

CSE 250B: Homework 6 Solutions

1. Here is a linear program, over variables $x \in \mathbb{R}^n$ and $v \in \mathbb{R}$:

$$\begin{aligned} & \min v \\ & -b_i + \sum_{j=1}^n a_{ij}x_j \leq v, \quad i = 1, 2, \dots, m \\ & b_i - \sum_{j=1}^n a_{ij}x_j \leq v, \quad i = 1, 2, \dots, m \end{aligned}$$

2. (a) Let K denote the intersection of halfspaces given by $w_1, w_2, \dots \in \mathbb{R}^d$ and $b_1, b_2, \dots \in \mathbb{R}$:

$$K = \bigcap_i \{x : w_i \cdot x \leq b_i\}.$$

For any $x, y \in K$ and $0 < \theta < 1$,

$$w_i \cdot (\theta x + (1 - \theta)y) = \theta w_i \cdot x + (1 - \theta)w_i \cdot y \leq \theta b_i + (1 - \theta)b_i = b_i, \quad \text{for } i = 1, 2, \dots$$

Therefore, $\theta x + (1 - \theta)y \in K$; and K is a convex set.

- (b) The unit ball in \mathbb{R}^d can be written as

$$\bigcap_{\|w\|=1} \{x : w \cdot x \leq 1\}.$$

3. P_1 and P_2 are polyhedra that are intersections of finitely many halfspaces. Let the halfspaces for P_1 be given by $u_1, \dots, u_m \in \mathbb{R}^d$ and $b_1, \dots, b_m \in \mathbb{R}$:

$$P_1 = \bigcap_{i=1}^m \{x : u_i \cdot x \leq b_i\}.$$

Likewise, let P_2 be given by $v_1, \dots, v_n \in \mathbb{R}^d$ and $c_1, \dots, c_n \in \mathbb{R}$:

$$P_2 = \bigcap_{i=1}^n \{x : v_i \cdot x \leq c_i\}.$$

We wish to find the point $x_1 \in P_1$ and $x_2 \in P_2$ that are closest to one another. Let us write $z = x_1 - x_2$. Here is the optimization problem:

$$\begin{aligned} & \min \|z\|^2 \\ & u_i \cdot x_1 \leq b_i, \quad i = 1, 2, \dots, m \\ & v_i \cdot x_2 \leq c_i, \quad i = 1, 2, \dots, n \\ & z = x_1 - x_2 \end{aligned}$$

The constraints are all linear, and the objective function is convex, so this is a convex optimization problem.

4. *Monotone disjunctions.*

- (a) There are as many disjunctions as there are subsets of features, so $|\mathcal{H}| = 2^d$.
- (b) The true error of h can be bounded thus, with probability at least $1 - \delta$:

$$\text{err}(h) \leq \frac{1}{n} \ln \frac{|\mathcal{H}|}{\delta} = \frac{1}{n} \left(d \ln 2 + \ln \frac{1}{\delta} \right).$$

- (c) $|\mathcal{H}_k| \leq d^k$, so we get

$$\text{err}(h) \leq \frac{1}{n} \ln \frac{|\mathcal{H}|}{\delta} = \frac{1}{n} \left(k \ln d + \ln \frac{1}{\delta} \right).$$

5. By the central limit theorem, \hat{p} follows roughly a $N(3/4, 1/1600)$ distribution. With 95% probability, \hat{p} will fall within 2 standard deviations of its mean, that is, in the interval $[0.7, 0.8]$.

6. *VC dimension.*

- (a) The class \mathcal{H} of intervals on the real line shatters any set of two distinct points: it can realize all four labelings of these points. But it cannot shatter any set of three points, because it cannot label the middle one 0 while making the other two 1. Therefore $\text{VC}(\mathcal{H}) = 2$.
- (b) The class \mathcal{H} of axis-aligned rectangles in the plane shatters the set $\{(0, 1), (0, -1), (1, 0), (-1, 0)\}$: all 16 labelings can be realized. But it cannot shatter any set of five points. To see this, pick any $x_1, \dots, x_5 \in \mathbb{R}^2$. One of them must lie in the bounding box of the other four points; say x_5 lies in the bounding box of x_1, x_2, x_3, x_4 . Then we cannot realize the labeling $y_1 = y_2 = y_3 = y_4 = 1$ and $y_5 = 0$. Thus $\text{VC}(\mathcal{H}) = 4$.

7. *Isotonic regression.*

- (a) Here's a monotonic function that goes through four of the points.

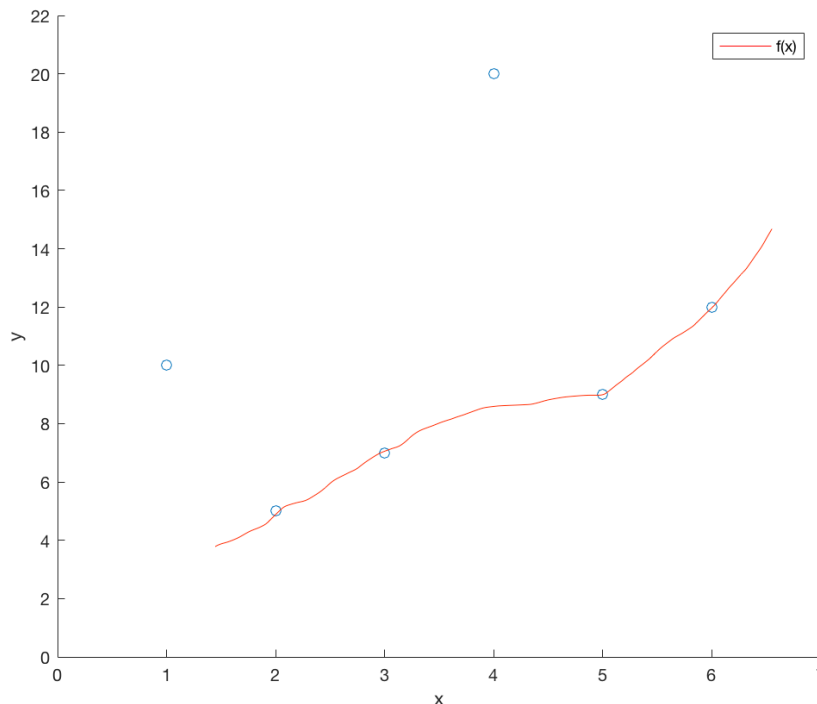


Figure 1: Sketch of $f(x)$

- (b) We can write the least-squares isotonic regression problem as follows:

$$\begin{aligned} \min L(f) &= \sum_{i=1}^n (y_i - f_i)^2 \\ f_i - f_{i+1} &\leq 0 \quad \text{for } i = 1, 2, \dots, n-1 \end{aligned}$$

The constraints are linear in f , and the objective function $L(f)$ is convex: its Hessian is $H(f) = 2I$, which is positive semidefinite. Therefore, the problem above is a convex problem.

- (c) When the pool-adjacent-violators algorithm is applied to the given set of six points, the final adjusted values are:

$$(1, 22/3), (2, 22/3), (3, 22/3), (4, 41/3), (5, 41/3), (6, 41/3).$$