



SYNTHESIZABLE PLATFORM FOR TERRIFIC SIMULATION



Virtual Platform (VP)

- Simulatable abstraction of a complex design
 - Composed of multiple IPs
 - Design reuse!
 - High performances
 - Adequate accuracy
- Enable HW-SW Codesign
 - Reducing time-to-market
 - Powerful debug and verification features
- Choice of abstraction level is fundamental
 - Compromise between accuracy and complexity



Virtual Platform (VP)

- Typical VP design components:
 - System IP models
 - Memory models how many works
 - Processor models → operations
 - A compiler is necessary to write software for the VP!
 - Cross-compilers enable the generation of platform-native executables on an external machine
 - Communication models
 - Accessing host interfaces in the Virtual Platform
 - Interfaces for communicating with external devices
 - Debugger interface support



- The platform includes:
 - CPU MOS 6502 (1975)
 - Vic 20, Commodore 64, Nintendo Entertainment System (NES), Apple II, Atari 800, Terminator
 - 16 bit addressing (16KB ROM, 16KB RAM),
 - 8 bit data width
 - Memory
 - ROM in one single bank
 - RAM splitted in 8 different blocks to enable multi read/write operations
 - Clock divider
 - manage MMIO operation between Peripherals, Memory
 - Manage multiple write on same cell between CPU and MMIO Interface
 - BUS ARM APB (Advanced Peripheral Bus)
 - Supports up to 8 peripherals
 - IO Module
 - Used to request or send data out from the platform
 - Simple Integer Multiplier



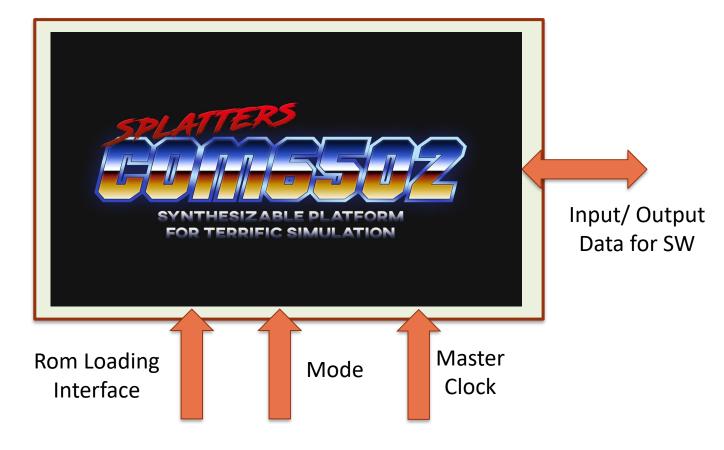
- Unzip com6502-splatters.tar.gz
 - Three directories
 - platform/
 - Contains the description of all Com6502-Splatters components including a tb
 - cc65/
 - Cross-compiler binaries (UNIX)
 - application/
 - Main example
 - MMIO functions simplementation of Hemory Mapped I/O date read and stored is contained in the main memory in a specific range of addresses
 - Drivers for Multiplier and IO Module



Splatters - Top Level

top_level.v

- Two different mode available
 - Load cross-compiled SW
 - Run SW with I/O interactions





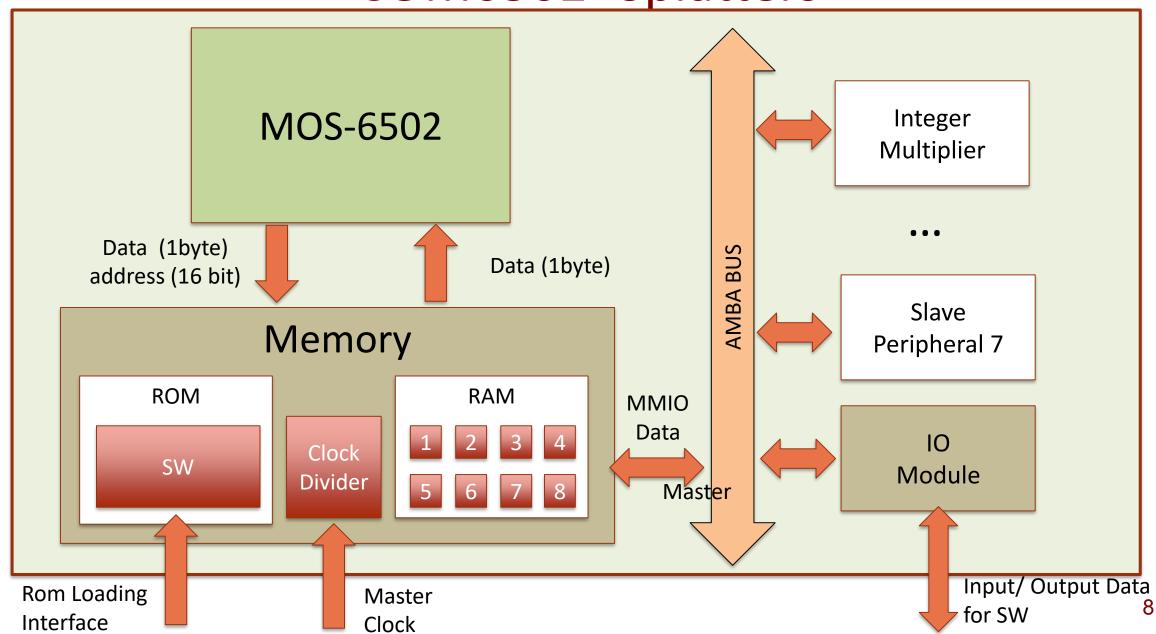
Top Level

Port	Description	Causality	Data width
clk	Platform clk	Input	1
rst	Platform Reset	Input	1
Mode	Mode = 0 Load Rom Mode = 1 Run Rom SW	Input	1
we_n_in	SW Write enable on negative edge	Input	1
sw_din	SW data input	Input	8
sw_addr	SW address	Input	14
dout	Output Data from Platform	Output	32
dout_rdy	Output Data Ready from Platform	Output	1
din_req	Data Request from Platform	Output	1
din	Input Data for Platform	Input	32
din_rdy	Input Data Ready for Platform	Input	1

Input/ Output Data for SW

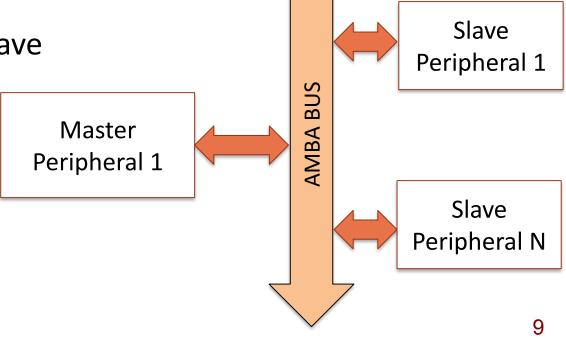
Rom Loading Interface







- The ARM Advanced Microcontroller Bus Architecture (AMBA) is an open-standard, on-chip interconnect specification for the connection and management of functional blocks in system-on-a-chip (SoC) designs.
- Specifies two actors
 - Master : control other peripherals
 - Slave: peripheral controlled by Master
- Defines specific interfaces for Master/Slave
- Defines how Master slave interacts





Master Interface (Bus Perspective)

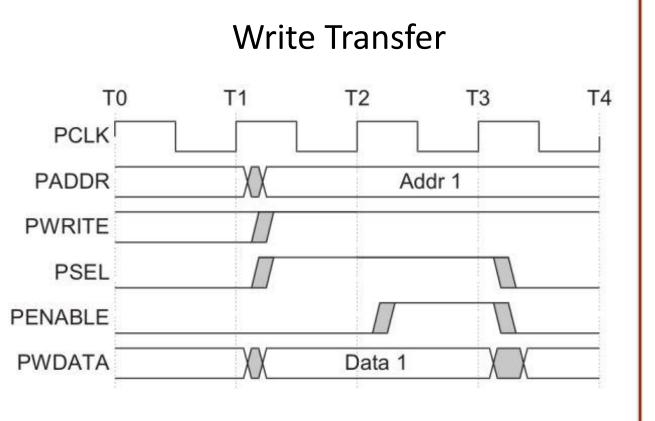
Port	Description	Causality	Data Width
apb_master_presetn	Reset the peripheral	Input	1
apb_master_paddr	Address for peripheral	Input	32
apb_master_pselX	Peripheral Selector (X = 18)	Input	1
apb_master_penable	Enable Peripheral	Input	1
apb_master_pwrite	Read/Write Operation	Input	1
apb_master_pwdata	Data for Peripheral	Input	32
apb_master_pready	Data Ready from Peripheral	Output	1
apb_master_prdata	Data From Peripheral	Output	32



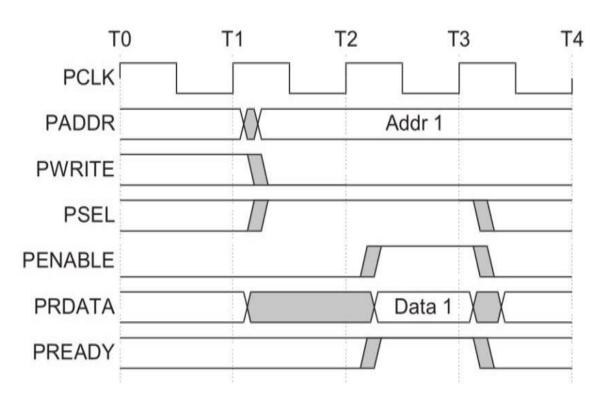
Slave Interface

(Bus Perspective)

Port	Description	Causality	Data Width
apb_X_pclk	Peripheral Clock	Output	1
apb_X_presetn	Reset	Output	1
apb_X_paddr	Data Address	Output	32
apb_X_psel	Peripheral Selected	Output	1
apb_X_penable	Enable Peripheral	Output	1
apb_X_pwrite	Read/Write Operation	Output	1
apb_X_pwdata	Data from Master	Output	32
apb_X_pready	Data Ready for Master	Input	1
apb_X_prdata	Data For Master	Input	32



Read Transfer





Integer Multiplier

Simple Integer Multiplier

APB Wrapper

Integer Multiplier

```
ENTITY multiplier IS
  PORT (
    clk : in std_logic;
    din_rdy: in std_logic;
    op1 : in std_logic_vector(15 downto 0);
    op2 : in std_logic_vector(15 downto 0);
    result : out std_logic_vector(31 downto 0);
    dout_rdy : out std_logic);
END multiplier;
```

```
ARCHITECTURE multiplier OF multiplier IS
BEGIN
    PROCESS (clk)
    BEGIN
        IF ( clk'event and clk = '1' ) THEN
            IF (din rdy = '1') THEN
                result <= (op1 * op2);
                dout rdy <= '1';</pre>
            ELSE
                result <= ( others => '0' );
                dout rdy <= '0';
            END IF;
        END IF;
    END PROCESS;
END multiplier;
                                                   13
```



Integer Multiplier

APB Wrapper

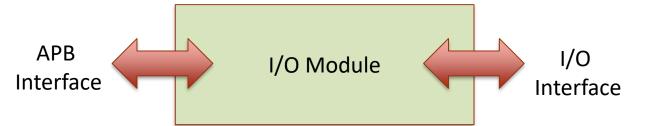
```
ENTITY multiplier apb wrapper IS
PORT (
 pclk : in std_logic;
 presetn : in std logic;
 paddr : in std logic vector(31 downto 0);
 psel : in std logic;
 penable : in std logic;
 pwrite : in std logic;
 pwdata : in std_logic_vector(31 downto 0);
 pready : out std logic;
 prdata : out std_logic_vector(31 downto 0));
END multiplier apb wrapper;
•••
```

```
ARCHITECTURE multiplier apb wrapper OF
multiplier apb wrapper IS
BEGIN
clk <= pclk;
op1 <= pwdata(15 downto 0);</pre>
op2 <= pwdata(31 downto 16);</pre>
din rdy <= penable;</pre>
pready <= dout rdy;</pre>
prdata <= result;</pre>
multiplier 0 : multiplier
PORT MAP(
        clk => clk,
        din rdy => din rdy,
        op1 => op1,
        op2 => op2,
        dout_rdy => dout_rdy,
        result => result
END multiplier_apb_wrapper;
```



I/O Module

- Allows external interaction with the platform
 - Expose output data via SW
 - Request external data for the SW



I/O Interface

Port	Description	Causality	Data
dout	Output Data from Platform	Output	32
dout_rdy	Output Data Ready from Platform	Output	1
din_req	Data Request from Platform	Output	1
din	Input Data for Platform	Input	32
din_rdy	Input Data Ready for Platform	Input	1



APB Slave Interface



COM6502 – Splatters

Software

- SW can be written in C Language
 - CC65 Cross Compiler for MOS 6502 CPU
 - https://www.cc65.org/
 - No support for float/double types
 - IEEE 754 didn't exists when MOS 6502 was developed!
 - Int datatype is only 1 byte
- ESD Team Developed a MMIO library in C
 - Allows to easily write simple drivers for Custom Slave Peripherals
- cc65 precompiled in com6502-splatter.tar.gz or source code from Github
 - https://github.com/cc65/cc65
 - Checkout this commit: 582aa41f2a702ff477a00a5d69a794390a13b544





COM6502 – Splatters

Software

- application/inc/mmio.h
 - Contains functions to interact with APB Master interface
 - set pwdata, set psel, set penable, get prdata, get pready ecc...
- application/inc/routines.h
 - Contains Multiplier and IO Module drivers

Multiplier Integer Simple Driver

```
uint32_t mul(uint16_t op1, uint16_t op2)
   // Prepare the variable
  uint32 t result = 0x0000;
   // Prepare the data to send.
  set pwdata 16(op1, op2);
  // Select the peripheral.
  set psel(PSEL1);
   // Enable the operation.
   set penable(1);
```

```
// stay here untile prdata rdy is ready.
while (get_pready() == 0) __asm__("nop");
// Get the result.
result = get prdata();
// Disable the operation.
set penable(0);
// Disable data stream from the bus.
set psel(NO PSEL);
// Return the result.
return result;
```



Software

application/src/main.c

```
int main()
       uint16 t op1 = 5;
       uint16_t op2 = 2;
       uint32_t result = 0;
       result = mul(op1, op2);
                                          // Call Multiplier Driver
       io_write(result);
                                          // Write the result on IO Module
              = (uint16_t) io_read();  // Read new data from IO Module
       op2
       result = mul(op1, op2);
                                          // Execute multiplication with new op2
       io_write(result);
                                          // Write result on IO Module
       return 0;
```



Hands on

- 1. Create a new Vivado Project importing all the components platform/
- 2. Export CC65_DIR global variable with the path to cc65/ directory
 - > export CC65_DIR=<your_path>/cc65/
- 3. Move into application/ directory
- 4. Launch compilation
 - > make
- 5. Import the cross compiled SW (application/bin/rom.mem) in Vivado
 - Add Sources
- 6. Run simulation!
 - run 1ms



Lecture Assignment

- Connect the Root module to COM6502-Splatters Platform
 - Wrap the design with APB Slave interface
 - Instantiate and bind the design to APB Bus
- Write a SW Driver for the Root
 - Add new function to routines.c file
 - Request at least one of four operators via I/O Module
- Detail the choices you made in the Report! Posth for wrapping and writing the driver