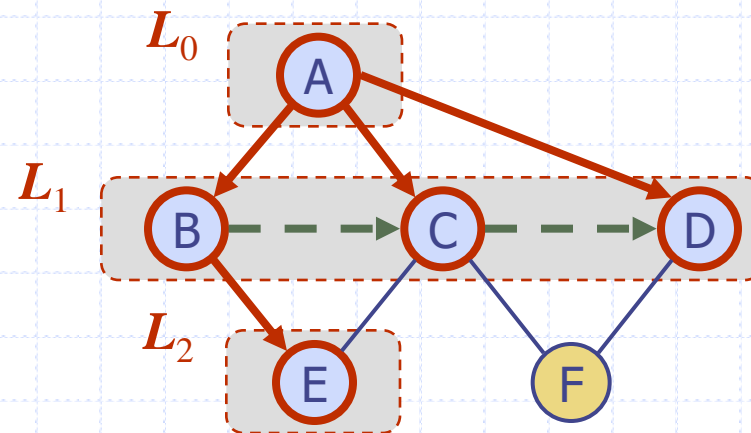


Presentation for use with the textbook **Data Structures and Algorithms in Java, 6<sup>th</sup> edition**, by M. T. Goodrich, R. Tamassia, and M. H. Goldwasser, Wiley, 2014

# Breadth-First Search



# Breadth-First Search

- Breadth-first search (BFS) is a general technique for traversing a graph
- A BFS traversal of a graph  $G$ 
  - Visits all the vertices and edges of  $G$
  - Can determine whether  $G$  is connected
  - Can compute the connected components of  $G$
  - Can compute a spanning forest of  $G$
- BFS can be further extended to solve other graph problems
  - Find and report a path with the minimum number of edges between two given vertices
  - Find a simple cycle, if there is one

# BFS Algorithm

**Algorithm** *BFS*( $G, s$ )

$Q \leftarrow$  new empty queue

$Q.enqueue(s)$

$mark(s)$

**while**  $Q$  is not empty **do** {

$u \leftarrow Q.dequeue()$

$visit(u)$

**for** each edge  $(u,v)$  incident on  $u$  **do**

**if**  $(u,v)$  is not labelled **then**

**if**  $v$  is not marked **then** {

                Label  $(u,v)$  as *DISCOVERY*

$mark(v)$

$Q.enqueue(v)$

            }

**else**

            Label  $(u,v)$  as *CROSS*

}

# Example



unexplored vertex



visited vertex



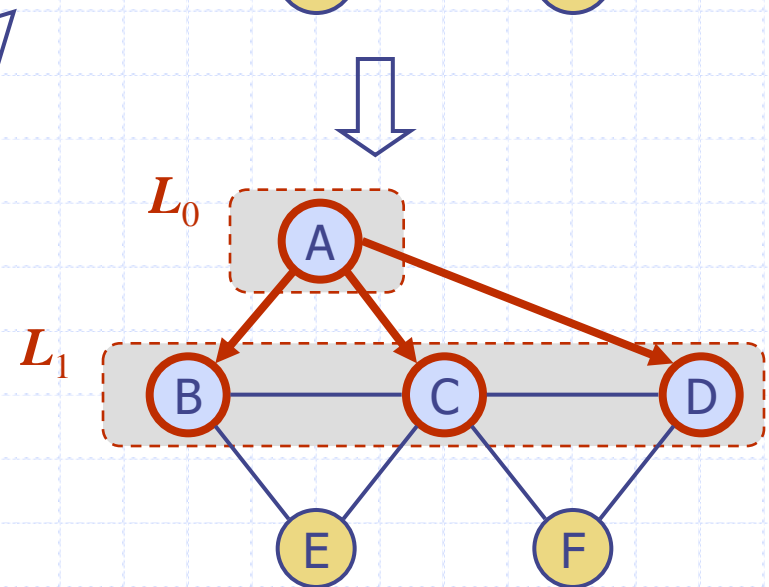
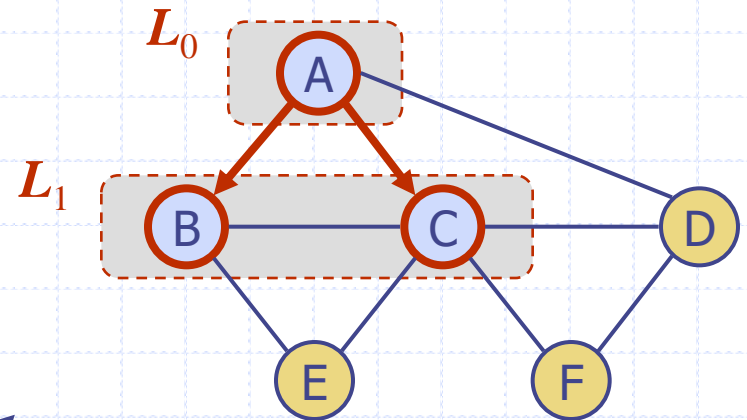
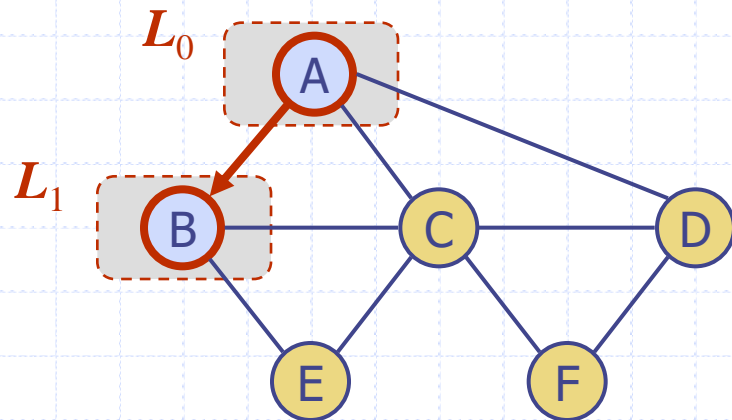
unexplored edge



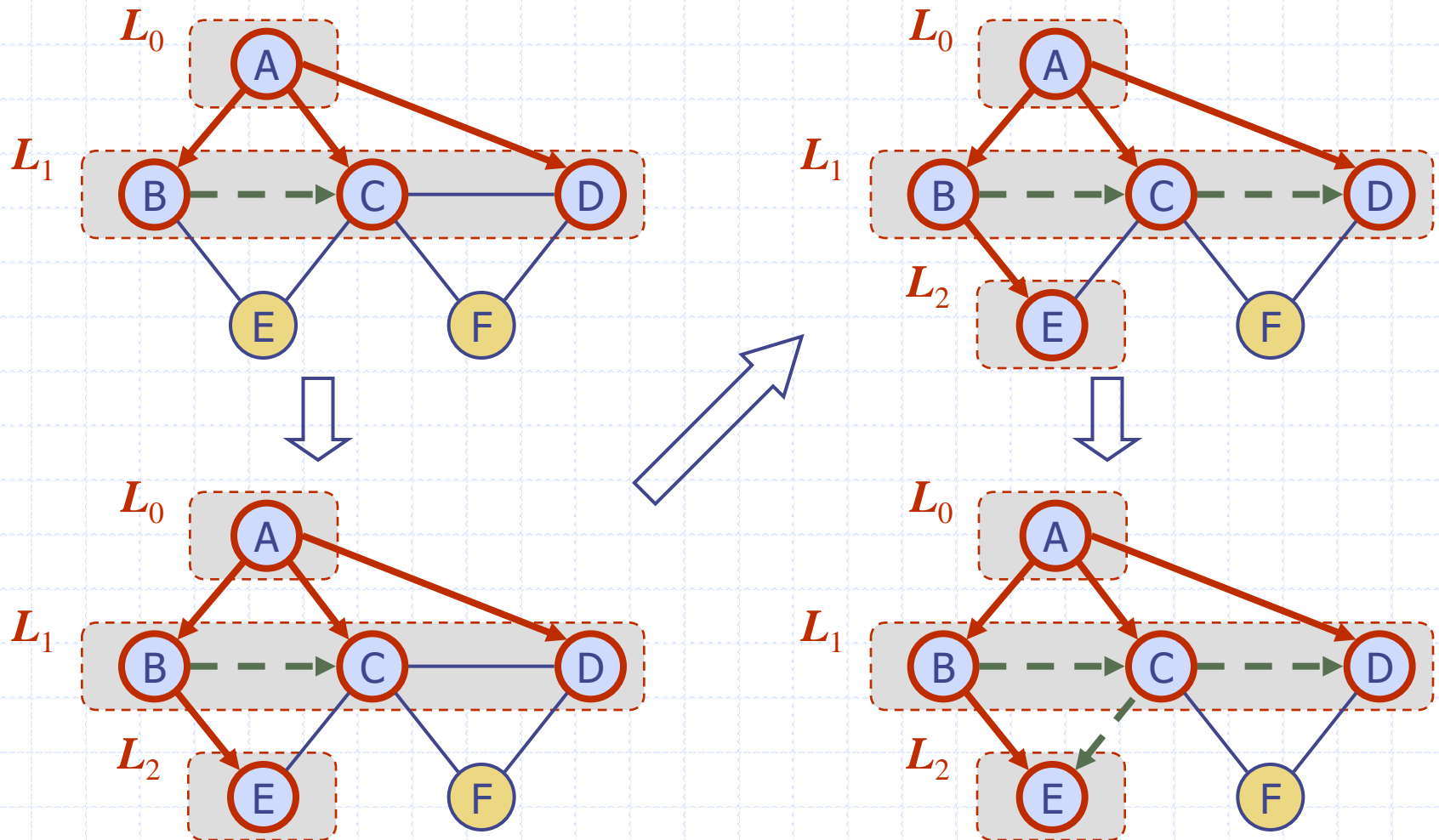
discovery edge



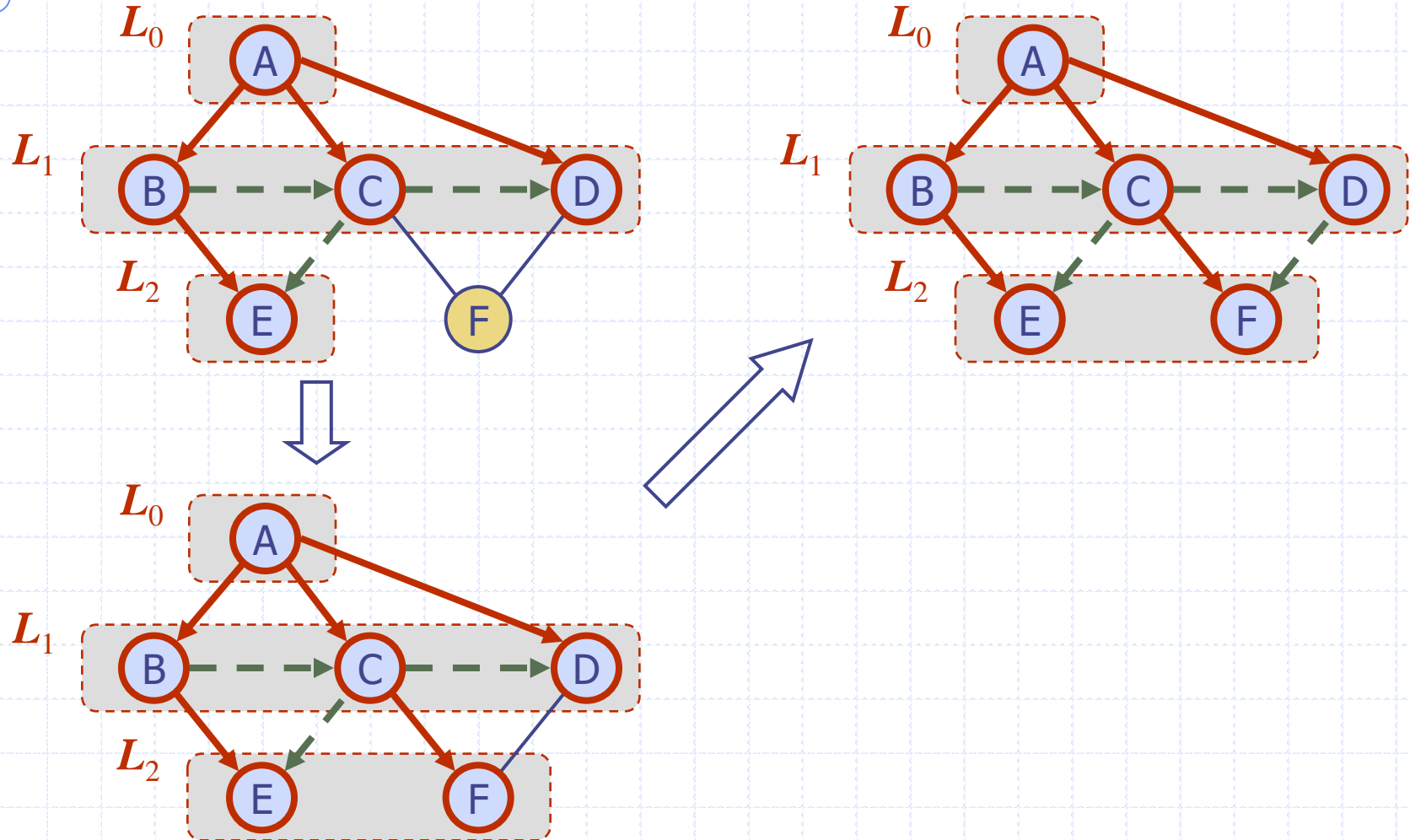
cross edge



# Example (cont.)



# Example (cont.)



Notation

$G_s$ : con

Property

$BFS(G, s)$   
edges of

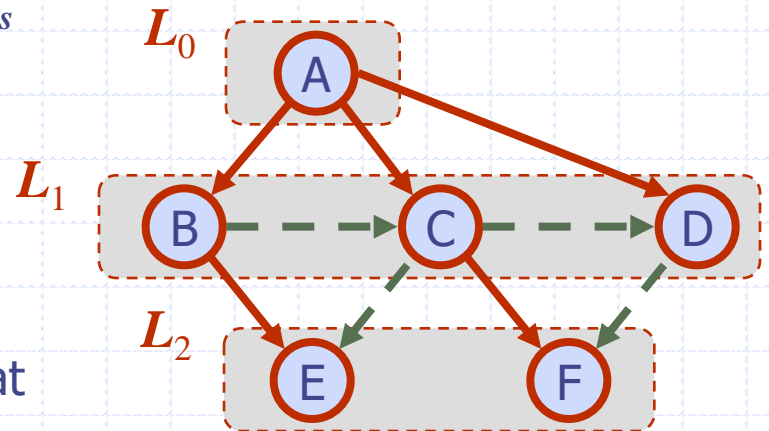
Property ?

$G_s$ : connected component of  $s$

**$BFS(G, s)$  visits all the vertices and edges of  $G_s$**

The discovery edges labeled by  $BFS(G, s)$  form a spanning tree  $T_s$  of  $G_s$  called a BFS tree

- For each vertex  $v$  in level  $L_i$ 
  - The path of  $T_s$  from  $s$  to  $v$  has  $i$  edges
  - Every path from  $s$  to  $v$  in  $G_s$  has at least  $i$  edges



# Analysis

- ❑ Setting/getting a vertex/edge label takes  $O(1)$  time
- ❑ Each vertex is labeled twice
  - once initialized as UNEXPLORED
  - once as VISITED
- ❑ Each edge is labeled twice
  - once initialized as UNEXPLORED
  - once as DISCOVERY or CROSS
- ❑ Each vertex is inserted once into the queue
- ❑ Method incidentEdges is called once for each vertex
- ❑ BFS runs in  $O(n + m)$  time provided the graph is represented by the adjacency list structure and it runs in  $O(n^2)$  time if the graph is represented by the adjacency matrix structure.

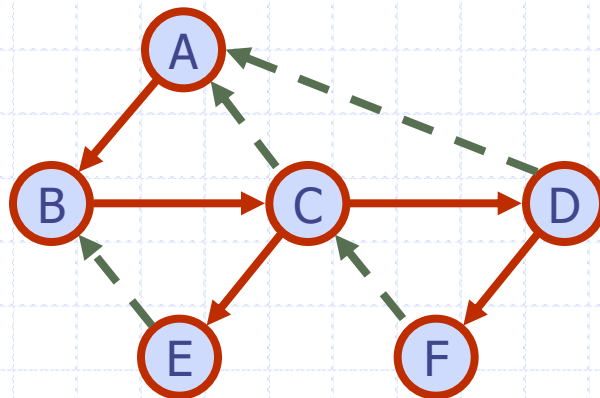


# Applications

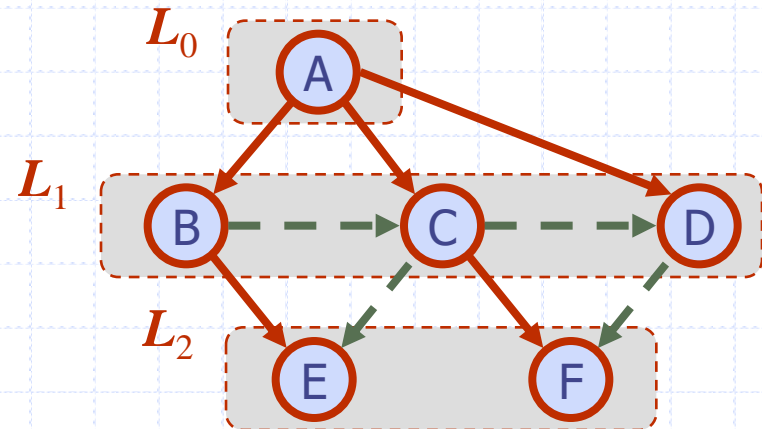
- We can use a BFS traversal of a graph  $G$  to solve the following problems in  $O(n + m)$  time
  - Compute the connected components of  $G$
  - Compute a spanning forest of  $G$
  - Find a simple cycle in  $G$ , or report that  $G$  is a forest
  - Given two vertices of  $G$ , find a path in  $G$  between them with the minimum number of edges, or report that no such path exists

# DFS vs. BFS

Applications	DFS	BFS
Spanning forest, connected components, paths, cycles	✓	✓
Shortest paths		✓



DFS

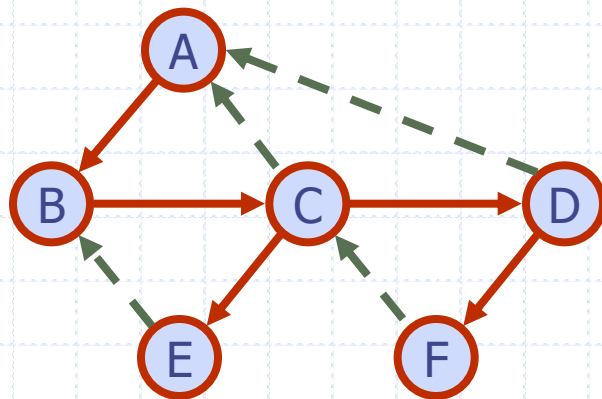


BFS

# DFS vs. BFS (cont.)

## Back edge ( $v, w$ )

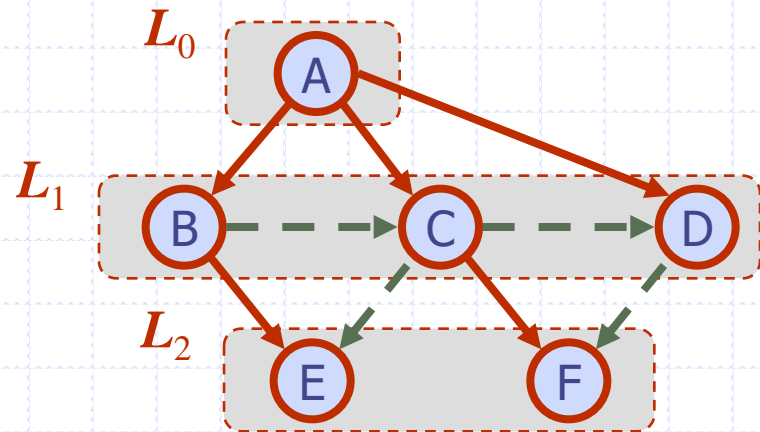
- $w$  is an ancestor of  $v$  in the tree of discovery edges



DFS

## Cross edge ( $v, w$ )

- $w$  is in the same level as  $v$  or in the next level



BFS