

# 250A SectionA HW7

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## 7.1 Viterbi algorithm

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The hidden message is

**"THOSE WHO CANOT REMEMBER THE PAST ARE CONDEMNED TO REPEAT IT"**

```
import numpy as np
from matplotlib import pyplot as plt
with open("emissionMatrix.txt",'r') as f:
    emissionF = f.readlines()
with open("initialStateDistribution.txt",'r') as f:
    initStateF = f.readlines()
with open("observations.txt",'r') as f:
    obsvF = f.readlines()
with open("transitionMatrix.txt",'r') as f:
    transF = f.readlines()
bM = np.zeros((27,2))
for index,line in enumerate(emissionF):
    item0,item1 = line.strip().split("\t")
    bM[index][0] = float(item0)
    bM[index][1] = float(item1)

pi = np.zeros((27,))
for index,line in enumerate(initStateF):
    pi[index] = float(line.strip())

obsvM = np.array([int (i) for i in obsvF[0].strip().split(" ")])

aM = np.zeros((27,27))
for index,line in enumerate(transF):
    items = line.strip().split(" ")
    for j,item in enumerate(items):
        aM[index][j] = float(item)
print("Start forwardrecursion...")
l = []
```

```

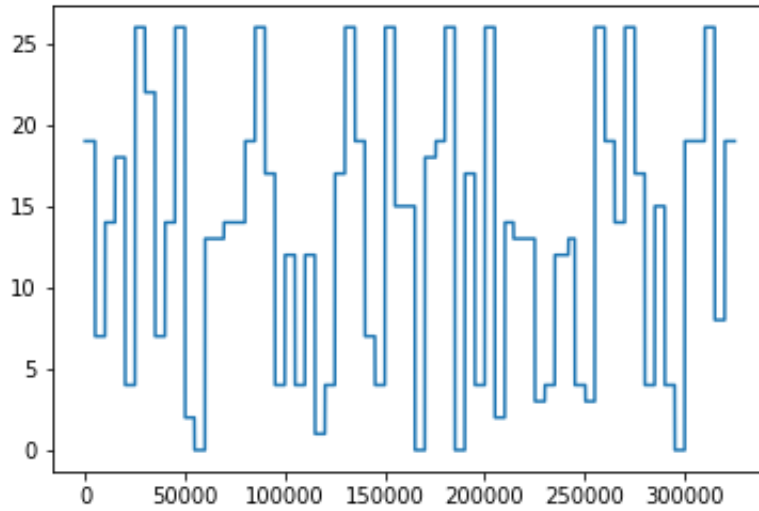
base = [0] * 27
for i in range(27):
    base[i] = np.log(pi[i]) + np.log(bM[i][obsvM[0]])
l.append(base)
T = obsvM.shape[0]
phi = []
for t in range(1,T):
    baseline = [0] * 27
    phiTmp = [0] * 27
    for j in range(27):
        maxTmp = l[t-1][0] + np.log(aM[0,j])
        for i in range(1,27):
            if (l[t-1][i] + np.log(aM[i,j])) > maxTmp:
                maxTmp = l[t-1][i] + np.log(aM[i,j])
                phiTmp[j] = i
        baseline[j] = maxTmp + np.log(bM[j,obsvM[t]])
    phi.append(phiTmp)
    l.append(baseline)

print("Start backtracking...")
maxTmp = l[T-1][0]
index = 0
for i in range(1, 27):
    if l[T-1][i] > maxTmp:
        maxTmp = l[T-1][i]

S = [index]
i = T-2
while (i >= 0):
    index = phi[i][index]
    S = [index] + S
    i -= 1
plt.plot(range(T),S)

message = chr(S[0]+65)
for index in range(1,T):
    if(S[index]!=S[index-1] and S[index]!=26):
        message += chr(S[index]+65)
    elif(S[index]!=S[index-1] and S[index]==26):
        message += ' '
print("The encoded hidden message is:",message)

```



## 7.2 Inference in HMMs

(a)

$$\begin{aligned}
 & P(S_t = i | S_{t+1} = j, O_1, O_2, \dots, O_T) \\
 &= \frac{P(S_{t+1} = j, S_t = i, O_1, O_2, \dots, O_T)}{P(S_{t+1} = j, O_1, O_2, \dots, O_T)} \quad (PR) \\
 &= \frac{P(S_t = i, O_1, \dots, O_t) P(S_{t+1} = j | S_t = i, O_1, O_2, \dots, O_t) \times}{P(O_{t+1} | S_{t+1} = j, S_t = i, O_1, \dots, O_t) P(O_{t+2}, \dots, O_T | S_{t+1} = j, S_t = i, O_1, \dots, O_{t+1})} \quad (PR) \\
 &= \frac{P(S_{t+1} = j, O_1, O_2, \dots, O_T)}{P(S_t = i, O_1, \dots, O_t) P(S_{t+1} = j | S_t = i) P(O_{t+1} | S_{t+1} = j) P(O_{t+2}, \dots, O_T | S_{t+1} = j)} \quad (Mar, CI) \\
 &= \frac{\sum_k P(S_{t+1} = j, S_t = k, O_1, \dots, O_T)}{P(S_{t+1} = j, O_1, O_2, \dots, O_T)} \\
 &= \frac{\alpha_{it} a_{ij} b_j(O_{t+1}) \beta_{jt+1}}{\sum_k \alpha_{kt} a_{kj} b_j(O_{t+1}) \beta_{jt+1}}
 \end{aligned}$$

(b)

$$\begin{aligned}
 & P(S_{t+1} = j | S_t = i, O_1, O_2, \dots, O_T) \\
 &= \frac{P(S_{t+1} = j, S_t = i, O_1, O_2, \dots, O_T)}{P(S_{t+1} = k, S_t = i, O_1, O_2, \dots, O_T)} \quad (PR + Mar) \\
 &= \frac{\alpha_{it} a_{ij} b_j(O_{t+1}) \beta_{jt+1}}{\sum_k \alpha_{it} a_{ik} b_k(O_{t+1}) \beta_{kt+1}}
 \end{aligned}$$

(c)

$$\begin{aligned}
& P(S_{t-1} = i, S_t = k, S_{t+1} = j | o_1, o_2, \dots, o_T) \\
&= \frac{P(S_{t-1} = i, S_t = k, S_{t+1} = j, o_1, o_2, \dots, o_T)}{P(o_1, o_2, \dots, o_T)} \\
& \quad P(o_1, \dots, o_{t-1}, S_{t-1} = i) \times \\
& \quad P(S_t = k | S_{t-1} = i, o_1, \dots, o_{t-1}) \times \\
& \quad P(O_t | S_t = k, S_{t-1} = i, o_1, \dots, o_{t-1}) \times \\
& \quad P(S_{t+1} = j | S_t = k, S_{t-1} = i, o_1, \dots, o_t) \times \\
& \quad P(O_{t+1} | S_{t+1} = j, S_t = k, S_{t-1} = i, o_1, \dots, o_t) \times \\
& \quad P(O_{t+2} \dots O_T | S_{t+1} = j, S_t = k, S_{t-1} = i) \\
&= \frac{\sum_i \alpha_{iT}}{(PR + MAR)} \\
& \quad P(o_1, \dots, o_{t-1}, S_{t-1} = i) P(S_t = k | S_{t-1} = i) P(O_t | S_t = k) \times \\
& \quad P(S_{t+1} = j | S_t = k) P(O_{t+1} | S_{t+1} = j) P(O_{t+2} \dots O_T | S_{t+1} = j) \\
&= \frac{\sum_i \alpha_{iT}}{(CI)} \\
&= \frac{\alpha_{it-1} a_{ik} b_k(O_t) a_{kj} b_j(O_{t+1}) \beta_{jt+2}}{\sum_i \alpha_{iT}}
\end{aligned}$$

(d)

$$\begin{aligned}
& P(S_{t-1} = i | S_{t+1} = j, o_1, o_2, \dots, o_T) \\
&= \frac{P(S_{t-1} = i, S_{t+1} = j, o_1, o_2, \dots, o_T)}{P(S_{t+1} = j, O_1, O_2, \dots, O_T)} \quad (PR) \\
&= \frac{\sum_k P(S_{t-1} = i, S_t = k, S_{t+1} = j, o_1, o_2, \dots, o_T)}{\sum_k P(S_{t+1} = j, S_t = k, o_1, o_2, \dots, o_T)} \quad (Mar) \\
&= \frac{\sum_k \alpha_{it-1} a_{ik} b_k(O_t) a_{kj} b_j(O_{t+1}) \beta_{jt+2}}{\sum_k \alpha_{kt} a_{kj} b_j(O_{t+1}) \beta_{jt+1} \sum_i \alpha_{iT}}
\end{aligned}$$

## 7.3 Conditional independence

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$P(S_t S_{t-1}) = P(S_t S_{t-1}, O_t)$	false
$P(S_t S_{t-1}) = P(S_t S_{t-1}, S_{t+1})$	false
$P(S_t S_{t-1}) = P(S_t S_{t-1}, O_{t-1})$	true
$P(S_t O_{t-1}) = P(S_t O_1, O_2, \dots, O_{t-1})$	false
$P(O_t S_{t-1}) = P(O_t S_{t-1}, O_{t-1})$	true
$P(O_t O_{t-1}) = P(O_t O_1, O_2, \dots, O_{t-1})$	false
$P(O_1, O_2, \dots, O_T) = \prod_{t=1}^T P(O_t O_1, \dots, O_{t-1})$	true
$P(S_2, S_3, \dots, S_T S_1) = \prod_{t=2}^T P(S_t S_{t-1})$	true
$P(S_1, S_2, \dots, S_{T-1} S_1) = \prod_{t=1}^{T-1} P(S_t S_{t-1})$	true
$P(O_1, O_2, \dots, O_{T-1}, S_2, \dots, S_T) = \prod_{t=1}^T P(O_t S_t)$	true
$P(S_1, S_2, \dots, S_{T-1}, O_1, O_2, \dots, O_T) = \prod_{t=1}^T P(S_t O_t)$	false
$P(S_1, S_2, \dots, S_T, O_1, O_2, \dots, O_T) = \prod_{t=1}^T P(S_t, O_t)$	false

## 7.4 Belief updating

(a)

$$\begin{aligned}
q_{jt} &= P(S_t = j|O_1, O_2, \dots, O_t) \\
&= \frac{P(S_t = j, O_1, O_2, \dots, O_t)}{P(O_1, O_2, \dots, O_t)} \\
&= \frac{\sum_i P(S_t = j, S_{t-1} = i, O_1, O_2, \dots, O_t)}{\sum_{k,i} P(S_t = k, S_{t-1} = i, O_1, O_2, \dots, O_t)} \\
&= \frac{\sum_j P(O_1, O_2, \dots, O_{t-1})P(S_{t-1} = i|O_1, O_2, \dots, O_{t-1})P(S_t = j|S_{t-1} = i)P(O_t|S_t = j)}{\sum_{k,i} P(O_1, O_2, \dots, O_t)P(S_{t-1} = i|O_1, O_2, \dots, O_{t-1})P(S_t = k|S_{t-1} = i)P(O_t|S_t = k)} \\
&= \frac{b_j(O_t) \sum_j q_{i(t-1)} a_{ji}}{\sum_{kj} q_{i(t-1)} a_{ik} b_k(O_t)}
\end{aligned}$$

(b)

$$\begin{aligned}
& P(x_t | y_1, y_2, \dots, y_t) \\
&= \frac{P(x_t, y_1, y_2, \dots, y_t)}{P(y_1, y_2, \dots, y_t)} \quad (PR) \\
&= \frac{\int dx_{t-1} P(x_t, x_{t-1}, y_1, y_2, \dots, y_t)}{\int dx_t \int dx_{t-1} P(x_t, x_{t-1}, y_1, y_2, \dots, y_t)} \quad (MAR) \\
&= \frac{\int dx_{t-1} P(y_t | x_t) P(x_t = j | x_{t-1}) P(x_{t-1} | y_1, y_2, \dots, y_{t-1}) P(y_1, y_2, \dots, y_{t-1})}{\int dx_t \int dx_{t-1} P(y_t | x_t) P(x_t = j | x_{t-1}) P(x_{t-1} | y_1, y_2, \dots, y_{t-1}) P(y_1, y_2, \dots, y_{t-1})} \quad (PR \& d - sep) \\
&= \frac{P(y_t | x_t) \int dx_{t-1} P(x_t | x_{t-1}) P(x_{t-1} | y_1, y_2, \dots, y_{t-1})}{\int P(y_t | x_t) dx_t \int dx_{t-1} P(x_t | x_{t-1}) P(x_{t-1} | y_1, y_2, \dots, y_{t-1})}
\end{aligned}$$

The reason why it's difficult for all is it's difficult to compute the integrals of conditional probability. However, if  $P(x)$  is Gaussian, then  $P(x_t | x_{t-1})$  is also Gaussian. So it will be easier to compute the integrals.

## 7.5 V-chain

### (a) Base case

$$\begin{aligned}
& P(Y_1 = j, O_1 = o_1) \\
&= \sum_i P(P_1 = o_1, Y_1 = j, X_1 = i) \\
&= \sum_i P(P_1 = o_1 | Y_1 = j, X_1 = i) P(X_1 = i) P(Y_1 = j) \\
&= \left\{ \sum_i b_{ij}(o_1) P(X_1 = i) \right\} \pi_j
\end{aligned}$$

### (b) Forward Algorithm

$$\begin{aligned}
\alpha_{j(t+1)} &= P(o_1, o_2, \dots, o_{t+1}, Y_{t+1} = j) \\
&= \sum_i P(o_1, o_2, \dots, o_{t+1}, X_{t+1} = i, Y_{t+1} = j) \quad (marginalization) \\
&= \sum_i P(o_{t+1} | X_{t+1} = i, Y_{t+1} = j) P(X_{t+1} = i, Y_{t+1} = j, o_1, \dots, o_t) \quad (PR + d - sep)
\end{aligned}$$

The second term can be denoted by

$$\begin{aligned}
& P(X_{t+1} = i, Y_{t+1} = j, o_1, \dots, o_t) \\
&= \sum_k P(X_{t+1} = i, Y_t = k, Y_{t+1} = j, o_1, \dots, o_t) \quad (marginalization) \\
&= \sum_k P(Y_t = k, o_1, \dots, o_t) P(X_{t+1} = i | Y_t = k, o_1, \dots, o_t) \times \quad (PR) \\
& \quad P(Y_{t+1} = j | X_{t+1} = i, Y_t = k, o_1, \dots, o_t) \\
&= \sum_k \alpha_{kt} a_{ki} \pi_j
\end{aligned}$$

Then substituting the result into the second term

$$\alpha_{j(t+1)} = \sum_i b_{ij}(o_{t+1}) \sum_k \alpha_{kt} a_{ki} \pi_j$$

### (c) Likelihood

$$\begin{aligned} P(o_1, o_2, \dots, o_T) &= \sum_j P(o_1, o_2, \dots, o_T, Y_T = j) \\ &= \sum_j \alpha_{jT} \end{aligned}$$

### (d) Complexity

The base case  $\alpha_{j1}$  is shown in part (a) and its complexity is  $n_x$ .

Then using the base case, we can compute the next case  $\alpha_{j2}$  and its complexity is  $n_x n_y$ .

And so on until computing out  $\alpha_{jT}$ , the whole process should cost  $[(T - 1)n_x n_y + n_x]$ .

Further, there are  $n_y$  cases for index  $j$ . Therefore, the whole complexity is  $n_y[(T - 1)n_x n_y + n_x]$ .

All in all, the complexity is  $O(n_x n_y^2 T)$ .