

## Disclaimer

This summary is part of the lecture “Electrodynamics” by Prof. Dr. L. Novotny (FS19). It is based on the lecture.

Please report errors to [huettern@student.ethz.ch](mailto:huettern@student.ethz.ch) such that others can benefit as well.

The upstream repository can be found at <https://github.com/noah95/formulasheets>

# ETH Electrodynamics

Noah Huetter

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## 1 Conventions

$V$	Volume
$dV$	infinitesimal volume elements
$A$	surface
$da$	infinitesimal surface elements
$ds$	infinitesimal line element
$\partial V$	closed surface of the volume $V$
$\partial A$	circumference of area $A$
$\mathbf{n}$	unit vector normal to surface / circumference
$\rho$	Charge density
$\mathbf{j}$	Current density
$\mathbf{E}$	Electric field
$\mathbf{H}$	Magnetic field
$\mathbf{B}$	Magnetic flux density
$\mathbf{D}$	Displacement
$\mathbf{M}$	Magnetization
$\varphi(r)$	Electrostatic potential at point $r$

## 2 Mathematics

### 2.1 Linear Algebra

$$\nabla = \begin{bmatrix} \frac{\partial}{\partial x} \\ \frac{\partial}{\partial y} \\ \frac{\partial}{\partial z} \end{bmatrix}$$

### Rotation

The cross product of the nabla operator and the vector field  $\vec{F}$

$$\nabla \times \vec{F} = \det \begin{bmatrix} \vec{e}_x & \vec{e}_y & \vec{e}_z \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ F_x & F_y & F_z \end{bmatrix} = \begin{bmatrix} \frac{\partial}{\partial y} F_z - \frac{\partial}{\partial z} F_y \\ -\frac{\partial}{\partial x} F_z + \frac{\partial}{\partial z} F_x \\ \frac{\partial}{\partial x} F_y - \frac{\partial}{\partial y} F_x \end{bmatrix}$$

### Divergence

$$\nabla \cdot \vec{F} = \frac{\partial}{\partial x} F_x + \frac{\partial}{\partial y} F_y + \frac{\partial}{\partial z} F_z = \text{div}(\vec{F})$$

### Combination

Always solve right to left.

$$\nabla \times \nabla \varphi(\vec{r}) = \nabla \times (\nabla \varphi(\vec{r})) = \dots = 0$$

$$\nabla \cdot \nabla \times \vec{F} = \nabla \cdot (\nabla \times \vec{F}) = \dots = 0$$

Rotation of rotation:

$$\nabla \times \nabla \times \vec{F} = \nabla(\nabla \cdot \vec{F}) - \nabla^2 \vec{F}$$

### 2.2 Integrals

#### Line integral inside Vector Field

1. Parametrize curve with  $t$ . Split integral if necessary for different parametrizations

$$x : f(t) \quad y : f(t) \quad z : f(t)$$

2. Calculate derivative of normal vector along curve

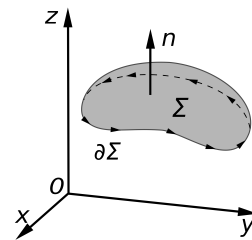
$$\frac{d\vec{s}}{dt} = x'(t)\vec{e}_x + y'(t)\vec{e}_y + z'(t)\vec{e}_z$$

$$d\vec{s} = \begin{bmatrix} x'(t) \\ y'(t) \\ z'(t) \end{bmatrix} dt$$

3. Solve integral

$$\int_{\partial A} F(\vec{r}) d\vec{s} = \int_a^b F(x(t), y(t), z(t)) \cdot \begin{bmatrix} x'(t) \\ y'(t) \\ z'(t) \end{bmatrix} dt$$

### 2.3 Stokes' Theorem

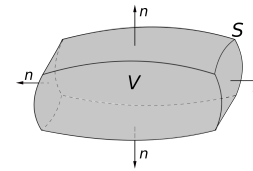


$$\int_{\partial A} F(\vec{r}) d\vec{s} = \int_A [\nabla \times F(\vec{r})] \cdot \vec{n} da$$

The sum of flux along the contour  $\partial A$  in contour direction is the same as the sum of curl  $\nabla \times \vec{F}$  in normal direction  $\vec{n}$  on the area  $A$ .

### 2.4 Gauss Theorem

Also known as divergence theorem.



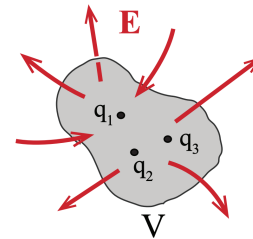
$$\int_{\partial V} \vec{F}(\vec{r}) \cdot \vec{n} da = \int_V \nabla \cdot \vec{F}(\vec{r}) dV$$

Sum of flux across surface  $\partial A$  in normal direction  $\vec{n}$  is the same as the sum of divergence inside the region  $V$ .

### 3 Pre-Maxwellian Electrodynamics

#### Gauss' Law

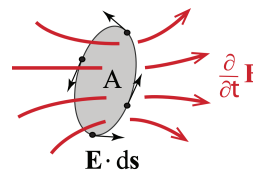
The net flux through a surface is equal to  $1/\epsilon_0$  times the net electric charge within that surface.



$$\int_{\partial V} \mathbf{E}(\mathbf{r}, t) \cdot \mathbf{n} da = \frac{1}{\epsilon_0} \int_V \rho(\mathbf{r}, t) dV$$

#### Faraday's Law

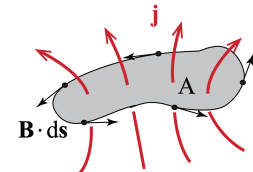
The electromotive force around a path is equal to the negative change in time of the magnetic flux enclosed by the path.



$$\int_{\partial A} \mathbf{E}(\mathbf{r}, t) \cdot d\mathbf{s} = -\frac{\partial}{\partial t} \int_A \mathbf{B}(\mathbf{r}, t) \cdot \mathbf{n} da$$

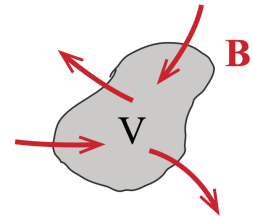
#### Ampere's Law

The magnetic field created by an electric current is proportional to the size of that electric current.



$$\int_{\partial A} \mathbf{B}(\mathbf{r}, t) \cdot d\mathbf{s} = \mu_0 \int_A \mathbf{j}(\mathbf{r}, t) \cdot \mathbf{n} da$$

#### Non-existence of magnetic charges



$$\int_{\partial V} \mathbf{B}(\mathbf{r}, t) \cdot \mathbf{n} da = 0$$

#### Kirchhoff

Reducing Ampere's law to any closed surface states that the flux of current through any closed surface is zero: What flows in has to flow out.

$$\int_{\partial V} \mathbf{j}(\mathbf{r}, t) \cdot \mathbf{n} da = 0$$

From Faraday's law if no time-varying magnetic fields are present follows the second Kirchhoff law (Knotenregel):

$$\int_{\partial A} \mathbf{E}(\mathbf{r}, t) \cdot d\mathbf{s} = 0$$

The two Kirchhoff laws form the basis for circuit theory and electronic design.

### 4 Electrostatics

We modify Faraday's law by setting the change of magnetic flux to zero.

$$\int_{\partial A} \mathbf{E}(\mathbf{r}, t) \cdot d\mathbf{s} = 0$$

By applying the theorems of Gauss and Stokes we get the following identities:

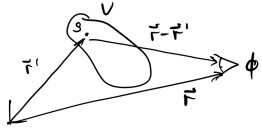
$$\nabla \cdot \mathbf{E}(\vec{r}) = \frac{1}{\epsilon_0 \rho(\vec{r})} \quad \nabla \times \mathbf{E}(\vec{r}) = 0$$

$$\mathbf{E} = -\nabla \varphi \quad \nabla^2 \varphi(\vec{r}) = -\frac{1}{\epsilon_0} \rho(\vec{r})$$

Combining them we can write the Poisson equation:

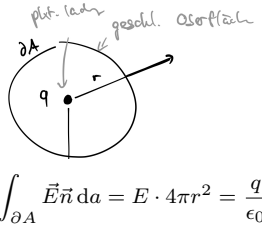
$$\nabla^2 \Phi(\vec{r}) = -\frac{1}{\epsilon_0} \rho(\vec{r}) \quad \varphi(\vec{r}) = \frac{1}{4\pi\epsilon_0} \int \frac{\rho(\vec{r}')}{|\vec{r} - \vec{r}'|} dV'$$

Where  $\varphi(\vec{r})$  is the electric potential at point  $\vec{r}$ .



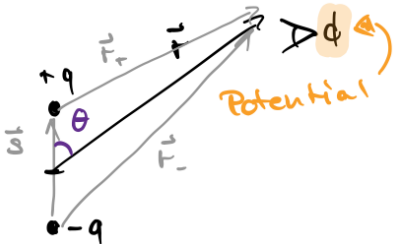
#### 4.1 Point Charge

E-field of a point charge:



$$\vec{E} = \frac{1}{4\pi\epsilon_0} \frac{q}{r^2} \vec{n}_r \quad \vec{E} = -\nabla\varphi \quad \varphi = \frac{1}{4\pi\epsilon_0} \frac{q}{r}$$

#### 4.2 Dipole: 2-Point Charge



The electrostatic potential at a given point  $\vec{r}$  for the two point charges is:

$$\varphi(\vec{r}) = \frac{q}{4\pi\epsilon_0} \left( \frac{1}{r_+} - \frac{1}{r_-} \right) = \frac{q}{4\pi\epsilon_0} \frac{s}{r^2} \cos\theta$$

$$\varphi(\vec{r}) = \frac{q}{4\pi\epsilon_0} \frac{\vec{s} \cdot \vec{r}}{r^3}$$

Where  $r = |\vec{r}|$ .

**Definition: Dipole**

$$\vec{p} = \lim_{\substack{\vec{s} \rightarrow 0 \\ \vec{q} \rightarrow \infty}} (q\vec{s}) \Rightarrow \varphi(\vec{r}) = \frac{1}{4\pi\epsilon_0} \frac{\vec{p} \cdot \vec{r}}{r^3}$$

## 5 Maxwell's Equations

The pre-Maxwellian equations summarize the electromagnetism before Maxwell. In 1873 however, Maxwell introduced a critical modification.

### 5.1 Displacement Current

The law that the net flux through a closed surface is zero is flawed. For example: Identical charges released will speed out because of Coulomb repulsion and there will be a net outward current. Kirchhoff's first law has to be corrected as follows:

$$\int_{\partial V} \mathbf{j}(\mathbf{r}, t) \cdot \mathbf{n} dA = -\frac{\partial}{\partial t} \int_V \rho(\mathbf{r}, t) dV$$

**continuity equation:** The outward current is balanced by the decrease of charge inside the surface.

**Modify Ampere's law**

To end up with the correct conservation law:

$$\int_{\partial A} \mathbf{B}(\mathbf{r}, t) \cdot d\mathbf{s} = \mu_0 \int_A \mathbf{j}(\mathbf{r}, t) \cdot \mathbf{n} dA + \frac{1}{c^2} \frac{\partial}{\partial t} \int_A \mathbf{E}(\mathbf{r}, t) \cdot \mathbf{n} dA$$

### 5.2 Interaction of Fields with Matter

$\mathbf{E}$  and  $\mathbf{B}$  can interact with materials and generate induced charges and currents. These are then called secondary sources.

**Induced by electrical field  $\mathbf{E}$**

$\rho_{\text{pol}}$  is the charge density induced in matter through the interaction with the electric field.  $\rho_{\text{pol}}$  is the polarization charge density. The net charge density inside the material remains zero.

$$\rho = \rho_0 + \rho_{\text{pol}}$$

To account for polarization charges we introduce the polarization  $\mathbf{P}$ :

$$\int_{\partial V} \mathbf{P}(\mathbf{r}, t) \cdot \mathbf{n} dA = \int_V \rho_{\text{pol}}(\mathbf{r}, t) dV$$

After inserting this into Gauss' law, we define the *electric displacement  $\mathbf{D}$*  as:

$$\mathbf{D} = \epsilon_0 \mathbf{E} + \mathbf{P}$$

Further we denote the change in polarization as the polarization current density:

$$\mathbf{j}_{\text{pol}} = \frac{\partial}{\partial t} \mathbf{P}(\mathbf{r}, t)$$

### Induced by magnetic field

According to Ampere's law, the interaction of matter with magnetic fields can induce magnetization currents. The magnetization current density is called  $\mathbf{j}_{\text{mag}}$ . The total current density can be written as

$$\mathbf{j} = \mathbf{j}_0 + \mathbf{j}_{\text{pol}} + \mathbf{j}_{\text{mag}}$$

To relate the induced magnetization current to the  $\mathbf{B}$ -field we define an analogy:

$$\int_{\partial A} \mathbf{M} \cdot d\mathbf{s} = \int_A \mathbf{j}_{\text{mag}} \cdot \mathbf{n} dA$$

We can write the magnetic field  $\mathbf{H}$ :

$$\mathbf{H} = \frac{1}{\mu_0} \mathbf{B} - \mathbf{M}$$

### 5.3 Maxwell's Equations in Integral Form

$$\begin{aligned} \int_{\partial V} \mathbf{D}(\mathbf{r}, t) \cdot \mathbf{n} dA &= \int_V \rho_0(\mathbf{r}, t) dV \\ \int_{\partial A} \mathbf{E}(\mathbf{r}, t) \cdot d\mathbf{s} &= -\frac{\partial}{\partial t} \int_A \mathbf{B}(\mathbf{r}, t) \cdot \mathbf{n} dA \\ \int_{\partial A} \mathbf{H}(\mathbf{r}, t) \cdot d\mathbf{s} &= \int_A \left[ \mathbf{j}_0(\mathbf{r}, t) + \frac{\partial}{\partial t} \mathbf{D}(\mathbf{r}, t) \right] \cdot \mathbf{n} dA \\ \int_{\partial V} \mathbf{B}(\mathbf{r}, t) \cdot \mathbf{n} dA &= 0 \end{aligned}$$

The displacement  $\mathbf{D}$  and the magnetic field  $\mathbf{H}$  account for secondary sources through

$$\mathbf{D}(\mathbf{r}, t) = \epsilon_0 \mathbf{E}(\mathbf{r}, t) + \mathbf{P}(\mathbf{r}, t)$$

$$\mathbf{B}(\mathbf{r}, t) = \mu_0 [\mathbf{H}(\mathbf{r}, t) + \mathbf{M}(\mathbf{r}, t)]$$

### 5.4 Maxwell's Equations in Differential Form

$$\begin{aligned} \nabla \cdot \mathbf{D}(\mathbf{r}, t) &= \rho_0(\mathbf{r}, t) \\ \nabla \times \mathbf{E}(\mathbf{r}, t) &= -\frac{\partial}{\partial t} \mathbf{B}(\mathbf{r}, t) \\ \nabla \times \mathbf{H}(\mathbf{r}, t) &= \frac{\partial}{\partial t} \mathbf{D}(\mathbf{r}, t) + \mathbf{j}_0(\mathbf{r}, t) \\ \nabla \cdot \mathbf{B}(\mathbf{r}, t) &= 0 \end{aligned}$$

### Continuity equation

$$\nabla \cdot \mathbf{j}_0(\mathbf{r}, t) + \frac{\partial}{\partial t} \rho_0(\mathbf{r}, t) = 0$$

## 6 Wave Equation

Arranging the first and second Maxwell equation yields the electro magnetic wave equation:

$$\begin{aligned} \nabla \times \nabla \times \mathbf{E} + \frac{1}{c^2} \frac{\partial^2 \mathbf{E}}{\partial t^2} &= -\mu_0 \frac{\partial}{\partial t} \left( \mathbf{j}_0 + \frac{\partial \mathbf{P}}{\partial t} + \nabla \times \mathbf{M} \right) \\ \nabla \times \nabla \times \mathbf{H} + \frac{1}{c^2} \frac{\partial^2 \mathbf{H}}{\partial t^2} &= \nabla \times \mathbf{j}_0 + \nabla \times \frac{\partial \mathbf{P}}{\partial t} - \frac{1}{c^2} \frac{\partial^2 \mathbf{M}}{\partial t^2} \end{aligned}$$

### 6.1 Homogeneous Solution in Free Space

In absence of matter and sources. In free space  $\nabla \cdot \mathbf{E} = 0$  the equation becomes:

$$\nabla^2 \mathbf{E} - \frac{1}{c^2} \frac{\partial^2}{\partial t^2} \mathbf{E} = 0$$

For  $\mathbf{H}$ -field it is equivalent. The 1D solution is solved by d'Alembert  $E(x, t) = E(x - ct)$ , which shows that the field propagates through space at constant velocity  $c$ .

For the general solution using separation of variables, the ansatz becomes:

$$\mathbf{E}(\mathbf{r}, t) = \text{Re} \{ \mathbf{E}(\mathbf{r}) e^{-i\omega t} \}$$

Where  $\mathbf{E}(\mathbf{r})$  is complex. Inserting into the wave equation result in the Helmholtz equation ( $\omega \in \mathbb{C}$ ):

$$\left[ \nabla^2 + \frac{\omega^2}{c^2} \right] \mathbf{E}(\mathbf{r}) = 0$$

### Plane waves

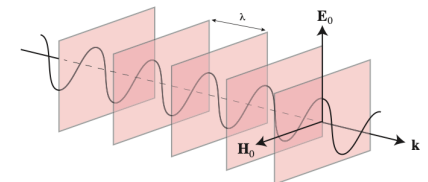
The solution is:

$$\vec{E}_0 e^{\pm i \vec{k} \cdot \vec{r}} \quad \vec{k} \perp \vec{E}_0$$

With the dispersion relation:

$$k = k_x^2 + k_y^2 + k_z^2 = \frac{\omega^2}{c^2}$$

Solutions with the + sign are outgoing waves propagating in direction of  $\vec{k}$ . The corresponding magnetic field is found by using Maxwell's equation  $\nabla \times \vec{E} = i\omega\mu_0 \vec{H}$  we find  $\vec{H}_0 = (\omega\mu_0)^{-1} (\vec{k} \times \vec{E}_0)$ , that is, the magnetic field vector is perpendicular to the electric field vector and the wavevector.



### Superposition of two waves

Superposition of two plane waves of the form:

$$\vec{E}(\vec{r}, t) = \text{Re} \left\{ (\vec{E}_1 + \vec{E}_2) e^{i(k_z z - \omega t)} \right\}$$

1. Linear polarized

$$\vec{E}_1, \vec{E}_2 \in \mathbb{R}$$

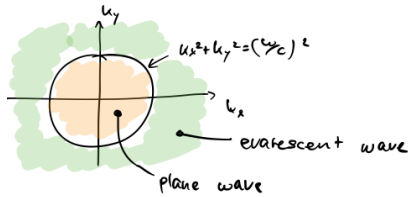
2. Circular polarized

$$\vec{E}_2 = i\vec{E}_1$$

3. Elliptic polarized

$$\vec{E}_1, \vec{E}_2 \in \mathbb{C}$$

### 6.2 Evanescent Waves



Exponentially decaying wave. Rewriting dispersion relation:

$$k_z \sqrt{(\omega^2/c^2) - (k_x^2 + k_y^2)}$$

If  $(k_x^2 + k_y^2)$  becomes larger than  $k^2 = \omega^2/c^2$  then  $k_z$  becomes imaginary. The solution then turns into

$$\vec{E}(\vec{r}, t) = \text{Re} \left\{ \vec{E}_0 e^{\pm i(k_x x + k_y y) - i\omega t} \right\} e^{\mp |k_z| z}$$

This wave exponentially decays in the direction of  $z$ .

## 7 Mathematic Appendix

### 7.1 Trigonometry

- Trigonometric Powers

$$\sin^2(x) = \frac{1}{2}[1 - \cos(x)]$$

$$\cos^2(x) = \frac{1}{2}[1 + \cos(2x)]$$

$$\sin^3(x) = \frac{1}{4}[3 \sin(x) - \sin(3x)]$$

$$\cos^3(x) = \frac{1}{4}[3 \cos(x) + \cos(3x)]$$

- Trigonometric Products

$$\sin(x) \sin(y) = \frac{1}{2}[\cos(x - y) - \cos(x + y)]$$

$$\cos(x) \cos(y) = \frac{1}{2}[\cos(x - y) + \cos(x + y)]$$

$$\sin(x) \cos(y) = \frac{1}{2}[\sin(x - y) + \sin(x + y)]$$

$$\sin(x) \cos(y) = \frac{1}{2} \sin(2x)$$

- Trigonometric Sumstest

$$\sin(x) + \sin(y) = 2 \sin\left(\frac{x+y}{2} \cos\left(\frac{x-y}{2}\right)\right)$$

$$\sin(x) - \sin(y) = 2 \cos\left(\frac{x+y}{2} \sin\left(\frac{x-y}{2}\right)\right)$$

$$\cos(x) + \cos(y) = 2 \cos\left(\frac{x+y}{2} \cos\left(\frac{x-y}{2}\right)\right)$$

$$\cos(x) - \cos(y) = 2 \sin\left(\frac{x+y}{2} \sin\left(\frac{x-y}{2}\right)\right)$$

- Double angle

$$\sin(2x) = 2 \sin(x) \cos(x)$$

$$\cos(2x) = \cos^2(x) - \sin^2(x) = 1 - 2 \sin^2(x) = 2 \cos^2(x) - 1$$

- Addition theorems

$$\sin(x \pm y) = \sin(x) \cos(y) \pm \cos(x) \sin(y)$$

$$\cos(x \pm y) = \cos(x) \cos(y) \mp \sin(x) \sin(y)$$

$$\sin(x + y) \sin(x - y) = \cos^2(y) - \cos^2(x) = \sin^2(x) - \sin^2(y)$$

$$\cos(x + y) \cos(x - y) = \cos^2(y) - \sin^2(x) = \cos^2(x) - \sin^2(y)$$

### 7.2 Poisson Equation

$$\nabla^2 f(\vec{r}) = -g(\vec{r})$$

Solution:

$$f(\vec{r}) = \int_V \frac{g(\vec{r}')}{4\pi|\vec{r} - \vec{r}'|} dV'$$

7.3 Vector operations

Operation		Cartesian Coordinates $(x, y, z)$	Cylindrical Coordinates $(r, \varphi, z)$	Spherical Coordinates $(r, \theta, \varphi)$
Vector field	$A$	$A_x \vec{n}_x + A_y \vec{n}_y + A_z \vec{n}_z$	$A_r \vec{n}_r + A_\varphi \vec{n}_\varphi + A_z \vec{n}_z$	$A_r \vec{n}_r + A_\theta \vec{n}_\theta + A_\varphi \sin \theta \vec{n}_\varphi$
Gradient	$\nabla f$	$\frac{\partial f}{\partial x} \vec{n}_x + \frac{\partial f}{\partial y} \vec{n}_y + \frac{\partial f}{\partial z} \vec{n}_z$	$\frac{\partial f}{\partial r} \vec{n}_r + \frac{1}{r} \frac{\partial f}{\partial \varphi} \vec{n}_\varphi + \frac{\partial f}{\partial z} \vec{n}_z$	$\frac{\partial f}{\partial r} \vec{n}_r + \frac{1}{r} \frac{\partial f}{\partial \theta} \vec{n}_\theta + \frac{1}{r \sin \theta} \frac{\partial f}{\partial \varphi} \vec{n}_\varphi$
Divergence	$\nabla \cdot A$	$\frac{\partial A_x}{\partial x} + \frac{\partial A_y}{\partial y} + \frac{\partial A_z}{\partial z}$	$\frac{1}{r} \frac{\partial}{\partial r} (r A_r) + \frac{1}{r} \frac{\partial}{\partial \varphi} A_\varphi + \frac{\partial}{\partial z} A_z$	$\frac{1}{r^2} \frac{\partial}{\partial r} (r^2 A_r) + \frac{1}{\sin \theta} \frac{\partial}{\partial \theta} (A_\theta \sin \theta) + \frac{1}{r \sin \theta} \frac{\partial}{\partial \varphi} A_\varphi$
Curl	$\nabla \times A$	$\left( \frac{\partial A_z}{\partial y} - \frac{\partial A_y}{\partial z} \right) \vec{n}_x + \left( \frac{\partial A_x}{\partial z} - \frac{\partial A_z}{\partial x} \right) \vec{n}_y + \left( \frac{\partial A_y}{\partial x} - \frac{\partial A_x}{\partial y} \right) \vec{n}_z$	$\left( \frac{1}{r} \frac{\partial A_z}{\partial \varphi} - \frac{\partial A_\varphi}{\partial z} \right) \vec{n}_r + \left( \frac{\partial A_r}{\partial z} - \frac{\partial A_z}{\partial r} \right) \vec{n}_\varphi + \left( \frac{\partial r A_\varphi}{\partial r} - \frac{\partial A_r}{\partial \varphi} \right) \vec{n}_z$	$\frac{1}{r \sin \theta} \left( \frac{\partial}{\partial \theta} (A_\varphi \sin \theta) - \frac{\partial A_\theta}{\partial \varphi} \right) \vec{n}_r + \frac{1}{r} \left( \frac{1}{\sin \theta} \frac{\partial A_r}{\partial \varphi} - \frac{\partial}{\partial r} (r A_\varphi) \right) \vec{n}_\theta + \frac{1}{r} \left( \frac{\partial}{\partial r} (r A_\theta) - \frac{\partial A_r}{\partial \theta} \right) \vec{n}_\varphi$