

# **Embedded Operating System RTOS dynamic priority servers**

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# Dynamic priority servers

Dynamic scheduling algorithms vs. Fixed priority scheduling

Higher schedulability bounds

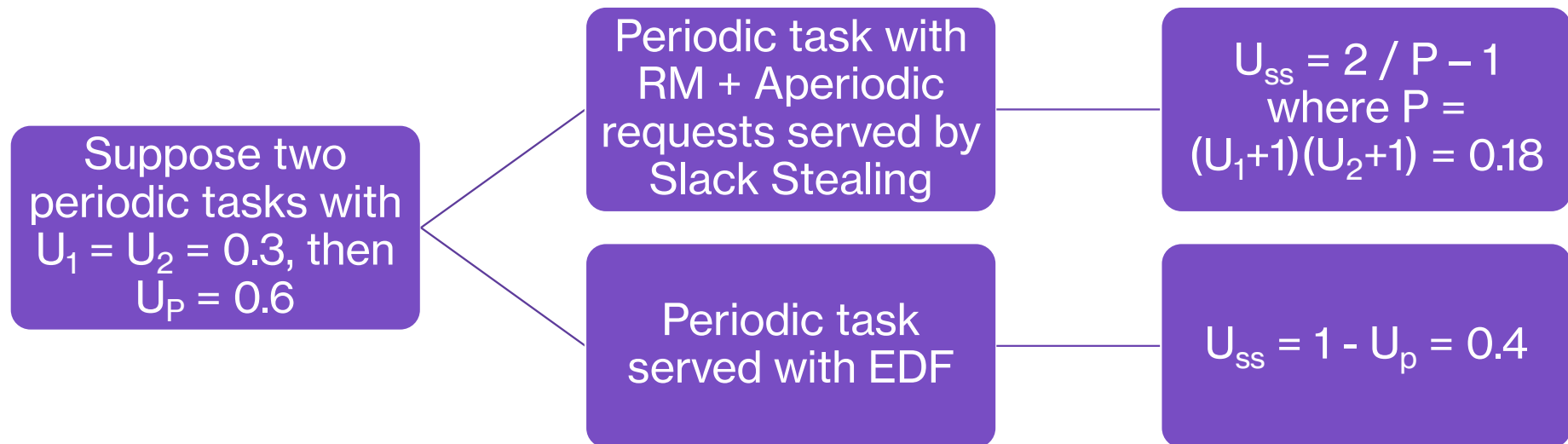


Processor better utilized

Higher capability of aperiodic server

Higher aperiodic responsiveness

# Example – Server capability



# Dynamic priority servers

## Goal

Decreasing average response time for aperiodic tasks

Preserving the schedulability of periodic tasks

## Solutions

Adaptation of static servers (EDF instead of RM for periodic tasks)

Dynamic priority exchange server

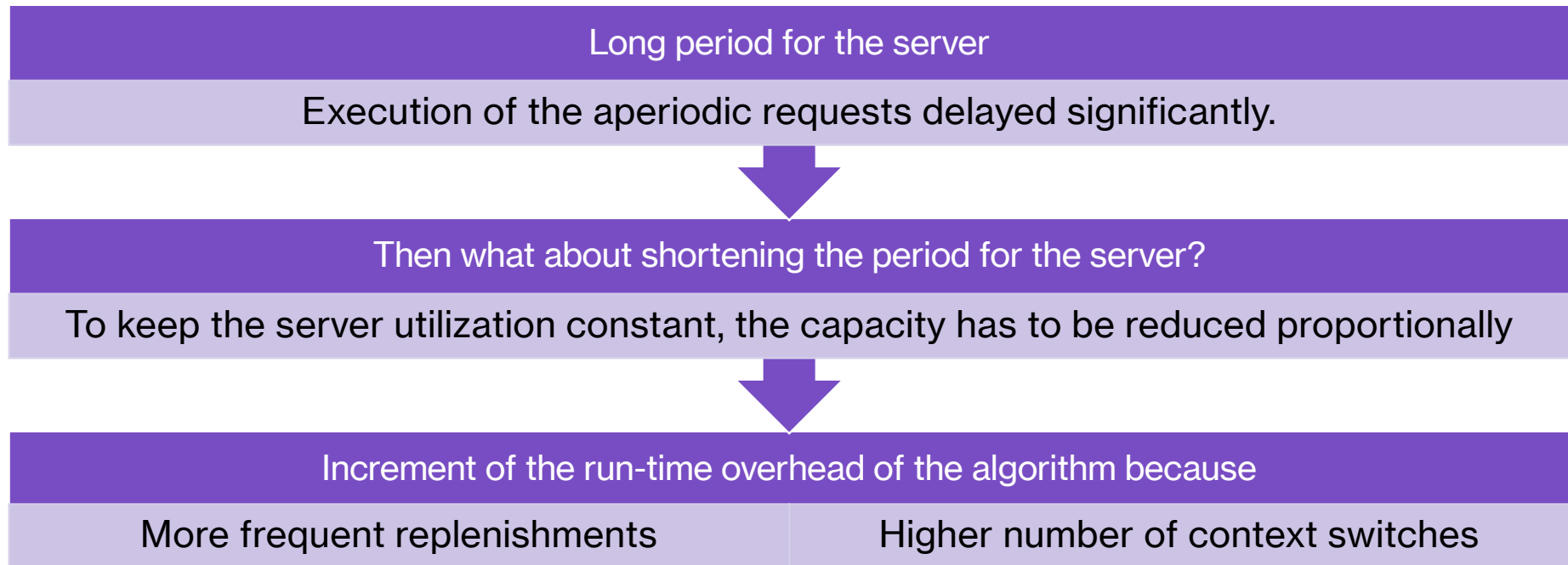
Improved priority exchange server

Dynamic sporadic server

Total Bandwidth Server

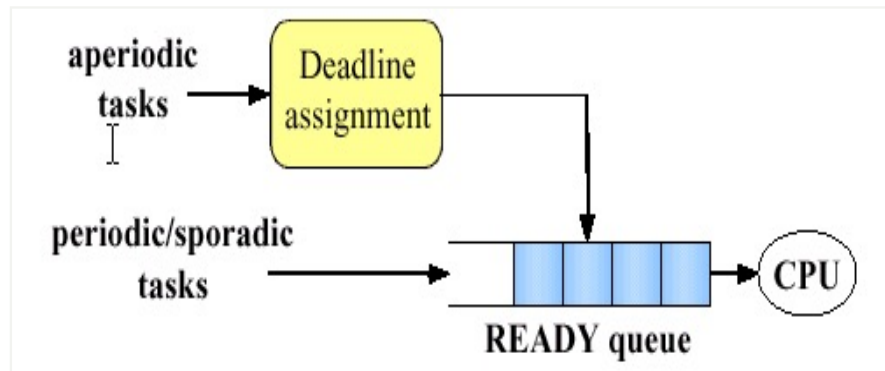
Whenever an aperiodic request enters the system the total bandwidth of the server is immediately assigned to it, whenever possible

# Adaptation of static servers with EDF



# An alternative – Total bandwidth server

- Dynamic priority server, used with EDF
  - Each aperiodic request is assigned a deadline so that the server demand does not exceed a given bandwidth  $U_s$
  - Aperiodic jobs are inserted in the ready queue and scheduled together with the hard tasks



Periodic tasks are  
guaranteed  
*if and only if*  
 $U_p + U_s \leq 1$

# Total bandwidth server - Deadlines

- Deadline assignment

- Job  $J_k$  with computation time  $C_k$  arriving at time  $r_k$  is assigned a deadline

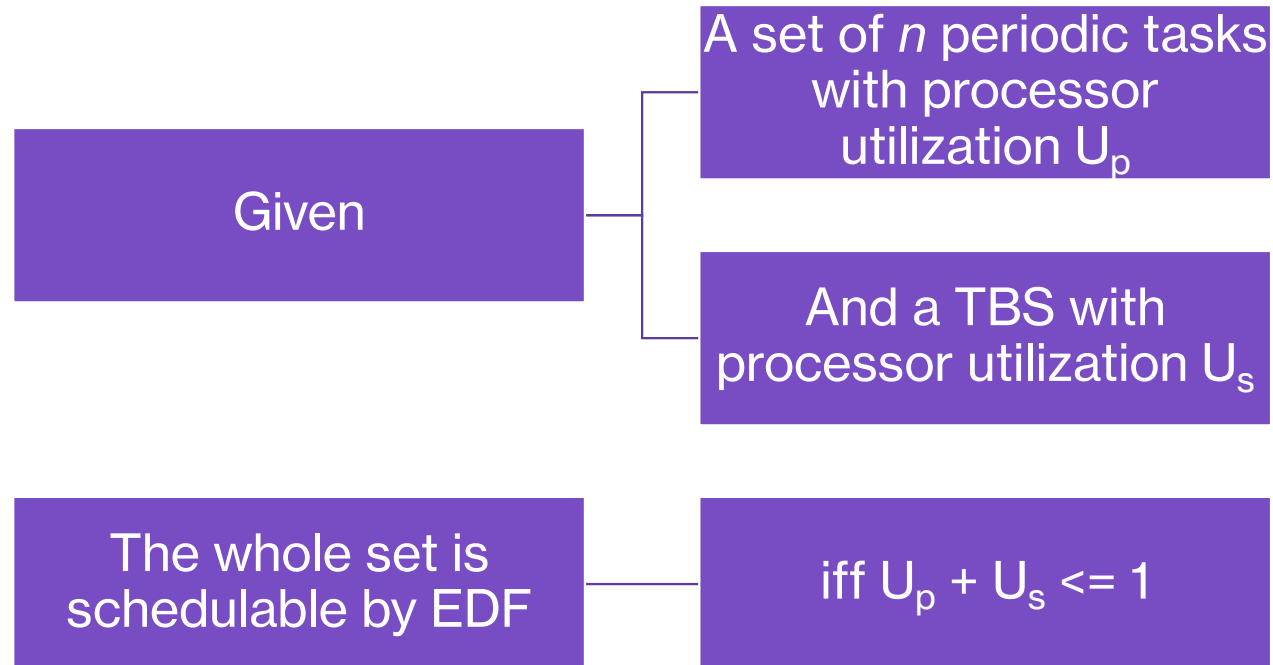
$$d_k = r_k + C_k / U_s$$

- To keep track of the bandwidth assigned to previous jobs,  $d_k$  must be computed as

$$d_k = \max (r_k , d_{k-1} ) + C_k / U_s$$

- Deadline used to assign priority

# Total bandwidth server - Schedulability





# Total bandwidth server – Example

| Task     | C | T | a |
|----------|---|---|---|
| $\tau_1$ | 1 | 4 | 0 |
| $\tau_2$ | 3 | 6 | 0 |
| ape 1    | 2 |   | 1 |
| ape 2    | 1 |   | 3 |