

P (complexity)

In computational complexity theory, **P**, also known as **PTIME** or **DTIME**($n^{O(1)}$), is a fundamental complexity class. It contains all decision problems that can be solved by a deterministic Turing machine using a polynomial amount of computation time, or polynomial time.

Cobham's thesis holds that P is the class of computational problems that are "efficiently solvable" or "tractable"; in practice, some problems not known to be in P have practical solutions, and some that are in P do not, but this is a useful rule of thumb.

1 Definition

A language L is in P if and only if there exists a deterministic Turing machine M , such that

- M runs for polynomial time on all inputs
- For all x in L , M outputs 1
- For all x not in L , M outputs 0

P can also be viewed as a uniform family of **boolean circuits**. A language L is in P if and only if there exists a **polynomial-time uniform** family of boolean circuits $\{C_n : n \in \mathbb{N}\}$, such that

- For all $n \in \mathbb{N}$, C_n takes n bits as input and outputs 1 bit
- For all x in L , $C_{|x|}(x) = 1$
- For all x not in L , $C_{|x|}(x) = 0$

The circuit definition can be weakened to use only a **logspace uniform** family without changing the complexity class.

2 Notable problems in P

P is known to contain many natural problems, including the decision versions of **linear programming**, calculating the **greatest common divisor**, and finding a **maximum matching**. In 2002, it was shown that the problem of determining if a number is **prime** is in P.^[1] The related class of **function problems** is FP.

Several natural problems are complete for P, including **st-connectivity** (or **reachability**) on alternating graphs.^[2]

The article on **P-complete problems** lists further relevant problems in P.

3 Relationships to other classes

A generalization of P is **NP**, which is the class of **decision problems** decidable by a **non-deterministic Turing machine** that runs in **polynomial time**. Equivalently, it is the class of decision problems where each "yes" instance has a polynomial size certificate, and certificates can be checked by a polynomial time deterministic Turing machine. The class of problems for which this is true for the "no" instances is called **co-NP**. P is trivially a subset of NP and of co-NP; most experts believe it is a proper subset,^[3] although this (the $P \subsetneq NP$ hypothesis) remains unproven. Another open problem is whether $NP = co-NP$ (a negative answer would imply $P \subsetneq NP$).

P is also known to be at least as large as L, the class of problems decidable in a **logarithmic** amount of **memory space**. A decider using $O(\log n)$ space cannot use more than $2^{O(\log n)} = n^{O(1)}$ time, because this is the total number of possible configurations; thus, L is a subset of P. Another important problem is whether $L = P$. We do know that $P = AL$, the set of problems solvable in logarithmic memory by **alternating Turing machines**. P is also known to be no larger than **PSPACE**, the class of problems decidable in polynomial space. Again, whether $P = PSPACE$ is an open problem. To summarize:

$$L \subseteq AL = P \subseteq NP \subseteq PSPACE \subseteq EXPTIME.$$

Here, **EXPTIME** is the class of problems solvable in exponential time. Of all the classes shown above, only two strict containments are known:

- P is strictly contained in EXPTIME. Consequently, all EXPTIME-hard problems lie outside P, and at least one of the containments to the right of P above is strict (in fact, it is widely believed that all three are strict).
- L is strictly contained in PSPACE.

The most difficult problems in P are **P-complete** problems.

Another generalization of P is **P/poly**, or Nonuniform Polynomial-Time. If a problem is in P/poly, then it can

be solved in deterministic polynomial time provided that an **advice string** is given that depends only on the length of the input. Unlike for NP, however, the polynomial-time machine doesn't need to detect fraudulent advice strings; it is not a verifier. P/poly is a large class containing nearly all practical problems, including all of BPP. If it contains NP, then the **polynomial hierarchy** collapses to the second level. On the other hand, it also contains some impractical problems, including some **undecidable problems** such as the unary version of any undecidable problem.

In 1999, Jin-Yi Cai and D. Sivakumar, building on work by Mitsunori Ogiwara, showed that if there exists a **sparse language** that is P-complete, then $L = P$.^[4]

4 Properties

Polynomial-time algorithms are closed under composition. Intuitively, this says that if one writes a function that is polynomial-time assuming that function calls are constant-time, and if those called functions themselves require polynomial time, then the entire algorithm takes polynomial time. One consequence of this is that P is **low** for itself. This is also one of the main reasons that P is considered to be a machine-independent class; any machine “feature”, such as **random access**, that can be simulated in polynomial time can simply be composed with the main polynomial-time algorithm to reduce it to a polynomial-time algorithm on a more basic machine.

Languages in P are also closed under reversal, intersection, union, concatenation, Kleene closure, inverse homomorphism, and complementation.^[5]

5 Pure existence proofs of polynomial-time algorithms

Some problems are known to be solvable in polynomial-time, but no concrete algorithm is known for solving them. For example, the **Robertson–Seymour theorem** guarantees that there is a finite list of **forbidden minors** that characterizes (for example) the set of graphs that can be embedded on a torus; moreover, Robertson and Seymour showed that there is an $O(n^3)$ algorithm for determining whether a graph has a given graph as a minor. This yields a **nonconstructive proof** that there is a polynomial-time algorithm for determining if a given graph can be embedded on a torus, despite the fact that no concrete algorithm is known for this problem.

6 Alternative characterizations

In descriptive complexity, P can be described as the problems expressible in FO(LFP), the **first-order logic**

with a **least fixed point** operator added to it, on ordered structures. In Immerman's 1999 textbook on descriptive complexity,^[6] Immerman ascribes this result to Vardi^[7] and to Immerman.^[8]

It was published in 2001 that PTIME corresponds to (positive) **range concatenation grammars**.^[9]

7 History

Kozen^[10] states that Cobham and Edmonds are “generally credited with the invention of the notion of polynomial time.” Cobham invented the class as a robust way of characterizing efficient algorithms, leading to Cobham's thesis. However, H. C. Pocklington, in a 1910 paper,^{[11][12]} analyzed two algorithms for solving quadratic congruences, and observed that one took time “proportional to a power of the logarithm of the modulus” and contrasted this with one that took time proportional “to the modulus itself or its square root”, thus explicitly drawing a distinction between an algorithm that ran in polynomial time versus one that did not.

8 Notes

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9 References

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10 External links

- *Complexity Zoo*: Class P
- *Complexity Zoo*: Class P/poly

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