

Q-Motion® Servo Controller, 1 Axis

For Piezoelectric Inertia Drives, SPI, TCP/IP, USB, RS-232 Interfaces



E-873

- Broadband encoder input
- Macro programmable for stand-alone functionality
- Fast startup due to ID chip detection
- Data recorder
- Digital I/O ports (TTL)
- Joystick for manual operation

Digital servo controller for piezo inertia drives

Integrated power amplifier and voltage generator for piezo inertia drives. Point-to-point motion, trapezoidal velocity profile, actuator mode for nanometer precision positioning at the target position. 1 axis.

Encoder inputs

Differential signal transmission for digital (A/B) or analog (sin/cos) encoder signals. BiSS interface for absolute encoders. TTL inputs for limit and reference switches.

Interfaces

USB, RS-232, TCP/IP, and SPI for commanding. I/O lines (analog/digital) for automation. Connector for analog joystick.

Extensive functions, software support

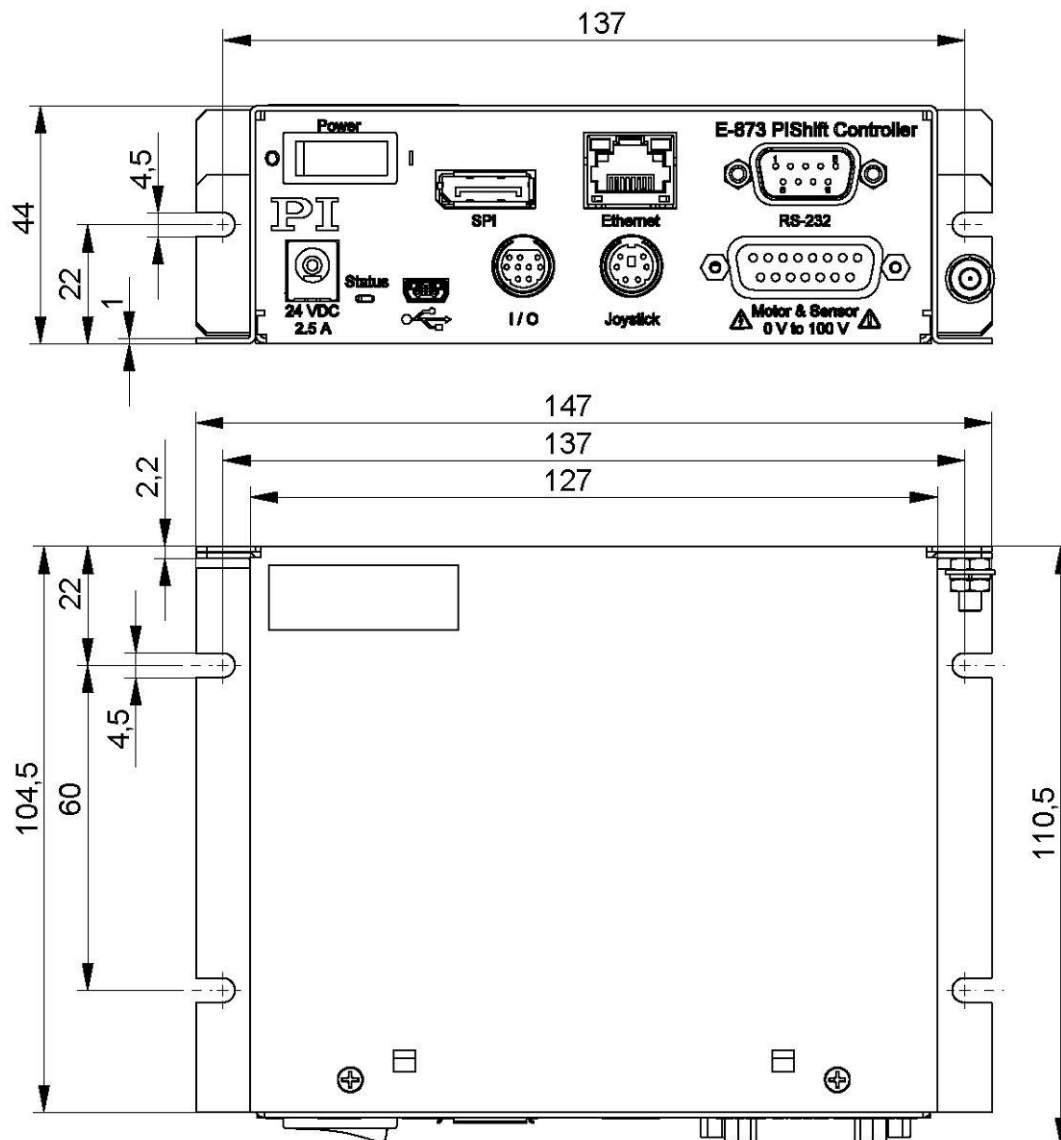
Powerful macro command language. Nonvolatile macro storage, e.g., for stand-alone operation with autostart macro. Data recorder. ID chip detection for fast startup. PID controller, parameter changing during operation. Extensive software support, e.g., for NI LabVIEW, C, C++, MATLAB, Python. PIMikroMove user software.

Specifications

	E-873.1AT
Function	Q-Motion® controller for positioning systems with piezo inertia drives, also suitable for closed-loop PiezoMikes Benchtop device with option for cabinet mounting
Axes	1
Supported functions	Startup macro. Data recorder for recording operating data such as motor voltage, velocity, position or position error. Internal safety circuitry: Watchdog timer. ID chip detection.
Motion and control	E-873.1AT
Controller type	PID controller, parameter changing during operation
Servo cycle time	50 µs
Dynamics profile	Trapezoidal velocity profile. Point-to-point motion.
Encoder input	Analog encoder inputs sine-cosine, interpolation selectable to 20000. Interpolation electronics preset to differential transmission, 1 V _{pp} and 2.5 V encoder signal offset. BiSS interface for absolute encoders.
Stall detection	Automatic motor stop
Input limit switch	2 × TTL (pull-up / pull-down, programmable)
Input reference switch	1 × TTL for integrated reference in the encoder
Electrical properties	E-873.1AT
Max. output power	30 W
Output voltage	0 to 100 V, drive-dependent selection
Interfaces and operation	E-873.1AT
Communication interfaces	TCP/IP: RJ45/Ethernet; USB: Mini-B; RS-232: D-sub 9 (m); SPI
Motor / sensor connector	D-sub 15 (f)
I/O lines	4 analog / digital inputs, 4 digital outputs
Command set	PI General Command Set (GCS)
User software	PIMikroMove
Application programming interfaces	API for C / C++ / C# / VB.NET / MATLAB / Python, drivers for NI LabVIEW
Manual control (optional)	Analog joystick
Miscellaneous	E-873.1AT
Operating voltage	24 V DC from external power adapter (included in the scope of delivery)
Max. current consumption	1.5 A
Operating temperature range	0 to 50 °C
Mass	0.335 kg
Dimensions	137 mm x 105 mm x 43.82 mm

Ask about customized versions.

Drawings / Images



E-873.1AT, dimensions in mm. Note that a comma is used in the drawings instead of a decimal point.

Ordering Information

E-873.1AT

Q-Motion® Controller for piezoelectric inertia drives, 1 axis, benchtop device (industry), SPI, TCP/IP, USB, RS-232, I/O, connector for joystick