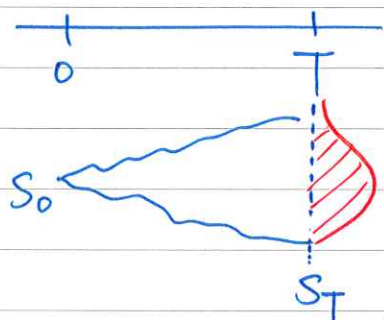


## Unit 3 BS model and Greek letters

● BS model  $\longrightarrow$  BS formulas



$$\begin{cases} C_0 = S_0 N(d_1) - Ke^{-rT} N(d_2) \\ P_0 = Ke^{-rT} N(-d_2) - S_0 N(-d_1) \end{cases}$$

①  $S_T = S_0 e^X$

$X \sim N\left((r - \frac{\sigma^2}{2})T, \sigma^2 T\right)$  under  $\mathbb{Q}$  measure

$E^{\mathbb{Q}}[S_T] = S_0 e^{rT}$

②  $dS_t = rS_t dt + \sigma S_t dW_t$

$\longleftarrow$  SDE

$S_t = S_0 e^{(r - \frac{\sigma^2}{2})T + \sigma W_t}$

$\xrightarrow{X}$

$W_t$  : Wiener process

$E^{\mathbb{Q}}[S_t] = S_0 e^{rT}$

$\uparrow$

stock return under the  $\mathbb{Q}$  measure

stochastic differential equation (stochastic calculus)  
 $\longleftarrow$  solution of the SDE

Note :  $W_T \sim N(0, T)$

$\sigma W_T \sim N(0, \sigma^2 T)$

$X = (r - \frac{\sigma^2}{2})T + \sigma W_T \sim N((r - \frac{\sigma^2}{2})T, \sigma^2 T)$

$\parallel$

$\ln S_T - \ln S_0 \quad \therefore \ln S_T \sim N(\ln S_0 + (r - \frac{\sigma^2}{2})T, \sigma^2 T)$

### ● Delta ( $\Delta$ )

$$\Delta_c = \frac{\partial C}{\partial S} = N(d_1)$$

$$\Delta_p = \frac{\partial P}{\partial S} = N(d_1) - 1$$

### ① Proof of $\Delta_c$

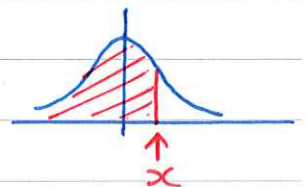
$$C = S N(d_1) - K e^{-rT} N(d_2)$$

$$\frac{\partial C}{\partial S} = \underbrace{N(d_1)}_{\textcircled{1}} + \underbrace{S n(d_1) \frac{\partial d_1}{\partial S}}_{\textcircled{2}} - \underbrace{K e^{-rT} n(d_2) \frac{\partial d_2}{\partial S}}_{\textcircled{3}}$$

Note:  $N(x) = \int_{-\infty}^x n(y) dy$

$$\frac{\partial}{\partial x}$$

$$n(x) = \frac{1}{\sqrt{2\pi}} e^{-\frac{x^2}{2}}$$



$$n(d_1) = \frac{1}{\sqrt{2\pi}} e^{-\frac{d_1^2}{2}}, \quad n(d_2) = \frac{1}{\sqrt{2\pi}} e^{-\frac{d_2^2}{2}}$$

$$d_1 = \frac{\ln \frac{S}{K} + (r + \frac{\sigma^2}{2})T}{\sigma\sqrt{T}}, \quad d_2 = d_1 - \sigma\sqrt{T}$$

$$\frac{\partial d_1}{\partial S} = \frac{\partial}{\partial S} \left[ \frac{1}{\sigma\sqrt{T}} \ln S \right] = \frac{1}{S \sigma\sqrt{T}} = \frac{\partial d_2}{\partial S}$$

$$d_2^2 = (d_1 - \sigma\sqrt{T})^2 = d_1^2 - 2d_1\sigma\sqrt{T} + \sigma^2 T$$

$$-\frac{d_2^2}{2} = -\frac{d_1^2}{2} + d_1\sigma\sqrt{T} - \frac{\sigma^2 T}{2}$$

② - ③

$$= S n(d_1) \frac{\partial d_1}{\partial S} - K e^{-rT} n(d_2) \frac{\partial d_2}{\partial S}$$

$$\begin{array}{ccccccc} \downarrow & & \downarrow & & \downarrow & & \downarrow \\ \frac{1}{\sqrt{2\pi}} e^{-\frac{d_1^2}{2}} & & \frac{1}{S\sigma\sqrt{T}} & & \frac{1}{\sqrt{2\pi}} e^{-\frac{d_2^2}{2} + d_1\sigma\sqrt{T} - \frac{\sigma^2 T}{2}} & & \frac{1}{S\sigma\sqrt{T}} \end{array}$$

$$= S \frac{1}{\sqrt{2\pi}} e^{-\frac{d_1^2}{2}} \frac{1}{S\sigma\sqrt{T}} \left[ 1 - \frac{K e^{-rT}}{S} e^{d_1\sigma\sqrt{T} - \frac{\sigma^2 T}{2}} \right] = 0$$

$$\rightarrow 1 - \frac{K e^{-rT}}{S} e^{\ln \frac{S}{K} + (r + \frac{\sigma^2}{2})T - \frac{\sigma^2 T}{2}} = 1 - \frac{K e^{-rT}}{S} \left( \frac{S}{K} \times e^{rT} \right) = 0$$

$$\therefore \textcircled{2} - \textcircled{3} = 0$$

$$\Delta_c = \frac{\partial C}{\partial S} = N(d_1)$$

⑥ Proof of  $\Delta_p$  is left to you as an exercise

Note: put-call parity

$$C + K e^{-rT} = P + S$$

$$\frac{\partial}{\partial S} \left( C + K e^{-rT} \right) = \frac{\partial}{\partial S} (P + S)$$

$$\frac{\partial C}{\partial S} + 0 = \frac{\partial P}{\partial S} + 1$$

$$\Delta_c + 0 = \Delta_p + 1$$

$$\parallel$$

$$N(d_1) \quad \therefore \Delta_p = \Delta_c - 1 = N(d_1) - 1$$



## ● Gamma ( $\Gamma$ )

$$\Gamma_c = \frac{\partial^2 C}{\partial S^2} = \frac{\partial \Delta_c}{\partial S} = \frac{n(d_1)}{S \sigma \sqrt{T}}$$

$$\Gamma_p = \frac{\partial^2 P}{\partial S^2} = \frac{\partial \Delta_p}{\partial S} = \frac{n(d_1)}{S \sigma \sqrt{T}}$$

### ① Proof of $\Gamma_c$

$$\Gamma_c = \frac{\partial \Delta_c}{\partial S} = n(d_1) \frac{\partial d_1}{\partial S} = \frac{n(d_1)}{S \sigma \sqrt{T}}$$

$\frac{\partial d_1}{\partial S} = \frac{1}{S \sigma \sqrt{T}}$

### ② Proof of $\Gamma_p$

$$\Gamma_p = \frac{\partial \Delta_p}{\partial S} = n(d_1) \frac{\partial d_1}{\partial S} = \frac{n(d_1)}{S \sigma \sqrt{T}}$$

Note: put-call parity

$$C + Ke^{-rT} = P + S$$

$$\frac{\partial}{\partial S} \left( C + 0 \right) = \frac{\partial}{\partial S} (P + S)$$

$$\Delta_c + 0 = \Delta_p + 1$$

$$\frac{\partial}{\partial S} \left( \Gamma_c + 0 \right) = \frac{\partial}{\partial S} (\Gamma_p + 0)$$

$$\Gamma_c + 0 = \Gamma_p + 0$$

## ● Vega ( $V$ )

$$V_c = \frac{\partial C}{\partial \sigma} = S \sqrt{T} n(d_1)$$

$$V_p = \frac{\partial P}{\partial \sigma} = S \sqrt{T} n(d_1)$$

### ① Proof of $V_c$

$$V_c = \frac{\partial C}{\partial \sigma} = S n(d_1) \frac{\partial d_1}{\partial \sigma} - K e^{-rT} n(d_2) \frac{\partial d_2}{\partial \sigma}$$

$$d_1 = d_2 + \sigma \sqrt{T}$$

$$\frac{\partial d_1}{\partial \sigma} = \frac{\partial d_2}{\partial \sigma} + \sqrt{T}$$

$$= \left[ S n(d_1) - K e^{-rT} n(d_2) \right] \frac{\partial d_2}{\partial \sigma} + S \sqrt{T} n(d_1)$$

||  
0

↓  
answer!

Why?

See p. 2a:  $S n(d_1) - K e^{-rT} n(d_2)$

$$= S \frac{1}{\sqrt{2\pi}} e^{-\frac{d_1^2}{2}} \left[ 1 - \frac{K e^{-rT}}{S} e^{d_1 \sigma \sqrt{T} - \frac{\sigma^2 T}{2}} \right] = 0$$

||  
0

$$= S \sqrt{T} n(d_1)$$

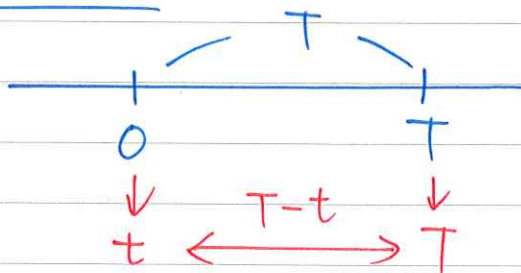
### ② Proof of $V_p$ : your exercise

#### ● Theta ( $\Theta$ )

$$\Theta_c = - \frac{S \sigma n(d_1)}{2\sqrt{T}} - r K e^{-rT} N(d_2)$$

$$\Theta_p = - \frac{S \sigma n(d_1)}{2\sqrt{T}} + r K e^{-rT} N(-d_2)$$

## (a) Proof of $\Theta_C$



$t \rightarrow t + \Delta t$  current time moves forward  
 $T \rightarrow T - \Delta T$  maturity time decreases!

$$\Theta_C = - \frac{\partial C}{\partial T}$$

$$= - S n(d_1) \frac{\partial d_1}{\partial T} - r k e^{-rT} N(d_2) + k e^{-rT} n(d_2) \frac{\partial d_2}{\partial T}$$

$$d_1 = d_2 + \sigma \sqrt{T}$$

$$\frac{\partial d_1}{\partial T} = \frac{\partial d_2}{\partial T} + \frac{\sigma}{2\sqrt{T}}$$

cancel out

$$= \frac{S \sigma n(d_1)}{2\sqrt{T}} - r k e^{-rT} N(d_2)$$

## (b) Proof of $\Theta_P$ = your exercise

● Rho ( $\rho$ )

$r$  usually doesn't change much!



$\frac{\partial \square}{\partial r} \Rightarrow$  this is not very useful!



$$p_c = \frac{\partial C}{\partial r} = K T e^{-rT} N(d_2)$$

$$p_p = \frac{\partial P}{\partial r} = -K T e^{-rT} N(-d_2)$$

① Proof of  $p_c$

$$p_c = \frac{\partial C}{\partial r} = S n(d_1) \frac{\partial d_1}{\partial r} + \underbrace{K T e^{-rT} N(d_2)}_{\text{Answer}}$$

$$- K e^{-rT} n(d_2) \frac{\partial d_2}{\partial r}$$

$$d_1 = d_2 + \sigma \sqrt{T}$$

$$\frac{\partial d_1}{\partial r} = \frac{\partial d_2}{\partial r}$$

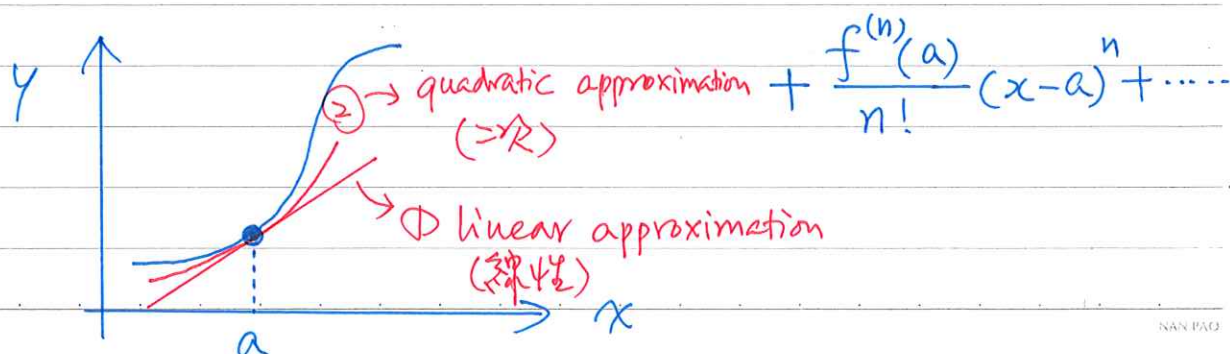
$$= K T e^{-rT} N(d_2)$$

② Proof of  $p_p$  : your exercise

③ Taylor series expansion

$$y = f(x)$$

$$f(x) = f(a) + f'(a)(x-a) + \frac{f''(a)}{2!}(x-a)^2 + \dots$$



① linear approximation

$$f(x) \cong f(a) + f'(a)(x-a)$$

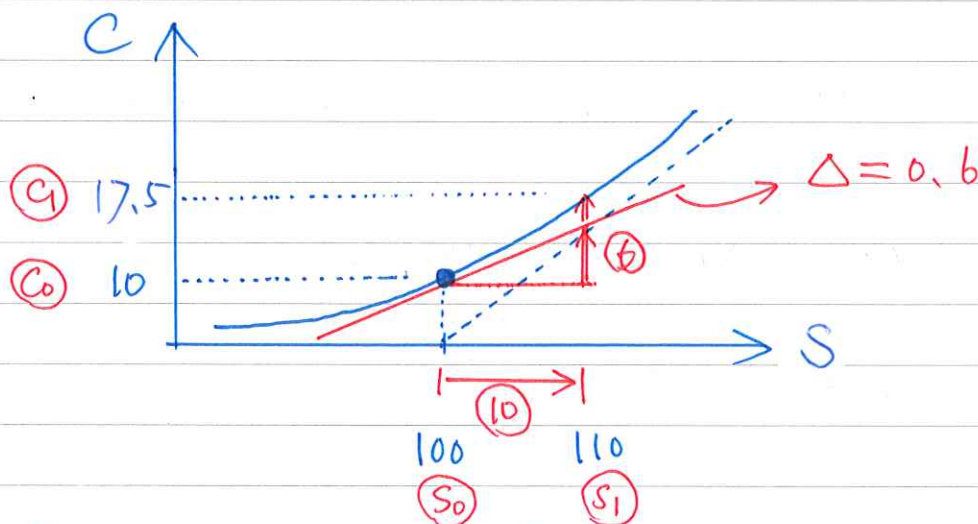
② quadratic approximation

$$f(x) \cong f(a) + f'(a)(x-a) + \frac{f''(a)}{2!}(x-a)^2$$

When we see  $C$  as a function of  $S$

$$C = f(S)$$

$$C = \underbrace{f(S_0)}_{C_0} + \underbrace{f'(S_0)}_{\frac{\partial C}{\partial S} = \Delta}(S - S_0) + \frac{\underbrace{f''(S_0)}_{\frac{\partial^2 C}{\partial S^2} = T}}{2!}(S - S_0)^2$$



$$S: S_0 \rightarrow S_1 (= S)$$

$$100 \quad 110$$

$$\Delta = 0.6$$

$$C: C_0 \rightarrow C_1 (= C)$$

$$10 \quad 17.5$$

$$T = 0.02$$



$$C - C_0 = \Delta C = \Delta (S - S_0) + \frac{T}{2} (S - S_0)^2$$

$\Delta C$  (above first  $\Delta$ )       $\Delta S$  (above  $\Delta$ )  
 $\Delta S$  (below  $(S - S_0)^2$ )

$$\textcircled{1} \quad \Delta C = \Delta \cdot \Delta S$$

$$\Delta C = 0.6 \times 10 = 6 \quad (10 \rightarrow 16)$$

$$\textcircled{2} \quad \Delta C = \Delta \cdot \Delta S + \frac{T}{2} \cdot (\Delta S)^2$$

$$\Delta C = 0.6 \times 10 + \frac{0.02}{2} \times (10)^2 = 7 \quad (10 \rightarrow 17)$$

③ In reality

$$\Delta C = 7.5 \quad (10 \rightarrow 17.5)$$

● Multivariate function

$$z = f(x, y)$$

$$f(x, y) = f(x_0, y_0) + \frac{\partial f}{\partial x} (x - x_0) + \frac{\partial f}{\partial y} (y - y_0)$$

$\downarrow$        $\downarrow$   
 $a$        $b$

$$+ \frac{1}{2} \frac{\partial^2 f}{\partial x^2} (x - x_0)^2 + \frac{\partial^2 f}{\partial x \partial y} (x - x_0)(y - y_0) + \frac{1}{2} \frac{\partial^2 f}{\partial y^2} (y - y_0)^2$$

$$\Rightarrow \Delta f = \frac{\partial f}{\partial x} \Delta x + \frac{\partial f}{\partial y} \Delta y$$

$$+ \frac{1}{2} \frac{\partial^2 f}{\partial x^2} (\Delta x)^2 + \frac{\partial^2 f}{\partial x \partial y} (\Delta x)(\Delta y) + \frac{1}{2} \frac{\partial^2 f}{\partial y^2} (\Delta y)^2$$

In fact,  $C$  is a fn of  $S, \sigma, T, r$

$$C = f(S, \sigma, T, r)$$

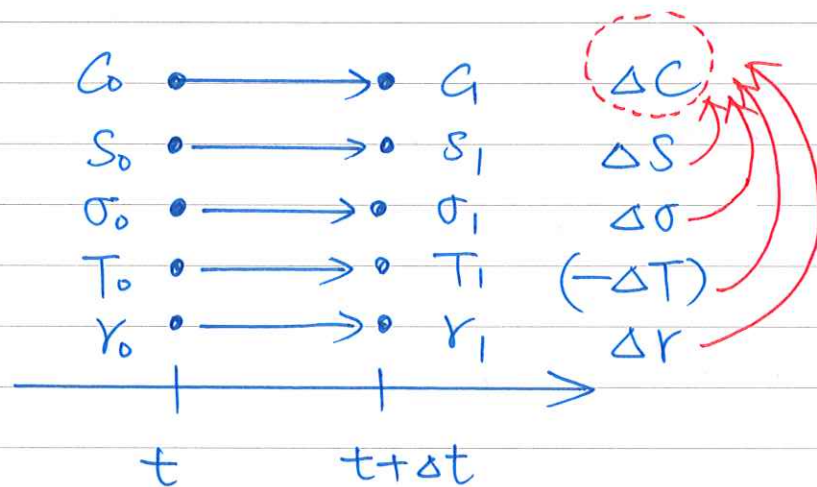
↑ don't need to consider  $K$   
( $\because K = \text{constant}$ )

$$\Delta C = \underbrace{\frac{\partial f}{\partial S}}_{\Delta} (\Delta S) + \frac{1}{2} \underbrace{\frac{\partial^2 f}{\partial S^2}}_T (\Delta S)^2$$

$$+ \underbrace{\frac{\partial f}{\partial \sigma}}_{\downarrow} (\Delta \sigma) + \underbrace{\left(-\frac{\partial f}{\partial T}\right)}_{(H)} (-\Delta T) + \underbrace{\frac{\partial f}{\partial r}}_{\rho} (\Delta r)$$

+ ... (cross terms, high order terms) ...

Idea :



In a small time interval, everything can change

$$\Delta C = \Delta \cdot (\Delta S) + \frac{T}{2} (\Delta S)^2$$

$$+ \downarrow \cdot (\Delta \sigma) + (H) (-\Delta T) + \rho \cdot (\Delta r)$$

(change in each factor can contribute to  $\Delta C$ )

↓  
 $T = 10 \rightarrow 9$   
 $\Delta T = -1, -\Delta T = 1$