

FIZZAH NASIR

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Junior Computer Science student with internship experience teaching in IT sector and proficiency in SQL query writing. Project experience includes data visualization and understanding databases using SQL.

EDUCATION

B.C.S., Computer Science

Graduating July, 2026

Forman Christian College University

3.46 GPA

Lahore College for Women University

Relevant coursework: Database systems, Software Engineering, Data Structures and Algorithm in Python

TECHNICAL SKILLS

Data Analysis: Power BI, MS Excel, MS SQL

Design and Modeling Tools: MATLAB

Programming: Python, Java

Certifications: 1st Position in the Robotics Competition held by IEEE

PERSONAL PROJECTS

E-commerce sales interactive Dashboard

Analysed e-commerce sales data

- Used complex parameters to drill down in worksheet and customization using filters and slicers.
- Created connections, join new tables, calculations to manipulate data and enable user-driven parameters for visualizations.

ACADEMIC PROJECTS

Hotel Management System

Spring 2024

Collaborated in a team of three to design database and software for Hotel management system.

- **Database Design:**
 - Designed a normalized database schema using Entity-Relationship (ER) diagrams and created various tables.
 - Developed the database using SQL (DBMS) and implemented primary keys, foreign keys, and indexes to ensure data integrity and optimized performance.
- **Software Design:**
 - Designed and developed a multi-tier hotel management system using HTML for the front-end and Python for the back-end.
 - Implemented core features such as reservation management, check-in/check-out workflows, and reporting with a user-friendly interface.

OTHER WORK EXPERIENCE

Daadras Foundation, Aabroo Welfare High School : IT Instructor

July 2024 – Aug 2024

- Taught 40-50 underprivileged and orphaned teenage students per week in HTML, Scratch programming and AI models

ACTIVITIES

Digital Logic Design Robot

Spring 2024

Won 2nd position in a digital logic design competition for a line-following and obstacle-detecting robot project.

- Designed a digital logic-based robot that autonomously follows lines and detects obstacles and implemented precise sensors and control algorithms for accurate navigation and obstacle avoidance.