

Chapter 11: Vector Spaces

July 25, 2023

Contents

1	General approach	1
1.1	Structure of a Vector Space	1
1.2	Defintion	1
1.2.1	Property	1
1.2.2	Example	2
1.3	Vector Subspaces (= linear subspaces)	2
1.3.1	Definition	2
1.3.2	Propositions	2
1.4	Sum of VSS	3
1.5	Examples	3
1.6	Direct Sum	4
1.6.1	Definition	4
1.6.2	Notation	4
1.6.3	Examples	4

During this chapter, \mathbb{K} will be either \mathbb{R} or \mathbb{C} .

1 General approach

1.1 Structure of a Vector Space

Let E be a set, we define two operations:

- An internal operation:

$$\oplus: E \times E \longrightarrow E$$

$$(u, v) \longmapsto u + v$$
- An external operation:

$$\odot: \mathbb{K} \times E \longrightarrow E$$

$$(\lambda, v) \longmapsto \lambda u$$

1.2 Defintion

We say that (E, \oplus, \odot) is a vector space if $\forall (u, v, w) \in E^3$ we have:

- $u + (v + w) = (u + v) + w$ (\oplus is associative)
- $u + v = v + u$ (\oplus is commutative)
- $\exists 0_E \in E$ such that $u + 0_E = 0_E + u = u$ (Existence of a neutral element for \oplus)
- $\exists -u \in E$, $u + (-u) = (-u) + u = 0_E$ (Existence of a symmetrical element for \oplus)

And $\forall (u, v) \in E^2$ and $\forall (\alpha, \beta) \in \mathbb{K}^2$ we have:

- $(\alpha + \beta) \cdot u = \alpha \cdot u + \beta \cdot u$ (\odot is distributive)
- $\alpha(u + v) = \alpha \cdot u + \alpha \cdot v$ (\odot is distributive)
- $(\alpha\beta)u = \alpha(\beta u)$ (\odot is associative)
- $1_{\mathbb{K}} \cdot u = u$ (Where $1_{\mathbb{K}}$ is the neutral element of multiplication of element of \mathbb{K})

Let (E, \oplus, \odot) be a \mathbb{K} -Vector Space,

Any element from E is called a vector and any element from \mathbb{K} is called a scalar.

0_E is called the zero vector.

1.2.1 Property

$\forall u \in E$ and $\forall \alpha \in \mathbb{K}$ we have:

1. $\alpha \cdot 0_E = 0_E$
2. $0_{\mathbb{K}} \cdot u = 0_E$
3. $\alpha \cdot u = 0_E \Leftrightarrow \alpha = 0_{\mathbb{K}} \text{ or } u = 0_E$

1.2.2 Example

1. $E = \mathbb{R}^2$, $U = \begin{pmatrix} 1 \\ 1 \end{pmatrix} \in \mathbb{R}^2$
2. $\mathbb{R}^3, \mathbb{R}^4, \dots, \mathbb{R}^n$ are \mathbb{R} -VS
3. $\mathbb{R}[X]$: Set of polynomials
 $0_{\mathbb{R}[X]} : \mathbb{R}_2[X] = \{aX^2 + bX + c, (a, b, c) \in \mathbb{R}^3\}$
 \mathbb{R}_2 means: "at least max2", here "a" can be 0
4. $\mathbb{R}^{\mathbb{N}}$ and $\mathbb{R}^{\mathbb{R}}$ are \mathbb{R} -VS
 ex: $\left(\frac{1}{n}\right)_{n \in \mathbb{N}^*} \Big\}$ VS: 8 Property are check

1.3 Vector Subspaces (= linear subspaces)

1.3.1 Definition

Let E be a \mathbb{K} -Vector Space:

- $F \subset E$ (F is a subset of E)
- $F \neq \emptyset$ (F is non-empty, $0_E \in F$)
- $\forall (u, v) \in F^2, \forall \alpha \in \mathbb{K}, (\alpha \cdot u + v) \in F$ (F is closed under linear combination)

1.3.2 Propositions

1.3.2.1 Proposition 1

Let E be a \mathbb{K} -Vector Space:

$$F \subset E \text{ is a Vector SubSpace of } E \implies 0_E \in F$$

$$\nLeftarrow$$

1.3.2.2 Example

$$E = \mathbb{R}^3$$

$$F_1 = \left\{ \begin{pmatrix} x \\ y \\ z \end{pmatrix} \in \mathbb{R}^3, x + y + z = 1 \right\} \text{ and } F'_1 = \left\{ \begin{pmatrix} x \\ y \\ z \end{pmatrix} \in \mathbb{R}^3, x + y + z = 0 \right\}$$

$$0_E \notin F_1 \implies F_1 \text{ is not a Vector SubSpace of } E$$

$$\forall (u, v) \in F'^2_1, \forall \alpha \in \mathbb{R}, u = \begin{pmatrix} x \\ y \\ z \end{pmatrix} \text{ and } v = \begin{pmatrix} x' \\ y' \\ z' \end{pmatrix}$$

$$\alpha u + v = \alpha(x, y, z) + (x', y', z') = 0_E \in F'_1 \implies F'_1 \text{ is a Vector SubSpace of } E$$

$$F_2 = \left\{ \begin{pmatrix} x \\ y \end{pmatrix} \in \mathbb{R}^2 \left\{ \begin{array}{l} \in \mathbb{R}^3 \\ \ni 0_E \end{array} \right. , 0_E \in xy \geq 0 \right\}$$

$$\left(\begin{pmatrix} 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ -1 \end{pmatrix} \right) \in F_2^2$$

$$\begin{pmatrix} 1 \\ 0 \end{pmatrix} + \begin{pmatrix} 0 \\ -1 \end{pmatrix} = \begin{pmatrix} 1 \\ -1 \end{pmatrix} \notin F_2^2 \text{ Not closed by linear combination}$$

Exercise on your own: $F_3 = \{P \in \mathbb{R}[X], P(2) = 0\}$

1.3.2.3 Proposition 2

Let E be a Vector Space, F and G two Vector SubSpaces of E . Then:

1. $F \cap G \subset E$, $F \cap G$ is a Vector SubSpace of E
2. $\left. \begin{array}{l} F \text{ VSS of } E \implies 0_E \in F \\ G \text{ VSS of } E \implies 0_E \in G \end{array} \right\} \implies 0_E \in F \cap G \implies F \cap G \neq \emptyset$
3. $\forall (u, v) \in F \cap G, \forall \alpha \in \mathbb{K}$ Then: F close under linear combination
 $\implies \alpha u + v \in F$.
 $\left. \begin{array}{l} \text{So far for } G \implies \alpha u + v \in G \\ \text{and } F \cap G \text{ is closed under linear combination.} \end{array} \right\} \alpha u + v \in F \cap G$

1.3.2.4 Proposition 3

Let E be a VS: $\{0_E\}$ (sigleton) is a VSS of E

1.3.2.5 Proof:

1. $\{0_E\} \subset E$
2. $0_E \in \{0_E\} \implies \{0_E\} \neq \emptyset$
3. $\forall (u, v) \in \{0_E\}^2, u = v = 0_E$ and $\forall \alpha \in \mathbb{K}, \alpha u = 0_E \implies \alpha u + v = 0_E \implies (\alpha u + v) \in \{0_E\}$

1.3.2.6 Proposition 4

Let (E, \oplus, \odot) be a VS and F a VSS of E , then F is a VS

1.4 Sum of VSS

Let E a \mathbb{K} -VS, F and G VSS of E , we say H is the sum of F and G if:

$$H = \{u \in E, \exists (v, w) \in F \times G, u = v + w\}$$

1.5 Examples

1. $E = \mathbb{R}^2, G = \left\{ \begin{pmatrix} x \\ 0 \end{pmatrix}, x \in \mathbb{R} \right\}, H = \left\{ \begin{pmatrix} 0 \\ y \end{pmatrix}, y \in \mathbb{R} \right\}$
 $G + H = \left\{ \begin{pmatrix} x \\ y \end{pmatrix}, (x, y) \in \mathbb{R}^2 = \mathbb{R}^2 \right\}$

$$\begin{aligned}
2. \quad & F = \left\{ \begin{pmatrix} x \\ 0 \\ 0 \end{pmatrix}, x \in \mathbb{R} \right\} \\
& G = \left\{ \begin{pmatrix} 0 \\ 0 \\ z \end{pmatrix}, z \in \mathbb{R} \right\} \\
& F + G = \left\{ \begin{pmatrix} x \\ 0 \\ z \end{pmatrix}, (x, z) \in \mathbb{R}^2 \right\} \in \mathbb{R}^3 \neq \mathbb{R}^3
\end{aligned}$$

VSS of \mathbb{R}^3

1.6 Direct Sum

1.6.1 Definition

Let E a \mathbb{K} -VS, F and G two VSS of E ,
we say that F and G are in direct sum if:

$$F \cap G = \{0_E\}$$

1.6.2 Notation

In that case we denote $F \oplus G$ instead of $F + G$

1.6.3 Examples

- Both of previous examples

$$\begin{aligned}
2. \quad & F = \left\{ \begin{pmatrix} x \\ y \\ z \end{pmatrix}, z = 0, x, y \in \mathbb{R}^2 \right\} \\
& G = \left\{ \begin{pmatrix} x \\ 0 \\ z \end{pmatrix}, (x, y) \in \mathbb{R}^2 \right\} \\
& F + G \text{ Check} \\
& F \oplus G \text{ Not bc } F \cap G \neq \{0_E\}
\end{aligned}$$

$\begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} \in F \cap G$