CSE 250B: Machine learning

Winter 2018

Homework 6 — More Convex programs and generalization theory

1. We are given a set of m equations in n unknowns x_1, \ldots, x_n :

$$a_{11}x_1 + \dots + a_{1n}x_n = b_1$$

$$a_{21}x_1 + \dots + a_{2n}x_n = b_2$$

$$\vdots$$

$$a_{m1}x_1 + \dots + a_{mn}x_n = b_m$$

It might not be possible to satisfy all these equations exactly; what we want is to find a solution $x = (x_1, \ldots, x_n)$ such that the maximum deviation

$$\max_{1 \le i \le m} \left| b_i - \sum_{j=1}^n a_{ij} x_j \right|$$

is as small as possible. Write this as a linear program.

- 2. A halfspace in \mathbb{R}^d is specified by a vector $w \in \mathbb{R}^d$ and an offset $b \in \mathbb{R}$, and is defined as $\{x : w \cdot x \leq b\}$.
 - (a) Now suppose we have a collection of halfspaces, given by w_1, w_2, \ldots and b_1, b_2, \ldots , respectively. There might be infinitely many of them. Show that their intersection is a convex set.
 - (b) Can you express the unit ball $\{x \in \mathbb{R}^d : ||x||_2 \le 1\}$ as the intersection of infinitely many halfspaces?
- 3. We are given two polyhedra $P_1, P_2 \subseteq \mathbb{R}^d$, each specified as the intersection of finitely many halfspaces. We would like to find the distance between these two bodies: the smallest possible value $||x_1 x_2||$, where $x_1 \in P_1$ and $x_2 \in P_2$. Show how to express this as a convex program.
- 4. Let $\mathcal{X} = \{0,1\}^d$. The class \mathcal{H} of monotone disjunctions consists of classifiers h that are given by a disjunction (logical OR) of some subset of the d features. For instance, the classifier

$$h(x) = x_1 \vee x_3 \vee x_8$$

assigns label 1 to points $x \in \mathcal{X}$ for which any of the features x_1, x_3, x_8 are set; and assigns label 0 otherwise. Suppose we obtain a training set of n points, drawn i.i.d. from an unknown underlying distribution, and we find a monotone disjunction $h \in \mathcal{H}$ that is correct on all n points. We would like to give a bound on the true error of h.

- (a) What is $|\mathcal{H}|$? Your answer should be a function of d.
- (b) Give a bound on the true error of h that holds with probability at least 1δ over the choice of training data.
- (c) What bound could you give if instead we looked at the smaller class $\mathcal{H}_k \subset \mathcal{H}$ of k-sparse monotone disjunctions: that is, monotone disjunctions consisting of at least 1 and at most k variables?

- 5. Estimating the bias of a coin. A coin of bias 3/4 is tossed 300 times and an empirical estimate \hat{p} of the bias is obtained. Use the central limit theorem to come up with an interval in which \hat{p} will lie, with 95% probability.
- 6. Determine the VC dimension of the following concept classes. Justify your answers.
 - (a) Intervals on the line. $\mathcal{X} = \mathbb{R}$ and $\mathcal{H} = \{h_{a,b} : a, b \in \mathbb{R}, a < b\}$ where $h_{a,b}(x) = 1(a \le x \le b)$.
 - (b) Axis-aligned rectangles in the plane. Each $h \in \mathcal{H}$ is given by an axis-aligned rectangle in \mathbb{R}^2 , where points inside the rectangle are labeled 1, and points outside are labeled 0.
- 7. Isotonic regression. In a line fitting problem, we have a data set consisting of pairs $(x_1, y_1), \ldots, (x_n, y_n) \in \mathbb{R}^2$ and we want to draw a line through them. More precisely, we want to find parameters $a, b \in \mathbb{R}$ such that f(x) = ax + b passes as close as possible to the points. We have already seen a least-squares formulation of this.

In isotonic regression, we allow a more general function f. It doesn't have to be a line: it just needs to be monotonically increasing, that is, $f(x) \ge f(x')$ whenever $x \ge x'$.

(a) Here is a training set of six points (x_i, y_i) :

$$(4,20), (2,5), (5,9), (3,7), (1,10), (6,12).$$

Plot these points, and sketch a function $f: \mathbb{R} \to \mathbb{R}$ that is monotonically increasing and that passes through as many of these points as possible.

Let's sort the data points so that $x_1 \leq x_2 \leq \cdots \leq x_n$. Monotonicity then means

$$f(x_1) < f(x_2) < \dots < f(x_n).$$

In fact, we can choose any $f(x_i)$ values that meet this requirement; and we can fill in the rest of the f-curve by, say, linearly interpolating between these points.

How shall we evaluate candidate functions f? In part (a), we used the loss function

$$L_o(f) = \#$$
 of training points that f does not pass through.

Finding the optimal such f is called the *longest increasing subsequence* problem in computer science, and can be solved efficiently. However, we typically prefer to use a different, *least-squares* loss.

Here is a least-squares formulation of our problem: given $x_1 \leq x_2 \leq \cdots \leq x_n$ and corresponding values y_1, \ldots, y_n , find $f_1, f_2, \ldots, f_n \in \mathbb{R}$ such that $f_1 \leq f_2 \leq \cdots \leq f_n$ and such that the squared loss

$$L(f) = \sum_{i=1}^{n} (y_i - f_i)^2$$

is minimized. (Here f_i corresponds to $f(x_i)$.)

(b) Show that this is a convex optimization problem.

An elegant approach to solving this problem is the *pool adjacent violators* algorithm. It starts by simply setting $f_i = y_i$ for all i, and then repeatedly fixes any monotonicity violations: any time it finds $f_i > f_{i+1}$, it resets both of them to the average of f_i , f_{i+1} and merges points x_i and x_{i+1} .

Here is the algorithm, given a set of x values and their corresponding y(x).

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- ullet Let S be the sorted list of x-values
- For all x in S:
 - Set f(x) = y(x)
 - Assign weight w(x) = 1
- While there adjacent values x < x' in S with f(x) > f(x'):
 - Remove x' from S and set a pointer from it to x
 - Let $f(x) = \frac{w(x)f(x) + w(x')f(x')}{w(x) + w(x')}$ Let w(x) = w(x) + w(x')

At the end, each of the original x-points either lies in the list S, in which case it receives value f(x), or leads to some \tilde{x} in list S by following pointers, in which case it receives value $f(\tilde{x})$.

(c) Run this algorithm on the small data set of six points from part (a). What values of f does it yield?