

# Stochastic Control for Optimal Market-Making

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# Trading Order Book (TOB)



# Basics of Trading Order Book (TOB)

- Buyers/Sellers express their intent to trade by submitting bids/asks
- These are Limit Orders (LO) with a price  $P$  and size  $N$
- Buy LO  $(P, N)$  states willingness to buy  $N$  shares at a price  $\leq P$
- Sell LO  $(P, N)$  states willingness to sell  $N$  shares at a price  $\geq P$
- Trading Order Book aggregates order sizes for each unique price
- So we can represent with two sorted lists of (Price, Size) pairs

Bids:  $[(P_i^{(b)}, N_i^{(b)}) \mid 1 \leq i \leq m], P_i^{(b)} > P_j^{(b)} \text{ for } i < j$

Asks:  $[(P_i^{(a)}, N_i^{(a)}) \mid 1 \leq i \leq n], P_i^{(a)} < P_j^{(a)} \text{ for } i < j$

- We call  $P_1^{(b)}$  as simply *Bid*,  $P_1^{(a)}$  as *Ask*,  $\frac{P_1^{(a)} + P_1^{(b)}}{2}$  as *Mid*
- We call  $P_1^{(a)} - P_1^{(b)}$  as *Spread*,  $P_n^{(a)} - P_m^{(b)}$  as *Market Depth*
- A Market Order (MO) states intent to buy/sell  $N$  shares at the *best possible price(s)* available on the TOB at the time of MO submission

# Trading Order Book (TOB) Activity

- A new Sell LO  $(P, N)$  potentially removes best bid prices on the TOB

$$\text{Removal: } [(P_i^{(b)}, \min(N_i^{(b)}, \max(0, N - \sum_{j=1}^{i-1} N_j^{(b)}))) \mid (i : P_i^{(b)} \geq P)]$$

- After this removal, it adds the following to the asks side of the TOB

$$(P, \max(0, N - \sum_{i: P_i^{(b)} \geq P} N_i^{(b)}))$$

- A new Buy MO operates analogously (on the other side of the TOB)
- A Sell Market Order  $N$  will remove the best bid prices on the TOB

$$\text{Removal: } [(P_i^{(b)}, \min(N_i^{(b)}, \max(0, N - \sum_{j=1}^{i-1} N_j^{(b)}))) \mid 1 \leq i \leq m]$$

- A Buy Market Order  $N$  will remove the best ask prices on the TOB

$$\text{Removal: } [(P_i^{(a)}, \min(N_i^{(a)}, \max(0, N - \sum_{j=1}^{i-1} N_j^{(a)}))) \mid 1 \leq i \leq n]$$

# TOB Dynamics and Market-Making

- Modeling TOB Dynamics involves predicting arrival of MOs and LOs
- Market-makers are liquidity providers (providers of Buy and Sell LOs)
- Other market participants are typically liquidity takers (MOs)
- But there are also other market participants that trade with LOs
- Complex interplay between market-makers & other mkt participants
- Hence, TOB Dynamics tend to be quite complex
- We view the TOB from the perspective of a single market-maker who aims to gain with Buy/Sell LOs of appropriate width/size
- By anticipating TOB Dynamics & dynamically adjusting Buy/Sell LOs
- Goal is to maximize *Utility of Gains* at the end of a suitable horizon
- If Buy/Sell LOs are too narrow, more frequent but small gains
- If Buy/Sell LOs are too wide, less frequent but large gains
- Market-maker also needs to manage potential unfavorable inventory (long or short) buildup and consequent unfavorable liquidation

# Notation for Optimal Market-Making Problem

- We simplify the setting for ease of exposition
- Assume finite time steps indexed by  $t = 0, 1, \dots, T$
- Denote  $W_t \in \mathbb{R}$  as Market-maker's trading PnL at time  $t$
- Denote  $I_t \in \mathbb{Z}$  as Market-maker's inventory of shares at time  $t$  ( $I_0 = 0$ )
- $S_t \in \mathbb{R}^+$  is the TOB Mid Price at time  $t$  (assume stochastic process)
- $P_t^{(b)} \in \mathbb{R}^+, N_t^{(b)} \in \mathbb{Z}^+$  are market maker's Bid Price, Bid Size at time  $t$
- $P_t^{(a)} \in \mathbb{R}^+, N_t^{(a)} \in \mathbb{Z}^+$  are market-maker's Ask Price, Ask Size at time  $t$
- Assume market-maker can add or remove bids/asks costlessly
- Denote  $\delta_t^{(b)} = S_t - P_t^{(b)}$  as Bid Spread,  $\delta_t^{(a)} = P_t^{(a)} - S_t$  as Ask Spread
- Random var  $X_t^{(b)} \in \mathbb{Z}_{\geq 0}$  denotes bid-shares "hit" up to time  $t$
- Random var  $X_t^{(a)} \in \mathbb{Z}_{\geq 0}$  denotes ask-shares "lifted" up to time  $t$

$$W_{t+1} = W_t + P_t^{(a)} \cdot (X_{t+1}^{(a)} - X_t^{(a)}) - P_t^{(b)} \cdot (X_{t+1}^{(b)} - X_t^{(b)}), \quad I_t = X_t^{(b)} - X_t^{(a)}$$

- Goal to maximize  $\mathbb{E}[U(W_T + I_T \cdot S_T)]$  for appropriate concave  $U(\cdot)$

# Markov Decision Process (MDP) Formulation

- Order of MDP activity in each time step  $0 \leq t \leq T - 1$ :
  - Observe  $State := (t, S_t, W_t, I_t)$
  - Perform  $Action := (P_t^{(b)}, N_t^{(b)}, P_t^{(a)}, N_t^{(a)})$
  - Experience TOB Dynamics resulting in:
    - random bid-shares hit =  $X_{t+1}^{(b)} - X_t^{(b)}$  and ask-shares lifted =  $X_{t+1}^{(a)} - X_t^{(a)}$
    - update of  $W_t$  to  $W_{t+1}$ , update of  $I_t$  to  $I_{t+1}$
    - stochastic evolution of  $S_t$  to  $S_{t+1}$
  - Receive next-step  $(t + 1)$  *Reward*  $R_{t+1}$

$$R_{t+1} := \begin{cases} 0 & \text{for } 1 \leq t + 1 \leq T - 1 \\ U(W_{t+1} + I_{t+1} \cdot S_{t+1}) & \text{for } t + 1 = T \end{cases}$$

- Goal is to find an *Optimal Policy*  $\pi^*$ :

$$\pi^*(t, S_t, W_t, I_t) = (P_t^{(b)}, N_t^{(b)}, P_t^{(a)}, N_t^{(a)}) \text{ that maximizes } \mathbb{E}\left[\sum_{t=1}^T R_t\right]$$

- Note: Discount Factor when aggregating Rewards in the MDP is 1



# Avellaneda-Stoikov Continuous Time Formulation

- We go over the [landmark paper by Avellaneda and Stoikov in 2006](#)
- They derive a simple, clean and intuitive analytical solution
- We adapt our discrete-time notation to their continuous-time setting
- $X_t^{(b)}, X_t^{(a)}$  are *Poisson processes* with *arrival-rate* means  $\lambda_t^{(b)}, \lambda_t^{(a)}$

$$dX_t^{(b)} \sim \text{Poisson}(\lambda_t^{(b)} \cdot dt), \quad dX_t^{(a)} \sim \text{Poisson}(\lambda_t^{(a)} \cdot dt)$$

$$\lambda_t^{(b)} = f^{(b)}(\delta_t^{(b)}), \quad \lambda_t^{(a)} = f^{(a)}(\delta_t^{(a)}) \text{ for decreasing functions } f^{(b)}, f^{(a)}$$

$$dW_t = P_t^{(a)} \cdot dX_t^{(a)} - P_t^{(b)} \cdot dX_t^{(b)}, \quad I_t = X_t^{(b)} - X_t^{(a)} \quad (\text{note: } I_0 = 0)$$

- Since infinitesimal Poisson random variables  $dX_t^{(b)}$  (shares hit in time  $dt$ ) and  $dX_t^{(a)}$  (shares lifted in time  $dt$ ) are Bernoulli (shares hit/lifted in time  $dt$  are 0 or 1),  $N_t^{(b)}$  and  $N_t^{(a)}$  can be assumed to be 1
- This simplifies the *Action* at time  $t$  to be just the pair:  $(\delta_t^{(b)}, \delta_t^{(a)})$
- TOB Mid Price Dynamics:  $dS_t = \sigma \cdot dz_t$  (scaled brownian motion)
- Utility function  $U(x) = -e^{-\gamma x}$  where  $\gamma$  is coefficient of risk-aversion

# Hamilton-Jacobi-Bellman (HJB) Equation

- We denote the Optimal Value function as  $V^*(t, S_t, W_t, I_t)$

$$V^*(t, S_t, W_t, I_t) = \max_{\delta_t^{(b)}, \delta_t^{(a)}} \mathbb{E}[-e^{-\gamma \cdot (W_T + I_t \cdot S_T)}]$$

- $V^*(t, S_t, W_t, I_t)$  satisfies a recursive formulation for  $0 \leq t < t_1 < T$ :

$$V^*(t, S_t, W_t, I_t) = \max_{\delta_t^{(b)}, \delta_t^{(a)}} \mathbb{E}[V^*(t_1, S_{t_1}, W_{t_1}, I_{t_1})]$$

- Rewriting in stochastic differential form, we have the HJB Equation

$$\max_{\delta_t^{(b)}, \delta_t^{(a)}} \mathbb{E}[dV^*(t, S_t, W_t, I_t)] = 0 \text{ for } t < T$$

$$V^*(T, S_T, W_T, I_T) = -e^{-\gamma \cdot (W_T + I_T \cdot S_T)}$$

# Converting HJB to a Partial Differential Equation

- Change to  $V^*(t, S_t, W_t, I_t)$  is comprised of 3 components:
  - Due to pure movement in time  $t$
  - Due to randomness in LOB Mid-Price  $S_t$
  - Due to randomness in hitting/lifting the Bid/Ask
- With this, we can expand  $dV^*(t, S_t, W_t, I_t)$  and rewrite HJB as:

$$\begin{aligned} \max_{\delta_t^{(b)}, \delta_t^{(a)}} \{ & \frac{\partial V^*}{\partial t} dt + \mathbb{E}[\sigma \frac{\partial V^*}{\partial S_t} dz_t + \frac{\sigma^2}{2} \frac{\partial^2 V^*}{\partial S_t^2} (dz_t)^2] \\ & + \lambda_t^{(b)} \cdot dt \cdot V^*(t, S_t, W_t - S_t + \delta_t^{(b)}, I_t + 1) \\ & + \lambda_t^{(a)} \cdot dt \cdot V^*(t, S_t, W_t + S_t + \delta_t^{(a)}, I_t - 1) \\ & + (1 - \lambda_t^{(b)} \cdot dt - \lambda_t^{(a)} \cdot dt) \cdot V^*(t, S_t, W_t, I_t) \\ & - V^*(t, S_t, W_t, I_t) \} = 0 \end{aligned}$$

# Converting HJB to a Partial Differential Equation

We can simplify this equation with a few observations:

- $\mathbb{E}[dz_t] = 0$
- $\mathbb{E}[(dz_t)^2] = dt$
- Organize the terms involving  $\lambda_t^{(b)}$  and  $\lambda_t^{(a)}$  better with some algebra
- Divide throughout by  $dt$

$$\begin{aligned} \max_{\delta_t^{(b)}, \delta_t^{(a)}} \left\{ \frac{\partial V^*}{\partial t} + \frac{\sigma^2}{2} \frac{\partial^2 V^*}{\partial S_t^2} \right. \\ \left. + \lambda_t^{(b)} \cdot (V^*(t, S_t, W_t - S_t + \delta_t^{(b)}, I_t + 1) - V^*(t, S_t, W_t, I_t)) \right. \\ \left. + \lambda_t^{(a)} \cdot (V^*(t, S_t, W_t + S_t + \delta_t^{(a)}, I_t - 1) - V^*(t, S_t, W_t, I_t)) \right\} = 0 \end{aligned}$$

# Converting HJB to a Partial Differential Equation

Next, note that  $\lambda_t^{(b)} = f^{(b)}(\delta_t^{(b)})$  and  $\lambda_t^{(a)} = f^{(a)}(\delta_t^{(a)})$ , and apply the max only on the relevant terms

$$\begin{aligned} & \frac{\partial V^*}{\partial t} + \frac{\sigma^2}{2} \frac{\partial^2 V^*}{\partial S_t^2} \\ & + \max_{\delta_t^{(b)}} \{ f^{(b)}(\delta_t^{(b)}) \cdot (V^*(t, S_t, W_t - S_t + \delta_t^{(b)}, I_t + 1) - V^*(t, S_t, W_t, I_t)) \} \\ & + \max_{\delta_t^{(a)}} \{ f^{(a)}(\delta_t^{(a)}) \cdot (V^*(t, S_t, W_t + S_t + \delta_t^{(a)}, I_t - 1) - V^*(t, S_t, W_t, I_t)) \} = 0 \end{aligned}$$

This combines with the boundary condition:

$$V^*(T, S_T, W_T, I_T) = -e^{-\gamma \cdot (W_T + I_T \cdot S_T)}$$

# Converting HJB to a Partial Differential Equation

- We make an “educated guess” for the structure of  $V^*(t, S_t, W_t, I_t)$ :

$$V^*(t, S_t, W_t, I_t) = -e^{-\gamma(W_t + \theta(t, S_t, I_t))} \quad (1)$$

and reduce the problem to a PDE in terms of  $\theta(t, S_t, I_t)$

- Substituting this into the above PDE for  $V^*(t, S_t, W_t, I_t)$  gives:

$$\begin{aligned} & \frac{\partial \theta}{\partial t} + \frac{\sigma^2}{2} \left( \frac{\partial^2 \theta}{\partial S_t^2} - \gamma \left( \frac{\partial \theta}{\partial S_t} \right)^2 \right) \\ & + \max_{\delta_t^{(b)}} \left\{ \frac{f^{(b)}(\delta_t^{(b)})}{\gamma} \cdot \left( 1 - e^{-\gamma(\delta_t^{(b)} - S_t + \theta(t, S_t, I_{t+1}) - \theta(t, S_t, I_t))} \right) \right\} \\ & + \max_{\delta_t^{(a)}} \left\{ \frac{f^{(a)}(\delta_t^{(a)})}{\gamma} \cdot \left( 1 - e^{-\gamma(\delta_t^{(a)} + S_t + \theta(t, S_t, I_{t-1}) - \theta(t, S_t, I_t))} \right) \right\} = 0 \end{aligned}$$

- The boundary condition is:

$$\theta(T, S_T, I_T) = I_T \cdot S_T$$

# Indifference Bid/Ask Price

- It turns out that  $\theta(t, S_t, I_t + 1) - \theta(t, S_t, I_t)$  and  $\theta(t, S_t, I_t) - \theta(t, S_t, I_t - 1)$  are equal to financially meaningful quantities known as *Indifference Bid and Ask Prices*
- Indifference Bid Price  $Q^{(b)}(t, S_t, I_t)$  is defined as:

$$V^*(t, S_t, W_t - Q^{(b)}(t, S_t, I_t), I_t + 1) = V^*(t, S_t, W_t, I_t) \quad (2)$$

- $Q^{(b)}(t, S_t, I_t)$  is the price to buy a share with *guarantee of immediate purchase* that results in Optimum Expected Utility being unchanged
- Likewise, Indifference Ask Price  $Q^{(a)}(t, S_t, I_t)$  is defined as:

$$V^*(t, S_t, W_t + Q^{(a)}(t, S_t, I_t), I_t - 1) = V^*(t, S_t, W_t, I_t) \quad (3)$$

- $Q^{(a)}(t, S_t, I_t)$  is the price to sell a share with *guarantee of immediate sale* that results in Optimum Expected Utility being unchanged
- We abbreviate  $Q^{(b)}(t, S_t, I_t)$  as  $Q_t^{(b)}$  and  $Q^{(a)}(t, S_t, I_t)$  as  $Q_t^{(a)}$

# Indifference Bid/Ask Price in the PDE for $\theta$

- Express  $V^*(t, S_t, W_t - Q_t^{(b)}, I_t + 1) = V^*(t, S_t, W_t, I_t)$  in terms of  $\theta$ :

$$\begin{aligned} -e^{-\gamma(W_t - Q_t^{(b)} + \theta(t, S_t, I_t + 1))} &= -e^{-\gamma(W_t + \theta(t, S_t, I_t))} \\ \Rightarrow Q_t^{(b)} &= \theta(t, S_t, I_t + 1) - \theta(t, S_t, I_t) \end{aligned} \quad (4)$$

- Likewise for  $Q_t^{(a)}$ , we get:

$$Q_t^{(a)} = \theta(t, S_t, I_t) - \theta(t, S_t, I_t - 1) \quad (5)$$

- Using equations (4) and (5), bring  $Q_t^{(b)}$  and  $Q_t^{(a)}$  in the PDE for  $\theta$

$$\frac{\partial \theta}{\partial t} + \frac{\sigma^2}{2} \left( \frac{\partial^2 \theta}{\partial S_t^2} - \gamma \left( \frac{\partial \theta}{\partial S_t} \right)^2 \right) + \max_{\delta_t^{(b)}} g(\delta_t^{(b)}) + \max_{\delta_t^{(a)}} h(\delta_t^{(a)}) = 0$$

$$\text{where } g(\delta_t^{(b)}) = \frac{f^{(b)}(\delta_t^{(b)})}{\gamma} \cdot (1 - e^{-\gamma(\delta_t^{(b)} - S_t + Q_t^{(b)})})$$

$$\text{and } h(\delta_t^{(a)}) = \frac{f^{(a)}(\delta_t^{(a)})}{\gamma} \cdot (1 - e^{-\gamma(\delta_t^{(a)} + S_t - Q_t^{(a)})})$$



# Optimal Bid Spread and Optimal Ask Spread

- To maximize  $g(\delta_t^{(b)})$ , differentiate  $g$  with respect to  $\delta_t^{(b)}$  and set to 0

$$e^{-\gamma(\delta_t^{(b)*} - S_t + Q_t^{(b)})} \cdot (\gamma \cdot f^{(b)}(\delta_t^{(b)*}) - \frac{\partial f^{(b)}}{\partial \delta_t^{(b)}}(\delta_t^{(b)*})) + \frac{\partial f^{(b)}}{\partial \delta_t^{(b)}}(\delta_t^{(b)*}) = 0$$
$$\Rightarrow \delta_t^{(b)*} = S_t - Q_t^{(b)} + \frac{1}{\gamma} \cdot \ln \left( 1 - \gamma \cdot \frac{f^{(b)}(\delta_t^{(b)*})}{\frac{\partial f^{(b)}}{\partial \delta_t^{(b)}}(\delta_t^{(b)*})} \right) \quad (6)$$

- To maximize  $g(\delta_t^{(a)})$ , differentiate  $g$  with respect to  $\delta_t^{(a)}$  and set to 0

$$e^{-\gamma(\delta_t^{(a)*} + S_t - Q_t^{(a)})} \cdot (\gamma \cdot f^{(a)}(\delta_t^{(a)*}) - \frac{\partial f^{(a)}}{\partial \delta_t^{(a)}}(\delta_t^{(a)*})) + \frac{\partial f^{(a)}}{\partial \delta_t^{(a)}}(\delta_t^{(a)*}) = 0$$
$$\Rightarrow \delta_t^{(a)*} = Q_t^{(a)} - S_t + \frac{1}{\gamma} \cdot \ln \left( 1 - \gamma \cdot \frac{f^{(a)}(\delta_t^{(a)*})}{\frac{\partial f^{(a)}}{\partial \delta_t^{(a)}}(\delta_t^{(a)*})} \right) \quad (7)$$

- (6) and (7) are implicit equations for  $\delta_t^{(b)*}$  and  $\delta_t^{(a)*}$  respectively

# Solving for $\theta$ and for Optimal Bid/Ask Spreads

- Let us write the PDE in terms of the Optimal Bid and Ask Spreads

$$\begin{aligned} & \frac{\partial \theta}{\partial t} + \frac{\sigma^2}{2} \left( \frac{\partial^2 \theta}{\partial S_t^2} - \gamma \left( \frac{\partial \theta}{\partial S_t} \right)^2 \right) \\ & + \frac{f^{(b)}(\delta_t^{(b)*})}{\gamma} \cdot (1 - e^{-\gamma(\delta_t^{(b)*} - S_t + \theta(t, S_t, l_t+1) - \theta(t, S_t, l_t))}) \\ & + \frac{f^{(a)}(\delta_t^{(a)*})}{\gamma} \cdot (1 - e^{-\gamma(\delta_t^{(a)*} + S_t + \theta(t, S_t, l_t-1) - \theta(t, S_t, l_t))}) = 0 \end{aligned} \quad (8)$$

with boundary condition  $\theta(T, S_T, l_T) = l_T \cdot S_T$

- First we solve PDE (8) for  $\theta$  in terms of  $\delta_t^{(b)*}$  and  $\delta_t^{(a)*}$
- In general, this would be a numerical PDE solution
- Using (4) and (5), we have  $Q_t^{(b)}$  and  $Q_t^{(a)}$  in terms of  $\delta_t^{(b)*}$  and  $\delta_t^{(a)*}$
- Substitute above-obtained  $Q_t^{(b)}$  and  $Q_t^{(a)}$  in equations (6) and (7)
- Solve implicit equations for  $\delta_t^{(b)*}$  and  $\delta_t^{(a)*}$  (in general, numerically)

# Building Intuition

- Define *Indifference Mid Price*  $Q_t^{(m)} = \frac{Q_t^{(b)} + Q_t^{(a)}}{2}$
- To develop intuition for Indifference Prices, consider a simple case where the market-maker doesn't supply any bids or asks. Then,

$$V^*(t, S_t, W_t, I_t) = \mathbb{E}[-e^{-\gamma(W_t + I_t \cdot S_T)}]$$

- Combining this with the diffusion  $dS_t = \sigma \cdot dz_t$ , we get:

$$V^*(t, S_t, W_t, I_t) = -e^{-\gamma(W_t + I_t \cdot S_t - \frac{\gamma \cdot I_t^2 \cdot \sigma^2 (T-t)}{2})}$$

- Combining this with equations (2) and (3), we get:

$$Q_t^{(b)} = S_t + (1 - 2I_t) \frac{\gamma \sigma^2 (T - t)}{2}$$

$$Q_t^{(a)} = S_t + (-1 - 2I_t) \frac{\gamma \sigma^2 (T - t)}{2}$$

$$Q_t^{(m)} = S_t - I_t \gamma \sigma^2 (T - t)$$

$$Q_t^{(a)} - Q_t^{(b)} = \gamma \sigma^2 (T - t)$$

# Building Intuition

- Think of  $Q_t^{(m)}$  as *inventory-risk-adjusted* mid-price (adjustment to  $S_t$ )
- If market-maker is long inventory ( $I_t > 0$ ),  $Q_t^{(m)} < S_t$  indicating inclination to sell than buy, and if market-maker is short inventory,  $Q_t^{(m)} > S_t$  indicating inclination to buy than sell
- Armed with this intuition, we come back to optimal market-making, observing from eqns (6) and (7):  $P_t^{(b)*} < Q_t^{(b)} < Q_t^{(m)} < Q_t^{(a)} < P_t^{(a)*}$
- Think of  $[P_t^{(b)*}, P_t^{(a)*}]$  as “centered” at  $Q_t^{(m)}$  (rather than at  $S_t$ ), i.e.,  $[P_t^{(b)*}, P_t^{(a)*}]$  will (together) move up/down in tandem with  $Q_t^{(m)}$  moving up/down (as a function of inventory position  $I_t$ )

$$Q_t^{(m)} - P_t^{(b)*} = \frac{Q_t^{(a)} - Q_t^{(b)}}{2} + \frac{1}{\gamma} \cdot \ln \left( 1 - \gamma \cdot \frac{f^{(b)}(\delta_t^{(b)*})}{\frac{\partial f^{(b)}}{\partial \delta_t^{(b)}}(\delta_t^{(b)*})} \right) \quad (9)$$

$$P_t^{(a)*} - Q_t^{(m)} = \frac{Q_t^{(a)} - Q_t^{(b)}}{2} + \frac{1}{\gamma} \cdot \ln \left( 1 - \gamma \cdot \frac{f^{(a)}(\delta_t^{(a)*})}{\frac{\partial f^{(a)}}{\partial \delta_t^{(a)}}(\delta_t^{(a)*})} \right) \quad (10)$$

# Real-world Market-Making and Reinforcement Learning

- Arbitrary Price Dynamics  $f_t(\cdot)$  and Temporary Price Impact  $g_t(\cdot)$
- Non-stationarity/non-linear dynamics/impact require (Numerical) DP
- Frictions: Discrete Prices/Sizes, Constraints on Prices/Sizes, Fees
- Large State space incorporate various external factors in the State
- We could also represent the entire TOB within the State
- So then we'd have to develop a simulator capturing all of the above
- Simulator is a *Data-learned Sampling Model* of TOB Dynamics
- In practice, we'd need to also capture *Cross-Asset Market Impact*
- Using this simulator and neural-networks func approx, we can do RL
- References: [Nevmyvaka, Feng, Kearns; 2006](#) and [Vyetrenko, Xu; 2019](#)
- Exciting area for Future Research as well as Engineering Design