Explains the mathematical concept of space, norm, and basis. Introduces Fourier transform and convolution.

WS 16/17
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Mathematical methods

Concepts of space and Fourier transform are connected and very important.

- Investigation of vibrating string, planet orbits
- Fourier transformation (1759-1805, Lagrange, Gauss, Fourier, Euler)
- Hilbert space (1900, Hilbert, Lebesgue, Quantum mechanics)

Euclidean space \mathbb{R}^N

x and **y** are vectors (x_1, x_2, \ldots, x_N) and (y_1, y_2, \ldots, y_N) .

Scalar product:

$$\langle \mathbf{x}, \mathbf{y} \rangle := \sum_{n=1}^{N} x_n y_n$$

Norm:

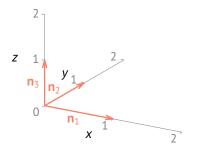
$$\|\mathbf{x}\| := \langle \mathbf{x}, \mathbf{x} \rangle^{\frac{1}{2}} = \left(\sum_{n=1}^{N} x_n^2\right)^{\frac{1}{2}}$$

Basis:

$$\boldsymbol{n}_1 = (1,0,\dots,0), \boldsymbol{n}_2 = (0,1,\dots,0),\dots, \boldsymbol{n}_n = (0,0,\dots,1)$$

Euclidean space \mathbb{R}^N

Example: \mathbb{R}^3

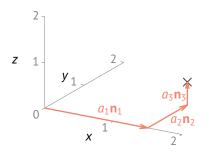


A space is spanned by its basis, here $\mathbf{n}_1, \mathbf{n}_2, \mathbf{n}_3$.

$$\left\langle \mathbf{n}_{i}, \mathbf{n}_{j} \right\rangle = \delta_{ij}$$
 $\|\mathbf{n}_{i}\| = \|\mathbf{n}_{j}\| = 1$

Euclidean space \mathbb{R}^N

Example: \mathbb{R}^3



Any point can be constructed by a linear combination of the basis.

$$\mathbf{x} = a_1 \mathbf{n}_1 + a_2 \mathbf{n}_2 + a_3 \mathbf{n}_3 = \sum_{n=1}^3 a_n \mathbf{n}_n$$

$$a_n = \langle \mathbf{x}, \mathbf{n}_n \rangle$$

Complex space $\mathbb C$

$$z_1 = x_1 + iy_1$$
 and $z_2 = x_2 + iy_2$ are complex numbers.

Scalar product:

$$\langle z_1, z_2 \rangle := z_1 z_2^* = (x_1 + iy_1)(x_2 - iy_2)$$

Norm:

$$||z_1|| := \langle z_1, z_1 \rangle^{\frac{1}{2}} = (z_1 z_1^*)^{\frac{1}{2}}$$

Basis:

1, i

$\overline{\text{Hilbert space } L^2}$

f(x) and g(x) are square-integrable functions.

Scalar product:

$$\langle f,g\rangle := \int_a^b f(x) g(x)^* dx$$

Norm:

$$||f||^2 := \langle f, f \rangle = \int_a^b |f(x)|^2 dx$$

Basis:

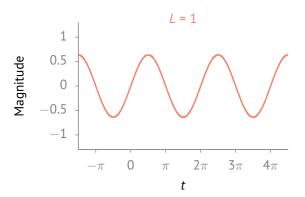
$$e^{i\omega x} = \cos(\omega x) + i\sin(\omega x)$$
 trigonometric functions

Every periodic signal can be approximated by a finite summation of basis functions.

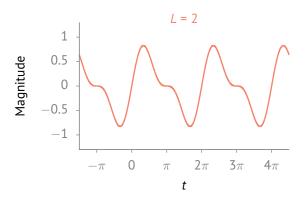
$$f(x) = \sum_{n=1}^{N} a_n e^{in\omega x}$$

$$a_n(\omega) = \left\langle f(x), e^{-in\omega x} \right\rangle = \frac{1}{T} \int_{-\frac{T}{2}}^{\frac{T}{2}} f(x) e^{-in\omega x} dx$$

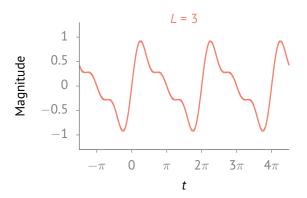
$$sawtooth(t) = \sum_{n=1}^{N} \frac{2 \sin(nt)}{n\pi}$$



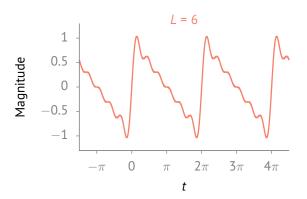
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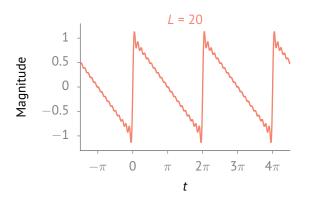
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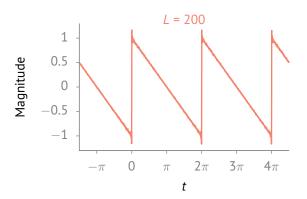
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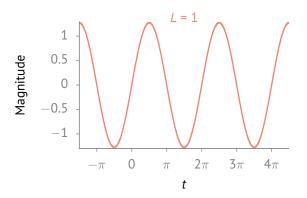
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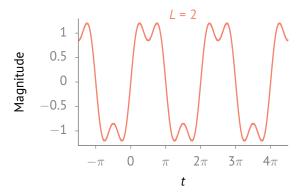
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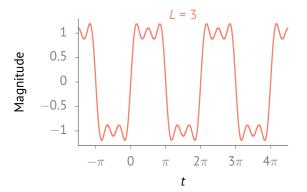
square(t) =
$$\sum_{n=1}^{N} \frac{4\sin((2n-1)t)}{(2n-1)\pi}$$



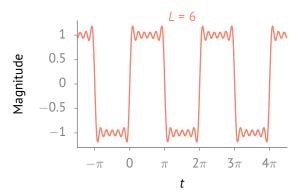
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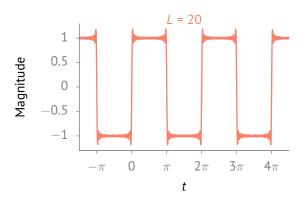
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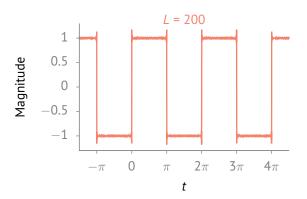
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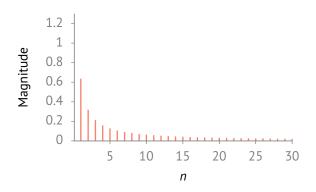
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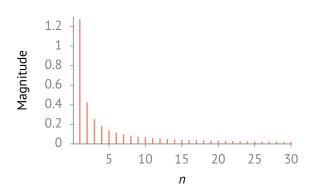
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$$a_n = \frac{1}{T_0} \int_{-\frac{T_0}{2}}^{\frac{T_0}{2}} \operatorname{sawtooth}(t) e^{-int} dt$$



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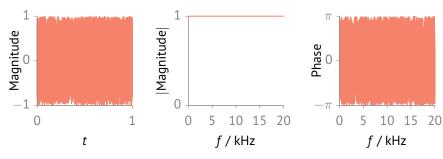
Temporal Fourier transformation:

$$S(\omega) = \mathcal{F}\left\{s(t)\right\} := \int_{-\infty}^{\infty} s(t) e^{-i\omega t} dt$$

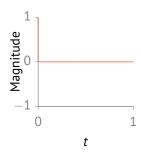
Inverse temporal Fourier transformation:

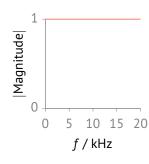
$$s(t) = \mathcal{F}^{-1} \{S(\omega)\} := \frac{1}{2\pi} \int_{-\infty}^{\infty} S(\omega) e^{i\omega t} d\omega$$

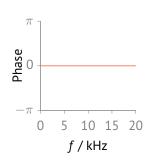
White noise



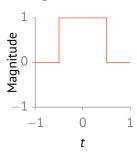
Dirac function

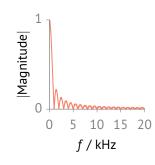


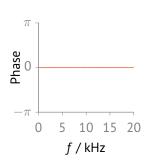




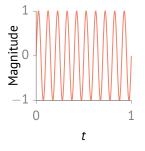
Rectangular function

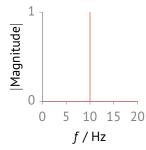


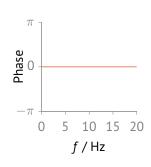




Sinusoid







Convolution theorem

Convolution:

$$(f*g)(t) := f(t)*g(t) := \int_{-\infty}^{\infty} f(\tau) g(t-\tau) d\tau$$

Convolution theorem:

$$\mathcal{F}\left\{f\ast g\right\}=\mathcal{F}\left\{f\right\}\cdot\mathcal{F}\left\{g\right\}$$

Take home

- Every acoustical signal is a combination of sinusoid tones with different frequency, amplitude and phase
- Fourier transformation is a way to characterize time signals