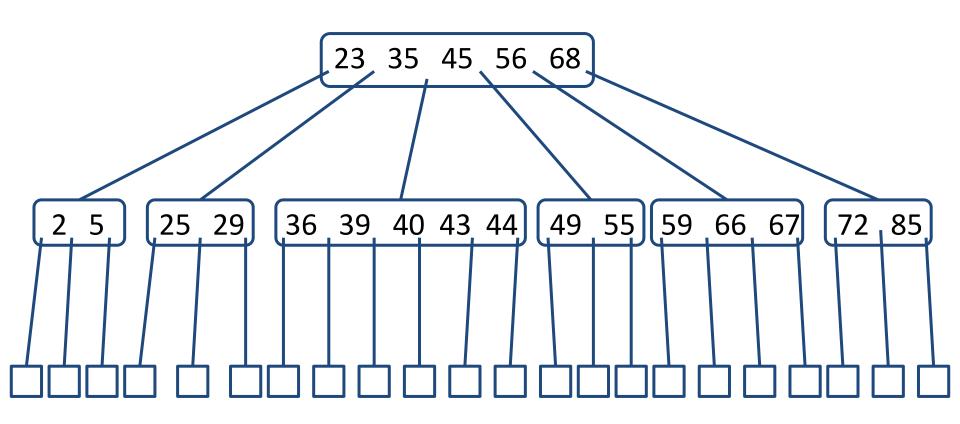
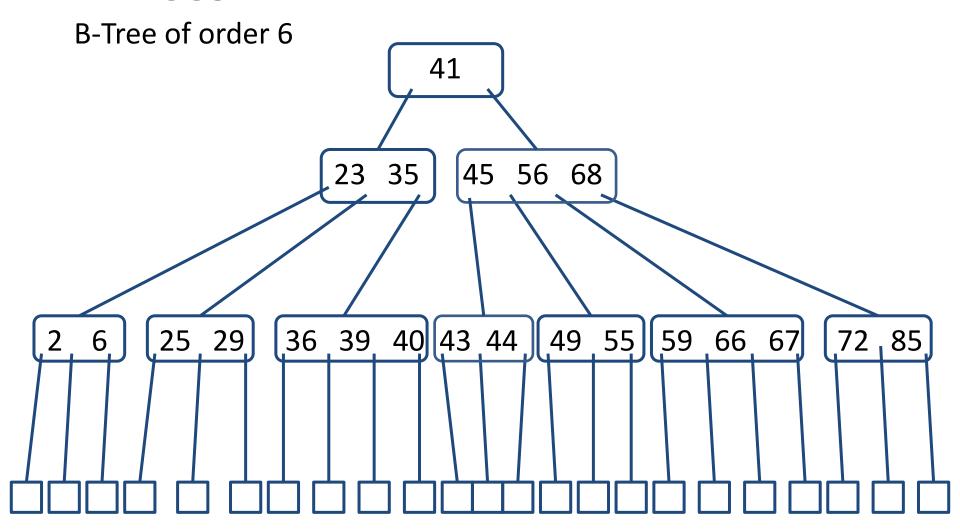
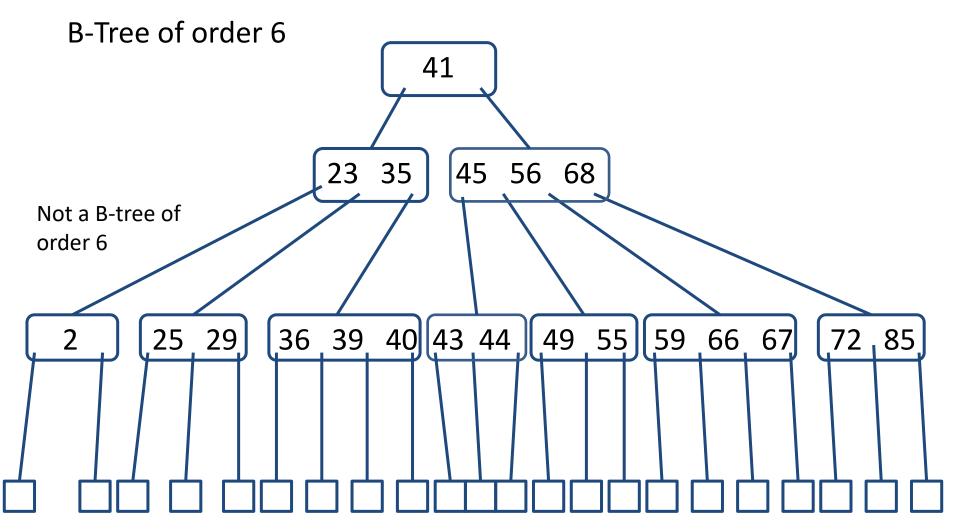
A B-tree of order *d* is a multiway search tree with the following properties:

- The root has at least 2 children and at most d.
- All internal nodes other than the root have at least  $\left| \frac{a}{2} \right|$  and at most d children
- All the leaves are at the same level

B-Tree of order 6



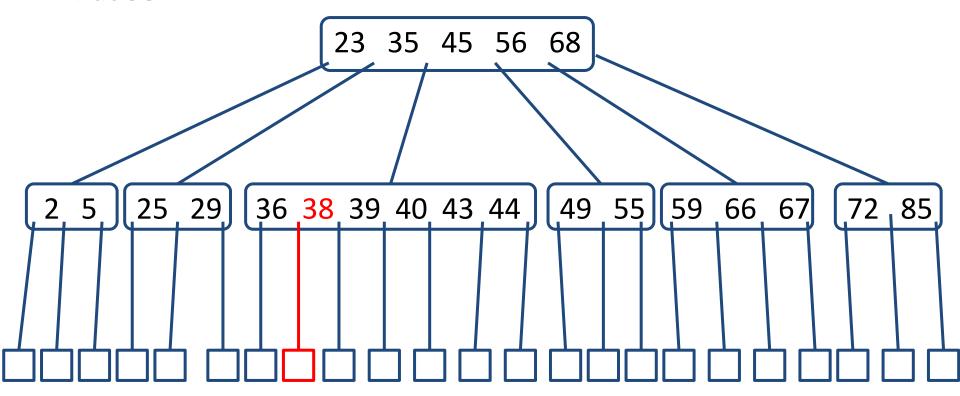




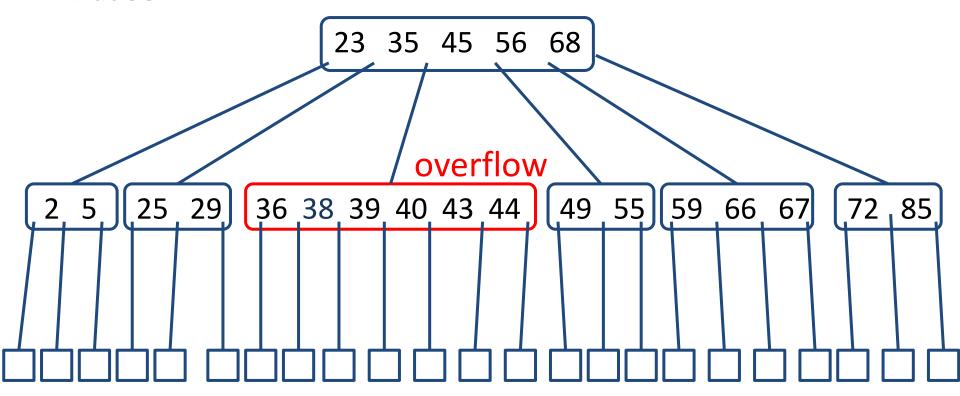
# What is the Maximum Height of a B-Tree?

Height is O(log<sub>d</sub> n)

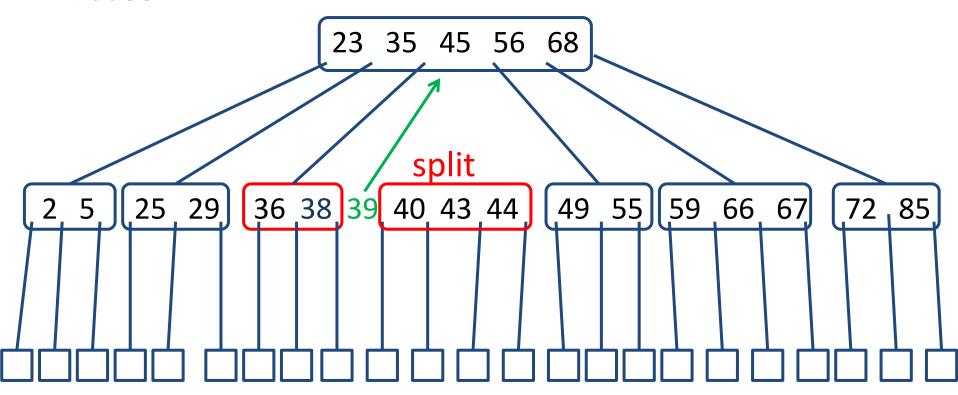
B-Tree of order 6



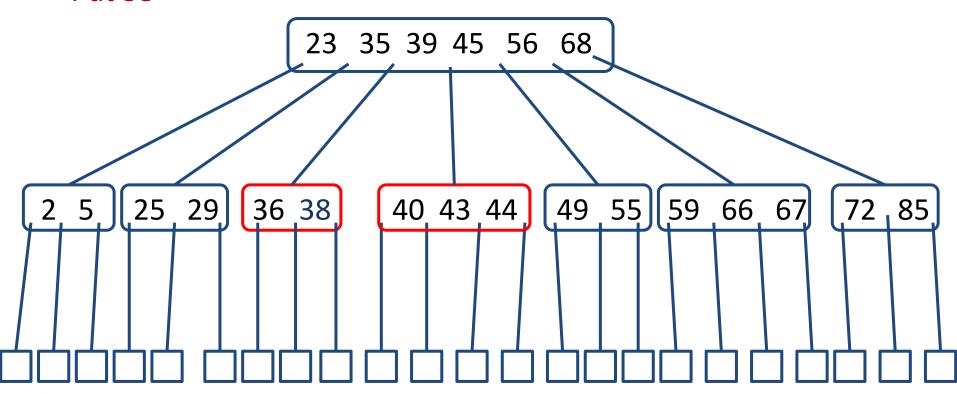
B-Tree of order 6



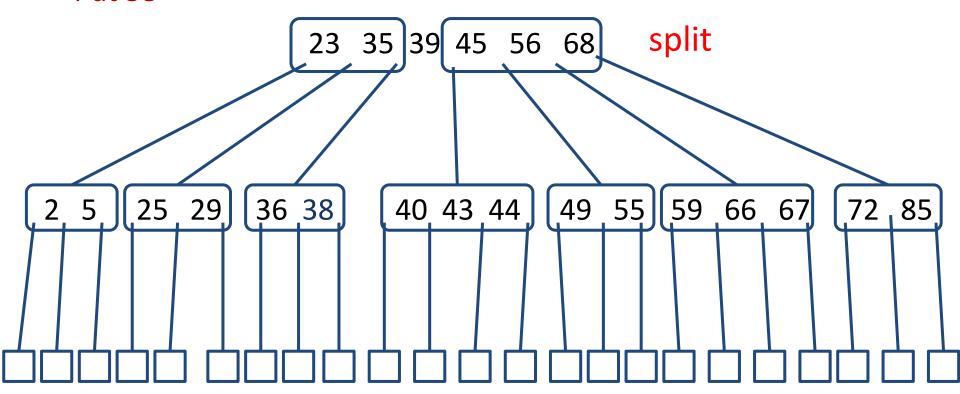
B-Tree of order 6

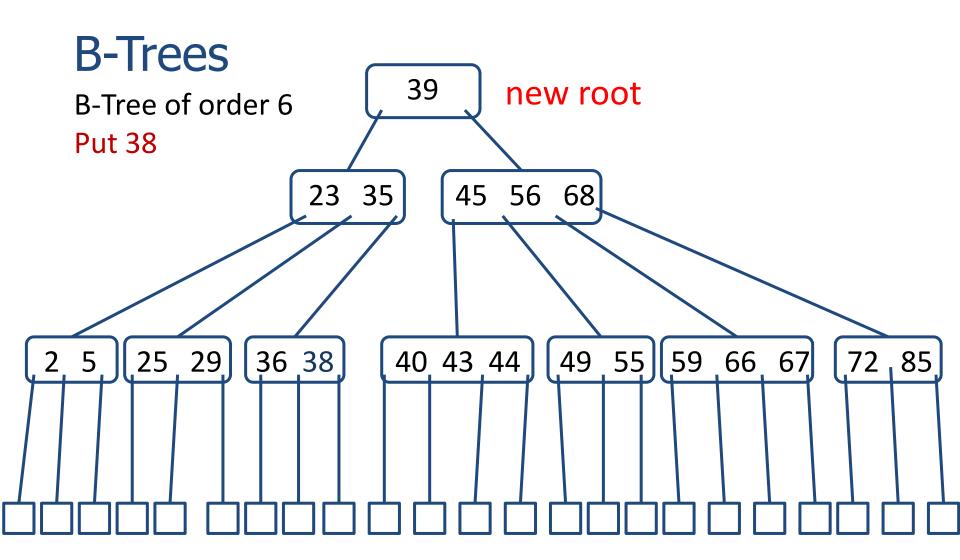


B-Tree of order 6



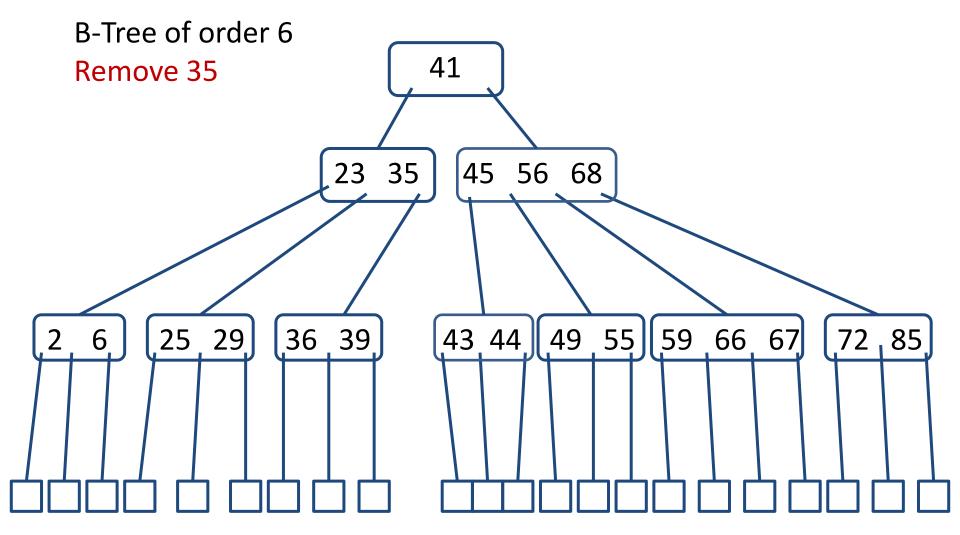
B-Tree of order 6

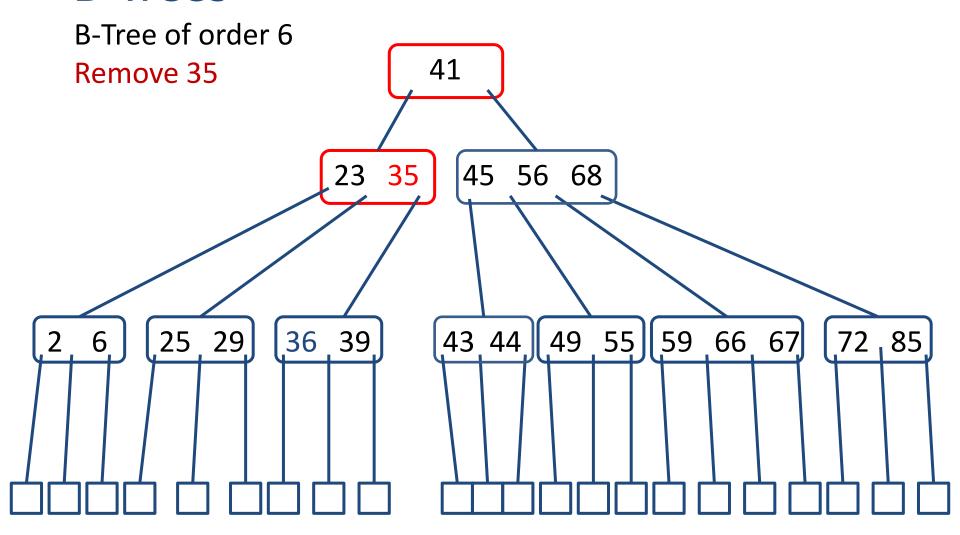


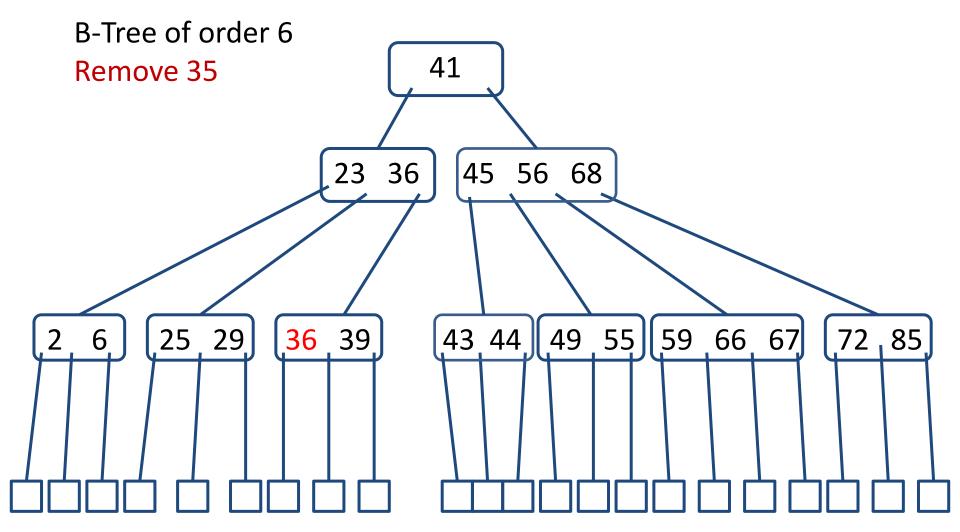


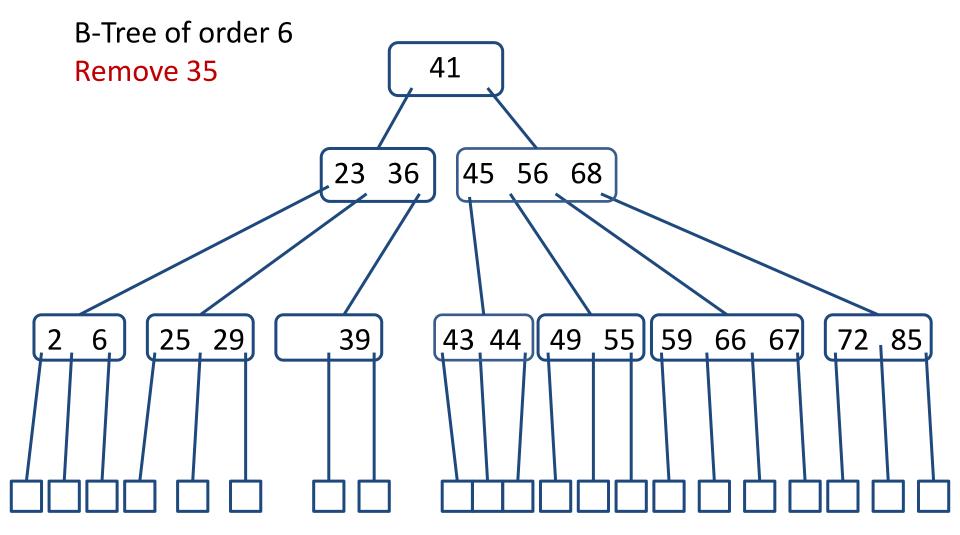
```
Algorithm put (r,k,o)
In: Root r of a B-tree, data item (k,o)
Out: {Insert data item (k,o) in the B-tree
   Search for k to find the lowest insertion internal node v
   Add the new data item (k, o) at node v
   while node v overflows do {
      if v is the root then
            Create a new empty root and set as parent of v
      Split v around the middle key k', move k' to parent, and
      update parent's children
      v \leftarrow \text{parent of } v
```

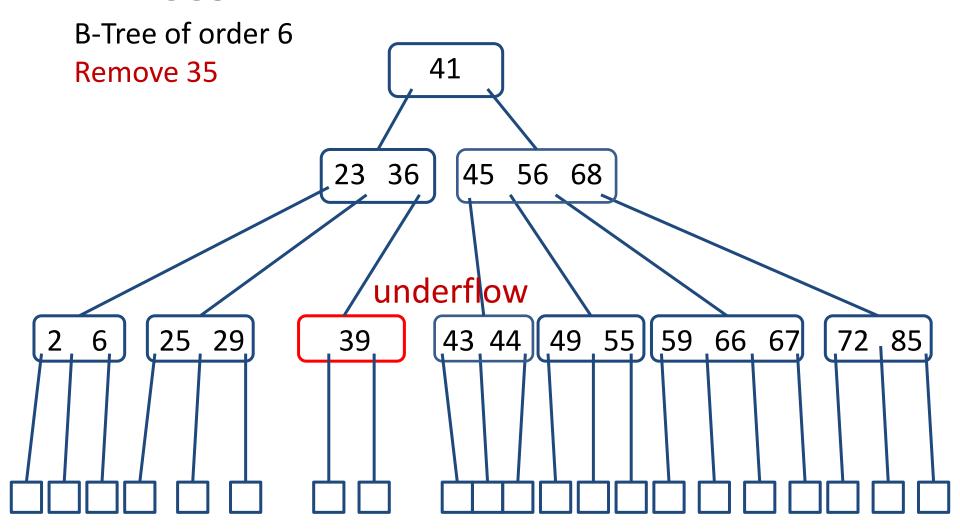
```
Algorithm put (r,k,o)
In: Root r of a B-tree, data item (k,o)
Out: {Insert data item (k,o) in the B-tree
                                                           O(\log d \times \log_d n)
    Search for k to find the lowest insertion internal node v
   Add the new data item (k, o) at node v
                                                         O(d)
   while node v overflows do {
      if v is the root then
                                                         O(d)
            Create a new empty root and set as parent of v
      Split v around the middle key k', move k' to parent, and
      update parent's children
      v \leftarrow \text{parent of } v
 Time complexity of put is O(d log<sub>d</sub> n)
```

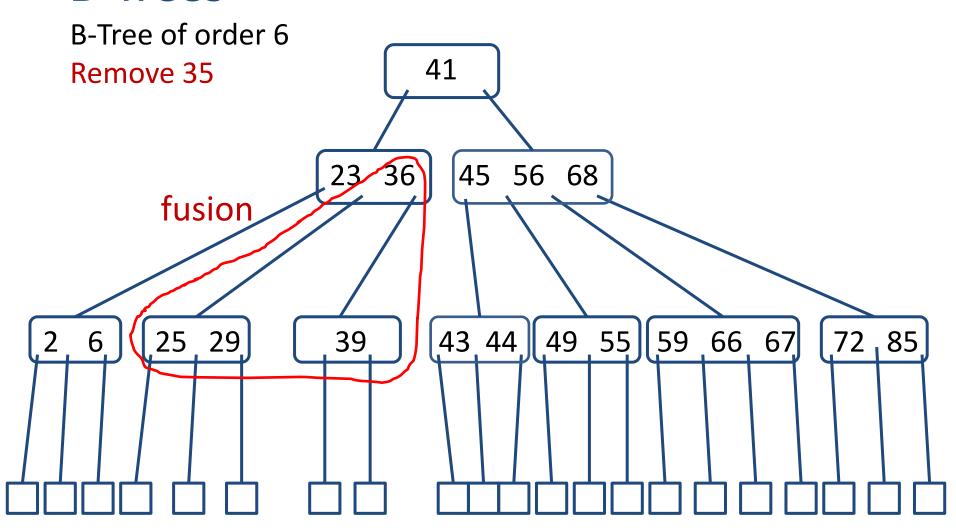


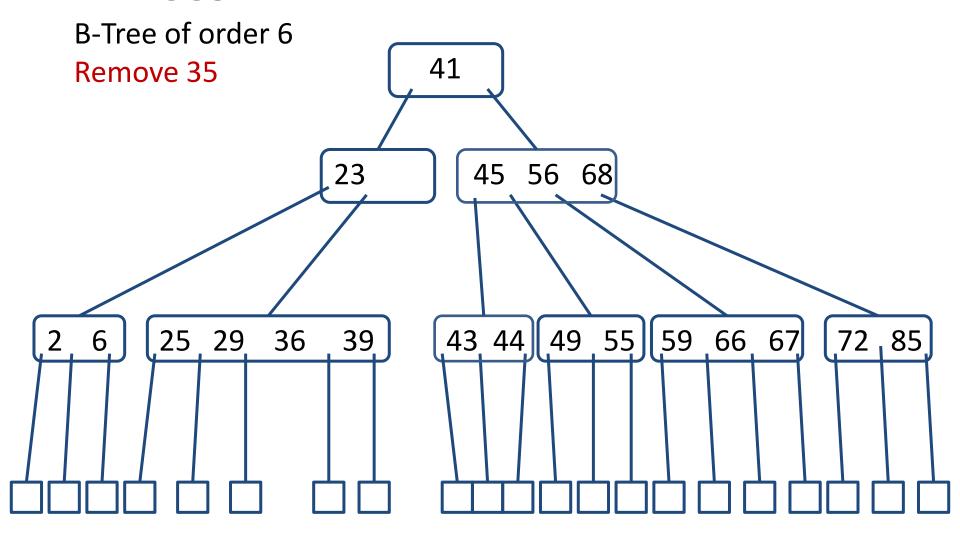


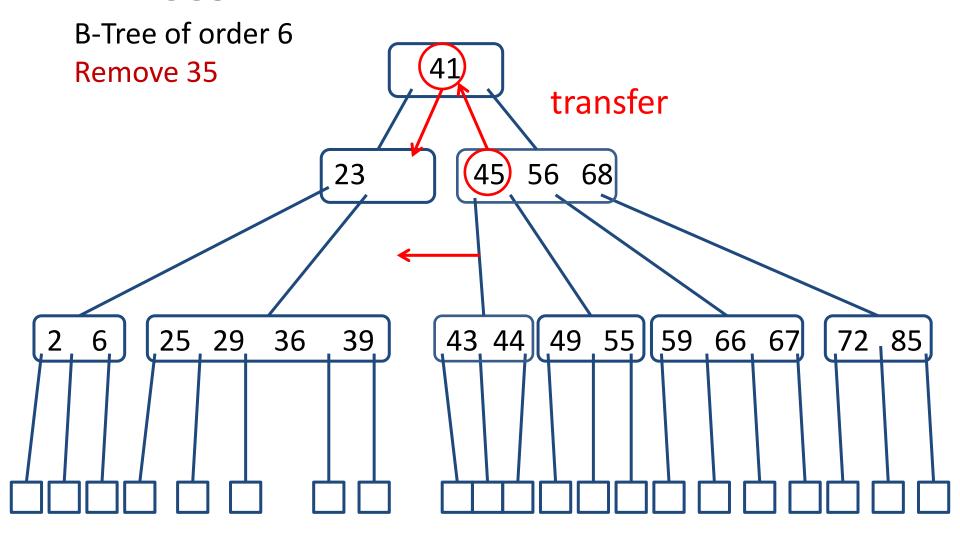


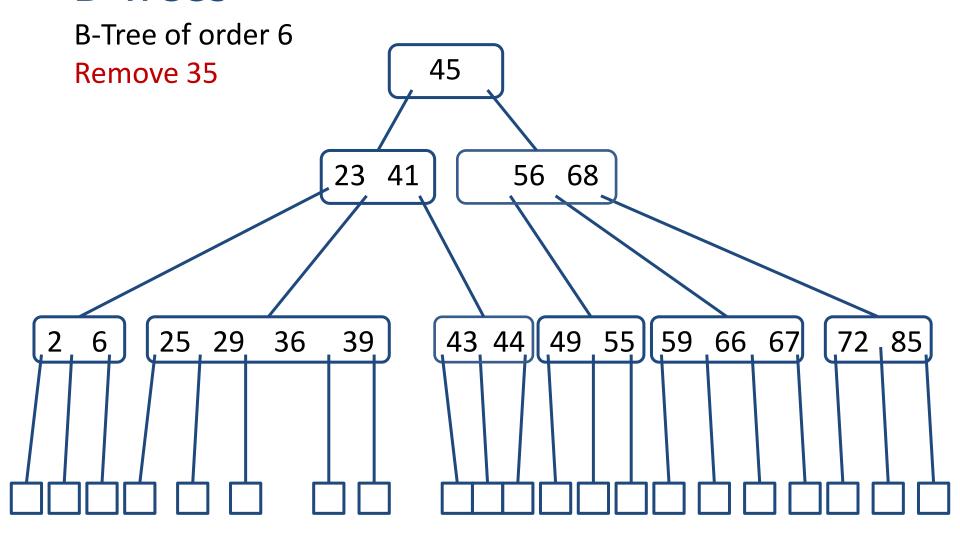












```
Algorithm remove(r,k)
In: Root r of a B-tree, key k
Out: {remove data item with key k from the tree}
   Find the node v storing key k
   Remove (k, o) from v replacing it with successor if needed
   while node v underflows do {
      if v is the root then
           make the first child of v the new root
      else if a sibling has more than \lceil d/2 \rceil keys then
                perform a transfer operation
            else {
                perform a fusion operation
                v \leftarrow \text{parent of } v
```

23

```
Algorithm remove(r,k)
                                   Time complexity O(d log<sub>d</sub> n)
   In: Root r of a B-tree, key k
   Out: {remove data item with key k from the tree}
                                                        \vdash O(log d × log<sub>d</sub> n)
       Find the node v storing key k
       Remove (k, o) from v replacing it with successor if needed
       while node v underflows do {
                                                               O(d + \log d \times \log_d n)
          if v is the root then
               make the first child of v the new root
O(d \log_d n)
          else if a sibling has at least \lceil d/2 \rceil keys then
                                                              O(d)
                     perform a transfer operation
                else {
                     perform a fusion operation
                     v \leftarrow \text{parent of } v
                                      24
```

#### **Disk Blocks**

- Consider the problem of maintaining a large collection of items that does not fit in main memory, such as a typical database.
- In this context, we refer to the external memory is divided into blocks, which we call disk blocks.
- The transfer of a block between external memory and primary memory is a disk transfer or I/O.
- There is a great time difference that exists between main memory accesses and disk accesses
- Thus, we want to minimize the number of disk transfers needed to perform a query or update. We refer to this count as the I/O complexity of the algorithm involved.

# **Memory Hierarchies**

- Computers have a hierarchy of different kinds of memories, which vary in terms of their size and distance from the CPU.
- Closest to the CPU are the internal registers. Access to such locations is very fast, but there are relatively few such locations.
- At the second level in the hierarchy are the memory caches.
- At the third level in the hierarchy is the internal memory, which is also known as main memory or core memory.
- Another level in the hierarchy is the external memory, which usually consists of disks.

