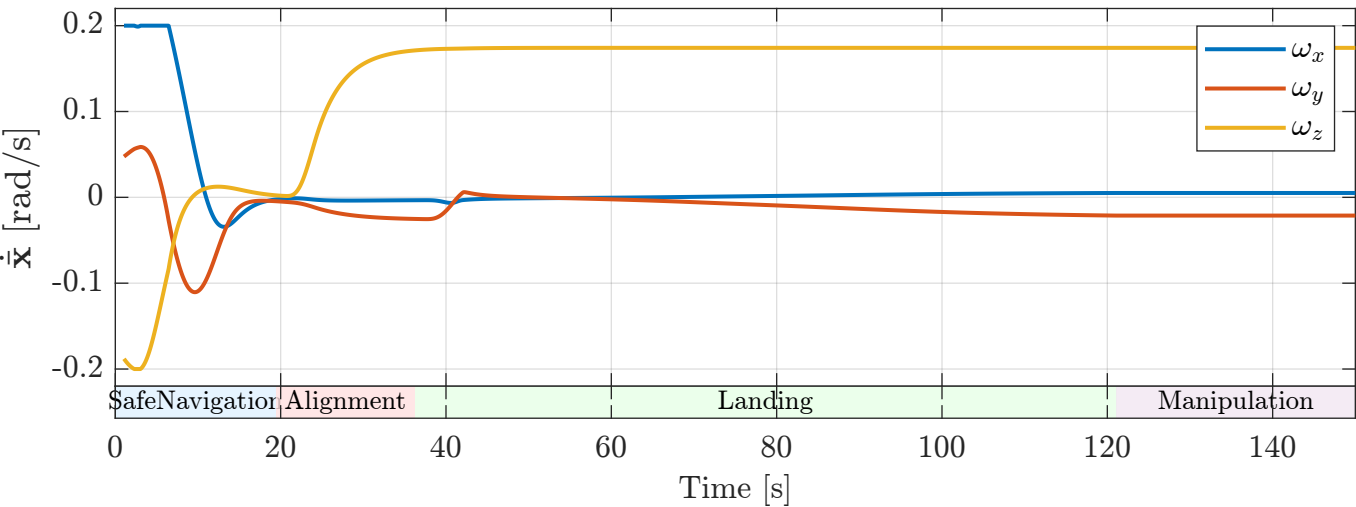


# Vehicle Orientation - Reference ( $\ddot{\mathbf{x}} = {}^w \ddot{\mathbf{x}}$ )



# Vehicle Orientation - Activation (A)

