

# Distributed GPGPU Computing

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"<IMAGE GPU vs CPU>"

# Why GPGPU?

The **theoretical** calculation power of a GPU is much higher than a CPU.

## Example

CPU (Intel Xeon E5-2670 v3):

- 12 Cores, 2.3 GHz, 32 FLOPS/cycle
  - **884 GFLOPS**
- Prize: ~ **1500 \$**

GPU (NVidia Tesla K40):

- 2880 Cores, 745 MHz, 2 FLOPS/cycle
  - **4291 GFLOPS**
- Prize: ~ **4000 \$**

So, what computational tasks are actually suitable for GPGPU?

# Problems suitable for GPGPU

Every problem that fits the **SPMD** programming scheme, can benefit greatly from GPGPU.

Examples:

- Fluid Simulations
- Mathematical Vector Operations
- Image Processing
- Stencil Based Simulations

SPMD based Programming Languages:

- CUDA (NVidia)
- OpenCL (Platform independent)

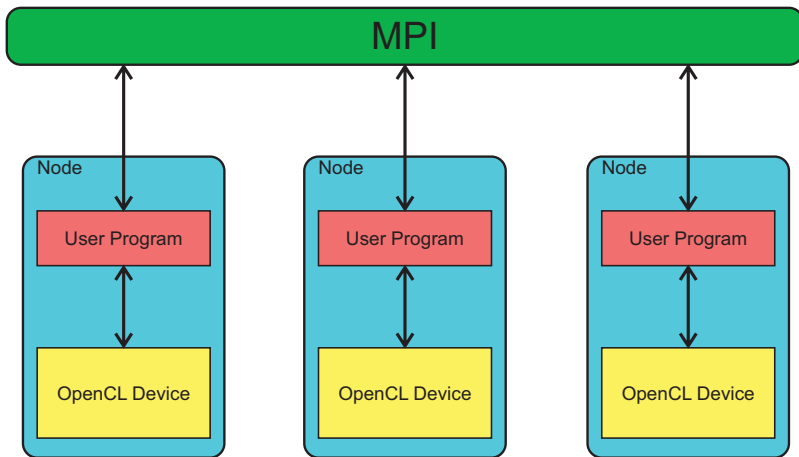
"<Image OpenCL host-device(kernel+buffer)>"

- An OpenCL device is split in two components:
  - The **Buffer**: Represents memory on the device
  - The **Kernel**: A C-style function that modifies one or multiple elements of a buffer
- Kernel source code stays plain text and gets compiled at **runtime**  
⇒ OpenCL programs are device independent
- Kernel executions on the device run asynchronous to the host program



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# Distributed OpenCL with MPI



## Disadvantages:

- MPI and OpenCL are independent from each other
  - ⇒ Connection between computation and data exchange has to be implemented manually
- Every OpenCL device can only be accessed within its own node
- If no further methods are used, the whole cluster will run in lockstep

# Outline

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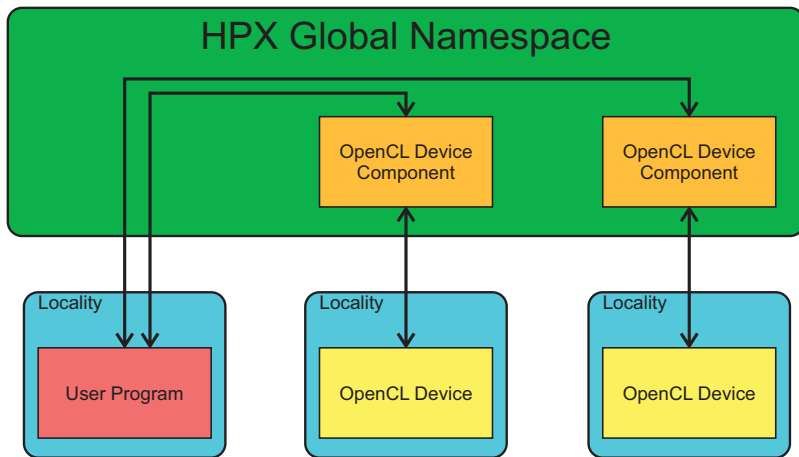
## What is HPX?

- A scaling C++ runtime system for parallel and distributed applications
- Based on the ParalleX model

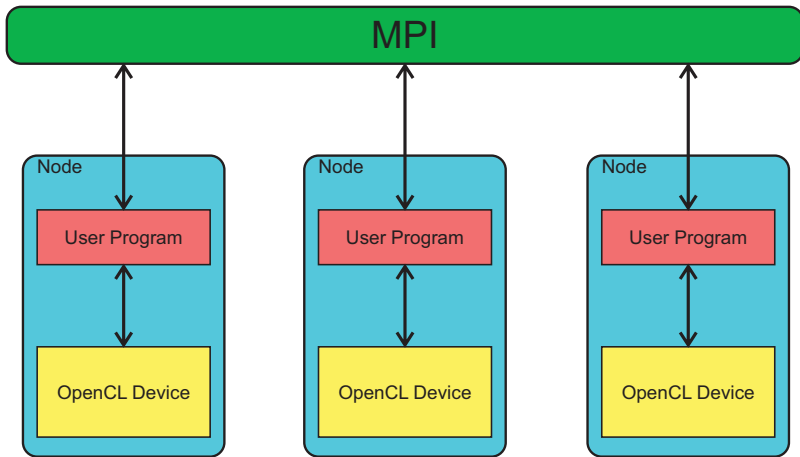
## Advantages for distributed OpenCL:

- Global Namespace
- Cluster as "one large machine" (MPI: every Node is autonomous)
- Data dependencies (futures) (MPI: Send-Wait)

# Distributed OpenCL with HPX



# Distributed OpenCL with MPI



# Affect on distributed GPGPU programming

- Abstracting the whole cluster as one machine
- Simpler, not need to think in a distributed way
- Data dependencies
  - faster due to prevention of lockstep
  - possible to apply synchronization techniques of standard opengl
- Seamless integration of more opengl nodes into the system
- Possibility to run heterogeneous nodes/devices in one system
- Easy to port non-distributed code to distributed opengl whilst maintaining descent scaling



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- Is an implementation of that concept.
- Wraps every OpenCL datastructure in a component:

OpenCL	HPXCL
cl_device	hpx::opengl::device
cl_program	hpx::opengl::program
cl_kernel	hpx::opengl::kernel
cl_mem	hpx::opengl::buffer
cl_event	hpx::opengl::event
	(soon: hpx::future)

# Hello, World! - Getting devices

# Hello, World! - Writing data to the device

# Hello, World! - Creating a kernel

# Hello, World! - Executing the kernel

# Hello, World! - Reading the result

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# Scaling

# Parallel Efficiency