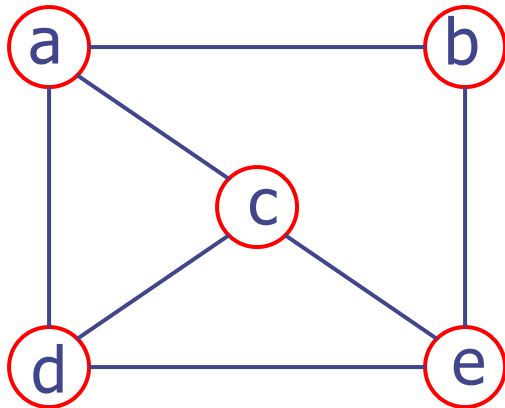


Graphs

A graph is a pair (V, E) , where

- V is a set of **nodes** or **vertices**
- E is a collection of pairs of vertices (u,v) , called **edges**, **links**, or **arcs**



$$V = \{a, b, c, d, e\}$$

$$E = \{(a,b), (a,c), (a,d), (b,e), (c,d), (c,e), (d,e)\}$$

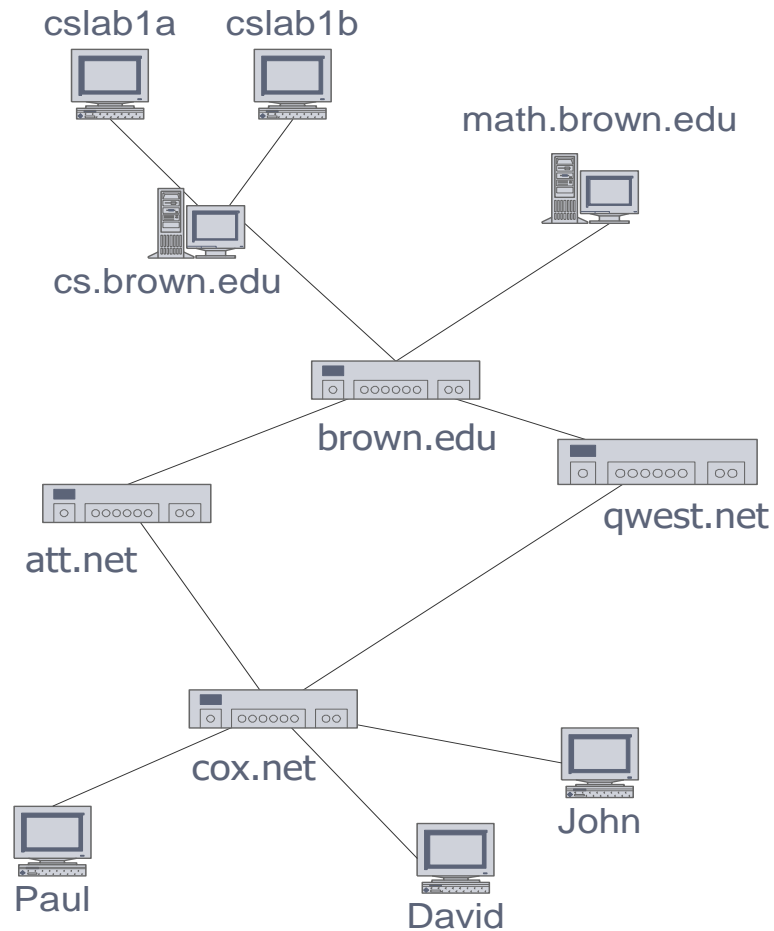
Edge Types

- ❑ Directed edge
 - ordered pair of vertices (u,v)
 - first vertex u is the origin
 - second vertex v is the destination
- ❑ Undirected edge
 - unordered pair of vertices (u,v)
- ❑ Directed graph or digraph
 - all the edges are directed
- ❑ Undirected graph
 - all the edges are undirected
- ❑ Mixed graph
 - directed and undirected edges



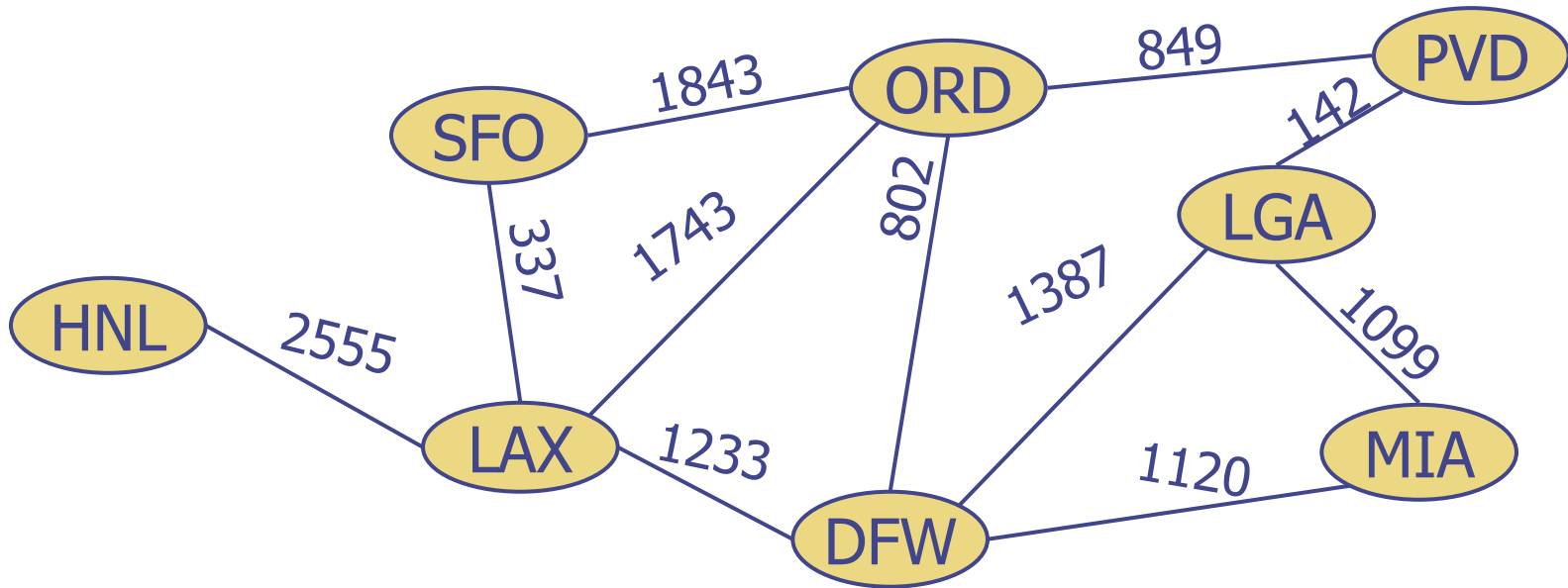
Applications

- Computer networks



Applications

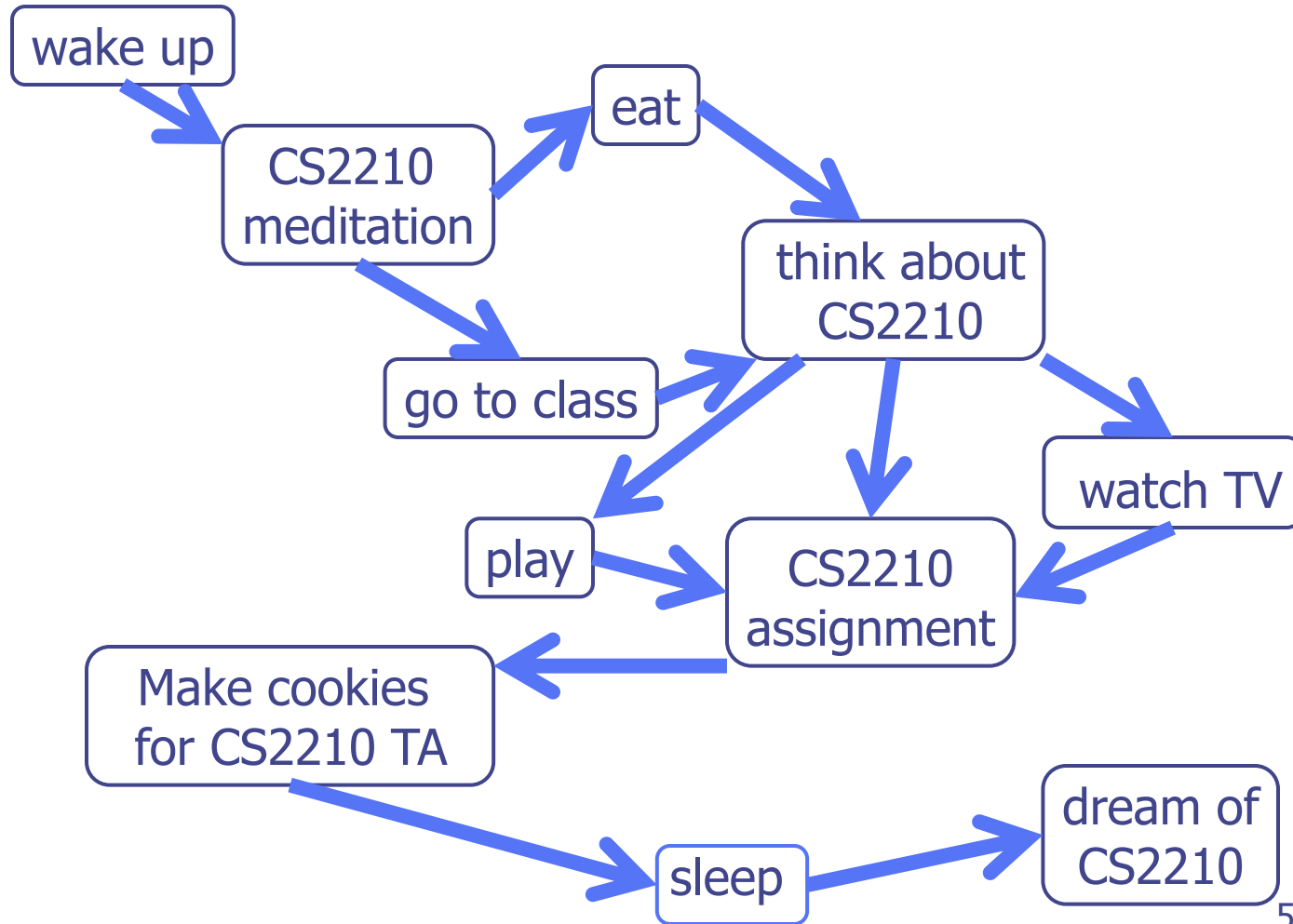
- Transportation networks



Applications

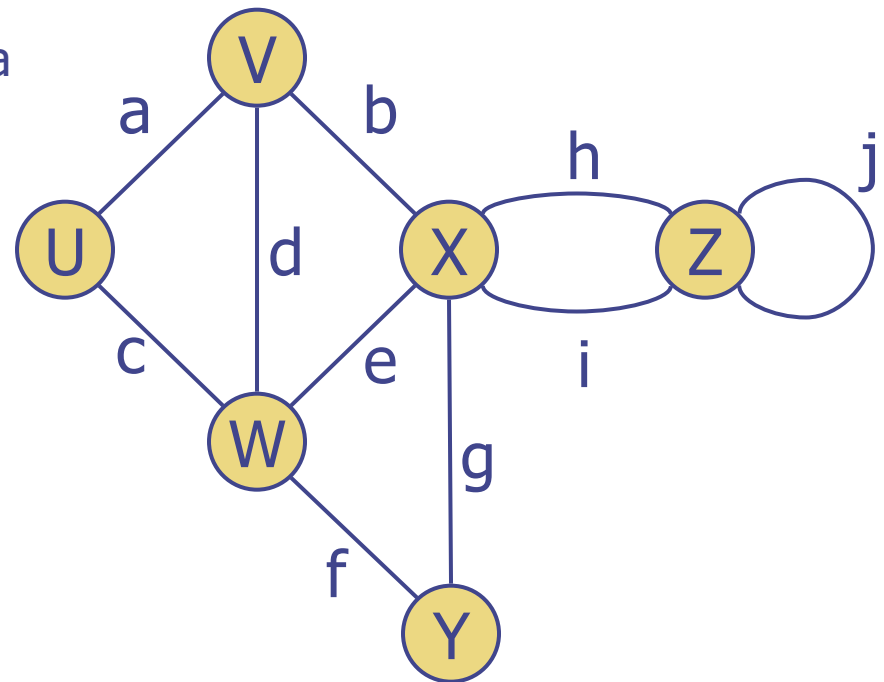
- Scheduling tasks

A typical student day



Terminology

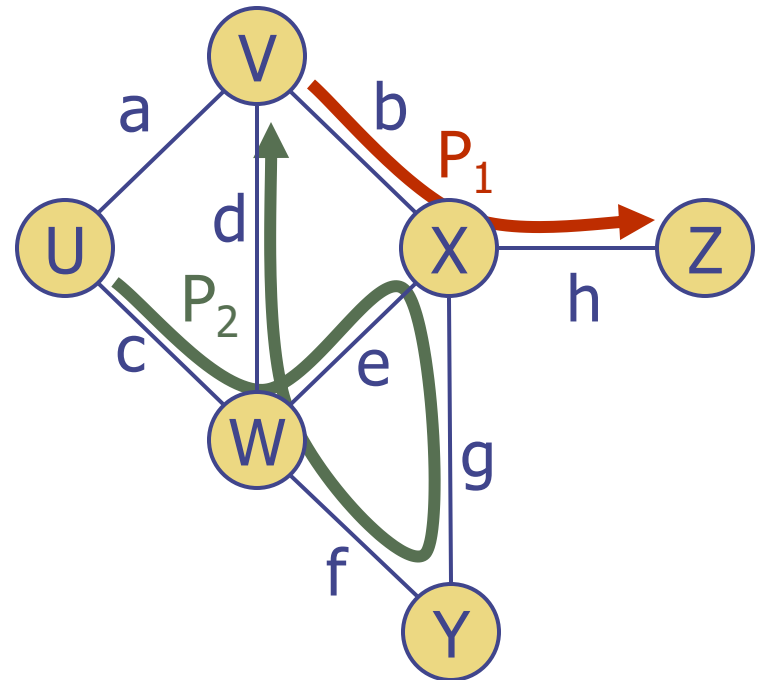
- End vertices (or endpoints) of an edge
 - U and V are the endpoints of a
- Edges incident on a vertex
 - a, d, and b are incident on V
- Adjacent vertices
 - U and V are adjacent
- Degree of a vertex
 - X has degree 5
- Parallel edges
 - h and i are parallel edges
- Self-loop
 - j is a self-loop



A graph without parallel edges or self-loops is called a simple graph

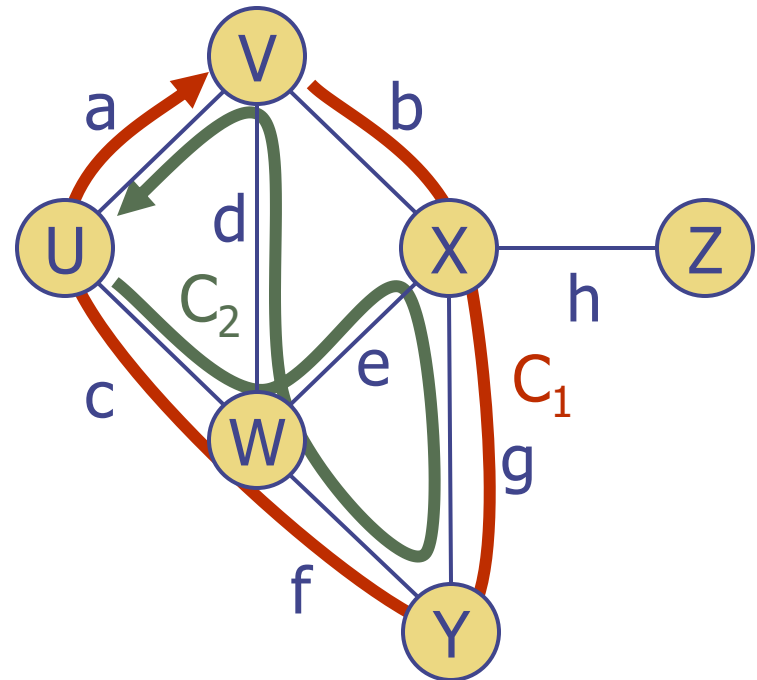
Terminology

- Path
 - sequence of adjacent vertices
- Simple path
 - path such that all its vertices and edges are distinct
- Examples
 - $P_1 = (V, X, Z)$ is a simple path
 - $P_2 = (U, W, X, Y, W, V)$ is a path that is not simple



Terminology

- Cycle
 - circular sequence of adjacent vertices
- Simple cycle
 - cycle such that all its vertices are distinct (except first and last)
- Examples
 - $C_1 = (V, X, Y, W, U, V)$ is a simple cycle
 - $C_2 = (U, W, X, Y, W, V, U)$ is a cycle that is not simple



Properties

Notation

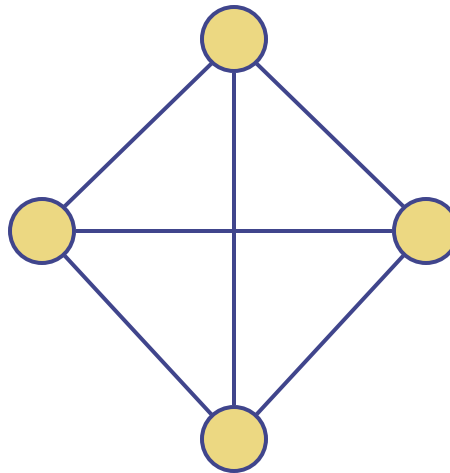
n number of vertices

m number of edges

$\deg(v)$ degree of vertex v

Property 1

$$\sum_v \deg(v) = 2m$$

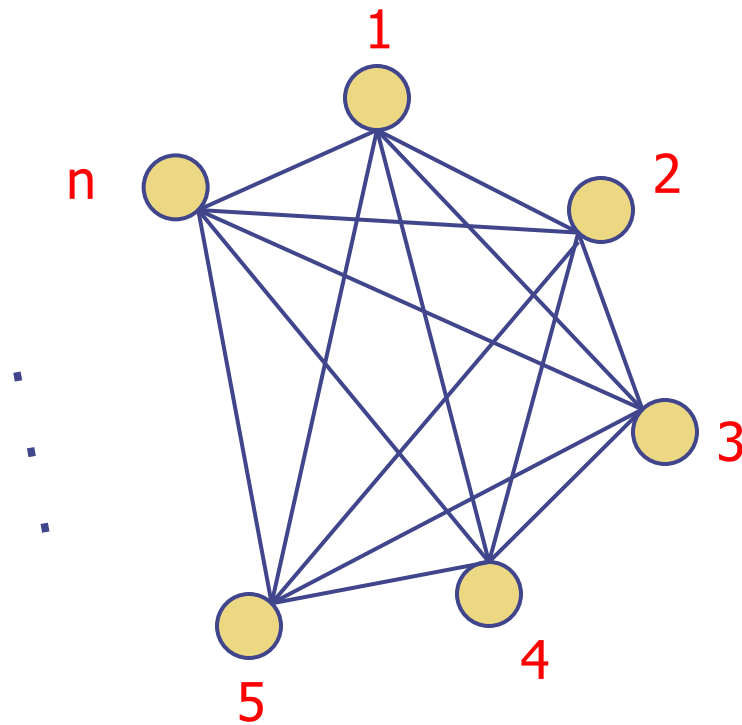


Example

- $n = 4$
- $m = 6$
- $\deg(v) = 3$
- $\sum_v \deg(v) = 12$

Complete Graph or Clique

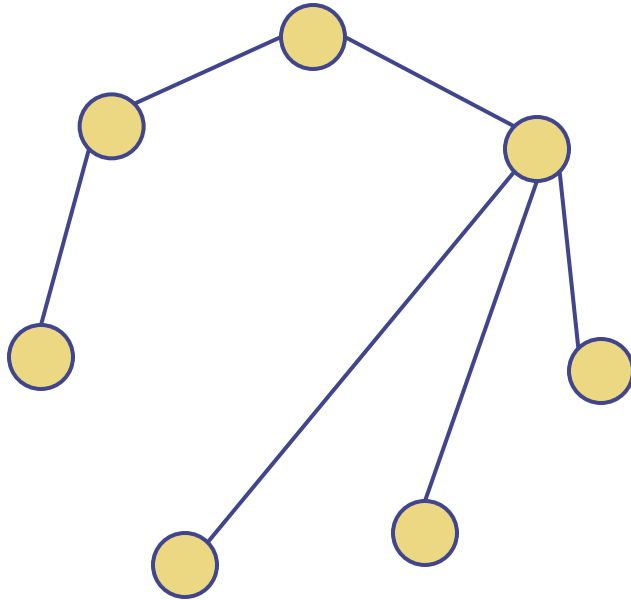
Each vertex is connected to every other vertex.



$$m = n(n-1)/2$$

Trees

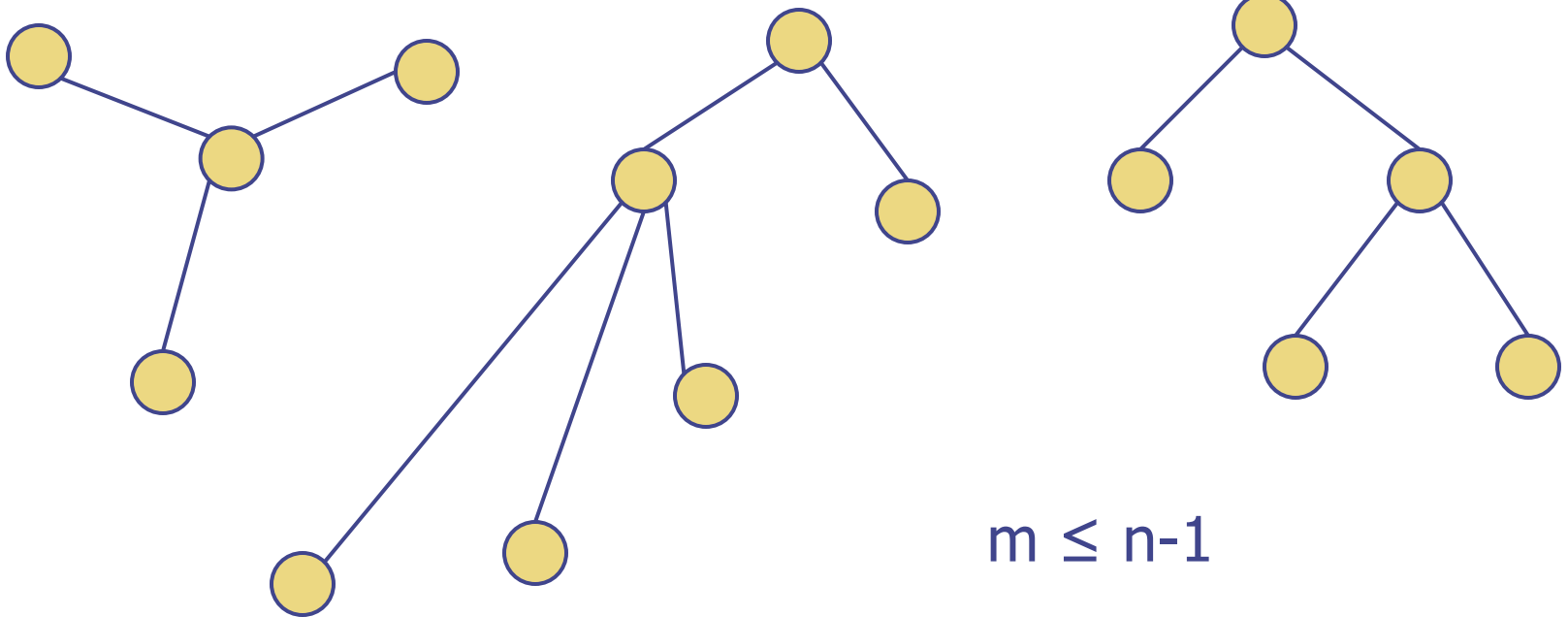
A tree is a graph without cycles.



$$m = n - 1$$

Forest

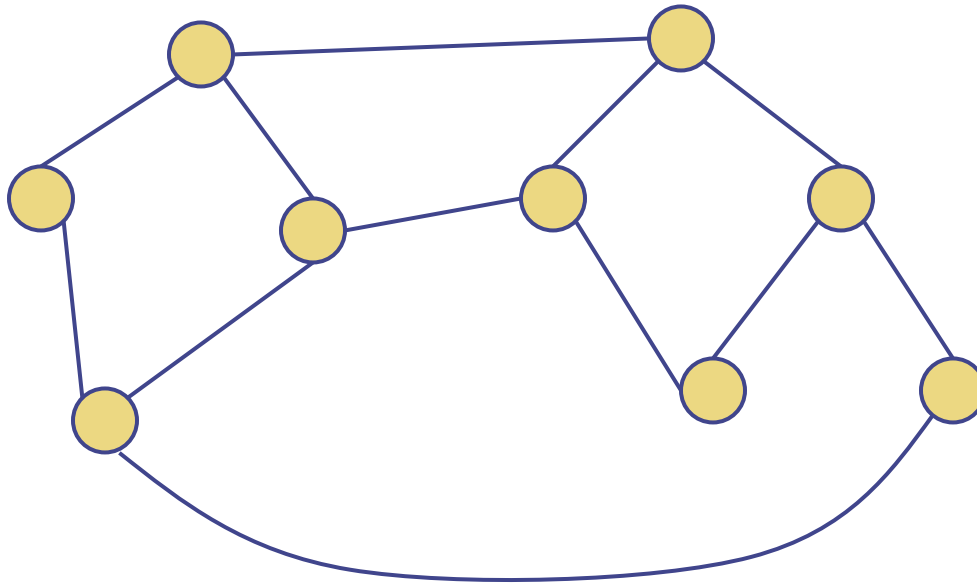
A forest is a set of trees.



$$m \leq n-1$$

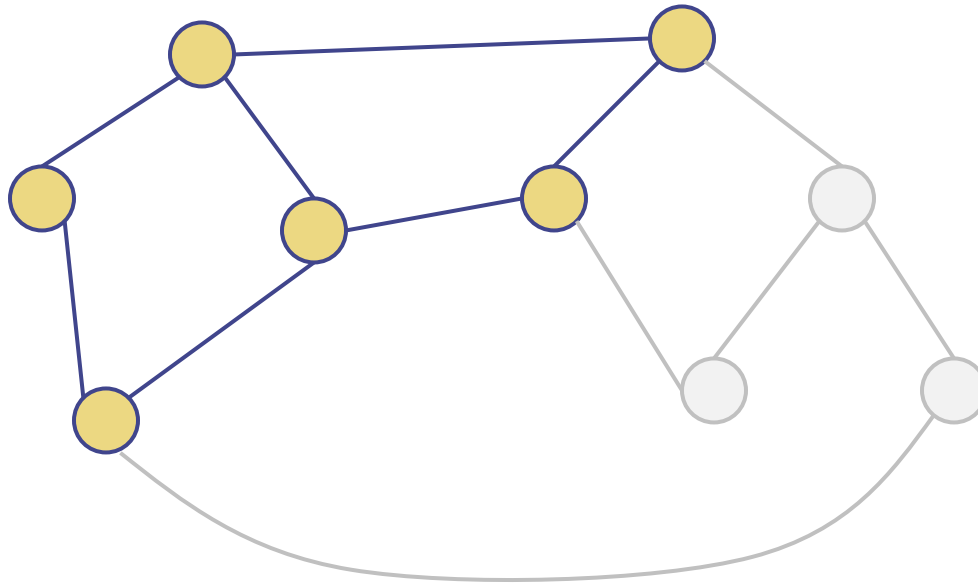
Subgraph

A subgraph is a subset of vertices and edges that forms a graph.



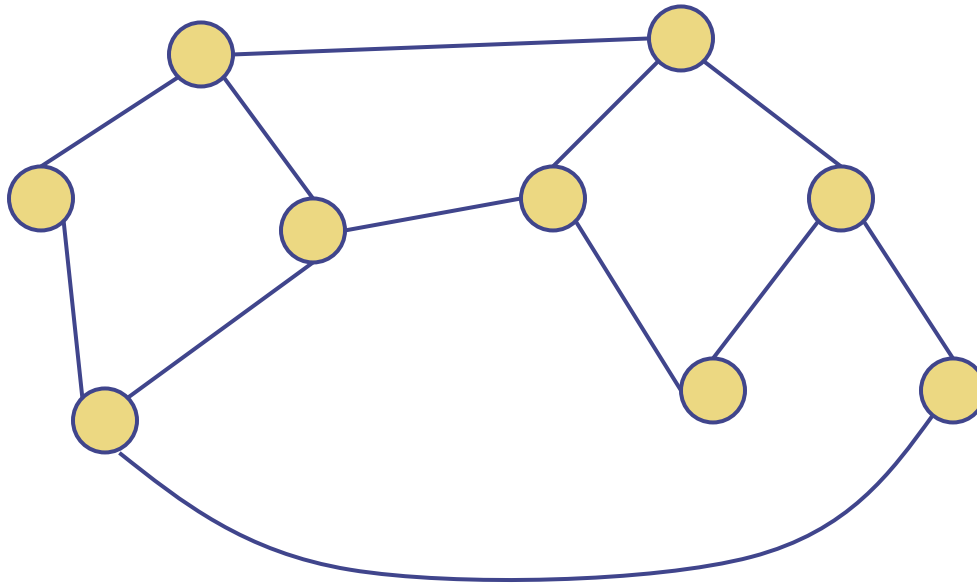
Subgraph

A subgraph is a subset of vertices and edges that forms a graph.



Connected Graph

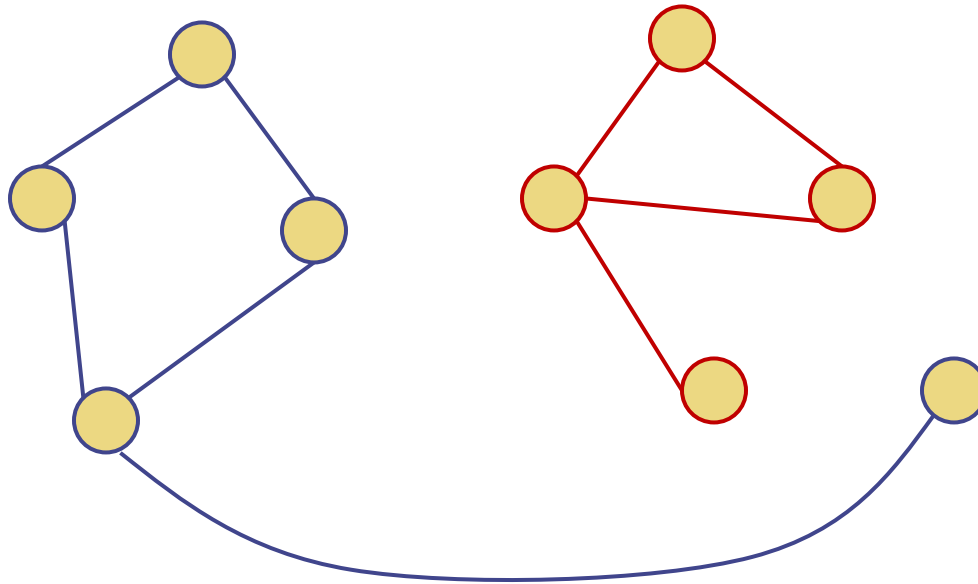
A graph is connected if there is a path from each vertex to every other vertex



Connected Component

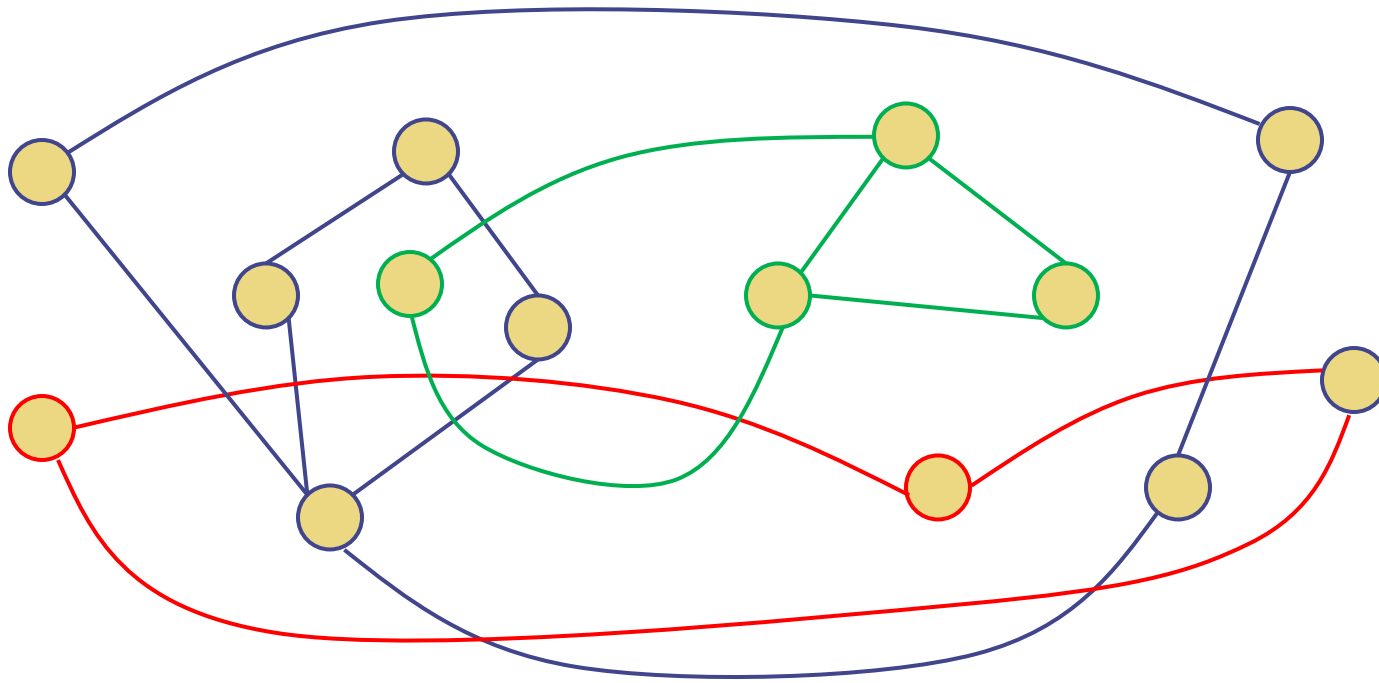
A connected component is a **maximal** connected subgraph.

2 connected components



Connected Component

A connected component is a **maximal** connected subgraph.



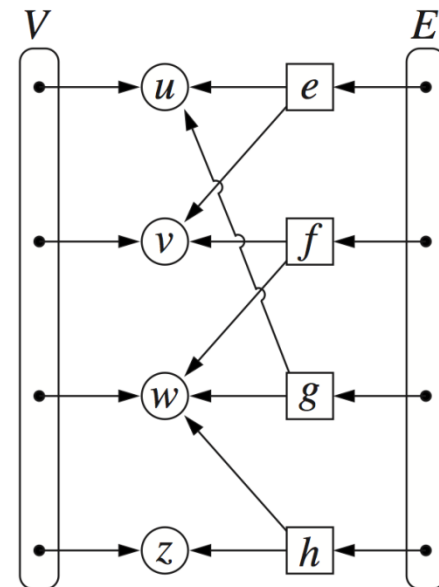
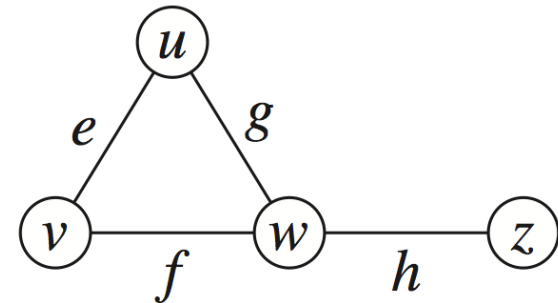
3 connected components

Graph ADT

`numVertices()`: number of vertices of the graph
`getEdge(u,v)`: returns the edge between vertices `u` and `v`
`opposite(v,e)`: returns the vertex other than `v` that is incident on `e`
`insertVertex(x)`: creates and returns a new vertex storing value `x`
`insertEdge(u,v,x)`: creates an edge between `u` and `v` storing value `x`
`removeVertex(v)`: removes vertex `v` and all edges incident on it
`removeEdge(e)`: removes edge `e`
`areAdjacent(u,v)`: returns true if `u` and `v` are adjacent; false otherwise
`incidentEdges(u)`: returns an iterator of all edges incident on vertex `u`.

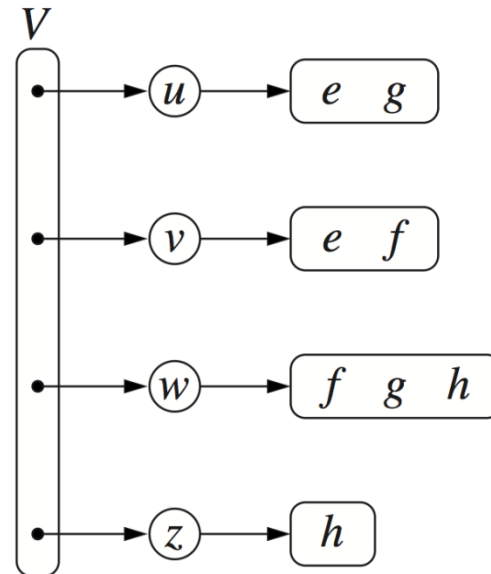
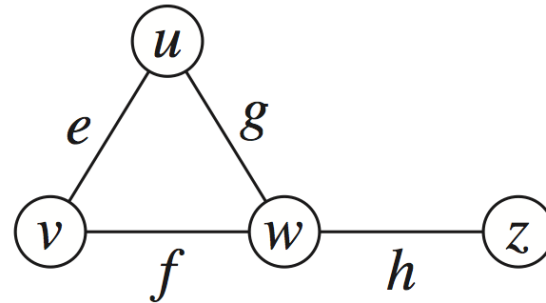
Edge List Structure

- Vertex object
 - element
- Edge object
 - element
 - origin vertex object
 - destination vertex object
- Vertex sequence
 - sequence of vertex objects
- Edge sequence
 - sequence of edge objects



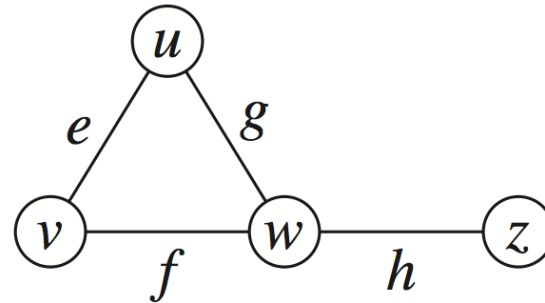
Adjacency List Structure

- Incidence sequence for each vertex
 - list of incident edges



Adjacency Matrix Structure

- 2D-array adjacency array
 - Reference to edges for adjacent vertices
 - Null for non adjacent vertices
- The “old fashioned” version just has 0 for no edge and 1 for edge



		0	1	2	3
$u \longrightarrow$	0		e	g	
$v \longrightarrow$	1	e		f	
$w \longrightarrow$	2	g	f		h
$z \longrightarrow$	3			h	

Performance

▪ n vertices, m edges	Edge List	Adjacency List	Adjacency Matrix
Space	$O(n + m)$	$O(n + m)$	$O(n^2)$
<code>incidentEdges(v)</code>	$O(m)$	$O(\deg(v))$	$O(n)$
<code>areAdjacent(v, w)</code>	$O(m)$	$O(\min\{\deg(v), \deg(w)\})$	$O(1)$
<code>insertVertex(o)</code>	$O(1)$	$O(1)$	$O(n^2)$
<code>insertEdge(v, w, o)</code>	$O(1)$	$O(1)$	$O(1)$
<code>removeVertex(v)</code>	$O(m)$	$O(\deg(v))$	$O(n^2)$
<code>removeEdge(v, w)</code>	$O(m)$	$O(\deg(u) + \deg(v))$	$O(1)$