HW5

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5.1 Gradient based learning

(a)

According to the shorthand,

$$p_t = P(Y=1|\overrightarrow{x_t})$$

Therefore the probability for Y=0 could be

$$P(Y=1|\overrightarrow{x_t})=1-p_t$$

Therefore, given the data for x, the conditional probability for variable Y can also be denoted by

$$P(Y=1|\overrightarrow{x_t})=p_t^{y_t}+(1-p_t)^{1-y_t}$$

Therefore, the log-likelihood can be denoted by

$$egin{aligned} L &= \sum_t log(P(y_t|\overrightarrow{x_t})) \ &= \sum_t log(p_t^{y_t} + (1-p_t)^{1-y_t}) \ &= \sum_t \left[y_t log(p_t) + (1-y_t) log(1-p_t)
ight] \end{aligned}$$

Further, the gradient of the log-likelihood with respect to a w_i can be denoted by

$$egin{aligned} rac{\partial L}{\partial w_i} &= \sum_t \left[rac{y_t}{p_t} f^{'}(ec{w}\cdot\overrightarrow{x_t}) \overrightarrow{x_{it}} - (1-y_t) rac{f^{'}(ec{w},\overrightarrow{x_t})}{1-p_t} x_{it}
ight] \ &= \sum_t rac{f^{'}(ec{w}\cdot\overrightarrow{x_t}) x_{it}}{p_t (1-p_t)} (y_t-p_t) \end{aligned}$$

(b)

If function f is the sigmoid function, accroding to the previous assignment, the derivative of function f can be denoted by

$$f^{'}(z)=f(z) imes (1-f(z))$$

In our situation, the first rerivative will be

$$f^{'}(ec{w}\cdot\overrightarrow{x_{t}})=f(ec{w}\cdot\overrightarrow{x_{t}}) imes(1-f(ec{w}\cdot\overrightarrow{x_{t}}))=p_{t}(1-p_{t})$$

Therefore, the gradient of log-lilelihood is

$$rac{\partial L}{\partial w_i} = \sum_{t=1}^T (y_t) x_{it}$$

5.2 Multinomial logistic regression

Similar to the last problem, we can re-denote p_{it} first.

In this situation, the labels for y is not binary but $1, 2, \ldots, c$

Therefore, the marginalization should be

$$p_{1t} + p_{2t} + \ldots + p_{ct} = 1$$

Therefore, for a given k, the conditional probability should be

$$\left\{egin{aligned} p_{kt} & y_t = 1 \ 1 - \sum_m p_{mt} \; (m
eq k) & y_t = 0 \end{aligned}
ight.$$

Therefore, the probability p_{it} can be denoted by

$$p_{it} = \sum_{k=1}^{c} \left[p_{kt}^{y_{kt}} + (1-p_{kt})^{1-y_{kt}}
ight]$$

Further, the gradient of log-likelihood is

$$egin{aligned} L &= \sum_{t} log(P(y_t = i | \overrightarrow{x_t})) \ &= \sum_{t} \sum_{k} \left[y_{kt} log(p_{kt}) + (1 - y_{kt}) log(1 - p_{kt})
ight] \end{aligned}$$

Therefore,

$$egin{aligned} rac{\partial L}{\partial w_i} &= \sum_t \sum_i rac{y_{it}}{p_{it}} \overrightarrow{x_t} - rac{(1-y_{it})}{1-p_{it}} \overrightarrow{x_t} \ &= \sum_t \sum_i rac{y_{it}-p_{it}}{p_{it} \left(1-p_{it}
ight)} rac{\partial p_{it}}{\partial \overrightarrow{w_t}} \end{aligned}$$

Therefore,

$$p_{it}(1-p_{it}) = \frac{e^{\overrightarrow{w_{j}} \cdot \overrightarrow{x_{t}}}}{\sum_{i=1}^{c} e^{\overrightarrow{w_{j}} \cdot \overrightarrow{x_{t}}}} \times \frac{\sum_{j=1}^{c} e^{\overrightarrow{w_{j}} \cdot \overrightarrow{x_{t}}} - e^{\overrightarrow{w_{j}} \cdot \overrightarrow{x_{t}}}}{\sum_{i=1}^{c} e^{\overrightarrow{w_{j}} \cdot \overrightarrow{x_{t}}}} = \frac{e^{\overrightarrow{w_{j}}}(\sum_{j=1}^{c} e^{\overrightarrow{w_{j}} \cdot \overrightarrow{x_{t}}} - e^{\overrightarrow{w_{j}} \cdot \overrightarrow{x_{t}}})}{(\sum_{i=1}^{c} e^{\overrightarrow{w_{j}} \cdot \overrightarrow{x_{t}}})^{2}}$$

And

$$\frac{\partial p_{it}}{\partial \overrightarrow{w_t}} = \frac{e^{\overrightarrow{w_j} \cdot \overrightarrow{x_t}} \overrightarrow{x_t} (\sum_{j=1}^c e^{\overrightarrow{w_j} \cdot \overrightarrow{x_t}}) - (e^{\overrightarrow{w_j} \cdot \overrightarrow{x_t}})^2 \overrightarrow{x_t}}{(\sum_{j=1}^c e^{\overrightarrow{w_j} \cdot \overrightarrow{x_t}})^2} = \frac{e^{\overrightarrow{w_j} \cdot \overrightarrow{x_t}} (\sum_{j=1}^c e^{\overrightarrow{w_j} \cdot \overrightarrow{x_t}} - e^{\overrightarrow{w_j} \cdot \overrightarrow{x_t}})}{\sum_{j=1}^c e^{\overrightarrow{w_j} \cdot \overrightarrow{x_t}}} \overrightarrow{x_t}$$

Therefore,

$$rac{\partial L}{\partial w_i} = \sum_t \left(y_{it} - p_{it}
ight) \overrightarrow{x_t}$$

5.3

(a)

For the function f(x) in this problem, the first derivative is

$$f^{'}(x) = \alpha(x - x_*)$$

Therefore, the n^{th} iteration can be denoted by

$$x_n=x_{n-1}-\eta lpha(x_{n-1}-x_*)$$

So, the error at n^{th} could be

$$\epsilon_n = \epsilon_{n-1} - \eta \alpha \epsilon_{n-1} = \epsilon_{n-1} (1 - \eta \alpha)$$

Finally, the error at n^{th} iteration can be denoted in terms of the initial error ϵ_0

$$\epsilon_n = \epsilon_0 (1 - \eta \alpha)^{n-1}$$

(b)

First of all, we need to determine the expression of $f^{''}(x_n)$.

$$f^{''}(x_n)=lpha$$

In order to make the update rule converging to x_* , we should enable the value of $|1 - \eta \alpha| < 1$ so that the error can be less and less.

Therefore, η should locate in the following range

$$0<\eta<rac{2}{lpha}$$

When $|1-\eta\alpha|$ becomes more closer to zero, the convergence will be faster. The smallest value of $|1-\eta\alpha|$ is 0. Therefore, at this moment,

$$\eta = \frac{1}{\alpha}$$

Using the expression of $f^{''}(x_n)$, the equation can also be denoted by following

$$\eta=rac{1}{f^{''}(x_n)}$$

(c)

Still focusing on the second the quadratic function $f(x)=\frac{\alpha}{2}(x-x_*)^2$ and $f'(x)=\alpha(x-x_*)$, the updating rule can be denoted by the following

$$egin{aligned} x_{n+1} &= x_n - \eta lpha(x_n - x_*) + eta(x_n - x_{n-1}) \ x_{n+1} - x_* &= x_n - x_* - \eta lpha(x_n - x_*) + eta(x_n - x_{n-1}) \ \epsilon_{n+1} &= \epsilon_n - \eta lpha \epsilon_n + eta((x_n - x_*) - (x_{n-1} - x_*)) \ \epsilon_{n+1} &= \epsilon_n - \eta lpha \epsilon_n + eta(\epsilon_n - \epsilon_{n-1}) \ \epsilon_{n+1} &= (1 - \eta lpha + eta) \epsilon_n - eta \epsilon_{n-1} \end{aligned}$$

(d)

Given the parameters

$$\epsilon_{n+1}=(1-rac{4}{9}+rac{1}{9})\epsilon_n-rac{1}{9}\epsilon_{n-1}$$
 $\epsilon_{n+1}=(rac{2}{3})\epsilon_n-rac{1}{9}\epsilon_{n-1}$

Therefore, we can recursively write down the equation for each iteration

Assume that one solution to the recursion is $\epsilon_n = \lambda^n \epsilon_0$, then substitute it in order to determine parameter λ .

$$\lambda^{n+1}\epsilon_0 = \frac{2}{3}\lambda^n\epsilon_0 - \frac{1}{9}\lambda^{n-1}\epsilon_0$$
$$9\lambda^2 - 6\lambda + 1 = 0$$
$$(3\lambda - 1)^2 = 0$$
$$\lambda = \frac{1}{3}$$

Therefore,

$$\epsilon_n=(rac{1}{3})^n\epsilon_0$$

5.4 Newton's method

(a)

First of all, we need to derive the expression for first derivative and second derivative for the given polynomial function.

$$f^{'}(x_n)=2p(x_n-x_*)^{2p-1} \ f^{''}(x_n)=2p(2p-1)(x_n-x_*)^{2p-2}$$

Further, computing the error for iteration n^{th}

$$egin{aligned} x_{n+1} &= x_n - rac{x_n - x_*}{2p-1} \ x_{n+1} - x_* &= x_n - x_* - rac{x_n - x_*}{2p-1} \ \epsilon_{n+1} &= \epsilon_n rac{2p-2}{2p-1} \end{aligned}$$

Recursively, it has

$$\epsilon_n = (\frac{2p-2}{2p-1})^n \epsilon_0$$

(b)

According to the requirement $\epsilon_n \leq \delta \epsilon_0$, it can be substitute with ϵ_n

$$(rac{2p-2}{2p-1})^n\epsilon_0 \leq \delta\epsilon_0 \ nlog(rac{2p-2}{2p-1}) \leq log(\delta)$$

According to the hint $log z \leq z-1$, the denominator can be denoted by

$$egin{aligned} n(rac{2p-2}{2p-1}-1) & \leq log(\delta) \ n(rac{-1}{2p-1}) & \leq log(\delta) \ n & \geq -(2p-1)log(\delta) \ n & \geq (2p-1)log(rac{1}{\delta}) \end{aligned}$$

(c)

In order to compute the minimum of the function, we should make the first derivative equal zero.

$$f^{'}(x) = -x_*rac{x}{x*}rac{x_*}{x^2}+1 = -rac{x_*}{x}+1 = 0$$

Therefore, when $x=x_*$, the function occurs minimum.

(d)

$$f^{''}(x) = \frac{x_*}{x^2}$$

According to Newton's method, the updating rule is

$$egin{aligned} x_{n+1} &= x_n - rac{f^{'}(x_n)}{f^{''}(x_n)} \ &= x_n - rac{x_n(x_n - x_*)}{x_*} \ &= rac{2x_nx_* - x_n^2}{x_*} \end{aligned}$$

Therefore, the relative error at n^{th} is

$$ho_n = rac{2n - 1x_* - x_n^2 - x_*^2}{x_*^2} = rac{-(x_* - x_{n-1})^2}{x_*^2} = -
ho_{n-1}^2$$

If the method want's to be converged, $|\rho_0|$ should less than 1, which means

$$egin{aligned} |
ho_0| &< 1 \ -1 &<
ho_0 &< 1 \ -1 &< rac{x_0 - x_*}{x_*} &< 1 \ 0 &< x_0 &< 2x_* \end{aligned}$$

5.5

(a)

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-0.08999777 -0.06336839]]
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The plots are shown in the attachment.

(b)

The error rate of the model is 7.1249999999999998

(c)

See in the attachment.