

Overview of Stochastic Calculus Foundations

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Continuous and Non-Differentiable Sample Paths

- Sample paths of Brownian motion z_t are continuous
- Sample paths of z_t are almost always non-differentiable, meaning

$$\lim_{h \rightarrow 0} \frac{z_{t+h} - z_t}{h} \text{ is almost always infinite}$$

- The intuition is that $\frac{dz_t}{dt}$ has standard deviation of $\frac{1}{\sqrt{dt}}$, which goes to ∞ as dt goes to 0
- So, this derivative $\frac{dz_t}{dt}$ is almost always infinite

Infinite Total Variation of Sample Paths

- Sample paths of Brownian motion are of infinite total variation, i.e.

$$\lim_{h \rightarrow 0} \sum_{i=m}^{n-1} |z_{(i+1)h} - z_{ih}| \text{ is almost always infinite}$$

- More succinctly, we write

$$\int_S^T |dz_t| = \infty \text{ (almost always)}$$

Finite Quadratic Variation of Sample Paths

- Sample paths of Brownian Motion are of finite quadratic variation, i.e.

$$\lim_{h \rightarrow 0} \sum_{i=m}^{n-1} (z_{(i+1)h} - z_{ih})^2 = h(n - m)$$

- More succinctly, we write

$$\int_S^T (dz_t)^2 = T - S$$

- This means it's expected value is $T - S$ and it's variance is 0
- This leads to Ito's Lemma and Ito Isometry

Fokker-Planck equation of a Stochastic Process

- Let's say we are given the following stochastic process

$$dX_t = \mu(X_t, t) \cdot dt + \sigma(X_t, t) \cdot dz_t$$

- The Fokker-Planck equation of this process is the PDE:

$$\frac{\partial p(x, t)}{\partial t} = -\frac{\partial \{\mu(x, t) \cdot p(x, t)\}}{\partial x} + \frac{\partial^2 \left\{ \frac{\sigma^2(x, t)}{2} \cdot p(x, t) \right\}}{\partial x^2}$$

where $p(x, t)$ is the probability density function of X_t

- The Fokker-Planck equation is used with problems where the initial distribution is known (Kolmogorov forward equation)
- However, if the problem is to know the distribution at previous times, the Feynman-Kac formula can be used (a consequence of the Kolmogorov backward equation)

Feynman-Kac Formula

- Consider the partial differential equation:

$$\frac{\partial u(x, t)}{\partial t} + \mu(x, t) \frac{\partial u(x, t)}{\partial x} + \frac{\sigma^2(x, t)}{2} \frac{\partial^2 u(x, t)}{\partial x^2} - V(x, t) u(x, t) = f(x, t)$$

defined for all $x \in \mathbb{R}$, $t \in [0, T]$, subject to boundary $u(x, T) = \psi(x)$, where μ, σ, ψ, V, f are known functions, T is a parameter and $u : \mathbb{R} \times [0, T] \rightarrow \mathbb{R}$ is the unknown.

- Then the Feynman-Kac formula tells us that the solution $u(x, t)$ can be written as the following conditional expectation:

$$\mathbb{E}^{\mathbb{Q}} \left[\int_t^T e^{-\int_t^r V(X_\tau, \tau) d\tau} \cdot f(X_r, r) \cdot dr + e^{-\int_t^T V(X_\tau, \tau) d\tau} \cdot \psi(X_T) \mid X_t = x \right]$$

under measure \mathbb{Q} such that X_t is an Ito process defined as:

$$dX_t = \mu(X_t, t) \cdot dt + \sigma(X_t, t) \cdot dz_t^{\mathbb{Q}}$$

where $z_t^{\mathbb{Q}}$ is Brownian motion under \mathbb{Q} , and initial condition $X_t = x$

Stopping Time τ

- Random variable τ such that $Pr[\tau \leq t]$ is in σ -algebra \mathcal{F}_t , for all t
- Deciding whether $\tau \leq t$ only depends on information up to time t
- Hitting time of a Borel set A for a process X_t is the first time X_t takes a value within the set A
- Hitting time is an example of stopping time. Formally,

$$T_{X,A} = \operatorname{argmin}_{t \in \mathbb{R}} \{X_t \in A\}$$

eg: Hitting time of a process to exceed a certain fixed level

Optimal Stopping Problem

- Optimal Stopping problem:

$$V(x) = \operatorname{argmax}_{\tau} \mathbb{E}[G(X_{\tau}) | X_0 = x]$$

where τ is a set of stopping times of X_t , $V(\cdot)$ is called the value function, and G is called the reward (or gain) function.

- Note that sometimes we can have several stopping times that maximize $\mathbb{E}[G(X_{\tau})]$ and we say that the optimal stopping time is the smallest stopping time achieving the maximum value.
- Optimal Exercise Time of an American Option is an example
 - X_t is underlying price
 - x is spot price
 - τ is set of times when option is in-the-money
 - $V(\cdot)$ is American option price as function of spot price
 - $G(\cdot)$ is the option payoff function

Markov Property

- Markov property says that the \mathcal{F}_t -conditional PDF of X_{t+h} depends only on the present state X_t
- Strong Markov property says that for every stopping time τ , the \mathcal{F}_τ -conditional PDF of $X_{\tau+h}$ depends only on X_τ

Infinitesimal Generator and Dynkin's Formula

- Infinitesimal Generator of a time homogeneous Ito diffusion X_t is the PDE operator A (operating on functions f) defined as

$$A \bullet f(x) = \lim_{t \rightarrow 0} \frac{\mathbb{E}[f(X_t) | X_0 = x] - f(x)}{t}$$

- If $dX_t = \mu(X) \cdot dt + \sigma(X) \cdot dz_t$, then

$$A \bullet f(x) = \sum_i \mu_i(x) \frac{\partial f}{\partial x_i}(x) + \sum_{i,j} (\sigma(x) \sigma(x)^T)_{i,j} \frac{\partial^2 f}{\partial x_i \partial x_j}(x)$$

- Let τ be a stopping time conditional on $X_0 = x$. Then, Dynkin's formula says:

$$\mathbb{E}[f(X_\tau) | X_0 = x] = f(x) + \mathbb{E}\left[\int_0^\tau A \bullet f(X_s) \cdot ds | X_0 = x\right]$$

- Stochastic generalization of 2nd fundamental theorem of calculus