

Finite Difference Methods

Goals

- | To understand Black Scholes PDE 1o1 and its implementation in C++
- | Understand 'big picture' from BS -> PDE -> FDM -> C++
- | Extend and debug existing (possibly undocumented) application code
- | Get an overview of popular FD methods as used in computational finance

Scope Problem

- | One-factor plain option (exercise at $t = T$)
- | Barrier options
- | Introduce early exercise by checking constraint at each time level
- | Different levels of how flexible the solution will be

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Black Scholes PDE

- | Describes the behaviour in time and space (S, t) of an option
- | Time-dependent convection-diffusion equation
- | Need extra boundary and initial conditions
- | Care to be taken with truncation/transformation of the S domain

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BS PDE

- |
$$-\frac{\partial V}{\partial t} + \frac{1}{2}\sigma^2 S^2 \frac{\partial^2 V}{\partial S^2} + rS \frac{\partial V}{\partial S} - rV = 0$$
- | Add boundary conditions at $S = 0$ and $S = S_{\max}$
- | Initial condition is the option payoff
- | These result in complete description of the PDE problem

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Boundary Conditions

- | Put

$$P(0, t) = Ke^{-rt}, \quad \lim_{S \rightarrow \infty} P(S, t) = 0$$

- | Call

$$C(0, t) = 0, \quad \lim_{S \rightarrow \infty} C(S, t) = S$$

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Finite Differencing

- | Approximate PDE problem on a continuous space by finite differences on discrete space
- | Approximate 2nd and 1st order derivatives in S by centred differences
- | Approximation in time can be Backward, Forward or Centred in time
- | (!! Stability and accuracy of finite difference schemes)

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Explicit Euler

- | Express the solution at level n+1 in terms of solution at time level n
- | Take boundary conditions into account

$$-\frac{V_j^{n+1}-V_j^n}{k} + \frac{1}{2} \sigma^2 S_j^2 \left(\frac{V_{j+1}^n - 2V_j^n + V_{j-1}^n}{k^2} \right) + r S_j \left(\frac{V_{j+1}^n - V_{j-1}^n}{h^2} \right) - r V_j^n = 0$$

$$V_j^{n+1} = \alpha_j V_{j-1}^n + \beta_j V_j^n + \gamma_j V_{j+1}^n$$

- | No matrix inversion needed

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Implicit Euler

$$-\frac{V_j^{n+1} - V_j^n}{k} + rj\Delta S \left(\frac{V_{j+1}^{n+1} - V_{j-1}^{n+1}}{2\Delta S} \right) + \frac{1}{2}\sigma^2 j^2 \Delta S^2 \left(\frac{V_{j+1}^{n+1} - 2V_j^{n+1} + V_{j-1}^{n+1}}{\Delta S^2} \right) = rV_j^{n+1}$$

$$a_j^{n+1} V_{j-1}^{n+1} + b_j^{n+1} V_j^{n+1} + c_j^{n+1} V_{j+1}^{n+1} = F_j^{n+1}$$

| Solve as a matrix system

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Crank Nicolson

| Average of implicit and explicit Euler

$$-\frac{V_j^{n+1} - V_j^n}{k} + rj\Delta S \left(\frac{V_{j+1}^{n+\frac{1}{2}} - V_{j-1}^{n+\frac{1}{2}}}{2\Delta S} \right) + \frac{1}{2}\sigma^2 j^2 \Delta S^2 \left(\frac{V_{j+1}^{n+\frac{1}{2}} - 2V_j^{n+\frac{1}{2}} + V_{j-1}^{n+\frac{1}{2}}}{\Delta S^2} \right) = \tau V_j^{n+\frac{1}{2}}$$

$$\left(V_j^{n+\frac{1}{2}} \equiv \frac{1}{2} (V_j^{n+1} + V_j^n) \right)$$

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Sanity Check

- | Can use put-call parity to check put and call from FDM
- | We also have explicit solutions for plain options

$$C(t) - P(t) = S(t) - KB(t, T)$$

$$B(t, T) = e^{-r(T-t)} \text{ (bond maturing at } T\text{)}$$

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General PDE Formulation

$$Lu \equiv -\frac{\partial u}{\partial t} + \sigma(x, t) \frac{\partial^2 u}{\partial x^2} + \mu(x, t) \frac{\partial u}{\partial x} + b(x, t)u = f(x, t) \text{ in } \Omega$$

$$u(x, 0) = \varphi(x), x \in \Omega$$

$$u(A, t) = g_0(t), u(B, t) = g_1(t), t \in (0, T)$$

$$D = (0, X_{\max}) \times (0, T)$$

$$\Omega = (0, X_{\max})$$

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Programming Tips

- | Make sure you have worked out your algorithm properly
- | Make sure C++ code 'mirrors' the algorithm
- | Take care with data structures and indexing
- | Take it step-by-step

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