

ALL-IN-ONE OUTDOOR SPORTS COMPUTER

M-TRACK

Repository:
https://github.com/Flanker-E/All_In_One_Outdoor_Sports_Computer

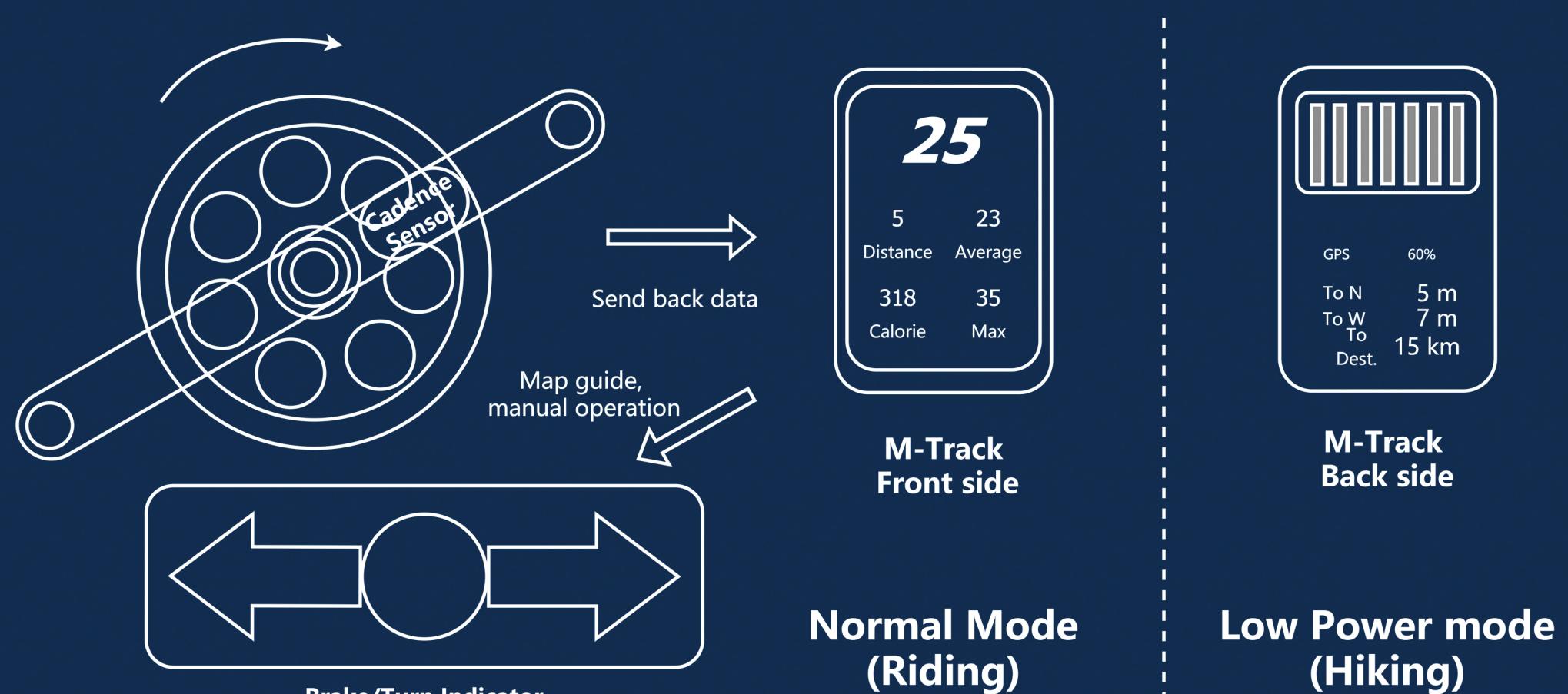
Introduction

We propose an all-in-one outdoor sports computer, the M-track, that offers map navigation and sports recording functions for outdoor sports lovers. It integrates a dual-screen display, SD card, and solar panel. Serving as a terminal, it can cooperate with some customized components to provide more types of data or functionality. Some other features, including a cadence sensor and a turn/brake indicator provided for cyclists, can give users a more professional experience.

Structure

We separate outdoor sports into two typical scenarios and provide different modes for them.

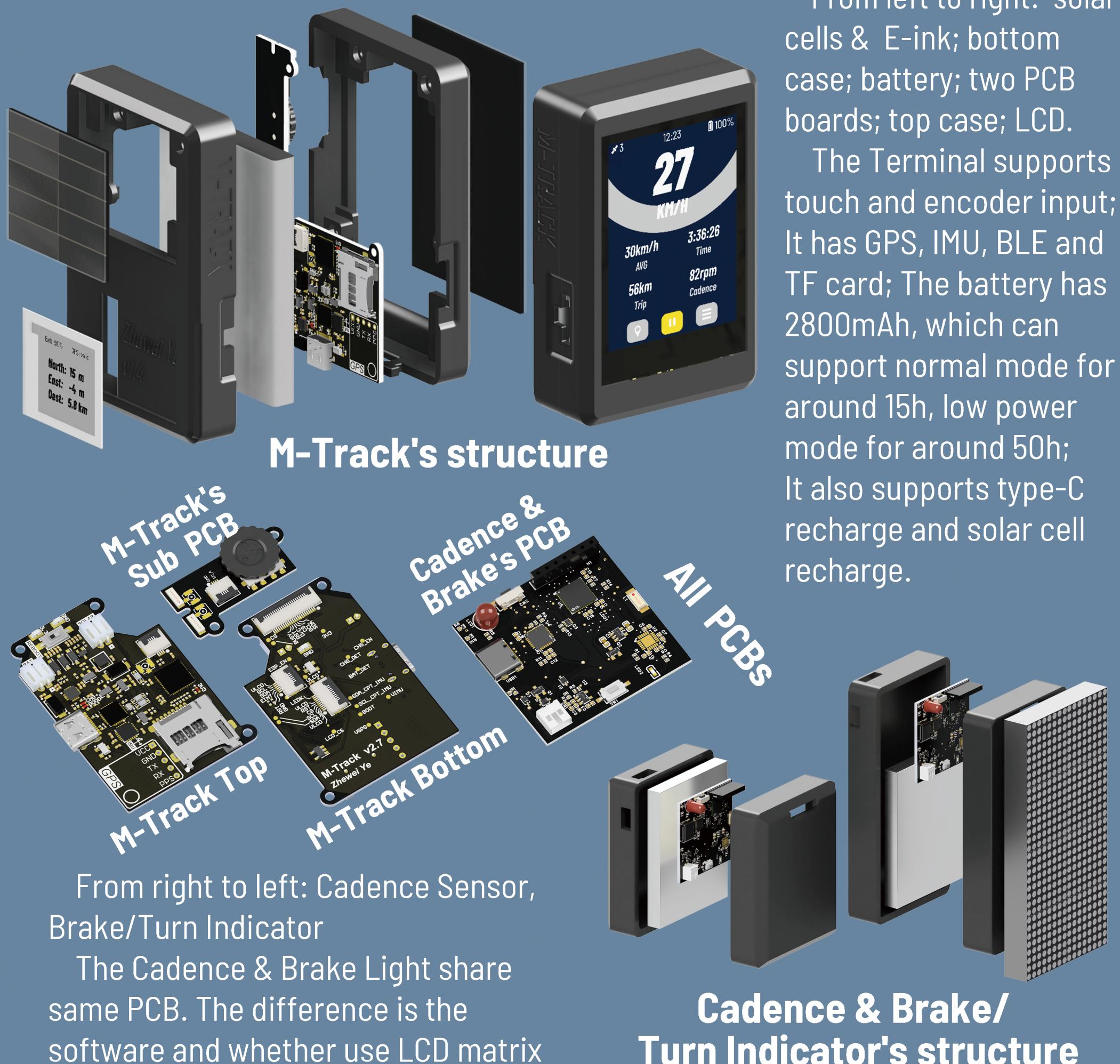
- 1) For sports like cycling, we provide a normal mode, which uses an LCD touch screen for clear navigation and sports data display to facilitate their training.
- 2) For sports like hiking, we will change to a low-power mode. These users can use a secondary E-ink mounted on the back to get succinct information. A solar panel is integrated to extend the M-Track's battery life.



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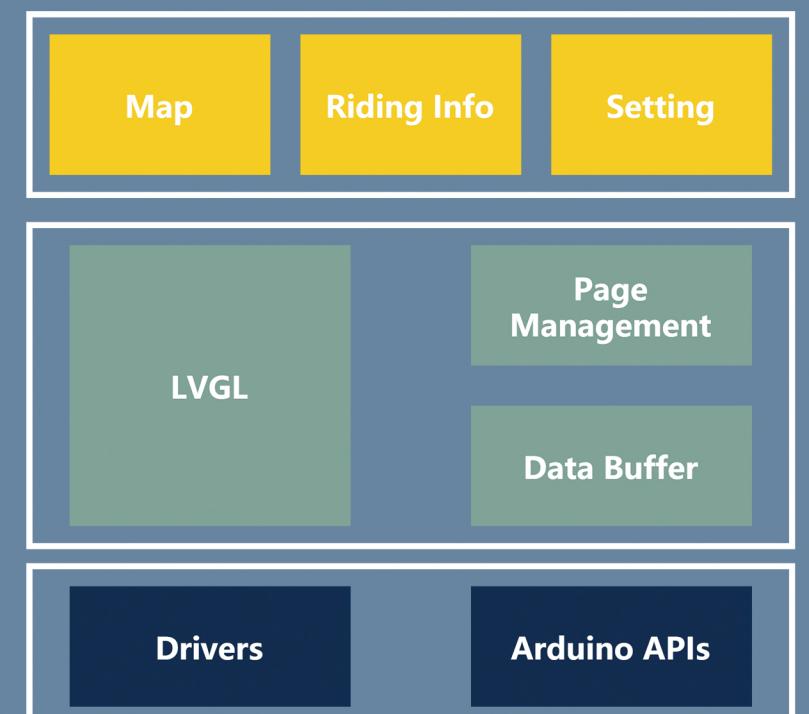
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Hardware



From left to right: solar cells & E-ink; bottom case; battery; two PCB boards; top case; LCD. The Terminal supports touch and encoder input; It has GPS, IMU, BLE and TF card; The battery has 2800mAh, which can support normal mode for around 15h, low power mode for around 50h; It also supports type-C recharge and solar cell recharge.

Software

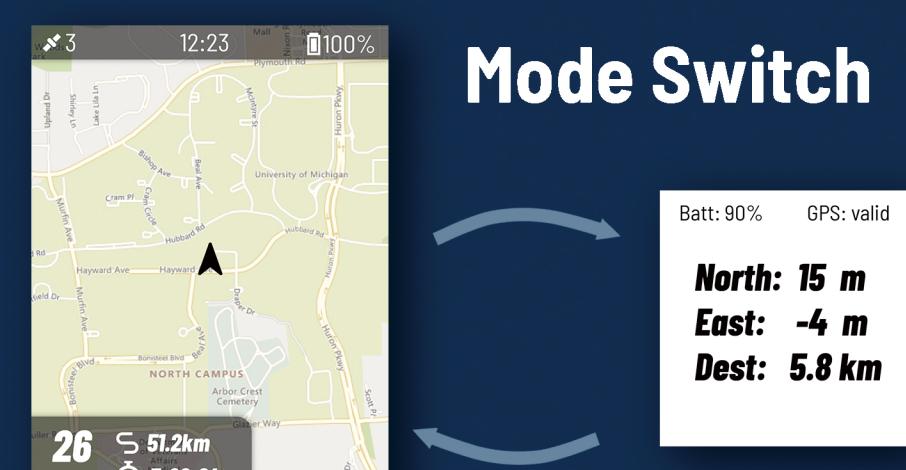


Software structure



Graphics UI's Logic

Features



The M-Track has normal mode and low power mode. This mode switch is provided when user is in LiveMap. The user can switch between two mode by double click on the encoder. Under low power mode, user can refresh the E-ink by long press the encoder.

Route Navigation

The M-Track can navigate the user with routes. It is an offline feature, the M-Track will load pre-planned route stored in TF card and display it on the screen. When the user is moving, the M-Track will analyze the distance between user and route, and decide whether it should provide navigation or warining that the user is off the route.

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