

Investigations - Pairs Project

Physical model and assumptions

model the bowl as

- rigid body of mass m
- geometrically spherical with radius R
- centre of mass C displaced a from geometric centre O
- displacement lies along a fixed body fixed symmetry axis
- rolling without slipping on horizontal plane
- gravity $\vec{g} = -g \hat{z}$
- no air resistance
- bowl remains upright

These assumptions isolate dominate first order effect

Kinematics of rolling without slipping

Let

- P be the instantaneous point of contact
- ω be the angular velocity
- v be the velocity of geometric centre

rolling without slipping gives

$$v = \omega \times \vec{R} \rightarrow \vec{R} = R\hat{z} \quad \text{vector from } P \text{ to } O$$

since bowl rolls upright $|\omega| = \frac{v}{R}$

Forces and Torques

Forces acting:

- gravity, $m\vec{g}$ acting at C
- normal reaction N at P
- static friction f at P

Torque

$$\tau_{pc} = R\hat{z} + a$$

$$\tau = \tau_{pc} \times mg \quad \text{since } g \text{ vertical}$$

$$|\tau| = mga$$

Angular Momentum of Rolling Bowl

$$L = Iw$$

$$I \approx \frac{2}{5} m R^2 \quad (\text{for near spherical bowl})$$

Rotational Equation of Motion

Euler's Equation

$$\frac{dL}{dt} = \tau$$

$$\frac{d}{dt}(Iw) = mga \hat{n} \rightarrow \text{perpendicular to direction of motion}$$

$$I \frac{dw}{dt} = mga$$

since I and Iw are approx constant, this equation describes precession of w , not a change in its magnitude.

Torque and Precession

$$|\frac{dw}{dt}| = \Omega |w|$$

$$Iw\Omega = mga$$

$$\Omega = \frac{mga}{Iw}$$

$$\Omega = \frac{mgaR}{Iv}$$

Direction of motion

$\theta(t)$ angle between velocity and initial x direction

$$\frac{d\theta}{dt} = \omega = \text{constant}$$

The direction of motion rotates uniformly in time

Radius of Curvature

$$k = \frac{1}{\rho} = \frac{1}{v} \frac{d\theta}{dt}$$

$$\rho = \frac{v}{\omega}$$

$$\Rightarrow \rho = \frac{mv^2}{mg\omega}$$

Parametric Equation of the Path

$$\dot{x} = v \cos(\omega t)$$

$$\dot{y} = v \sin(\omega t)$$

$$\Rightarrow x(t) = \frac{v}{\omega} \sin(\omega t)$$

$$y(t) = \frac{v}{\omega} (1 - \cos(\omega t))$$