

Local Volatility Calibration 로직설명서

1. Dupire Local Volatility 계산로직

$$\sigma_L^2(K, T) = \frac{\sigma^2 + \sigma T \left(\frac{\Delta \sigma}{\Delta T} + (r - q) K \frac{\Delta \sigma}{\Delta K} \right)}{\left(1 + K \cdot d_1 \cdot \frac{\Delta \sigma}{\Delta K} \sqrt{T} \right)^2 + \sigma K^2 T \left(\left(\frac{\Delta^2 \sigma}{\Delta K^2} \right) - d_1 \left(\frac{\Delta \sigma}{\Delta K} \right)^2 \sqrt{T} \right)}$$

2. SABR Implied Volatility

$$\sigma_{\text{SABRIV}} = \frac{\alpha \left\{ 1 + \left[\frac{(1-\beta)^2}{24} \frac{\alpha^2}{(FK)^{\frac{1-\beta}{2}}} + \frac{1}{4} \cdot \frac{\rho \beta v \alpha}{(FK)^{\frac{1-\beta}{2}}} + \frac{2-3\rho^2}{24} v^2 \right] T \right\}}{(FK)^{\frac{(1-\beta)}{2}} \left[1 + \frac{(1-\beta)^2}{24} \ln^2 \left(\frac{F}{K} \right) + \frac{(1-\beta)^4}{1920} \ln^4 \left(\frac{F}{K} \right) \right]} \times \frac{z}{\chi(z)}$$

$$z = \frac{v}{\alpha} (FK)^{\frac{1-\beta}{2}} \ln \left(\frac{F}{K} \right)$$

$$\chi(z) = \ln \left[\frac{\sqrt{1-2\rho z + z^2} + z - \rho}{1-\rho} \right]$$

3. Estimating α, v and ρ .

$$(\alpha^*, v^*, \rho^*) = \underset{\alpha, \rho, v}{\operatorname{argmin}} \sum_i \left\{ \sigma_i^{\text{mkt}} - \sigma_{\text{SABRIV}}(F_i, \alpha, K_i, \rho, v) \right\}^2$$

s. t. $[-1 < \rho < 1, \quad \& \ v > 0]$

4. SABR Calibration을 위한 Levenberg-Marquardt 로직

$$P_{k+1} = P_k - (J^T J + \mu_k I)^{-1} J^T R(p_k)$$

(간혹 $\mu_k I$ 대신에 $\mu_k (J^T J)$ 를 사용하기도 함)

$$\text{여기서 } J = \begin{bmatrix} \frac{\delta r_1(p)}{\delta p_1} & \cdots & \frac{\delta r_1(p)}{\delta p_m} \\ \vdots & \ddots & \vdots \\ \frac{\delta r_n(p)}{\delta p_1} & \cdots & \frac{\delta r_n(p)}{\delta p_m} \end{bmatrix}, \quad R(p) = \begin{bmatrix} r_1(p) \\ \vdots \\ r_n(p) \end{bmatrix}$$

5. SABR LocalVol

➔ 2~4를 통해 SABR Implied Vol을 추정하고 1 Dupire 식을 통해 산출