#### Announcements

#### Assignments

- HW9
  - Out Friday
  - Due Wed, 12/9, 11:59 pm
  - The two slip days are free (last possible submission Fri, 12/11, 11:59 pm)

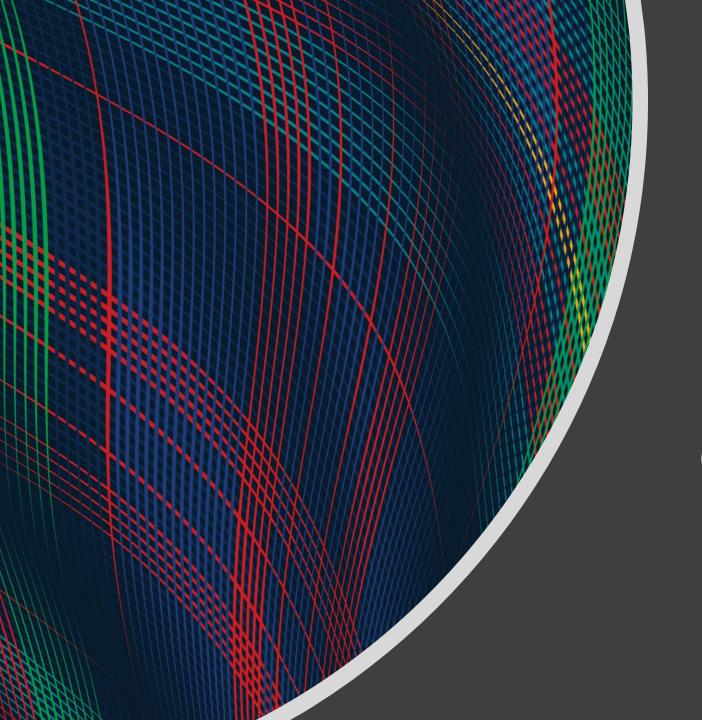
#### Final Exam

- Mon, 12/14
- Stay tuned to Piazza for more details

#### Course Feedback

#### See Piazza for two surveys

- FCE (Faculty Course Evaluation)
- TA survey
  - Fill out once for each TA that you can provide feedback for



Introduction to Machine Learning

Clustering

Instructor: Pat Virtue

# ide credit: CMU MLD, Matt Gormlev

# Learning Paradigms

Data
$\mathcal{D} = \{\mathbf{x}^{(i)}, y^{(i)}\}_{i=1}^N \qquad \mathbf{x} \sim p^*(\cdot) \text{ and } y = c^*(\cdot)$
$y^{(i)} \in \mathbb{R}$
$y^{(i)} \in \{1, \dots, K\}$
$y^{(i)} \in \{+1, -1\}$
$\mathbf{y}^{(i)}$ is a vector
$\mathcal{D} = \{\mathbf{x}^{(i)}\}_{i=1}^{N} \qquad \mathbf{x} \sim p^*(\cdot)$
$\mathcal{D} = \{\mathbf{x}^{(i)}, y^{(i)}\}_{i=1}^{N_1} \cup \{\mathbf{x}^{(j)}\}_{j=1}^{N_2}$
$\mathcal{D} = \{ (\mathbf{x}^{(1)}, y^{(1)}), (\mathbf{x}^{(2)}, y^{(2)}), (\mathbf{x}^{(3)}, y^{(3)}), \ldots \}$
$\mathcal{D} = \{\mathbf{x}^{(i)}\}_{i=1}^N$ and can query $y^{(i)} = c^*(\cdot)$ at a cost
$\mathcal{D} = \{(s^{(1)}, a^{(1)}), (s^{(2)}, a^{(2)}), \ldots\}$
$\mathcal{D} = \{(s^{(1)}, a^{(1)}, r^{(1)}), (s^{(2)}, a^{(2)}, r^{(2)}), \ldots\}$

## Clustering, Informal Goals

Goal: Automatically partition unlabeled data into groups of similar datapoints.

Question: When and why would we want to do this?

#### **Useful for:**

- Automatically organizing data.
- Understanding hidden structure in data.
- Preprocessing for further analysis.
  - Representing high-dimensional data in a low-dimensional space (e.g., for visualization purposes).

Slide credit: CMU MLD Nina Balcan

#### Applications (Clustering comes up everywhere...)

Cluster news articles or web pages or search results by topic.



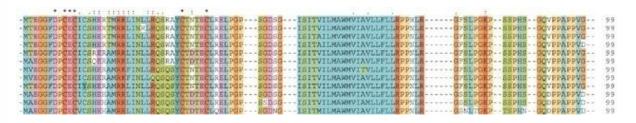




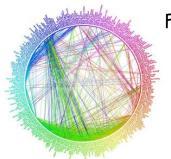


• Cluster protein sequences by function or genes according to expression profile.

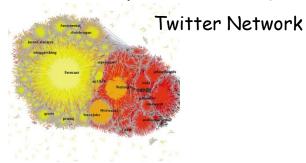




• Cluster users of social networks by interest (community detection).



Facebook network



## **Applications** (Clustering comes up everywhere...)

Cluster customers according to purchase history.





• Cluster galaxies or nearby stars (e.g. Sloan Digital Sky Survey)



And many many more applications....

Slide credit: CMU MLD Nina Balcan

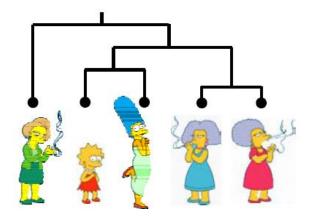
# Clustering Applications

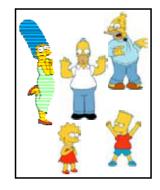
Jigsaw puzzles!



# **Clustering Algorithms**

- Hierarchical algorithms
  - Bottom-up: Agglomerative Clustering
  - Top-down: Divisive
- Partition algorithms
  - K means clustering
  - Mixture-Model based clustering







# **Hierarchical Clustering**

Bottom-Up Agglomerative Clustering

Starts with each object in a separate cluster, and repeat:

- Joins the most similar pair of clusters,
- Update the similarity of the new cluster to others until there is only one cluster.

Greedy - less accurate but simple to implement

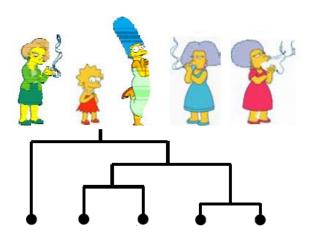


Starts with all the data in a single cluster, and repeat:

Split each cluster into two using a partition algorithm
 Until each object is a separate cluster.

More accurate but complex to implement





# **Hierarchical Clustering**

Bottom-Up Agglomerative Clustering

Starts with each object in a separate cluster, and repeat:

- Joins the most similar pair of clusters,
- Update the similarity of the new cluster to others until there is only one cluster.

Greedy - less accurate but simple to implement

Top-Down divisive

Starts with all the data in a single cluster, and repeat:

Split each cluster into two using a partition algorithm
 Until each object is a separate cluster.

More accurate but complex to implement



# **Partitioning Algorithms**

Partitioning method: Construct a partition of N objects into a set of K clusters

• Given: a set of objects and the number *K* 

- Find: a partition of *K* clusters that optimizes the chosen partitioning criterion
  - Globally optimal: exhaustively enumerate all partitions
  - Effective heuristic method: K-means algorithm

### **K-Means**

#### **Algorithm**

Iterate –

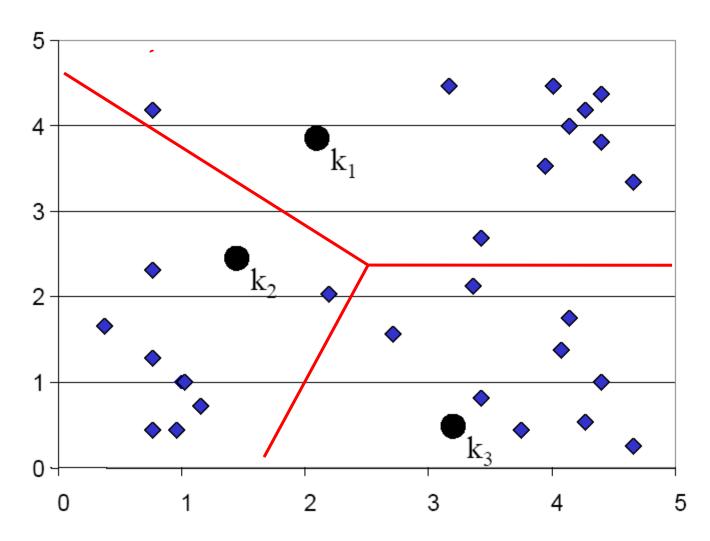
```
Input – Data, x^{(i)}, Desired number of clusters, K
Initialize – the K cluster centers (randomly if necessary)
```

- 1. Assign points to the nearest cluster centers
- 2. Re-estimate the *K* cluster centers (aka the centroid or mean), by assuming the memberships found above are correct.

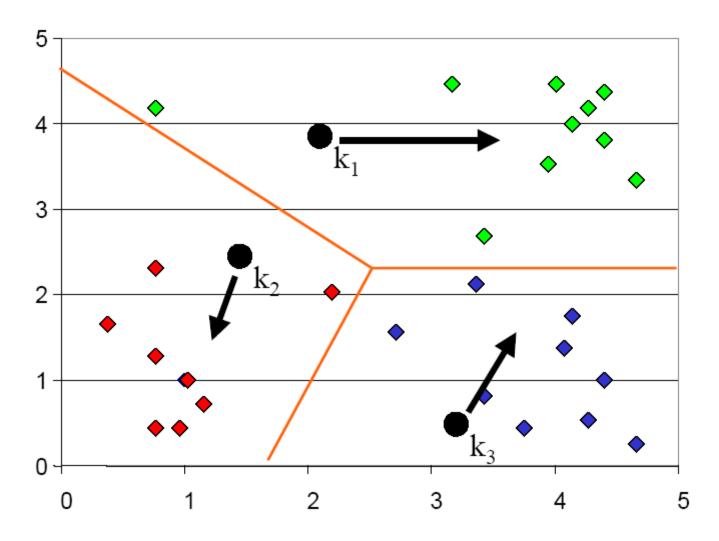
#### Termination -

If none of the objects changed membership in the last iteration, exit. Otherwise go to 1.

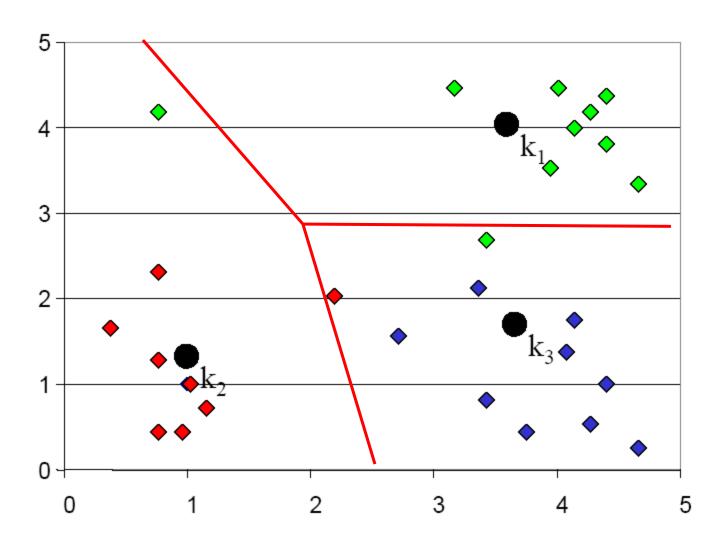
# K-means Clustering: Assign points



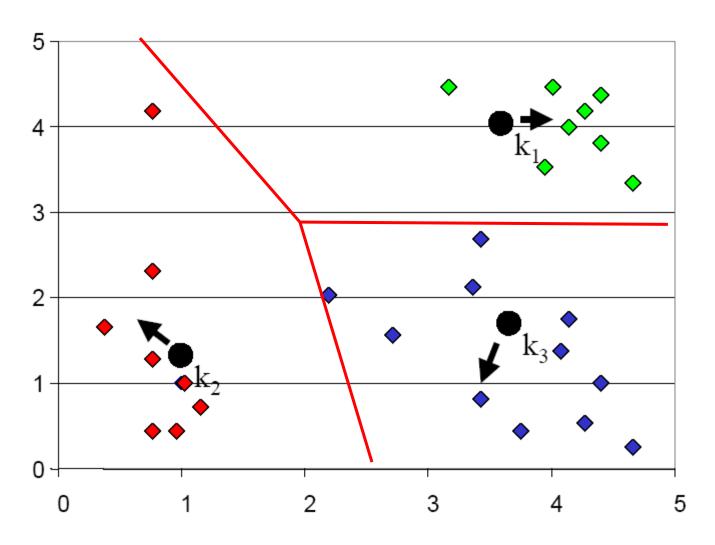
# K-means Clustering: Update centers



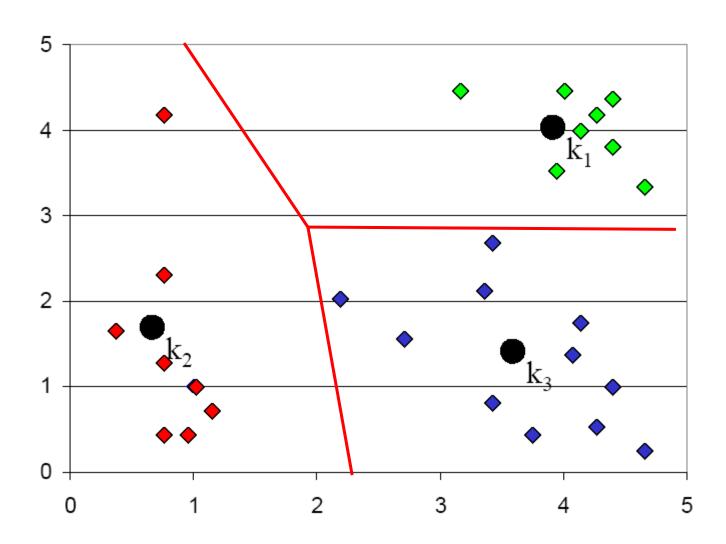
# K-means Clustering: Assign points



# K-means Clustering: Update centers



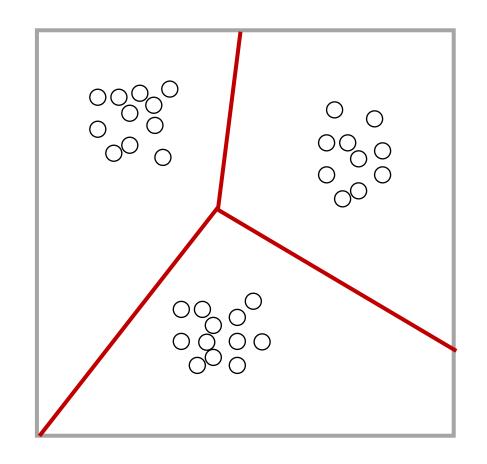
# K-means Clustering: Assign points

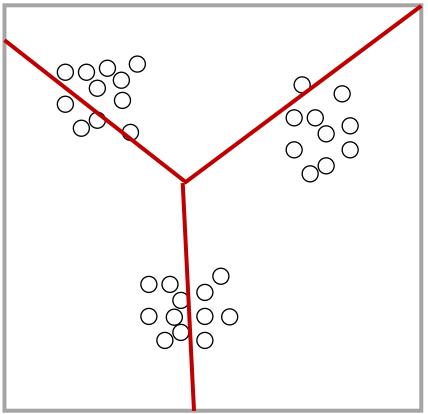


# K-means Optimization Optimization recipe

- 1. Formulate objective
- 2. Minimize objective

Question: Which of these partitions is "better"?





Input: K,  $x^{(1)}$ , ...,  $x^{(N)}$ ,  $x^{(i)} \in \mathbb{R}^{M}$ 

Output:  $z^{(1)}, ..., z^{(N)}, z^{(i)} \in \{1 ... K\}$ 

Output:  $\mu_1, ..., \mu_K, \quad \mu_k \in \mathbb{R}^M$ 

Num clusters, unlabeled data
Cluster assignments per point
Cluster centers

#### Computational complexity

$$\mu_1, \dots, \mu_K, z = \underset{\mu_1, \dots, \mu_K, z}{\operatorname{argmin}} \sum_{i=1}^N ||x^{(i)} - \mu_{z^{(i)}}||_2^2$$

#### Alternating minimization

a) 
$$z = \underset{z}{\operatorname{argmin}} \sum_{i=1}^{N} ||x^{(i)} - \mu_{z^{(i)}}||_{2}^{2}$$

b) 
$$\mu_1, \dots, \mu_K = \underset{\mu_1, \dots, \mu_K}{\operatorname{argmin}} \sum_{i=1}^N ||x^{(i)} - \mu_{z^{(i)}}||_2^2$$

# Alternating minimization

#### Coordinate descent

Two different approaches

$$\min_{\theta_1,\theta_2} J(\theta_1,\theta_2)$$

1. Step based on derivative for one parameter

a. 
$$\theta_1 \leftarrow \theta_1 - \eta \ \partial J / \partial \theta_1$$

b. 
$$\theta_2 \leftarrow \theta_2 - \eta \partial J/\partial \theta_2$$

2. Find minimum for one parameter

a. 
$$\theta_1 \leftarrow \underset{\theta_1}{\operatorname{argmin}} J(\theta_1, \theta_2)$$

b. 
$$\theta_2 \leftarrow \underset{\theta_2}{\operatorname{argmin}} J(\theta_1, \theta_2)$$

# Alternating minimization

#### Block coordinate descent

Two different approaches

$$\min_{\alpha,\beta} J(\alpha,\beta)$$

- 1. Step based on gradient for one set of parameters (step size  $\eta$ )
  - a.  $\alpha \leftarrow \alpha \eta \nabla_{\alpha} I$
  - b.  $\boldsymbol{\beta} \leftarrow \boldsymbol{\beta} \eta \nabla_{\boldsymbol{\beta}} J$

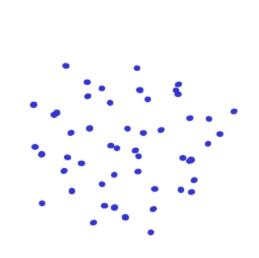
- 2. Find minimum for one set of parameter (no hyperparameters!)
  - a.  $\alpha \leftarrow \operatorname{argmin} J(\alpha, \beta)$
  - b.  $\beta \leftarrow \underset{\beta}{\operatorname{argmin}} J(\alpha, \beta)$

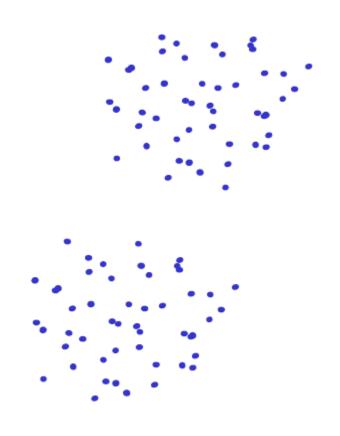
# **Computational Complexity**

- At each iteration,
  - Computing cluster centers: Each object gets added once to some cluster: O(N)
  - Computing distance between each of the N objects and the K cluster centers is O(KN)

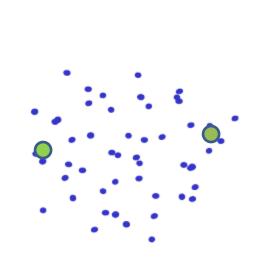
• Assume these two steps are each done once for l iterations: O(lKN)

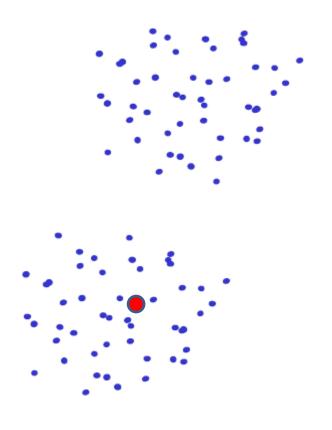
• Results are quite sensitive to seed selection.



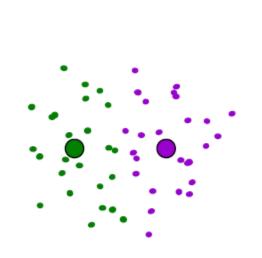


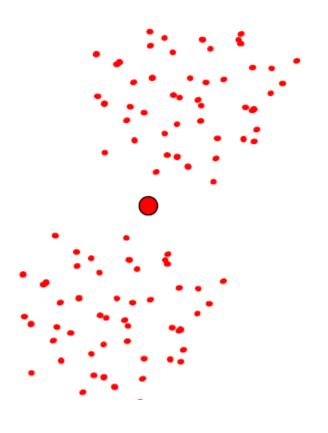
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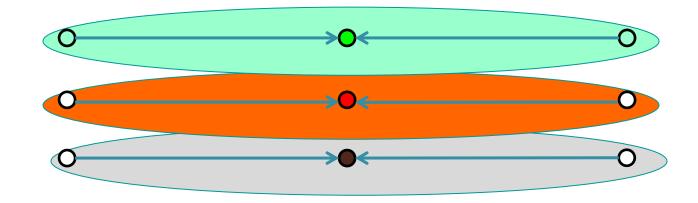




• Results are quite sensitive to seed selection.







K-means always converges, but it may converge at a local optimum that is different from the global optimum, and in fact could be arbitrarily worse in terms of its objective.

- Results can vary based on random seed selection.
- Some seeds can result in poor convergence rate, or convergence to sub-optimal clustering.
  - Try out multiple starting points (very important!!!)
  - k-means ++ algorithm of Arthur and Vassilvitskii
     key idea: choose centers that are far apart
     (probability of picking a point as cluster center 

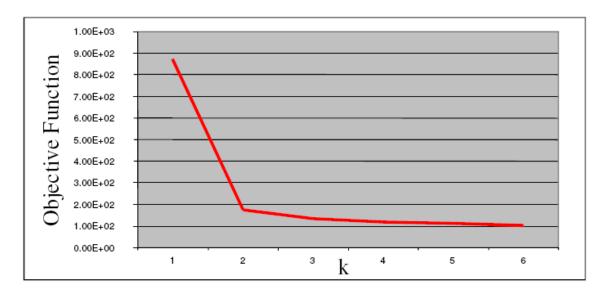
     distance from nearest center picked so far)

## **Other Issues**

- Number of clusters K
  - Objective function

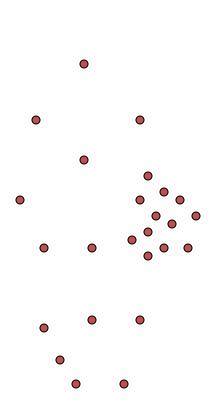
$$\sum_{j=1}^{m} ||\mu_{C(j)} - x_j||^2$$

Look for "Knee" in objective function



— Can you pick K by minimizing the objective over K?

# (One) bad case for K-means



- Clusters may overlap
- Some clusters may be "wider" than others
- Clusters may not be linearly separable