

Stochastic Control for Optimal Market-Making

Ashwin Rao

ICME, Stanford University

December 25, 2019

- 1 Trading Order Book Dynamics
- 2 Definition of Optimal Market-Making Problem
- 3 Derivation of Avellaneda-Stoikov Analytical Solution
- 4 Real-world Optimal Market-Making and Reinforcement Learning

Trading Order Book (TOB)



Basics of Trading Order Book (TOB)

- Buyers/Sellers express their intent to trade by submitting bids/asks
- These are Limit Orders (LO) with a price P and size N
- Buy LO (P, N) states willingness to buy N shares at a price $\leq P$
- Sell LO (P, N) states willingness to sell N shares at a price $\geq P$
- Trading Order Book aggregates order sizes for each unique price
- So we can represent with two sorted lists of (Price, Size) pairs

Bids: $[(P_i^{(b)}, N_i^{(b)}) \mid 1 \leq i \leq m], P_i^{(b)} > P_j^{(b)} \text{ for } i < j$

Asks: $[(P_i^{(a)}, N_i^{(a)}) \mid 1 \leq i \leq n], P_i^{(a)} < P_j^{(a)} \text{ for } i < j$

- We call $P_1^{(b)}$ as simply *Bid*, $P_1^{(a)}$ as *Ask*, $\frac{P_1^{(a)} + P_1^{(b)}}{2}$ as *Mid*
- We call $P_1^{(a)} - P_1^{(b)}$ as *Spread*, $P_n^{(a)} - P_m^{(b)}$ as *Market Depth*
- A Market Order (MO) states intent to buy/sell N shares at the *best possible price(s)* available on the TOB at the time of MO submission

Trading Order Book (TOB) Activity

- A new Sell LO (P, N) potentially removes best bid prices on the TOB

$$\text{Removal: } [(P_i^{(b)}, \min(N_i^{(b)}, \max(0, N - \sum_{j=1}^{i-1} N_j^{(b)}))) \mid (i : P_i^{(b)} \geq P)]$$

- After this removal, it adds the following to the asks side of the TOB

$$(P, \max(0, N - \sum_{i: P_i^{(b)} \geq P} N_i^{(b)}))$$

- A new Buy MO operates analogously (on the other side of the TOB)
- A Sell Market Order N will remove the best bid prices on the TOB

$$\text{Removal: } [(P_i^{(b)}, \min(N_i^{(b)}, \max(0, N - \sum_{j=1}^{i-1} N_j^{(b)}))) \mid 1 \leq i \leq m]$$

- A Buy Market Order N will remove the best ask prices on the TOB

$$\text{Removal: } [(P_i^{(a)}, \min(N_i^{(a)}, \max(0, N - \sum_{j=1}^{i-1} N_j^{(a)}))) \mid 1 \leq i \leq n]$$

TOB Dynamics and Market-Making

- Modeling TOB Dynamics involves predicting arrival of MOs and LOs
- Market-makers are liquidity providers (providers of Buy and Sell LOs)
- Other market participants are typically liquidity takers (MOs)
- But there are also other market participants that trade with LOs
- Complex interplay between market-makers & other mkt participants
- Hence, TOB Dynamics tend to be quite complex
- We view the TOB from the perspective of a single market-maker who aims to gain with Buy/Sell LOs of appropriate width/size
- By anticipating TOB Dynamics & dynamically adjusting Buy/Sell LOs
- Goal is to maximize *Utility of Gains* at the end of a suitable horizon
- If Buy/Sell LOs are too narrow, more frequent but small gains
- If Buy/Sell LOs are too wide, less frequent but large gains
- Market-maker also needs to manage potential unfavorable inventory (long or short) buildup and consequent unfavorable liquidation

Notation for Optimal Market-Making Problem

- We simplify the setting for ease of exposition
- Assume finite time steps indexed by $t = 0, 1, \dots, T$
- Denote $W_t \in \mathbb{R}$ as Market-maker's trading PnL at time t
- Denote $I_t \in \mathbb{Z}$ as Market-maker's inventory of shares at time t ($I_0 = 0$)
- $S_t \in \mathbb{R}^+$ is the TOB Mid Price at time t (assume stochastic process)
- $P_t^{(b)} \in \mathbb{R}^+, N_t^{(b)} \in \mathbb{Z}^+$ are market maker's Bid Price, Bid Size at time t
- $P_t^{(a)} \in \mathbb{R}^+, N_t^{(a)} \in \mathbb{Z}^+$ are market-maker's Ask Price, Ask Size at time t
- Assume market-maker can add or remove bids/asks costlessly
- Denote $\delta_t^{(b)} = S_t - P_t^{(b)}$ as Bid Spread, $\delta_t^{(a)} = P_t^{(a)} - S_t$ as Ask Spread
- Random var $X_t^{(b)} \in \mathbb{Z}_{\geq 0}$ denotes bid-shares "hit" up to time t
- Random var $X_t^{(a)} \in \mathbb{Z}_{\geq 0}$ denotes ask-shares "lifted" up to time t

$$W_{t+1} = W_t + P_t^{(a)} \cdot (X_{t+1}^{(a)} - X_t^{(a)}) - P_t^{(b)} \cdot (X_{t+1}^{(b)} - X_t^{(b)}), \quad I_t = X_t^{(b)} - X_t^{(a)}$$

- Goal to maximize $\mathbb{E}[U(W_T + I_T \cdot S_T)]$ for appropriate concave $U(\cdot)$

Markov Decision Process (MDP) Formulation

- Order of MDP activity in each time step $0 \leq t \leq T - 1$:
 - Observe $State := (t, S_t, W_t, I_t)$
 - Perform $Action := (P_t^{(b)}, N_t^{(b)}, P_t^{(a)}, N_t^{(a)})$
 - Experience TOB Dynamics resulting in:
 - random bid-shares hit = $X_{t+1}^{(b)} - X_t^{(b)}$ and ask-shares lifted = $X_{t+1}^{(a)} - X_t^{(a)}$
 - update of W_t to W_{t+1} , update of I_t to I_{t+1}
 - stochastic evolution of S_t to S_{t+1}
 - Receive next-step $(t + 1)$ *Reward* R_{t+1}

$$R_{t+1} := \begin{cases} 0 & \text{for } 1 \leq t + 1 \leq T - 1 \\ U(W_{t+1} + I_{t+1} \cdot S_{t+1}) & \text{for } t + 1 = T \end{cases}$$

- Goal is to find an *Optimal Policy* π^* :

$$\pi^*(t, S_t, W_t, I_t) = (P_t^{(b)}, N_t^{(b)}, P_t^{(a)}, N_t^{(a)}) \text{ that maximizes } \mathbb{E}\left[\sum_{t=1}^T R_t\right]$$

- Note: Discount Factor when aggregating Rewards in the MDP is 1

Avellaneda-Stoikov Continuous Time Formulation

- We go over the [landmark paper by Avellaneda and Stoikov in 2006](#)
- They derive a simple, clean and intuitive solution
- We adapt our discrete-time notation to their continuous-time setting
- $X_t^{(b)}, X_t^{(a)}$ are *Poisson processes* with *hit/lift-rate* means $\lambda_t^{(b)}, \lambda_t^{(a)}$

$$dX_t^{(b)} \sim \text{Poisson}(\lambda_t^{(b)} \cdot dt), \quad dX_t^{(a)} \sim \text{Poisson}(\lambda_t^{(a)} \cdot dt)$$

$$\lambda_t^{(b)} = f^{(b)}(\delta_t^{(b)}), \quad \lambda_t^{(a)} = f^{(a)}(\delta_t^{(a)}) \text{ for decreasing functions } f^{(b)}, f^{(a)}$$

$$dW_t = P_t^{(a)} \cdot dX_t^{(a)} - P_t^{(b)} \cdot dX_t^{(b)}, \quad I_t = X_t^{(b)} - X_t^{(a)} \quad (\text{note: } I_0 = 0)$$

- Since infinitesimal Poisson random variables $dX_t^{(b)}$ (shares hit in time dt) and $dX_t^{(a)}$ (shares lifted in time dt) are Bernoulli (shares hit/lifted in time dt are 0 or 1), $N_t^{(b)}$ and $N_t^{(a)}$ can be assumed to be 1
- This simplifies the *Action* at time t to be just the pair: $(\delta_t^{(b)}, \delta_t^{(a)})$
- TOB Mid Price Dynamics: $dS_t = \sigma \cdot dz_t$ (scaled brownian motion)
- Utility function $U(x) = -e^{-\gamma x}$ where γ is coefficient of risk-aversion

Hamilton-Jacobi-Bellman (HJB) Equation

- We denote the Optimal Value function as $V^*(t, S_t, W_t, I_t)$

$$V^*(t, S_t, W_t, I_t) = \max_{\delta_t^{(b)}, \delta_t^{(a)}} \mathbb{E}[-e^{-\gamma \cdot (W_T + I_t \cdot S_T)}]$$

- $V^*(t, S_t, W_t, I_t)$ satisfies a recursive formulation for $0 \leq t < t_1 < T$:

$$V^*(t, S_t, W_t, I_t) = \max_{\delta_t^{(b)}, \delta_t^{(a)}} \mathbb{E}[V^*(t_1, S_{t_1}, W_{t_1}, I_{t_1})]$$

- Rewriting in stochastic differential form, we have the HJB Equation

$$\max_{\delta_t^{(b)}, \delta_t^{(a)}} \mathbb{E}[dV^*(t, S_t, W_t, I_t)] = 0 \text{ for } t < T$$

$$V^*(T, S_T, W_T, I_T) = -e^{-\gamma \cdot (W_T + I_T \cdot S_T)}$$

Converting HJB to a Partial Differential Equation

- Change to $V^*(t, S_t, W_t, I_t)$ is comprised of 3 components:
 - Due to pure movement in time t
 - Due to randomness in TOB Mid-Price S_t
 - Due to randomness in hitting/lifting the Bid/Ask
- With this, we can expand $dV^*(t, S_t, W_t, I_t)$ and rewrite HJB as:

$$\begin{aligned} \max_{\delta_t^{(b)}, \delta_t^{(a)}} \{ & \frac{\partial V^*}{\partial t} dt + \mathbb{E} \left[\sigma \frac{\partial V^*}{\partial S_t} dz_t + \frac{\sigma^2}{2} \frac{\partial^2 V^*}{\partial S_t^2} (dz_t)^2 \right] \\ & + \lambda_t^{(b)} \cdot dt \cdot V^*(t, S_t, W_t - S_t + \delta_t^{(b)}, I_t + 1) \\ & + \lambda_t^{(a)} \cdot dt \cdot V^*(t, S_t, W_t + S_t + \delta_t^{(a)}, I_t - 1) \\ & + (1 - \lambda_t^{(b)} \cdot dt - \lambda_t^{(a)} \cdot dt) \cdot V^*(t, S_t, W_t, I_t) \\ & - V^*(t, S_t, W_t, I_t) \} = 0 \end{aligned}$$

Converting HJB to a Partial Differential Equation

We can simplify this equation with a few observations:

- $\mathbb{E}[dz_t] = 0$
- $\mathbb{E}[(dz_t)^2] = dt$
- Organize the terms involving $\lambda_t^{(b)}$ and $\lambda_t^{(a)}$ better with some algebra
- Divide throughout by dt

$$\begin{aligned} \max_{\delta_t^{(b)}, \delta_t^{(a)}} \left\{ \frac{\partial V^*}{\partial t} + \frac{\sigma^2}{2} \frac{\partial^2 V^*}{\partial S_t^2} \right. \\ \left. + \lambda_t^{(b)} \cdot (V^*(t, S_t, W_t - S_t + \delta_t^{(b)}, I_t + 1) - V^*(t, S_t, W_t, I_t)) \right. \\ \left. + \lambda_t^{(a)} \cdot (V^*(t, S_t, W_t + S_t + \delta_t^{(a)}, I_t - 1) - V^*(t, S_t, W_t, I_t)) \right\} = 0 \end{aligned}$$

Converting HJB to a Partial Differential Equation

Next, note that $\lambda_t^{(b)} = f^{(b)}(\delta_t^{(b)})$ and $\lambda_t^{(a)} = f^{(a)}(\delta_t^{(a)})$, and apply the max only on the relevant terms

$$\begin{aligned} & \frac{\partial V^*}{\partial t} + \frac{\sigma^2}{2} \frac{\partial^2 V^*}{\partial S_t^2} \\ & + \max_{\delta_t^{(b)}} \{ f^{(b)}(\delta_t^{(b)}) \cdot (V^*(t, S_t, W_t - S_t + \delta_t^{(b)}, I_t + 1) - V^*(t, S_t, W_t, I_t)) \} \\ & + \max_{\delta_t^{(a)}} \{ f^{(a)}(\delta_t^{(a)}) \cdot (V^*(t, S_t, W_t + S_t + \delta_t^{(a)}, I_t - 1) - V^*(t, S_t, W_t, I_t)) \} = 0 \end{aligned}$$

This combines with the boundary condition:

$$V^*(T, S_T, W_T, I_T) = -e^{-\gamma \cdot (W_T + I_T \cdot S_T)}$$

Converting HJB to a Partial Differential Equation

- We make an “educated guess” for the structure of $V^*(t, S_t, W_t, I_t)$:

$$V^*(t, S_t, W_t, I_t) = -e^{-\gamma(W_t + \theta(t, S_t, I_t))} \quad (1)$$

and reduce the problem to a PDE in terms of $\theta(t, S_t, I_t)$

- Substituting this into the above PDE for $V^*(t, S_t, W_t, I_t)$ gives:

$$\begin{aligned} & \frac{\partial \theta}{\partial t} + \frac{\sigma^2}{2} \left(\frac{\partial^2 \theta}{\partial S_t^2} - \gamma \left(\frac{\partial \theta}{\partial S_t} \right)^2 \right) \\ & + \max_{\delta_t^{(b)}} \left\{ \frac{f^{(b)}(\delta_t^{(b)})}{\gamma} \cdot \left(1 - e^{-\gamma(\delta_t^{(b)} - S_t + \theta(t, S_t, I_{t+1}) - \theta(t, S_t, I_t))} \right) \right\} \\ & + \max_{\delta_t^{(a)}} \left\{ \frac{f^{(a)}(\delta_t^{(a)})}{\gamma} \cdot \left(1 - e^{-\gamma(\delta_t^{(a)} + S_t + \theta(t, S_t, I_{t-1}) - \theta(t, S_t, I_t))} \right) \right\} = 0 \end{aligned}$$

- The boundary condition is:

$$\theta(T, S_T, I_T) = I_T \cdot S_T$$

Indifference Bid/Ask Price

- It turns out that $\theta(t, S_t, I_t + 1) - \theta(t, S_t, I_t)$ and $\theta(t, S_t, I_t) - \theta(t, S_t, I_t - 1)$ are equal to financially meaningful quantities known as *Indifference Bid and Ask Prices*
- Indifference Bid Price $Q^{(b)}(t, S_t, I_t)$ is defined as:

$$V^*(t, S_t, W_t - Q^{(b)}(t, S_t, I_t), I_t + 1) = V^*(t, S_t, W_t, I_t) \quad (2)$$

- $Q^{(b)}(t, S_t, I_t)$ is the price to buy a share with *guarantee of immediate purchase* that results in Optimum Expected Utility being unchanged
- Likewise, Indifference Ask Price $Q^{(a)}(t, S_t, I_t)$ is defined as:

$$V^*(t, S_t, W_t + Q^{(a)}(t, S_t, I_t), I_t - 1) = V^*(t, S_t, W_t, I_t) \quad (3)$$

- $Q^{(a)}(t, S_t, I_t)$ is the price to sell a share with *guarantee of immediate sale* that results in Optimum Expected Utility being unchanged
- We abbreviate $Q^{(b)}(t, S_t, I_t)$ as $Q_t^{(b)}$ and $Q^{(a)}(t, S_t, I_t)$ as $Q_t^{(a)}$

Indifference Bid/Ask Price in the PDE for θ

- Express $V^*(t, S_t, W_t - Q_t^{(b)}, I_t + 1) = V^*(t, S_t, W_t, I_t)$ in terms of θ :

$$\begin{aligned} -e^{-\gamma(W_t - Q_t^{(b)} + \theta(t, S_t, I_t + 1))} &= -e^{-\gamma(W_t + \theta(t, S_t, I_t))} \\ \Rightarrow Q_t^{(b)} &= \theta(t, S_t, I_t + 1) - \theta(t, S_t, I_t) \end{aligned} \quad (4)$$

- Likewise for $Q_t^{(a)}$, we get:

$$Q_t^{(a)} = \theta(t, S_t, I_t) - \theta(t, S_t, I_t - 1) \quad (5)$$

- Using equations (4) and (5), bring $Q_t^{(b)}$ and $Q_t^{(a)}$ in the PDE for θ

$$\frac{\partial \theta}{\partial t} + \frac{\sigma^2}{2} \left(\frac{\partial^2 \theta}{\partial S_t^2} - \gamma \left(\frac{\partial \theta}{\partial S_t} \right)^2 \right) + \max_{\delta_t^{(b)}} g(\delta_t^{(b)}) + \max_{\delta_t^{(a)}} h(\delta_t^{(a)}) = 0$$

$$\text{where } g(\delta_t^{(b)}) = \frac{f^{(b)}(\delta_t^{(b)})}{\gamma} \cdot (1 - e^{-\gamma(\delta_t^{(b)} - S_t + Q_t^{(b)})})$$

$$\text{and } h(\delta_t^{(a)}) = \frac{f^{(a)}(\delta_t^{(a)})}{\gamma} \cdot (1 - e^{-\gamma(\delta_t^{(a)} + S_t - Q_t^{(a)})})$$

Optimal Bid Spread and Optimal Ask Spread

- To maximize $g(\delta_t^{(b)})$, differentiate g with respect to $\delta_t^{(b)}$ and set to 0

$$e^{-\gamma(\delta_t^{(b)*} - S_t + Q_t^{(b)})} \cdot (\gamma \cdot f^{(b)}(\delta_t^{(b)*}) - \frac{\partial f^{(b)}}{\partial \delta_t^{(b)}}(\delta_t^{(b)*})) + \frac{\partial f^{(b)}}{\partial \delta_t^{(b)}}(\delta_t^{(b)*}) = 0$$
$$\Rightarrow \delta_t^{(b)*} = S_t - Q_t^{(b)} + \frac{1}{\gamma} \cdot \ln \left(1 - \gamma \cdot \frac{f^{(b)}(\delta_t^{(b)*})}{\frac{\partial f^{(b)}}{\partial \delta_t^{(b)}}(\delta_t^{(b)*})} \right) \quad (6)$$

- To maximize $g(\delta_t^{(a)})$, differentiate g with respect to $\delta_t^{(a)}$ and set to 0

$$e^{-\gamma(\delta_t^{(a)*} + S_t - Q_t^{(a)})} \cdot (\gamma \cdot f^{(a)}(\delta_t^{(a)*}) - \frac{\partial f^{(a)}}{\partial \delta_t^{(a)}}(\delta_t^{(a)*})) + \frac{\partial f^{(a)}}{\partial \delta_t^{(a)}}(\delta_t^{(a)*}) = 0$$
$$\Rightarrow \delta_t^{(a)*} = Q_t^{(a)} - S_t + \frac{1}{\gamma} \cdot \ln \left(1 - \gamma \cdot \frac{f^{(a)}(\delta_t^{(a)*})}{\frac{\partial f^{(a)}}{\partial \delta_t^{(a)}}(\delta_t^{(a)*})} \right) \quad (7)$$

- (6) and (7) are implicit equations for $\delta_t^{(b)*}$ and $\delta_t^{(a)*}$ respectively

Solving for θ and for Optimal Bid/Ask Spreads

- Let us write the PDE in terms of the Optimal Bid and Ask Spreads

$$\begin{aligned} & \frac{\partial \theta}{\partial t} + \frac{\sigma^2}{2} \left(\frac{\partial^2 \theta}{\partial S_t^2} - \gamma \left(\frac{\partial \theta}{\partial S_t} \right)^2 \right) \\ & + \frac{f^{(b)}(\delta_t^{(b)*})}{\gamma} \cdot (1 - e^{-\gamma(\delta_t^{(b)*} - S_t + \theta(t, S_t, l_t+1) - \theta(t, S_t, l_t))}) \\ & + \frac{f^{(a)}(\delta_t^{(a)*})}{\gamma} \cdot (1 - e^{-\gamma(\delta_t^{(a)*} + S_t + \theta(t, S_t, l_t-1) - \theta(t, S_t, l_t))}) = 0 \end{aligned} \quad (8)$$

with boundary condition $\theta(T, S_T, l_T) = l_T \cdot S_T$

- First we solve PDE (8) for θ in terms of $\delta_t^{(b)*}$ and $\delta_t^{(a)*}$
- In general, this would be a numerical PDE solution
- Using (4) and (5), we have $Q_t^{(b)}$ and $Q_t^{(a)}$ in terms of $\delta_t^{(b)*}$ and $\delta_t^{(a)*}$
- Substitute above-obtained $Q_t^{(b)}$ and $Q_t^{(a)}$ in equations (6) and (7)
- Solve implicit equations for $\delta_t^{(b)*}$ and $\delta_t^{(a)*}$ (in general, numerically)

Building Intuition

- Define *Indifference Mid Price* $Q_t^{(m)} = \frac{Q_t^{(b)} + Q_t^{(a)}}{2}$
- To develop intuition for Indifference Prices, consider a simple case where the market-maker doesn't supply any bids or asks

$$V^*(t, S_t, W_t, I_t) = \mathbb{E}[-e^{-\gamma(W_t + I_t \cdot S_T)}]$$

- Combining this with the diffusion $dS_t = \sigma \cdot dz_t$, we get:

$$V^*(t, S_t, W_t, I_t) = -e^{-\gamma(W_t + I_t \cdot S_t - \frac{\gamma \cdot I_t^2 \cdot \sigma^2 (T-t)}{2})}$$

- Combining this with equations (2) and (3), we get:

$$Q_t^{(b)} = S_t + (1 - 2I_t) \frac{\gamma \sigma^2 (T-t)}{2}, \quad Q_t^{(a)} = S_t + (-1 - 2I_t) \frac{\gamma \sigma^2 (T-t)}{2}$$

$$Q_t^{(m)} = S_t - I_t \gamma \sigma^2 (T-t), \quad Q_t^{(a)} - Q_t^{(b)} = \gamma \sigma^2 (T-t)$$

- These results for the simple case of no-market-making serve as approximations for our problem of optimal market-making

Building Intuition

- Think of $Q_t^{(m)}$ as *inventory-risk-adjusted* mid-price (adjustment to S_t)
- If market-maker is long inventory ($I_t > 0$), $Q_t^{(m)} < S_t$ indicating inclination to sell than buy, and if market-maker is short inventory, $Q_t^{(m)} > S_t$ indicating inclination to buy than sell
- Armed with this intuition, we come back to optimal market-making, observing from eqns (6) and (7): $P_t^{(b)*} < Q_t^{(b)} < Q_t^{(m)} < Q_t^{(a)} < P_t^{(a)*}$
- Think of $[P_t^{(b)*}, P_t^{(a)*}]$ as “centered” at $Q_t^{(m)}$ (rather than at S_t), i.e., $[P_t^{(b)*}, P_t^{(a)*}]$ will (together) move up/down in tandem with $Q_t^{(m)}$ moving up/down (as a function of inventory position I_t)

$$Q_t^{(m)} - P_t^{(b)*} = \frac{Q_t^{(a)} - Q_t^{(b)}}{2} + \frac{1}{\gamma} \cdot \ln \left(1 - \gamma \cdot \frac{f^{(b)}(\delta_t^{(b)*})}{\frac{\partial f^{(b)}}{\partial \delta_t^{(b)}}(\delta_t^{(b)*})} \right) \quad (9)$$

$$P_t^{(a)*} - Q_t^{(m)} = \frac{Q_t^{(a)} - Q_t^{(b)}}{2} + \frac{1}{\gamma} \cdot \ln \left(1 - \gamma \cdot \frac{f^{(a)}(\delta_t^{(a)*})}{\frac{\partial f^{(a)}}{\partial \delta_t^{(a)}}(\delta_t^{(a)*})} \right) \quad (10)$$

Simple Functional Form for Hitting/Lifting Rate Means

- The PDE for θ and the implicit equations for $\delta_t^{(b)*}, \delta_t^{(a)*}$ are messy
- We make some assumptions, simplify, derive analytical approximations
- First we assume a fairly standard functional form for $f^{(b)}$ and $f^{(a)}$

$$f^{(b)}(\delta) = f^{(a)}(\delta) = c \cdot e^{-k \cdot \delta}$$

- This reduces equations (6) and (7) to:

$$\delta_t^{(b)*} = S_t - Q_t^{(b)} + \frac{1}{\gamma} \ln \left(1 + \frac{\gamma}{k} \right) \quad (11)$$

$$\delta_t^{(a)*} = Q_t^{(a)} - S_t + \frac{1}{\gamma} \ln \left(1 + \frac{\gamma}{k} \right) \quad (12)$$

$\Rightarrow P_t^{(b)*}$ and $P_t^{(a)*}$ are equidistant from $Q_t^{(m)}$

- Substituting these simplified $\delta_t^{(b)*}, \delta_t^{(a)*}$ in (8) reduces the PDE to:

$$\frac{\partial \theta}{\partial t} + \frac{\sigma^2}{2} \left(\frac{\partial^2 \theta}{\partial S_t^2} - \gamma \left(\frac{\partial \theta}{\partial S_t} \right)^2 \right) + \frac{c}{k + \gamma} \left(e^{-k \cdot \delta_t^{(b)*}} + e^{-k \cdot \delta_t^{(a)*}} \right) = 0 \quad (13)$$

with boundary condition $\theta(T, S_T, I_T) = I_T \cdot S_T$

Simplifying the PDE with Approximations

- Note that this PDE (13) involves $\delta_t^{(b)*}$ and $\delta_t^{(a)*}$
- However, equations (11), (12), (4), (5) enable expressing $\delta_t^{(b)*}$ and $\delta_t^{(a)*}$ in terms of $\theta(t, S_t, l_t - 1), \theta(t, S_t, l_t), \theta(t, S_t, l_t + 1)$
- This would give us a PDE just in terms of θ
- Solving that PDE for θ would not only give us $V^*(t, S_t, W_t, l_t)$ but also $\delta_t^{(b)*}$ and $\delta_t^{(a)*}$ (using equations (11), (12), (4), (5))
- To solve the PDE, we need to make a couple of approximations
- First we make a linear approx for $e^{-k \cdot \delta_t^{(b)*}}$ and $e^{-k \cdot \delta_t^{(a)*}}$ in PDE (13):

$$\frac{\partial \theta}{\partial t} + \frac{\sigma^2}{2} \left(\frac{\partial^2 \theta}{\partial S_t^2} - \gamma \left(\frac{\partial \theta}{\partial S_t} \right)^2 \right) + \frac{c}{k + \gamma} (1 - k \cdot \delta_t^{(b)*} + 1 - k \cdot \delta_t^{(a)*}) = 0 \quad (14)$$

- Equations (11), (12), (4), (5) tell us that:

$$\delta_t^{(b)*} + \delta_t^{(a)*} = \frac{2}{\gamma} \ln \left(1 + \frac{\gamma}{k} \right) + 2\theta(t, S_t, l_t) - \theta(t, S_t, l_t + 1) - \theta(t, S_t, l_t - 1)$$

Asymptotic Expansion of θ in I_t

- With this expression for $\delta_t^{(b)*} + \delta_t^{(a)*}$, PDE (14) takes the form:

$$\frac{\partial \theta}{\partial t} + \frac{\sigma^2}{2} \left(\frac{\partial^2 \theta}{\partial S_t^2} - \gamma \left(\frac{\partial \theta}{\partial S_t} \right)^2 \right) + \frac{c}{k + \gamma} \left(2 + \frac{2}{\gamma} \ln \left(1 + \frac{\gamma}{k} \right) - k(2\theta(t, S_t, I_t) - \theta(t, S_t, I_t + 1) - \theta(t, S_t, I_t - 1)) \right) = 0 \quad (15)$$

- To solve PDE (15), we consider this asymptotic expansion of θ in I_t :

$$\theta(t, S_t, I_t) = \sum_{n=0}^{\infty} \frac{I_t^n}{n!} \cdot \theta^{(n)}(t, S_t)$$

- So we need to determine the functions $\theta^{(n)}(t, S_t)$ for all $n = 0, 1, 2, \dots$
- For tractability, we approximate this expansion to the first 3 terms:

$$\theta(t, S_t, I_t) \approx \theta^{(0)}(t, S_t) + I_t \cdot \theta^{(1)}(t, S_t) + \frac{I_t^2}{2} \cdot \theta^{(2)}(t, S_t)$$

Approximation of the Expansion of θ in I_t

- We note that the Optimal Value Function V^* can depend on S_t only through the current *Value of the Inventory* (i.e., through $I_t \cdot S_t$), i.e., it cannot depend on S_t in any other way
- This means $V^*(t, S_t, W_t, 0) = -e^{-\gamma(W_t + \theta^{(0)}(t, S_t))}$ is independent of S_t
- This means $\theta^{(0)}(t, S_t)$ is independent of S_t
- So, we can write it as simply $\theta^{(0)}(t)$, meaning $\frac{\partial \theta^{(0)}}{\partial S_t}$ and $\frac{\partial^2 \theta^{(0)}}{\partial S_t^2}$ are 0
- Therefore, we can write the approximate expansion for $\theta(t, S_t, I_t)$ as:

$$\theta(t, S_t, I_t) = \theta^{(0)}(t) + I_t \cdot \theta^{(1)}(t, S_t) + \frac{I_t^2}{2} \cdot \theta^{(2)}(t, S_t) \quad (16)$$

Solving the PDE

- Substitute this approximation (16) for $\theta(t, S_t, I_t)$ in PDE (15)

$$\begin{aligned} & \frac{\partial \theta^{(0)}}{\partial t} + I_t \frac{\partial \theta^{(1)}}{\partial t} + \frac{I_t^2}{2} \frac{\partial \theta^{(2)}}{\partial t} + \frac{\sigma^2}{2} \left(I_t \frac{\partial^2 \theta^{(1)}}{\partial S_t^2} + \frac{I_t^2}{2} \frac{\partial^2 \theta^{(2)}}{\partial S_t^2} \right) \\ & - \frac{\gamma \sigma^2}{2} \left(I_t \frac{\partial \theta^{(1)}}{\partial S_t} + \frac{I_t^2}{2} \frac{\partial \theta^{(2)}}{\partial S_t} \right)^2 + \frac{c}{k + \gamma} \left(2 + \frac{2}{\gamma} \ln \left(1 + \frac{\gamma}{k} \right) + k \cdot \theta^{(2)} \right) = 0 \end{aligned}$$

with boundary condition:

$$\theta^{(0)}(T) + I_T \cdot \theta^{(1)}(T, S_T) + \frac{I_T^2}{2} \cdot \theta^{(2)}(T, S_T) = I_T \cdot S_T \quad (17)$$

- We will separately collect terms involving specific powers of I_t , each yielding a separate PDE:
 - Terms devoid of I_t (i.e., I_t^0)
 - Terms involving I_t (i.e., I_t^1)
 - Terms involving I_t^2

Solving the PDE

- We start by collecting terms involving I_t

$$\frac{\partial \theta^{(1)}}{\partial t} + \frac{\sigma^2}{2} \cdot \frac{\partial^2 \theta^{(1)}}{\partial S_t^2} = 0 \text{ with boundary condition } \theta^{(1)}(T, S_T) = S_T$$

- The solution to this PDE is:

$$\theta^{(1)}(t, S_t) = S_t \quad (18)$$

- Next, we collect terms involving I_t^2

$$\frac{\partial \theta^{(2)}}{\partial t} + \frac{\sigma^2}{2} \cdot \frac{\partial^2 \theta^{(2)}}{\partial S_t^2} - \gamma \sigma^2 \cdot \left(\frac{\partial \theta^{(1)}}{\partial S_t} \right)^2 = 0 \text{ with boundary } \theta^{(2)}(T, S_T) = 0$$

- Noting that $\theta^{(1)}(t, S_t) = S_t$, we solve this PDE as:

$$\theta^{(2)}(t, S_t) = -\gamma \sigma^2 (T - t) \quad (19)$$

Solving the PDE

- Finally, we collect the terms devoid of I_t

$$\frac{\partial \theta^{(0)}}{\partial t} + \frac{c}{k + \gamma} \left(2 + \frac{2}{\gamma} \ln \left(1 + \frac{\gamma}{k} \right) + k \cdot \theta^{(2)} \right) = 0 \text{ with boundary } \theta^{(0)}(T) = 0$$

- Noting that $\theta^{(2)}(t, S_t) = -\gamma \sigma^2 (T - t)$, we solve as:

$$\theta^{(0)}(t) = \frac{c}{k + \gamma} \left(\left(2 + \frac{2}{\gamma} \ln \left(1 + \frac{\gamma}{k} \right) \right) (T - t) - \frac{k \gamma \sigma^2}{2} (T - t)^2 \right) \quad (20)$$

- This completes the PDE solution for $\theta(t, S_t, I_t)$ and hence, for $V^*(t, S_t, W_t, I_t)$
- Lastly, we derive formulas for $Q_t^{(b)}$, $Q_t^{(a)}$, $Q_t^{(m)}$, $\delta_t^{(b)*}$, $\delta_t^{(a)*}$

Formulas for Prices and Spreads

- Using equations (4) and (5), we get:

$$Q_t^{(b)} = \theta^{(1)}(t, S_t) + (2l_t + 1) \cdot \theta^{(2)}(t, S_t) = S_t - (2l_t + 1) \frac{\gamma \sigma^2 (T - t)}{2} \quad (21)$$

$$Q_t^{(a)} = \theta^{(1)}(t, S_t) + (2l_t - 1) \cdot \theta^{(2)}(t, S_t) = S_t - (2l_t - 1) \frac{\gamma \sigma^2 (T - t)}{2} \quad (22)$$

- Using equations (11) and (12), we get:

$$\delta_t^{(b)*} = \frac{(2l_t + 1) \gamma \sigma^2 (T - t)}{2} + \frac{1}{\gamma} \ln \left(1 + \frac{\gamma}{k} \right) \quad (23)$$

$$\delta_t^{(a)*} = \frac{(1 - 2l_t) \gamma \sigma^2 (T - t)}{2} + \frac{1}{\gamma} \ln \left(1 + \frac{\gamma}{k} \right) \quad (24)$$

$$\text{Optimal Bid-Ask Spread } \delta_t^{(b)*} + \delta_t^{(a)*} = \gamma \sigma^2 (T - t) + \frac{2}{\gamma} \ln \left(1 + \frac{\gamma}{k} \right) \quad (25)$$

$$\text{Optimal "Mid" } Q_t^{(m)} = \frac{Q_t^{(b)} + Q_t^{(a)}}{2} = \frac{P_t^{(b)*} + P_t^{(a)*}}{2} = S_t - l_t \gamma \sigma^2 (T - t) \quad (26)$$

Back to Intuition

- Think of $Q_t^{(m)}$ as *inventory-risk-adjusted* mid-price (adjustment to S_t)
- If market-maker is long inventory ($I_t > 0$), $Q_t^{(m)} < S_t$ indicating inclination to sell than buy, and if market-maker is short inventory, $Q_t^{(m)} > S_t$ indicating inclination to buy than sell
- Think of $[P_t^{(b)*}, P_t^{(a)*}]$ as “centered” at $Q_t^{(m)}$ (rather than at S_t), i.e., $[P_t^{(b)*}, P_t^{(a)*}]$ will (together) move up/down in tandem with $Q_t^{(m)}$ moving up/down (as a function of inventory position I_t)
- Note from equation (25) that the Optimal Bid-Ask Spread $P_t^{(a)*} - P_t^{(b)*}$ is independent of inventory I_t
- Useful view: $P_t^{(b)*} < Q_t^{(b)} < Q_t^{(m)} < Q_t^{(a)} < P_t^{(a)*}$, with these spreads:

$$\text{Outer Spreads } P_t^{(a)*} - Q_t^{(a)} = Q_t^{(b)} - P_t^{(b)*} = \frac{1}{\gamma} \ln \left(1 + \frac{\gamma}{k} \right)$$

$$\text{Inner Spreads } Q_t^{(a)} - Q_t^{(m)} = Q_t^{(m)} - Q_t^{(b)} = \frac{\gamma \sigma^2 (T - t)}{2}$$

Real-world Market-Making and Reinforcement Learning

- Real-world TOB dynamics are non-stationarity, non-linear, complex
- Frictions: Discrete Prices/Sizes, Constraints on Prices/Sizes, Fees
- Need to capture various market factors in the *State* & TOB Dynamics
- This leads to Curse of Dimensionality and Curse of Modeling
- The practical route is to develop a simulator capturing all of the above
- Simulator is a *Market-Data-learnt Sampling Model* of TOB Dynamics
- Using this simulator and neural-networks func approx, we can do RL
- References: [2018 Paper from University of Liverpool](#) and [2019 Paper from JP Morgan Research](#)
- Exciting area for Future Research as well as Engineering Design