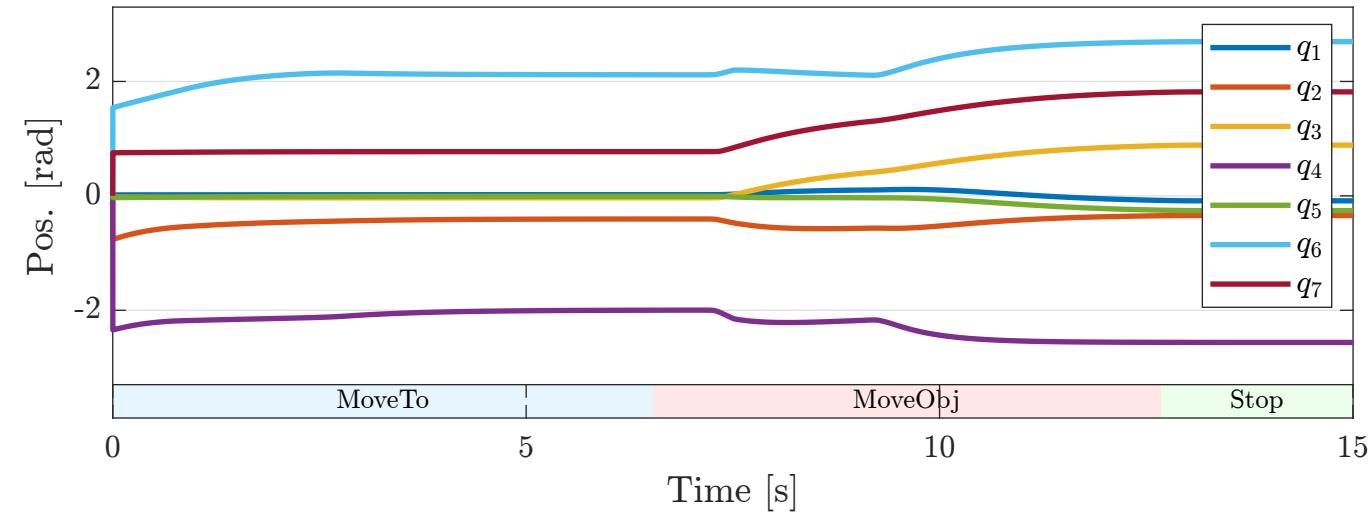


Right Arm - Joint Positions (q_R)



Right Arm - Joint Velocities (\dot{q}_R)

