

Computer Game Technologies

Animation in Java 3D

Animation in Java 3D

- *Animation* is a change without any direct user action
- Time-based animation
 - Interpolators
 - Alpha objects
 - Custom behaviours
- Collision detection
 - Same as for 2D
 - Bounding boxes and spheres

Time in Java 3D

- Java 3D rendering engine runs in a continuous loop at as fast a frame rate as possible
- WakeUp criteria
 - On elapsed time
 - One elapsed frames
- Alpha object
 - Value from 0.0 to 1.0
 - Value changes as a continuous function of time

Alpha Objects

- Synchronized against Java 3D system start time
- Four phases

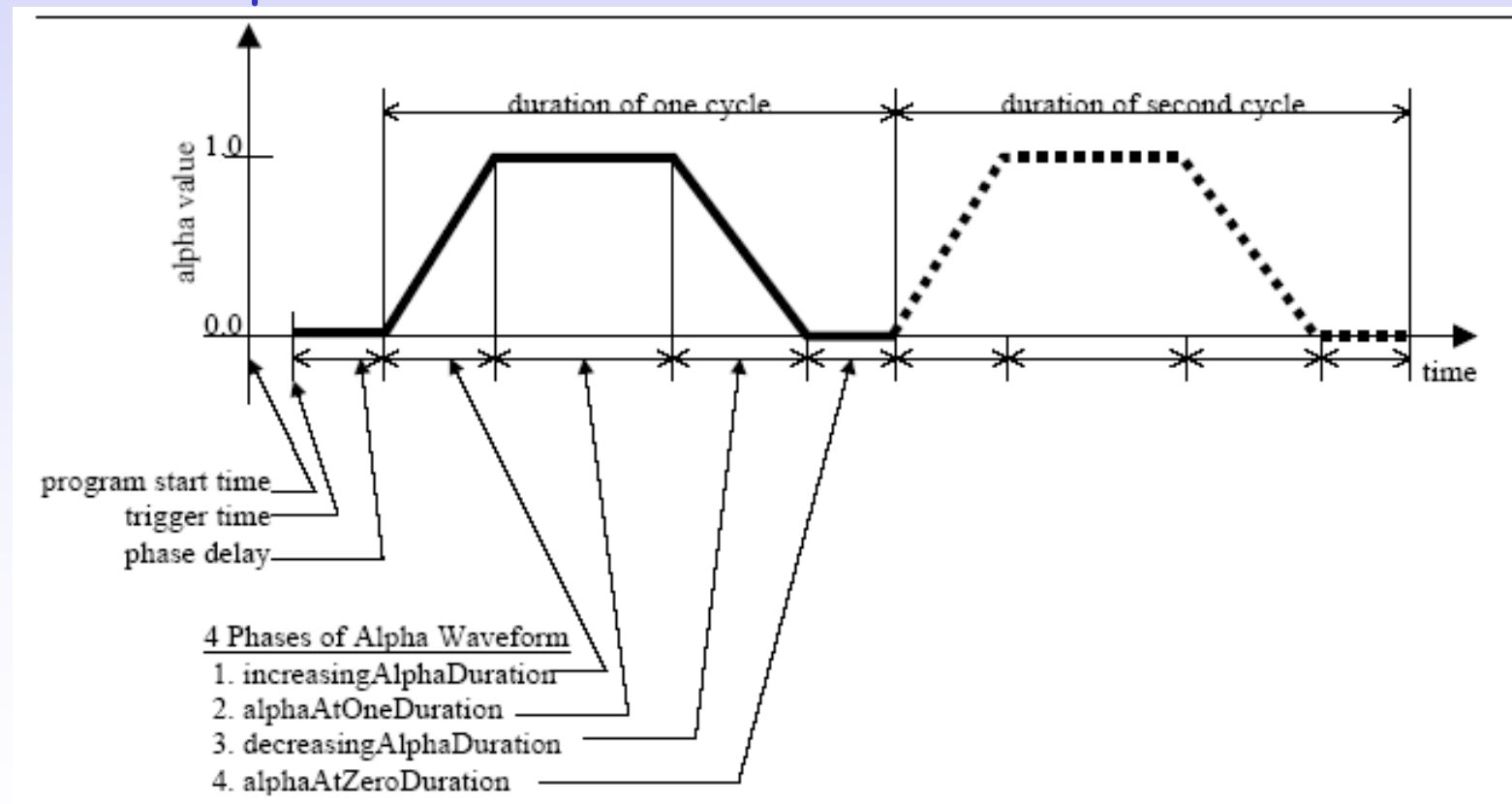
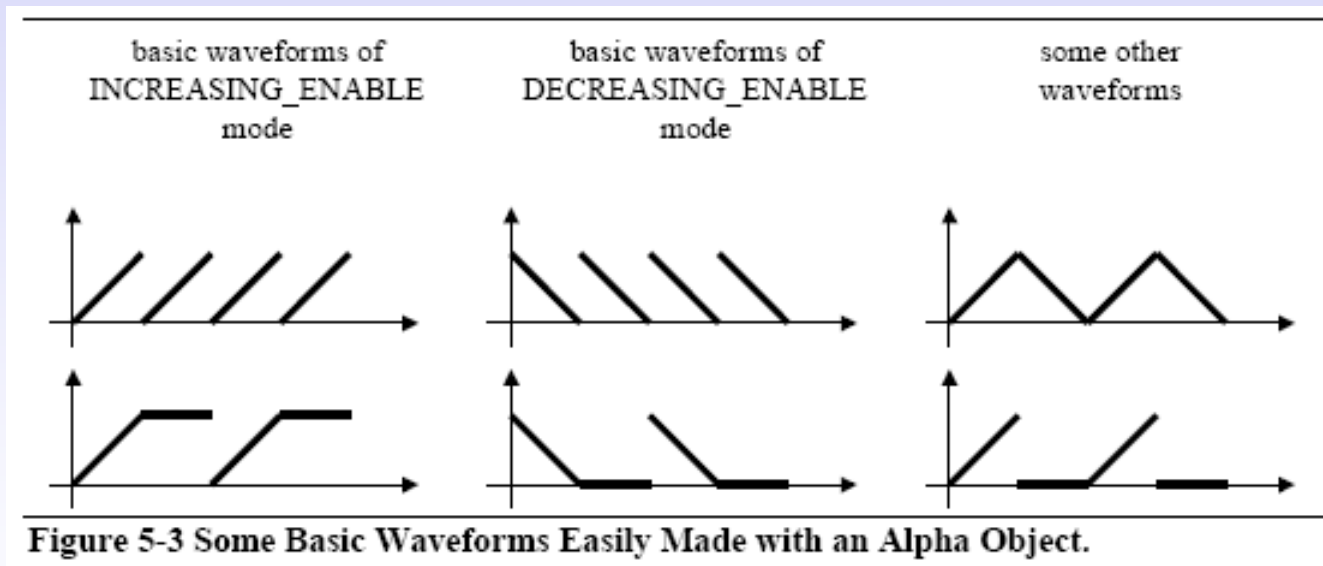


Figure 5-2 Phases of the Alpha Waveform.

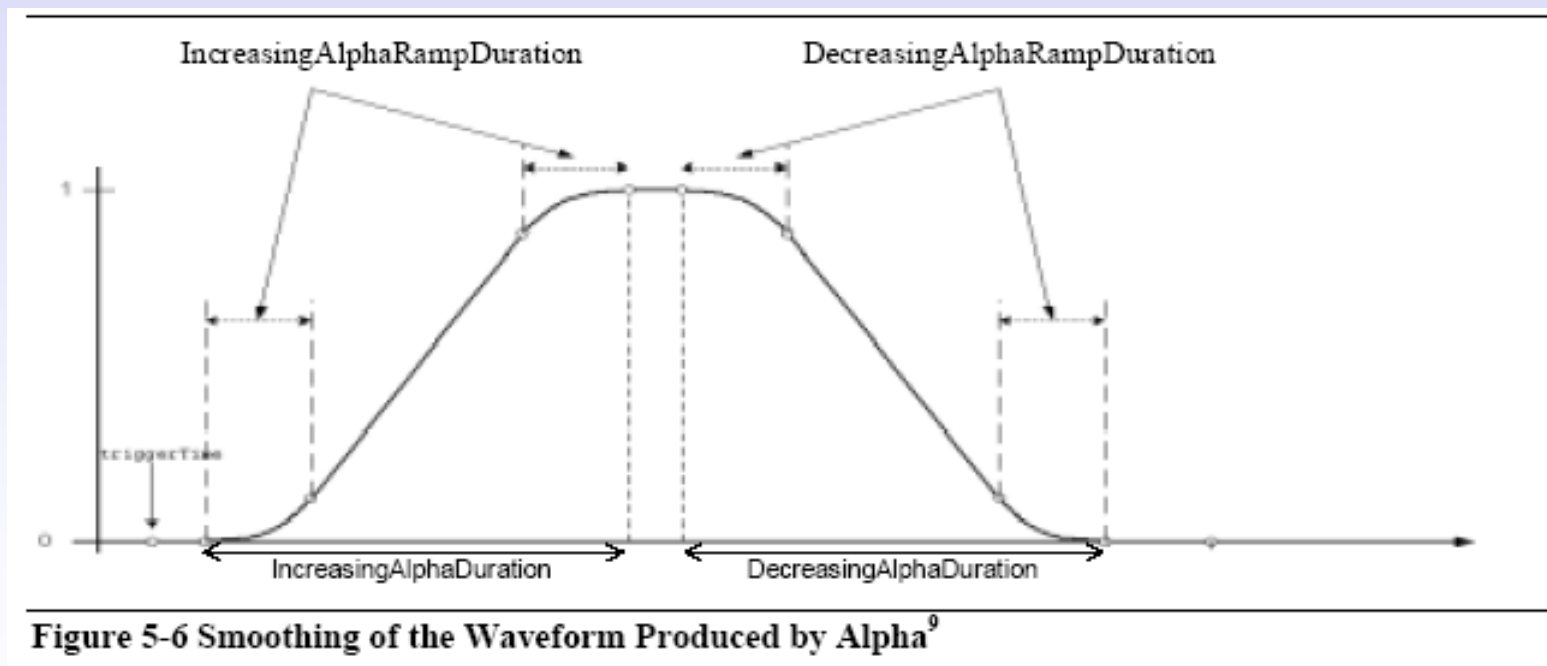
Alpha Objects (2)

- Patterns using one to all four phases
- Fixed number of cycles or continuous



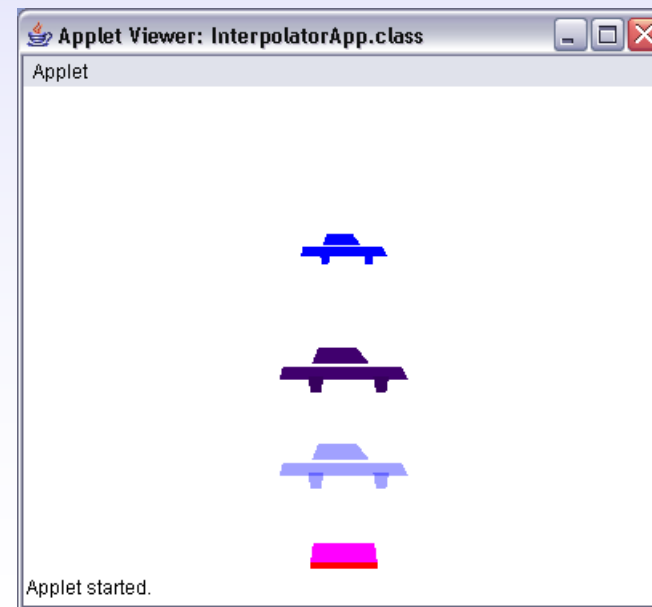
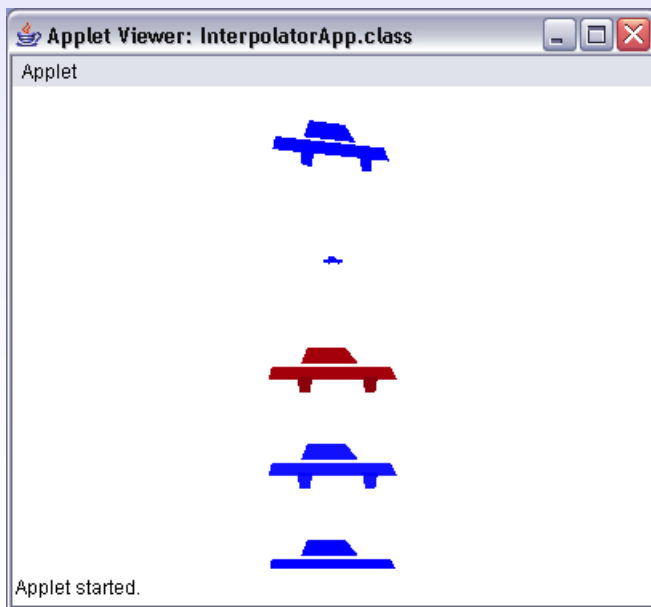
Alpha Objects (3)

- Waveforms can be smoothed
 - Useful for acceleration / deceleration effects



Interpolators

- Change a property of a visual object
 - Location (translation) and orientation (rotation)
 - Size, colour and transparency
- Property changes over time
 - Interpolated against an Alpha object value



Built-in Interpolators

- Utility classes provided for interpolating most object properties of interest

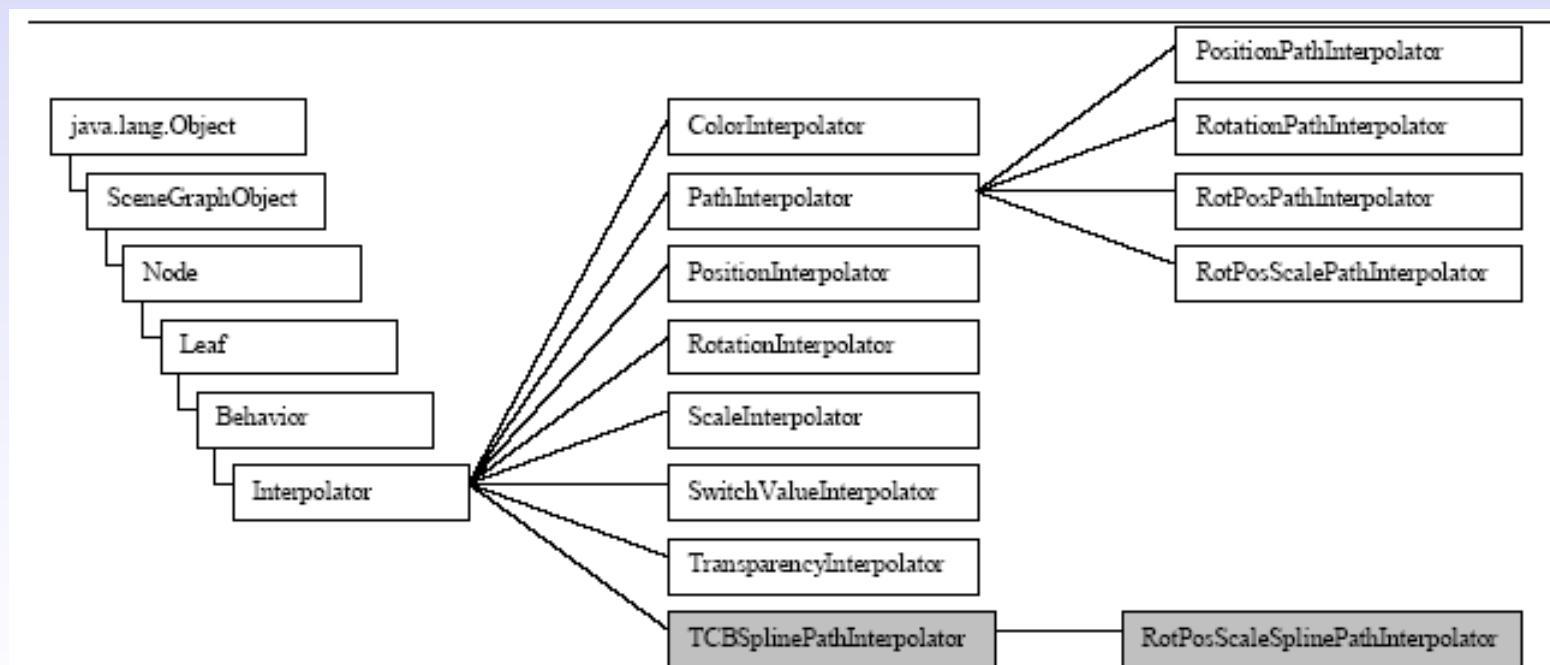


Figure 5-8 Java 3D Core and Utility (shaded boxes) Interpolator Classes Hierarchy.

Hand-crafted Animation

- Can write custom behaviours that use Alphas
 - value() method of Alpha object
- But movement in games is not always regular
 - Determined by interaction between sprites
 - Game state
- Custom animation behaviors using time or frame-based wakeup criteria
 - Identical to approach used for 2D games

The Animated Hand

- Davison, "Killer Game Programming" chapter 18
- Movement updated every few milliseconds via a custom behavior
- TimeBehavior has a reference to the AlienSprite object
- TimeBehavior calls the AlienSprite update() method every time it wakes up
- AlienSprite update() calculates the new sprite position based on location of player sprite and required distance to move on each update

TimeBehavior

```
public class TimeBehavior extends Behavior
{
    private WakeupCondition timeOut;
    private AlienSprite alien;

    public TimeBehavior(int timeDelay, AlienSprite as)
    { alien = as;
      timeOut = new WakeupOnElapsedTime(timeDelay);
    }

    public void initialize()
    { wakeupOn( timeOut );
    }

    public void processStimulus( Enumeration criteria )
    { // ignore criteria
      alien.update();
      wakeupOn( timeOut );
    } // end of processStimulus()
} // end of TimeBehavior class
```

AlienSprite

```
public class AlienSprite extends TourSprite
{
    private TourSprite ts;
    private double currAngle;    // current y-axis angle

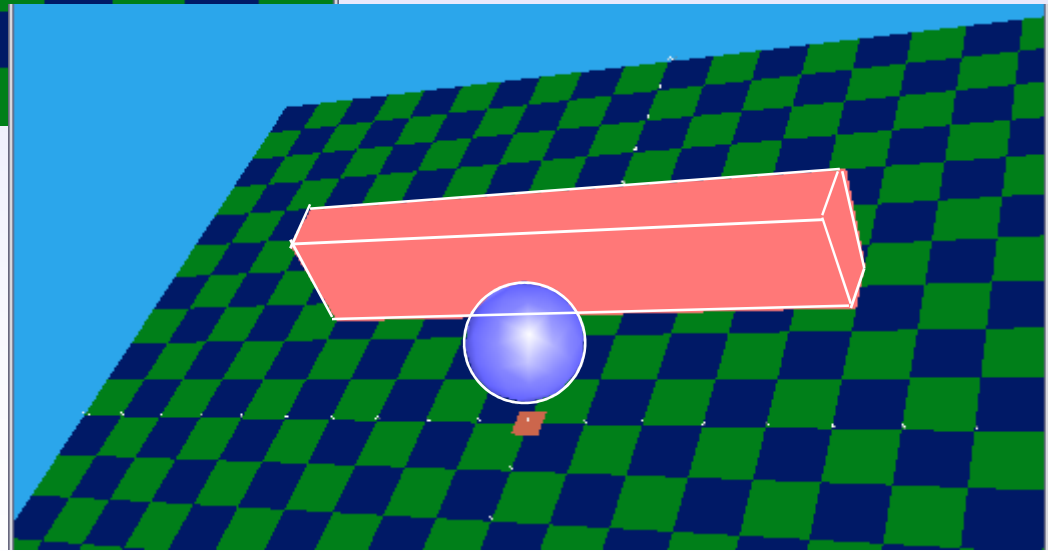
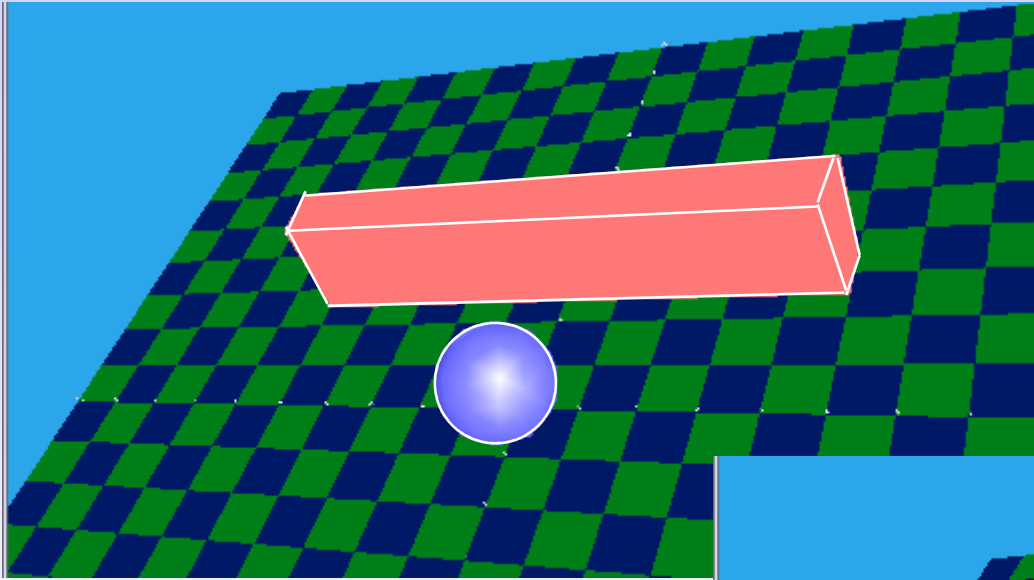
    public AlienSprite(Obstacles obs, TourSprite ts)
    {
        super(fnm, obs);
        this.ts = ts;
        currAngle = 0.0;
    }    // end of AlienSprite()

    public void update()
    // called by TimeBehaviour to update the alien
    {
        if (isActive()) {
            headTowardsTourist();
        }
    }    // end of updateSprite()
```

Collision Detection

- Collision detection based on bounding regions of objects
 - Boxes (cubes), spheres
 - More complex polytopes
 - Define explicitly for each object of interest
- Need to detect when bounding regions of colliding objects overlap
 - Bounding regions in Java 3D have a built-in method `intersect()` that can detect overlap with another bounding region
- Take appropriate action in response to collision

Collision Detection (2)



Example Time Behavior

```
public TimeBehavior(int timeDelay, TransformGroup oTG, float orad,
    Bounds obsBnds)
// oTG is transform group of object to be controlled
// orad is radius of object (for collision detection)
// obsBnds is bounds of obstacle (for collision detection)
{
    objectTG = oTG;
    collRad = orad;
    obsBounds = obsBnds;
    t3d = new Transform3D();
    toMove = new Transform3D();

    currMove = new Vector3d(0, 0, -MOVERATE);

    timeOut = new WakeupOnElapsedTime(timeDelay);
}

public void initialize()
{ wakeupOn( timeOut );
}
```

Example Time Behavior (2)

```
public void processStimulus( Enumeration criteria )
{ // ignore criteria
    currMove = doMove( currMove );
    wakeupOn( timeOut );
} // end of processStimulus()

private Vector3d doMove(Vector3d theMove)
// Move the sprite by the amount in theMove
{
    objectTG.getTransform( t3d );
    toMove.setTranslation(theMove);    // overwrite previous trans
    t3d.mul(toMove);
    Vector3d trans = new Vector3d();
    t3d.get( trans ); // get translational component of transform
    Point3d newLoc = new Point3d( trans.x, trans.y, trans.z);
    // next location
    BoundingSphere testBnds = new BoundingSphere(newLoc, collRad);
    // only allow move if does not intersect with obstacle
    if ( !obsBounds.intersect(testBnds) )
        objectTG.setTransform(t3d);
    return theMove;
} // end of doMove()
```


Collision Detection Recipe

- Give each object an associated bounding region
 - Cube, sphere
 - E.g. `BoundingSphere playerbnds = new BoundingSphere();`
 - When an object moves, its bounding region must be moved with it
 - Manually apply transform or recreate bounds at new location
 - Add bounds to a `BoundingLeaf` node
- Time-based behavior checks for *(predicted)* intersections between bounds of visible objects
 - Schemes for checking similar to 2D
 - E.g. `if (playerbnds.intersect(enemybnds)) { fix collision }`

The End