

src/Node2_service.cpp

```
graph TD; A[src/Node2_service.cpp] --> B[ros/ros.h]; A --> C[assignment2_rt/ReturnLastTarget.h];
```

The diagram illustrates the dependencies of the source file `src/Node2_service.cpp`. It is represented by a grey rectangular box at the top. Two blue arrows originate from the bottom of this box. The left arrow points to a white rectangular box containing the text `ros/ros.h`. The right arrow points to a white rectangular box containing the text `assignment2_rt/ReturnLastTarget.h`, which is split across two lines.

ros/ros.h

assignment2_rt/ReturnLast
Target.h