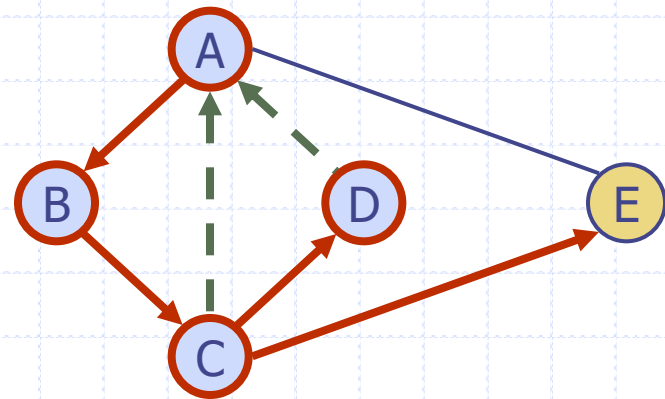


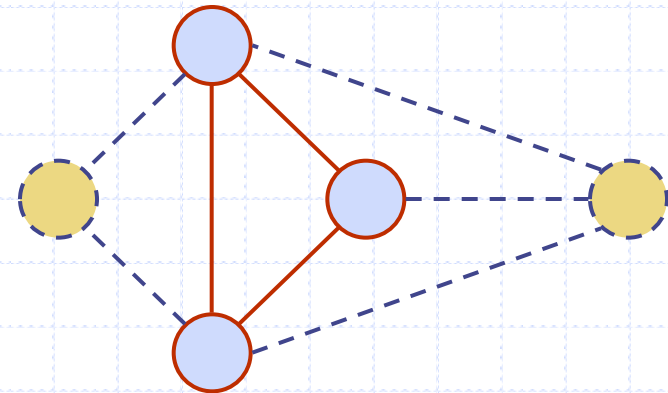
Presentation for use with the textbook **Data Structures and Algorithms in Java, 6<sup>th</sup> edition**, by M. T. Goodrich, R. Tamassia, and M. H. Goldwasser, Wiley, 2014

# Depth-First Search

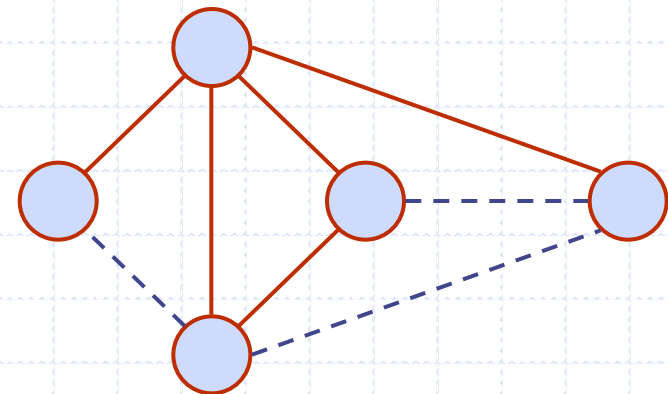


# Subgraphs

- A subgraph  $S$  of a graph  $G$  is a graph such that
  - The vertices of  $S$  are a subset of the vertices of  $G$
  - The edges of  $S$  are a subset of the edges of  $G$
- A spanning subgraph of  $G$  is a subgraph that contains all the vertices of  $G$



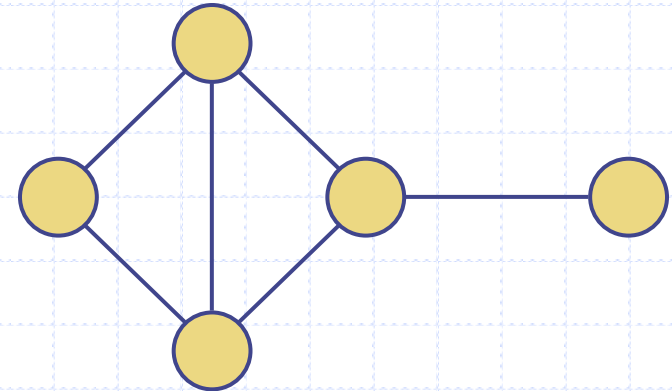
Subgraph



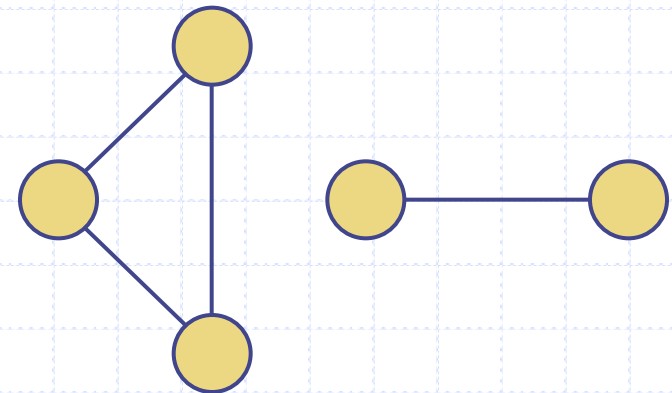
Spanning subgraph

# Connectivity

- A graph is connected if there is a path between every pair of vertices
- A connected component of a graph  $G$  is a maximal connected subgraph of  $G$



Connected graph



Non connected graph with two connected components

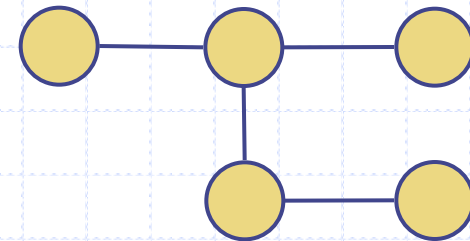
# Trees and Forests

- A (free) tree is an undirected graph  $T$  such that

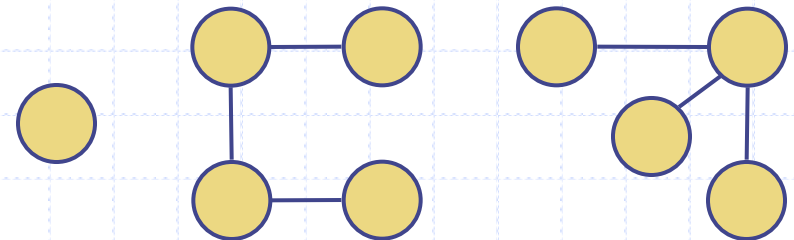
- $T$  is connected
- $T$  has no cycles

This definition of tree is different from the one of a rooted tree

- A forest is an undirected graph without cycles
- The connected components of a forest are trees



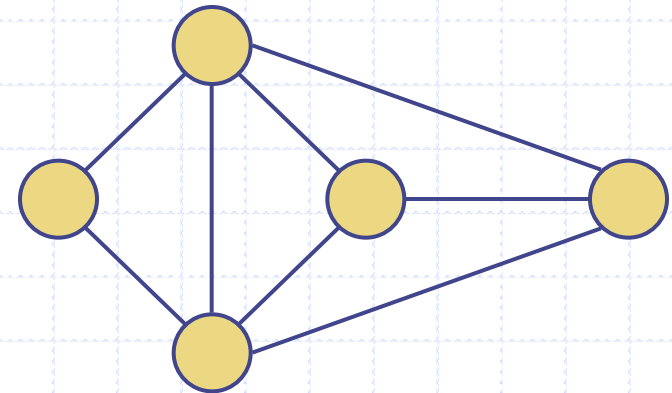
Tree



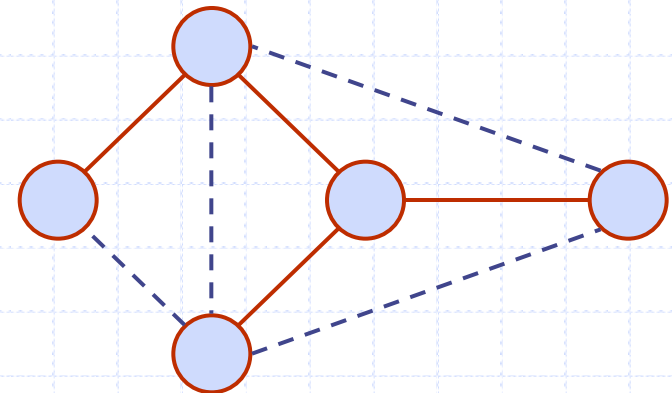
Forest

# Spanning Trees and Forests

- ❑ A spanning tree of a connected graph is a spanning subgraph that is a tree
- ❑ A spanning tree is not unique unless the graph is a tree
- ❑ Spanning trees have applications to the design of communication networks
- ❑ A spanning forest of a graph is a spanning subgraph that is a forest



Graph



Spanning tree

# Depth-First Search

- Depth-first search (DFS) is a general technique for traversing a graph
- A DFS traversal of a graph  $G$ 
  - Visits all the vertices and edges of  $G$
  - Can determine whether  $G$  is connected
  - Can compute the connected components of  $G$
  - Can compute a spanning forest of  $G$
- DFS can be further extended to solve other graph problems
  - Find and report a path between two given vertices
  - Find a cycle in the graph

# DFS Algorithm from a Vertex

**Algorithm** DFS( $u$ )

**In:** Vertex  $u$  of a graph  $G$

**Out:** {DFS traversal of  $G$  starting at  $u$ }

Mark ( $u$ )

**For** each edge  $(u,v)$  incident on  $u$  **do**

**if**  $(u,v)$  is not labelled **then**

**if**  $v$  is not marked **then** {

            Label  $(u,v)$  as “discovery edge”

            DFS( $v$ )

        }

**else** label  $(u,v)$  as “back edge”

# Example

A

unexplored vertex

A

visited vertex

—

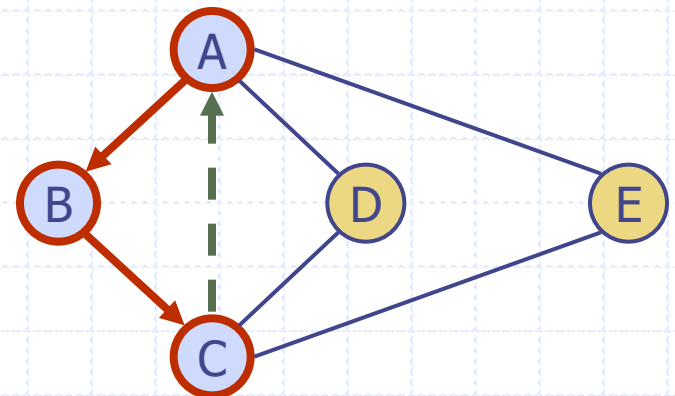
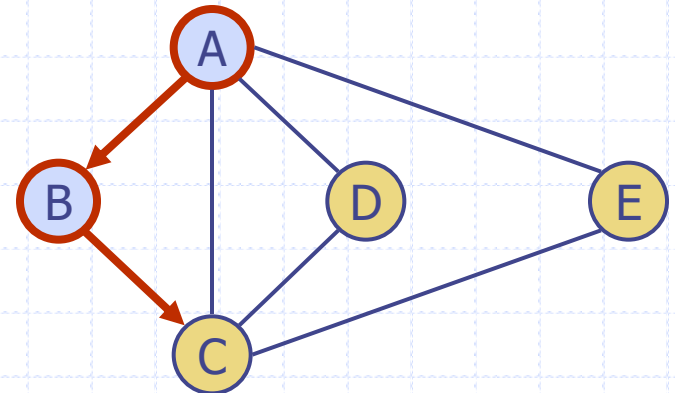
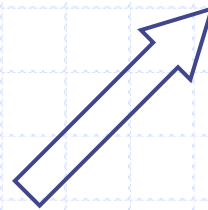
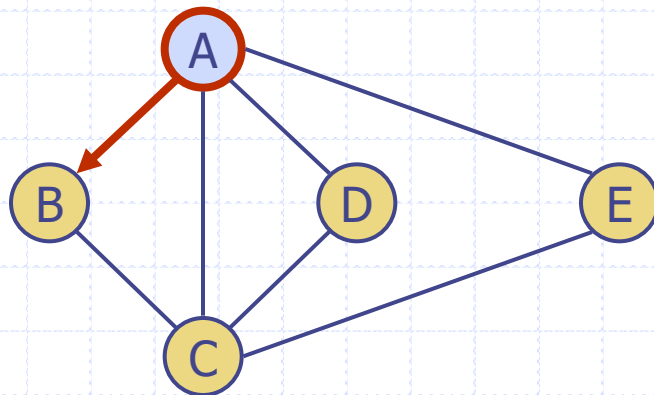
unexplored edge

→

discovery edge

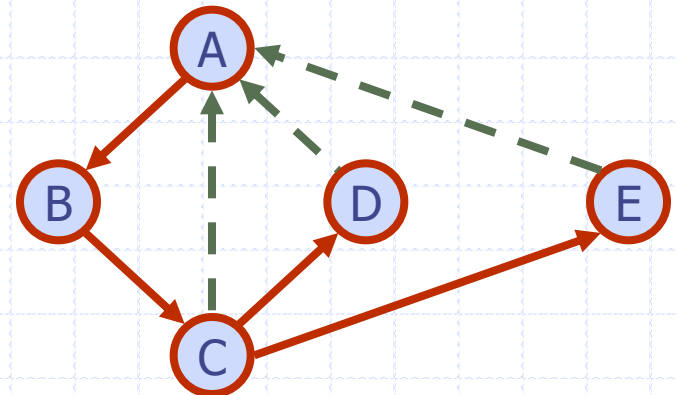
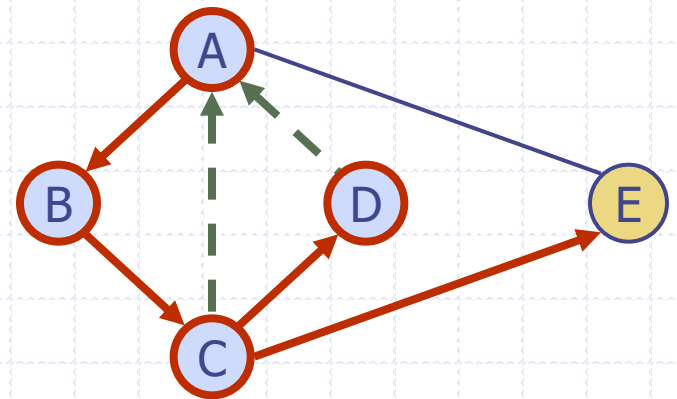
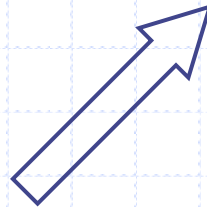
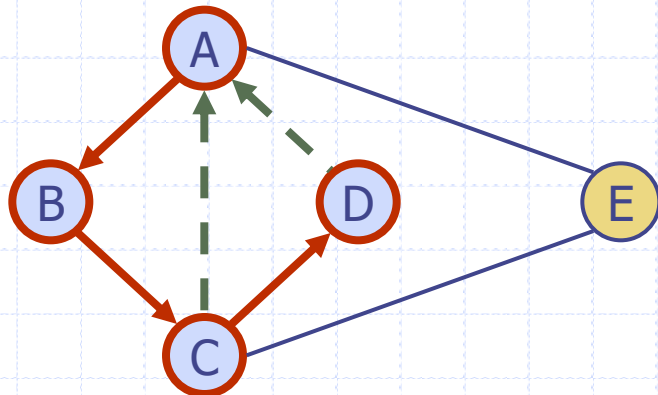
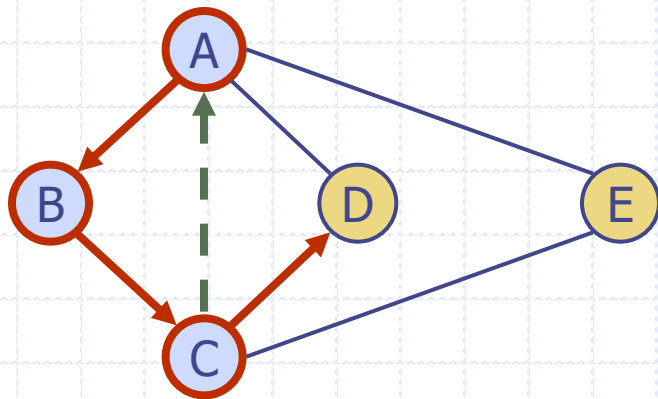
- - -

back edge





# Example (cont.)



-

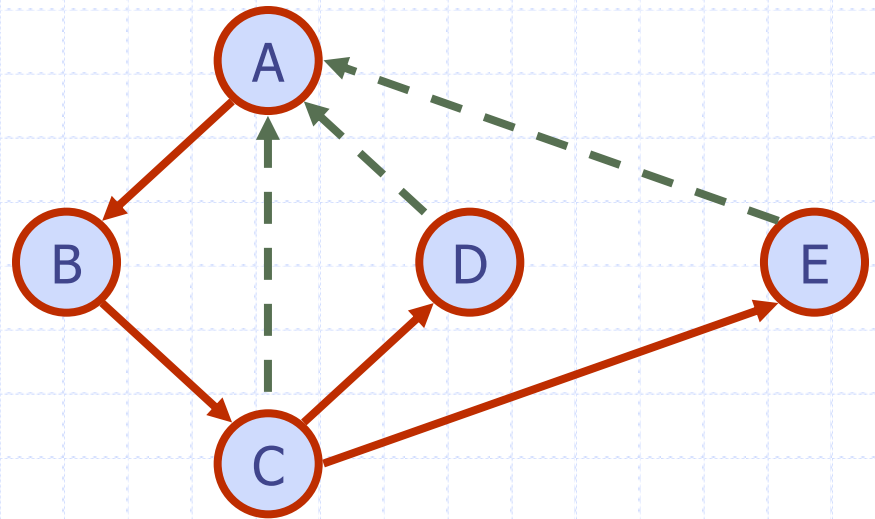
# Properties of DFS

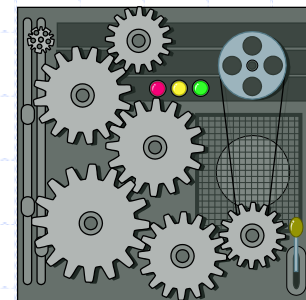
## Property 1

$DFS(G, v)$  visits all the vertices and edges in the connected component of  $v$

## Property 2

The discovery edges labeled by  $DFS(G, v)$  form a spanning tree of the connected component of  $v$  called a **DFS tree**





# Analysis of DFS

- ❑ Setting/getting a vertex/edge label takes  $O(1)$  time
- ❑ Each vertex is labeled twice
  - once initialized as UNEXPLORED
  - once as **VISITED**
- ❑ Each edge is labeled twice
  - once initialized as UNEXPLORED
  - once as **DISCOVERY** or **BACK**
- ❑ Method incidentEdges is called once for each vertex
- ❑ DFS runs in  $O(n + m)$  time provided the graph is represented by the adjacency list structure and it runs in  $O(n^2)$  time if the graph is stored in an adjacency matrix.

# Path Finding



- We can specialize the DFS algorithm to find a path between two given vertices  $u$  and  $z$
- We call  $DFS(u)$  with  $u$  as the start vertex
- We use a stack  $S$  to keep track of the path between the start vertex and the current vertex
- As soon as destination vertex  $z$  is encountered, we return the path as the contents of the stack

**Algorithm** *pathDFS*( $G, v, z$ )

*Mark*( $v$ )

*S.push*( $v$ )

**if**  $v = z$

**return true**

**for all** edges  $(v, w)$  incident on  $v$  **do**

**if**  $w$  *is not marked* **then**

**if** *pathDFS*( $G, w, z$ ) **then**

**return true**

*S.pop*( $v$ )

**return false**