# Routing on rails with OpenStreetMap

Michael Reichert (Nakaner)



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Michael Reichert (Nakaner)

Current solution

OSM data

Feature

Demo

Performance

Implementation



### Current solutions Travic

Michael Reichert

Current solutions

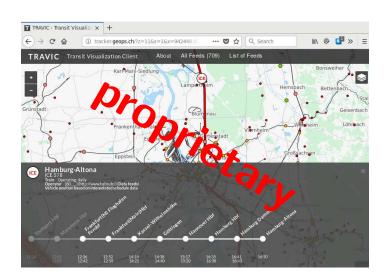
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Demo

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# Current solutions Mentz

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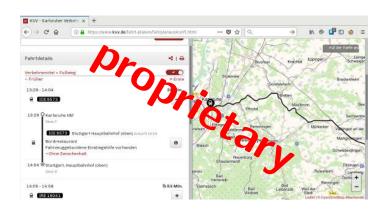
Current solutions

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### Current solutions Raildar.fr

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Current solutions

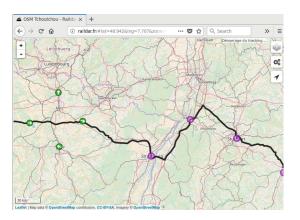
OSM da

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Performance

Implemen-

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filtering the planet using osmfilter, routing with OSRM, rumours about tag replacement

# Current solutions Signal.eu.org

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Current solutions

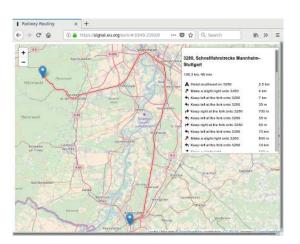
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Future



OSRM, support of left/right track, reversing

### Railway tracks in OpenStreetMap

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Current

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Implemen-

- connected
- one way per track
- 1841 430 km tracks (608 055 km in Europe)
- 1 239 753 possible points (634 524 in Europe)
- 289 423 points tagged with railway=switch (208 078 in Europe)



# Railway tracks in OpenStreetMap Simple points

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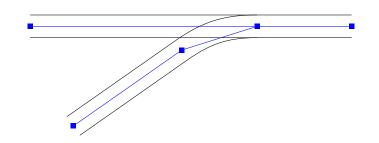
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# Railway tracks in OpenStreetMap Slip points

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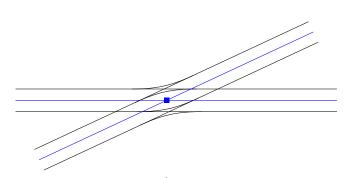
Current solution

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double slip point (railway=switch +
 railway:switch=double\_slip)

# Railway tracks in OpenStreetMap Slip points

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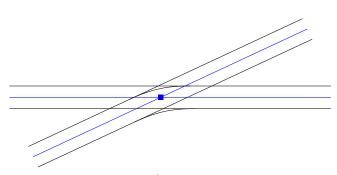
**Current** solution

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single slip point (railway=switch +
railway:switch=single\_slip)

# Railway tracks in OpenStreetMap Slip points

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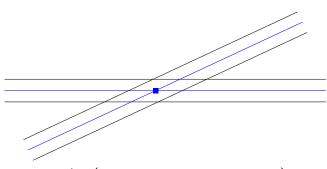
Current

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crossing (railway=railway\_crossing)

### Railway tracks in OpenStreetMap

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Current solution

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Implementation

- railway=rail/light\_rail/tram/ subway/narrow\_gauge
- gauge=\*
- electrified=no/yes/contact\_line/rail
- voltage=\*
- frequency=\*
- See Railways at OpenStreetMap at SotM 2016 for more.

#### **Features**

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Current solution:

OSM dat

Features

Performance

Implementation

- power systems
- gauges
- preconfigured profiles
  - freight train and TGV profiles for France and Germany/Austria/Switzerland
  - universal diesel train (any gauges), max. 120 kph
  - universal electric train (any gauges, any power system), max. 140 kph
- profile customization via YAML file
- reversing
- reduced default speeds for crossovers and other slower tracks
- map matching (CSV, GPX)

### Demo

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Current solution

OSM data

Features

Demo

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Future

### Demo

### Performance

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solutions

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Performance

Implemenation

- osmium tags-filter -o planet-rail.osm.pbf planet.osm.pbf nw/railway 6 minutes on a fast server, 1-2 GB RAM
- 168 MB .osm.pbf file
- import: about 1 minute, 1200 MB RAM without contraction hierarchies
- graph: 204 MB
- 2450 routes through Germany
  - 2352 successfull routes
  - 2 minutes 8 seconds, 1 thread
  - average length per route: 409 km

### Implementation

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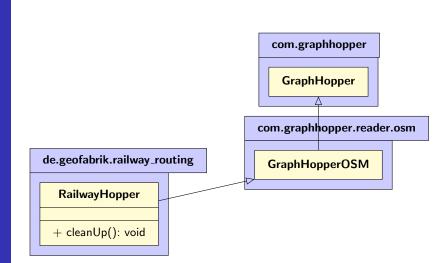
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# Implementierung FlagEncoder

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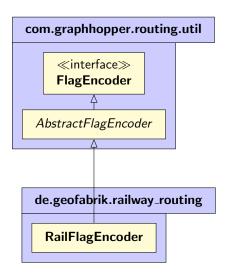
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# Implementierung RailFlagEncoder

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Implementation

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#### RailFlagEncoder

- electrifiedValues: ArrayList<String>
- acceptedVoltages: ArrayList<Integer>
- acceptedFrequencies: ArrayList<Double>
- acceptedGauges: ArrayList<Integer>
- speedCorrectionFactor: double
- + RailFlagEncoder(properties: PMap)

# Implementierung RailFlagEncoder

Michael Reichert

Current solution:

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#### RailFlagEncoder

- electrifiedValues: ArrayList<String>
- acceptedVoltages: ArrayList<Integer>
- acceptedFrequencies: ArrayList<Double>
- acceptedGauges: ArrayList<Integer>
- speedCorrectionFactor: double
- + RailFlagEncoder(properties: PMap)

### YAML config

name electrified voltages frequencies gauges maxspeed speedFactor

### Experiences with GraphHopper

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Implementation

- + suitable for routing on any routeable OSM network
- introduction into FlagEncoder could be more verbose
- TurnCostExtension without good documentation  $\rightarrow$  misconceptions
- no different penalities for reversing for each FlagEncoder
- a library for car routing only
  - flag encoders designed to be extensible
  - addition of turn restrictions not designed to be extensible
  - ullet reading of OSM files not extensible o fork of GraphHopper
- + forum
- Read the unit tests!

# Space for improvement Left/right track on double-tracked lines

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### Space for improvement

Tag to distinguish left and right tracks

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 ${\tt railway:} {\tt preferred\_direction=forward/backward}$ 

### Space for improvement Estimation of travel times

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currently  $0.9 \cdot \text{speed limit}$ 

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### Space for improvement Estimation of travel times

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Solution Solution

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currently 0.9 · speed limit

Comparison of timetables of nonstop IC trains using the TGV profile (max. 160 kph due to old infrastructure)

	timetable	routing
IC Koblenz–Mainz	1:05	0:50
IC Magdeburg–Dessau	0:42	0:36

# Space for improvement Specify heading direction

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Current solution

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# Space for improvement Specify heading direction

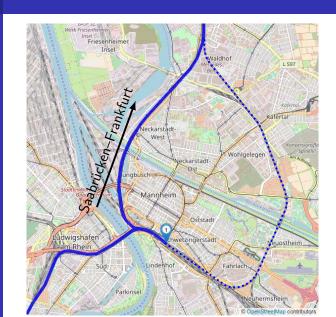
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### Missing data Gradients

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### Missing data Gradients

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#### **Problems**

- SRTM resolution too low
  - cuttings and embankments in SRTM data
  - narrow valleys
  - vertical precision

### Missing data Gradients

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#### **Problems**

- SRTM resolution too low
  - cuttings and embankments in SRTM data
  - narrow valleys
  - vertical precision

#### Solutions?

- Use railway lines to correct elevation data?
- elevation profiles provided by operator of infrastructure
- Measure elevation profiles data ourselves?

### Missing data

Lines for special purpose (S-train, RER, ...), diesel engine bans

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### Missing data Loading gauge

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# Missing data Loading gauge

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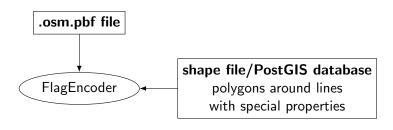
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The development of this software has been sponsored by





Source code:

https://github.com/geofabrik/railway\_routing