

TIME-DEPENDENT N-S

For $I = (0, T)$

$$\begin{cases} u_t - \nu \Delta u + (u \cdot \nabla) u + \nabla p = f & \text{in } \Omega \times I \\ \nabla \cdot u = 0 & \text{in } \Omega \times I \end{cases}$$

+ i.c. and b.c.

$$u(x, 0) = u_0(x), \text{ with } \nabla \cdot u_0 = 0$$

$$u|_{\partial \Omega \times I} = g(x, t) \quad \text{in } \underbrace{\partial \Omega \times I}_{\text{parabolic boundary}}$$

WEAK FORM

N-S are non-linear parabolic eqs.

$$V = [H_0^1(\Omega)]^d, \quad Q = L_0^2(\Omega)$$

$$\text{Find } u \in L^2(I; [H^1(\Omega)]^d) \cap C^0(\bar{I}; [L^2(\Omega)]^d), \quad p \in L^2(I; Q)$$

$$1) \underbrace{\int_{\Omega} u_t v}_{m(u_t, v)} + \underbrace{\int_{\Omega} \nabla u : \nabla v}_{a(u, v)} + \underbrace{\int_{\Omega} (u \cdot \nabla) u v}_{c(u, u, v)} - \underbrace{\int_{\Omega} p \operatorname{div} v}_{b(v, p)} = \underbrace{\int_{\Omega} f v}_{f(v)} \quad \forall v \in V$$

$$2) - \int_{\Omega} q \operatorname{div} u = 0 \quad \forall q \in Q$$

$$\text{with } u(x, 0) = u_0$$

(Quarteroni, page 463)

For u sol. of 1)-2) in the div-free space, if Ω is Lipschitz

$\Rightarrow \exists!$ p sol. of the above problem

SEMI-DISCRETE (IN SPACE) DISCRETIZATION

$g=0$ FOR SIMPLICITY

V_h, Q_h FEM SPACES

Find $(u_h, p_h) \in V_h \times Q_h$:

$$\begin{cases} m(\partial_t u_h, v_h) + a(u_h, v_h) + c(u_h, u_h, v_h) + b(p_h, v_h) = (f_h, v_h) \quad \forall v_h \in V_h \\ b(u_h, q_h) = 0 \quad \forall q_h \in Q_h \end{cases}$$

YIELDING TO A NON-LINEAR SYSTEM OF ODES:

$$\begin{cases} M \frac{du(t)}{dt} + A u(t) + \underbrace{C(u(t)) u(t)} + B^T p(t) = F(t) \\ B u(t) = 0 \end{cases}$$

TIME DISCRETIZATION

1) FINITE DIFFERENCES

FOR INSTANCE θ -METHOD, BDF SCHEMES

$$\theta C(u^{k+1}) u^{k+1} + (1-\theta) C(u^k) u^k$$

• $\theta=0 \Rightarrow$ EXPLICIT EULER :

$$\begin{cases} M u^{k+1} = H(u^k, p^k, f^k) \\ B u^{k+1} = 0 \end{cases}$$

\Rightarrow MODIFY TO USE p^{k+1} and if $\text{Ker}(B^T) = 0$:
(semi-implicit)

$$\begin{cases} \frac{1}{\Delta t} M u^{k+1} + B^T p^{k+1} = G \\ B u^{k+1} = 0 \end{cases} \Rightarrow \begin{cases} u^{k+1} = \Delta t M^{-1} (G - B^T p^{k+1}) \\ \underbrace{B M^{-1} B^T}_{\text{NON-SINGULAR}} p^{k+1} = B M^{-1} G \end{cases}$$

Stable if $\Delta t \leq C \min \left(\frac{h^2}{D}, \frac{h}{\max_x |u^k(x)|} \right)$

• $\theta > 0 \rightarrow$ OK (IMPLICIT), Newton-Krylov (GKRES, BicGstab)

• $\theta=1 \rightarrow$ FULLY IMPLICIT, stable if $\Delta t \leq C \frac{h}{\max_x |u^k(x)|}$

2) FRACTIONAL STEPS OR PROJECTION METHODS (Chorin-Temam)

$$\begin{cases} u' + Lu = 0 & \mathbb{R} \times I \\ u(x,0) = u_0 \end{cases}$$

EXPL. EULER

$$u^0 = u_0$$

$$\frac{u^{k+1} - u^k}{\Delta t} + Lu^k = 0$$

IDEA: $L = \sum_{i=1}^q L_i$ (SPLITTING)

$$\frac{u^{k+\frac{i}{q}} - u^{k+\frac{(i-1)}{q}}}{\Delta t} + L_i u^{k+\frac{(i-1)}{q}} = 0 \quad \forall i=1, \dots, q$$

(FRACTIONAL STEPPING)

\rightarrow IF IMPLICIT INVERT $I + \Delta t L_i$, HOPEFULLY EASIER THAN $I + \Delta t L$ (IMPL. EULER)

Ex. $q=2$, $L_1 = -\nu \Delta u + (u \cdot \nabla)u - f$, $L_2 = \nabla p$.

$$\frac{u^{k+1} - u^k}{\Delta t} - \nu \Delta u^k + (u^k \cdot \nabla) u^k + \nabla p^{k+1} = f^k$$

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$$\frac{u^{k+1} - u^*}{\Delta t} + \frac{u^* - u^k}{\Delta t}$$

EQUIVALENT TO SPLITTING:

$$1) \frac{u^* - u^k}{\Delta t} = \nu \Delta u^k + (u^k \cdot \nabla) u^k + f^k$$

$$2) \frac{u^{k+1} - u^*}{\Delta t} = \nabla p^{k+1}$$

WE CAN MODIFY 2) BY "PROJECTION"

$$\nabla \cdot \left( \frac{u^{k+1} - u^*}{\Delta t} \right) = \nabla \cdot \nabla p^{k+1}$$

$$\nabla \cdot u^{k+1} = 0$$

$$\rightarrow -\Delta p^{k+1} = \frac{1}{\Delta t} \nabla \cdot u^* \quad \text{POISSON PROBLEM FOR THE PRESSURE}$$

Step-35 in deal.II:

- BDF2 (based on extrapolation)

- splitting  $(u \cdot \nabla)u$  in its skew-symmetric form

$$(u \cdot \nabla)u \rightarrow (u \cdot \nabla)u + \frac{1}{2}(\nabla \cdot u)u$$

$$\sim (u^* \cdot \nabla)u^{k+1} + \frac{1}{2}(\nabla \cdot u^*)u^{k+1} \quad (\text{semi-implicit})$$

$\rightarrow$  STABLE