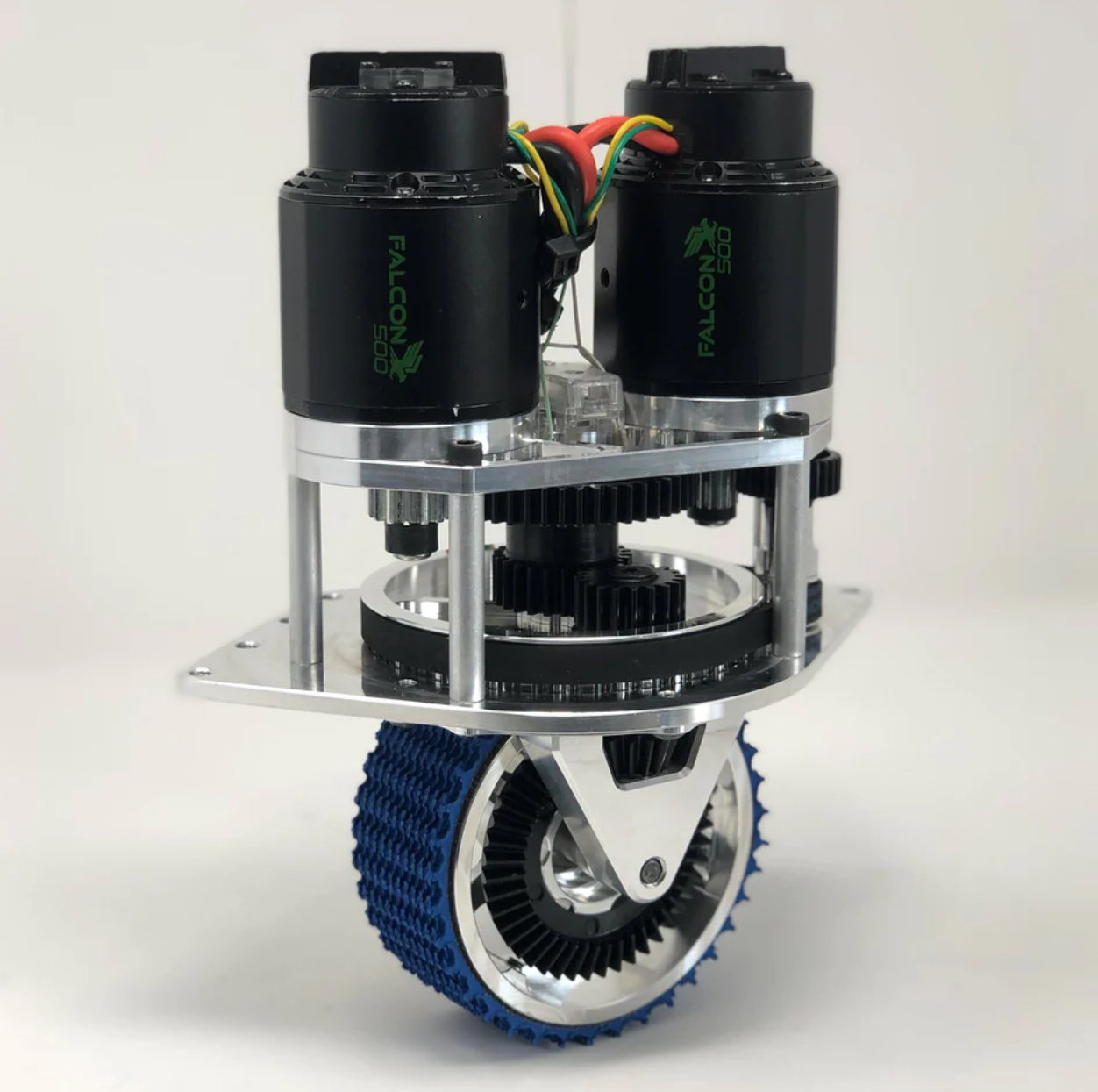


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MK4 Swerve Module

\$300.00

For Motor Shaft

Falcon 500

Gear Ratio

L1

Wheel

Colson

Quantity

1

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Check this spreadsheet for current swerve module lead times.

New for late summer 2023, this swerve module can be configured with a Colson Wheel (further details [here](#)). If you have a swerve module order that has not shipped yet and would like it configured with Colson Wheels, please contact us with your order number.

Effective 7-Aug-2023 at 12:01 am PT: This swerve module will ship (regardless of the *order* date) with an updated Intermediate Shaft (V3), Base Pulley (V3) and upper bearing (non-flanged) for the shaft. Details:

- The collective change enables the flanged bearing supporting the top of the Intermediate Shaft to be replaced with a non-flanged bearing. That bearing can consequently only be installed in the updated Base Pulley one way to help ensure the swerve module is assembled correctly.

Please note:

- The *NEO* or *NEO Vortex* kit works for the NEO and NEO Vortex motors with the 8mm keyed shaft.
- The *Falcon 500* kit is primarily for the Falcon 500 motor. It can also work for the NEO Vortex motor with the Falcon spline shaft, but the shaft spacers are not included (they are supplied with the Falcon motors). Going this route for the NEO Vortex utilizes a splined steering pinion gear, so no press/slip fit is needed there.

New for the summer of 2021, The MK4 Swerve Module is our latest swerve drive iteration. The MK4 is an upgraded version of our popular [MK3 module](#).

The MK4 features our new 1.5" width Billet Wheel. Because of the 50% increase of width, greater tread life and slightly better traction can be expected. This module now ships with black neoprene tread (blue nitrile is pictured), which extends the tread life even further. To accommodate the new wheel the MK4 uses our new 2nd Generation bevel gear set.

Despite it being one of the most compact and lightweight modules available, the MK4 module does not compromise on robustness. MK4 modules use all steel gears for superior wear resistance. Under typical use, the modules will be able to handle multiple seasons of robotics competition. In order to keep weight to a minimum, the steel gears are pocketed.

Like the MK3, the MK4 uses a centrally located steering encoder to directly measure steering angle without the use of gears. This eliminates encoder backlash and reduces part count.

The MK4 module ships unassembled, and **the following components are not included:**

- Drive motor (REV Robotics NEO or VEX Falcon 500 recommended)
- Steering motor (REV Robotics NEO or VEX Falcon 500 recommended)
- Steering encoder (CTRE CANcoder, Thrifty Absolute Magnetic Encoder, or equivalent)

Note: The above steering encoders come with the $\varnothing.250$ "x 0.500" magnet that gets installed in the Swerve Module's Center Column. That magnet is not included in the Swerve Module kit.

The MK4 is also compatible with VersaPlanetary gearboxes with CIM output shafts. CIM motors are not compatible with the MK4 due to their larger diameter. The MK4 module is available with either NEO 8mm bore pinion gears, or Falcon 500 spline bore pinion gears.

The steering gear ratio of the MK4 is 12.8:1 The MK4 is available in 4 different drive gear ratios. The table below shows the drive gear ratios and free speeds with NEO and Falcon 500 motors. L1 and L2 ratios are the most popular ratios and are suitable for standard full weight competition robots. The L3 ratio is more aggressive and is recommended for light weight robots. The L4 ratio is very aggressive and is only recommended for very light weight mini bots.

Gear Ratio Options								
Stage	L1 Ratio		L2 Ratio		L3 Ratio		L4 Ratio	
	Driving Gear (teeth)	Driven Gear (teeth)	Driving Gear (teeth)	Driven Gear (teeth)	Driving Gear (teeth)	Driven Gear (teeth)	Driving Gear (teeth)	Driven Gear (teeth)
First	14	50	14	50	14	50	16	48
Second	25	19	27	17	28	16	28	16
Third	15	45	15	45	15	45	15	45
Overall Gear Ratio	8.14 : 1		6.75 : 1		6.12 : 1		5.14 : 1	

Motor			Drivetrain Free Speed (ft/s)			
Model	FOC	Free Speed (RPM)	L1 (8.14 : 1)	L2 (6.75 : 1)	L3 (6.12 : 1)	L4 (5.14 : 1)
Kraken X60	Y	5,800	12.4	15.0	16.5	19.7
	N	6,000	12.9	15.5	17.1	20.4
Falcon 500	Y	6,080	13.0	15.7	17.3	20.6
	N	6,380	13.7	16.5	18.2	21.7
NEO V1.0/V1.1	N/A	5,820	12.5	15.1	16.6	19.8
NEO Vortex	N/A	6,784	14.5	17.6	19.3	23.0

The module easily mounts to common 2X1 frame material. The module typically mounts on top of the robot chassis, however, there is also clearance to mount the chassis on top of the module to maximize ground clearance.

The MK4 module design requires the length of both motor shafts to be reduced by about 0.25in. Alternatively, [motor spacers](#) can be used to eliminate the need to cut the motor shafts.

Starting the week of 12/20/21 MK4 modules have been upgraded to the 15mm width belt and corresponding base pulley that was introduced with the MK4i module. Modules shipped prior to the week of 12/20/21 will have the original 9mm width belt and pulleys.

Weight:

- MK4 module with NEO motors - 4.9 pounds
- MK4 module with Falcon 500 motors - 5.2 pounds

CAD Files:

- [SDS MK4 Swerve Module, Falcons.STEP](#)
- [SDS MK4 Swerve Module, NEOs.STEP](#)

Layout Drawing:

- [PDF File](#)

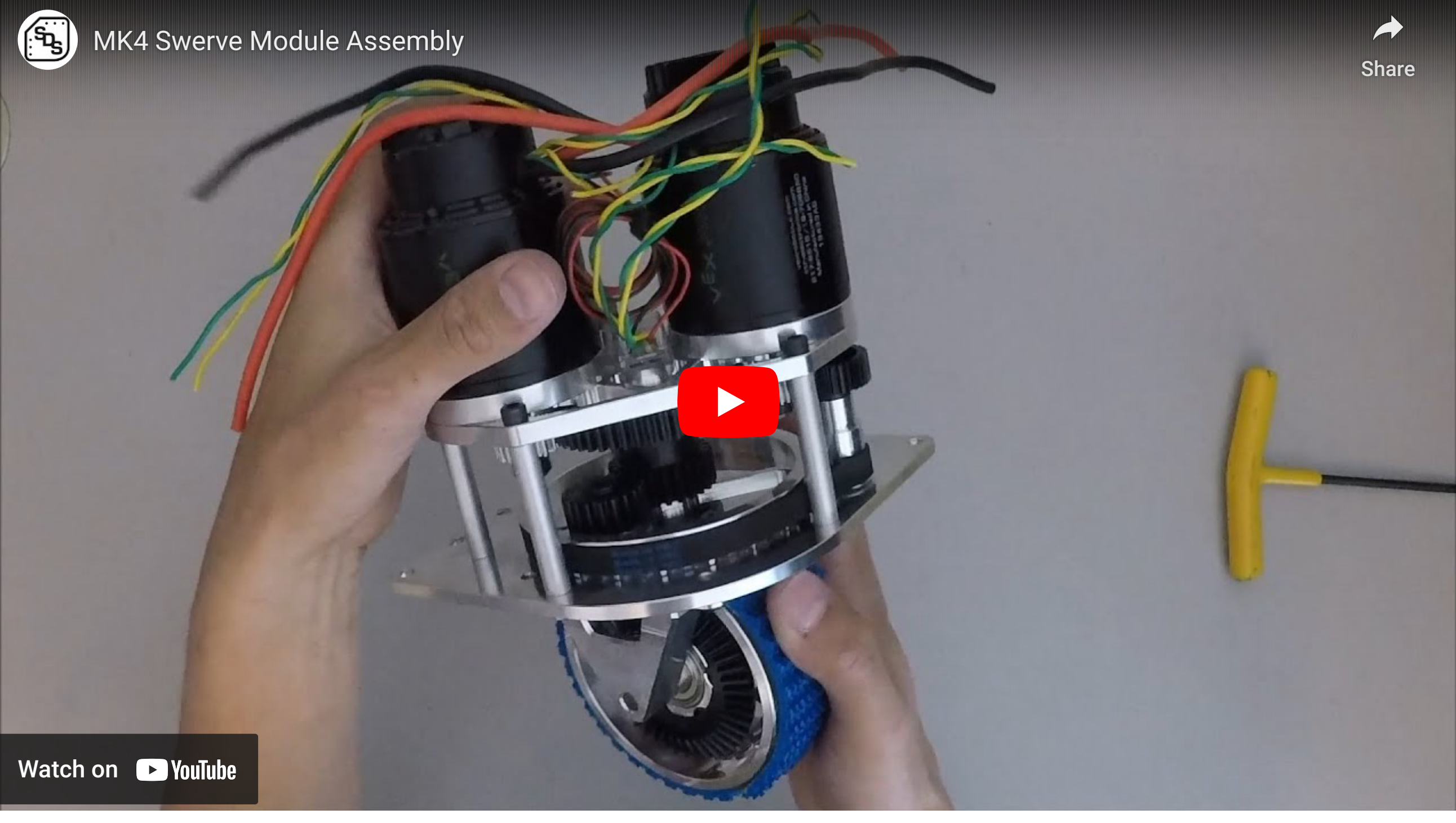
Parts List

- [MK4 Parts List](#)

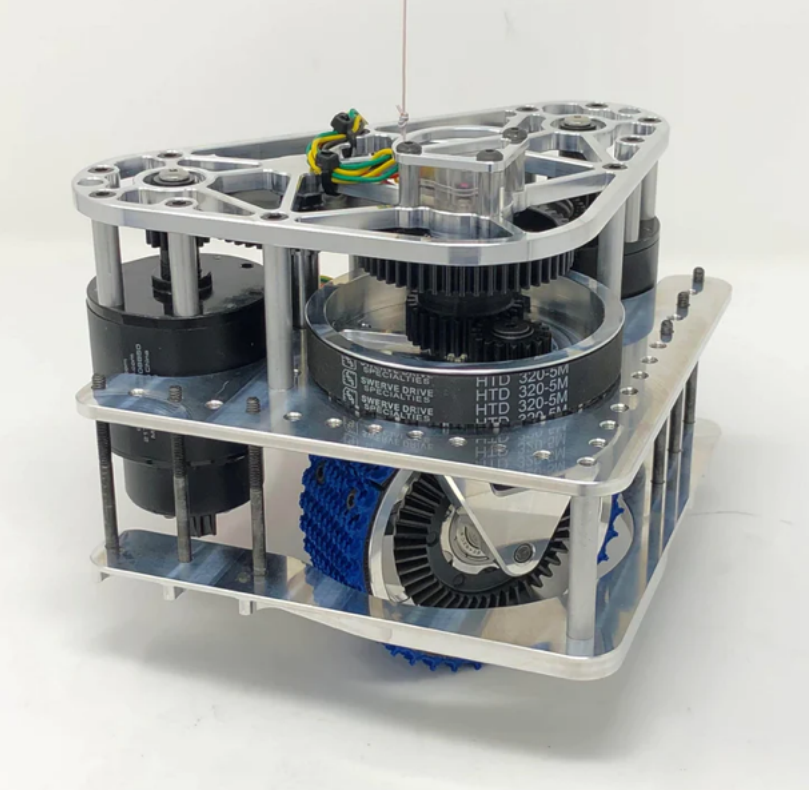
Assembly Guide:

- [MK4 Assembly Guide](#)

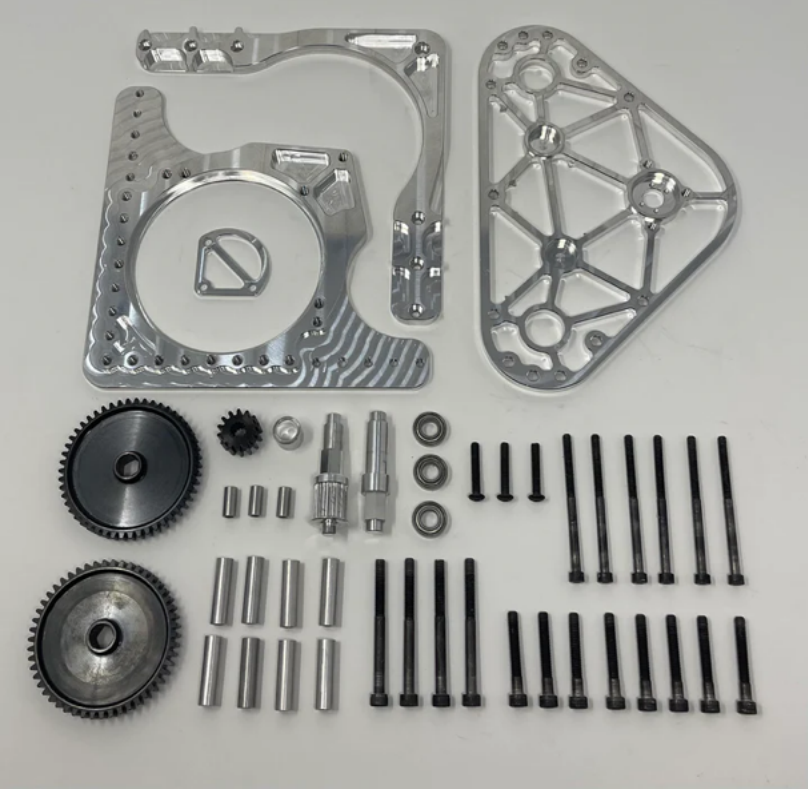
MK4 Assembly Video:



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