

Master's Degree in Computer Science and Engineering

# Unity for Collektive: Reducing Reality Gap in the Simulation of Collective Adaptive Systems

Thesis in:  
SOFTWARE PROCESS ENGINEERING

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# **Abstract**

Max 2000 characters, strict.



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# Chapter 1

## Introduction

The landscape of modern computing is undergoing a fundamental shift. We are moving away from an era defined by powerful, isolated machines toward one characterized by massive, interconnected ensembles of devices. This transition is visible in everything from global IoT sensor networks to smart city infrastructures. In these scenarios, the challenge is no longer just ‘how to compute’, but rather ‘how to coordinate’.

As the number of devices in these systems grows into the thousands or millions, traditional centralized management becomes a bottleneck. The latency, bandwidth constraints, and single-point-of-failure risks of a ‘command-and-control’ architecture make it unsuitable for the dynamic, often unpredictable environments these systems inhabit. Instead, we must look toward decentralized coordination, where collective intelligence arises from local interactions rather than global oversight.

This thesis explores the intersection of high-level collective programming and high-fidelity simulation. Specifically, it addresses the engineering gap between abstract coordination models, such as Aggregate Computing, and the practical requirements of developing, testing, and deploying these models within realistic 3D environments. By leveraging the power of modern game engines and automated development workflows, this work aims to provide a robust infrastructure for the next generation of collective system design.

## 1.1 Motivation: Swarm Behaviour

## 1.2 Problem Statement: Engineering Challenges in Simulation

## 1.3 Contributions

### 1.3.1 A Standardized Automation Workflow for Unity Pack- ages

### 1.3.2 A 3D Aggregate Computing Simulator

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# **Chapter 2**

## **Background and State of the Art**

### **2.1 Distributed Systems and Organizational Complexity**

### **2.2 Self-Organizing Frameworks**

#### **2.2.1 Aggregate Computing**

### **2.3 Simulation Landscape**

#### **2.3.1 Paradigms**

#### **2.3.2 The Reality Gap**

#### **2.3.3 Reéalism vs. Scalability**

### **2.4 Game Engines as Simulators**



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# **Chapter 3**

## **Unity-Package-Template: Automated Unity Development Infrastructure**

### **3.1 Requirements**

### **3.2 Features**

### 3.2. FEATURES

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# **Chapter 4**

## **Collektive×Unity: Designing a 3D Simulator for Collective Systems**

### **4.1 Goal**

### **4.2 Requirements**

### **4.3 Architecture**



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# **Chapter 5**

## **Implementation of Collektive×Unity**

### **5.1 Design**

### **5.2 Implementation Details**



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# Chapter 6

## Case Study: Environment-aware Gradient Ascent



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# Chapter 7

## Results

### 7.1 Comparison with Socket-based Communication



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# **Chapter 8**

## **Conclusions and Future Work**



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# Acknowledgements

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