```
┌─────────────────────────────────┐
│        view_frames Result       │
│                                 │
│  Recorded at time: 1481903982.902 │
└─────────────────────────────────┘
```

(map)

Broadcaster: /map_2_base_footprint
Average rate: 10.188 Hz
Most recent transform: 1481903982.917 (-0.015 sec old)
Buffer length: 4.711 sec

(base_footprint)

Broadcaster: /arduino
Average rate: 19.075 Hz
Most recent transform: 1481903982.943 (-0.041 sec old)
Buffer length: 4.823 sec

(base_link)

Broadcaster: /base_link_2_base_stabilized_link
Average rate: 10.178 Hz
Most recent transform: 1481903982.917 (-0.015 sec old)
Buffer length: 4.716 sec

(base_stabilized)

Broadcaster: /base_stablized_2_base_frame
Average rate: 10.180 Hz
Most recent transform: 1481903982.964 (-0.062 sec old)
Buffer length: 4.715 sec

(base_frame)

Broadcaster: /base_2_nav_link
Average rate: 10.183 Hz
Most recent transform: 1481903982.924 (-0.022 sec old)
Buffer length: 4.714 sec

Broadcaster: /base_frame_2_laser_link
Average rate: 10.187 Hz
Most recent transform: 1481903982.929 (-0.027 sec old)
Buffer length: 4.712 sec

(odom)   (camera_link)