

Subgraph isomorphism problem

In theoretical computer science, the **subgraph isomorphism problem** is a computational task in which two graphs G and H are given as input, and one must determine whether G contains a subgraph that is isomorphic to H . Subgraph isomorphism is a generalization of both the **maximum clique problem** and the problem of testing whether a graph contains a **Hamiltonian cycle**, and is therefore **NP-complete**.^[1] However certain other cases of subgraph isomorphism may be solved in polynomial time.^[2]

Sometimes the name **subgraph matching** is also used for the same problem. This name puts emphasis on finding such a subgraph as opposed to the bare decision problem.

1 Decision problem and computational complexity

To prove subgraph isomorphism is NP-complete, it must be formulated as a **decision problem**. The input to the decision problem is a pair of graphs G and H . The answer to the problem is positive if H is isomorphic to a subgraph of G , and negative otherwise.

Formal question:

Let $G = (V, E)$, $H = (V', E')$ be graphs. Is there a subgraph $G_0 = (V_0, E_0) : V_0 \subseteq V, E_0 \subseteq E \cap (V_0 \times V_0)$ such that $G_0 \cong H$? I.e., does there exist an $f : V_0 \rightarrow V'$ such that $(v_1, v_2) \in E_0 \Leftrightarrow (f(v_1), f(v_2)) \in E'$?

The proof of subgraph isomorphism being NP-complete is simple and based on reduction of the **clique problem**, an NP-complete decision problem in which the input is a single graph G and a number k , and the question is whether G contains a **complete subgraph** with k vertices. To translate this to a subgraph isomorphism problem, simply let H be the complete graph K_k ; then the answer to the subgraph isomorphism problem for G and H is equal to the answer to the clique problem for G and k . Since the clique problem is NP-complete, this **polynomial-time many-one reduction** shows that subgraph isomorphism is also NP-complete.^[3]

An alternative reduction from the **Hamiltonian cycle** problem translates a graph G which is to be tested for Hamiltonicity into the pair of graphs G and H , where H is a cycle having the same number of vertices as G . Because the Hamiltonian cycle problem is NP-complete even for **planar graphs**, this shows that subgraph isomorphism remains NP-complete even in the planar case.^[4]

Subgraph isomorphism is a generalization of the **graph isomorphism problem**, which asks whether G is isomorphic to H : the answer to the graph isomorphism problem is true if and only if G and H both have the same numbers of vertices and edges and the subgraph isomorphism problem for G and H is true. However the complexity-theoretic status of graph isomorphism remains an open question.

In the context of the **Aanderaa–Karp–Rosenberg conjecture** on the **query complexity** of monotone graph properties, **Gröger (1992)** showed that any subgraph isomorphism problem has query complexity $\Omega(n^{3/2})$; that is, solving the subgraph isomorphism requires an algorithm to check the presence or absence in the input of $\Omega(n^{3/2})$ different edges in the graph.^[5]

2 Algorithms

Ullmann (1976) describes a recursive backtracking procedure for solving the subgraph isomorphism problem. Although its running time is, in general, exponential, it takes polynomial time for any fixed choice of H (with a polynomial that depends on the choice of H). When G is a **planar graph** (or more generally a graph of **bounded expansion**) and H is fixed, the running time of subgraph isomorphism can be reduced to **linear time**.^[2]

Ullmann (2010) is a substantial update to the 1976 subgraph isomorphism algorithm paper.

3 Applications

As subgraph isomorphism has been applied in the area of **cheminformatics** to find similarities between chemical compounds from their structural formula; often in this area the term **substructure search** is used.^[6] A query structure is often defined graphically using a **structure editor** program; **SMILES** based database systems typically define queries using **SMARTS**, a **SMILES** extension.

The closely related problem of counting the number of isomorphic copies of a graph H in a larger graph G has been applied to pattern discovery in databases,^[7] the **bioinformatics** of protein-protein interaction networks,^[8] and in **exponential random graph** methods for mathematically modeling **social networks**.^[9]

Ohlrich et al. (1993) describe an application of subgraph isomorphism in the computer-aided design of electronic

circuits. Subgraph matching is also a substep in graph rewriting (the most runtime-intensive), and thus offered by graph rewrite tools.

The problem is also of interest in artificial intelligence, where it is considered part of an array of pattern matching in graphs problems; an extension of subgraph isomorphism known as graph mining is also of interest in that area.^[10]


4 See also

- Frequent subtree mining
- Induced subgraph isomorphism problem
- Maximum common edge subgraph problem
- Maximum common subgraph isomorphism problem

5 Notes

- [1] The original Cook (1971) paper that proves the Cook–Levin theorem already showed subgraph isomorphism to be NP-complete, using a reduction from 3-SAT involving cliques.
- [2] Eppstein (1999); Nešetřil & Ossona de Mendez (2012)
- [3] Wegener, Ingo (2005), *Complexity Theory: Exploring the Limits of Efficient Algorithms*, Springer, p. 81, ISBN 9783540210450.
- [4] de la Higuera, Colin; Janodet, Jean-Christophe; Samuel, Émilie; Damiand, Guillaume; Solnon, Christine (2013), “Polynomial algorithms for open plane graph and subgraph isomorphisms” (PDF), *Theoretical Computer Science*, **498**: 76–99, doi:10.1016/j.tcs.2013.05.026, MR 3083515, It is known since the mid-70’s that the isomorphism problem is solvable in polynomial time for plane graphs. However, it has also been noted that the subisomorphism problem is still NP-complete, in particular because the Hamiltonian cycle problem is NP-complete for planar graphs.
- [5] Here Ω invokes Big Omega notation.
- [6] Ullmann (1976)
- [7] Kuramochi & Karypis (2001).
- [8] Pržulj, Corneil & Jurisica (2006).
- [9] Snijders et al. (2006).
- [10] <http://www.aaai.org/Papers/Symposia/Fall/2006/FS-06-02/FS06-02-007.pdf>; expanded version at <https://e-reports-ext.llnl.gov/pdf/332302.pdf>

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