

E07 FF Planner

17341068 Yangfan Jiang

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1 Examples

1.1 Spare Tire

domain_spare_tire.pddl

```
1 (define (domain spare_tire)
2   (:requirements :strips :equality :typing)
3   (:types physob location)
4   (:predicates (Tire ?x – physob)
5                 (at ?x – physob ?y – location))
6
7   (:action Remove
8     :parameters (?x – physob ?y – location)
9     :precondition (At ?x ?y)
10    :effect (and (not (At ?x ?y)) (At ?x Ground)))
11
12   (:action PutOn
13     :parameters (?x – physob)
14     :precondition (and (Tire ?x) (At ?x Ground)
15                       (not (At Flat Axle)))
16     :effect (and (not (At ?x Ground)) (At ?x Axle)))
17   (:action LeaveOvernight
18     :effect (and (not (At Spare Ground)) (not (At Spare Axle))
19                 (not (At Spare Trunk)) (not (At Flat Ground))
20                 (not (At Flat Axle)) (not (At Flat Trunk)) ))
21 )
```

spare_tire.pddl

```
1 (define (problem prob)
2   (:domain spare_tire)
3   (:objects Flat Spare –physob Axle Trunk Ground – location)
4   (:init (Tire Flat)(Tire Spare)(At Flat Axle)(At Spare Trunk))
5   (:goal (At Spare Axle))
6 )
```

```

ai2017@osboxes:~/Desktop/spare_tire$ ff -o domain_spare_tire.pddl -f spare_tire.pddl

ff: parsing domain file
domain 'SPARE_TIRE' defined
... done.
ff: parsing problem file
problem 'PROB' defined
... done.

Cueing down from goal distance:    3 into depth [1]
                                   2             [1]
                                   1             [1]
                                   0

ff: found legal plan as follows

step    0: REMOVE FLAT AXLE
        1: REMOVE SPARE TRUNK
        2: PUTON SPARE

time spent:    0.00 seconds instantiating 9 easy, 0 hard action templates
               0.00 seconds reachability analysis, yielding 11 facts and 8 actions
               0.00 seconds creating final representation with 10 relevant facts
               0.00 seconds building connectivity graph
               0.00 seconds searching, evaluating 4 states, to a max depth of 1
               0.00 seconds total time

```

1.2 Briefcase World

Please refer to `pddl.pdf` at page 2. Please pay More attention to the usages of `forall` and `when`.

For more examples, please refer to `ff-domains.tgz` and `benchmarksV1.1.zip`. For more usages of FF planner, please refer to the documentation `pddl.pdf`.

2 Tasks

2.1 8-puzzle

1	2	3
7	8	
6	4	5

Please complete `domain_puzzle.pddl` and `puzzle.pddl` to solve the 8-puzzle problem.

domain_puzzle.pddl

```
1 (define (domain puzzle)
2   (:requirements :strips :equality :typing)
3   (:types num loc)
4   (:predicates ())
5
6   (:action slide
7     :parameters ()
8     :precondition ()
9     :effect ())
10 )
11 )
```

domain_puzzle.pddl

```
1 (define (problem prob)
2   (:domain puzzle)
3   (:objects )
4   (:init )
5   (:goal ()))
6 )
```

2.2 Blocks World

现有积木若干，积木可以放在桌子上，也可以放在另一块积木上面。有两种操作：

- ❶ $move(x, y)$ ：把积木 x 放到积木 y 上面。前提是积木 x 和 y 上面都没有其他积木。
- ❷ $moveToTable(x)$ ：把积木 x 放到桌子上，前提是积木 x 上面无其他积木，且积木 x 不在桌子上。

Please complete the file `domain_blocks.pddl` to solve the blocks world problem. You should know the usages of `forall` and `when`.

domain_blocks.pddl

```

1 (define (domain blocks)
2   (:requirements :strips :typing:equality
3                 :universal-preconditions
4                 :conditional-effects)
5   (:types physob)
6   (:predicates
7     (ontable ?x - physob)
8     (clear ?x - physob)
9     (on ?x ?y - physob))
10
11   (:action move
12     :parameters (?x ?y - physob)
13     :precondition ()
14     :effect ()
15     )
16
17   (:action moveToTable
18     :parameters (?x - physob)
19     :precondition ()
20     :effect ( )
21   )

```

blocks.pddl

```

1 (define (problem prob)
2   (:domain blocks)
3   (:objects A B C D E F - physob)
4   (:init (clear A)(on A B)(on B C)(ontable C) (ontable D)
5     (ontable F)(on E D)(clear E)(clear F)
6   )
7   (:goal (and (clear F) (on F A) (on A C) (ontable C)(clear E) (on E B)
8     (on B D) (ontable D)) )
9   )

```

3 Codes and Results

3.1 8-puzzle

Codes

domain_puzzle.pddl

```
1 (define (domain puzzle)
2 (:requirements :strips :equality :typing)
3 (:types num loc)
4 (:predicates (empty ?x - loc)
5               (at ?x - num ?y - loc)
6               (near ?x - loc ?y - loc))
7
8 (:action slide
9   :parameters (?x - num ?z - loc ?y - loc)
10  :precondition (and (empty ?y) (at ?x ?z) (near ?z ?y) )
11  :effect (and (not (empty ?y)) (empty ?z)
12            (not (at ?x ?z)) (at ?x ?y) )
13 )
14 )
```

puzzle.pddl

```
1 (define (problem prob)
2 (:domain puzzle)
3 (:objects n1 n2 n3 n4 n5 n6 n7 n8 - num 11 12 13 14 15 16 17 18 19 - loc)
4 (:init (empty 16)(at n1 11)(at n2 12)(at n3 13)(at n7 14)(at n8 15)
5        (at n6 17)(at n4 18)(at n5 19)(near 11 12)(near 11 14)(near 12 11)
6        (near 12 13)(near 12 15)(near 13 12)(near 13 16)(near 14 11)
7        (near 14 15)(near 14 17)(near 15 14)(near 15 12)(near 15 18)
8        (near 15 16)(near 16 15)(near 16 13)(near 16 19)(near 17 14)
9        (near 17 18)(near 18 17)(near 18 15)(near 18 19)(near 19 18)
10       (near 19 16))
```

```

11  (:goal ( and (at n1 11)(at n2 12)(at n3 13)(at n4 14)
12          (at n5 15)(at n6 16)(at n7 17)(at n8 18)) )
13  )

```

Result



Figure 1: Results

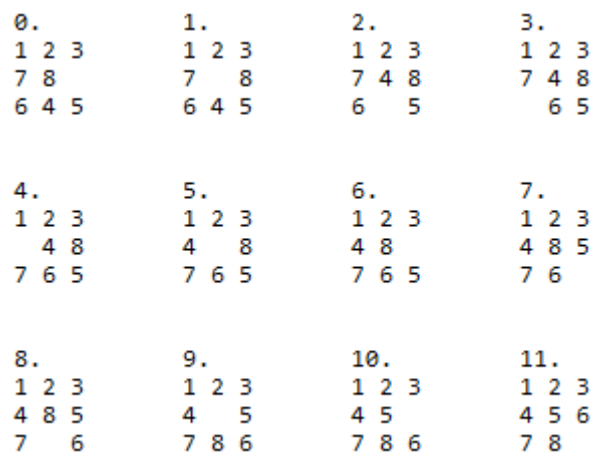


Figure 2: Actions

3.2 block-world

Codes

domain_blocks.pddl

```
1  (define (domain blocks)
2  (:requirements :strips :typing:equality
3                :universal-preconditions
4                :conditional-effects)
5  (:types physob)
6  (:predicates
7      (ontable ?x - physob)
8      (clear ?x - physob)
9      (on ?x ?y - physob))
10
11  (:action move
12      :parameters (?x ?y - physob)
13      :precondition (and (clear ?x) (clear ?y) )
14      :effect (and
15              (when (ontable ?x)
16                  (not (ontable ?x)))
17              (forall (?z - physob)
18                  (when (on ?x ?z)
19                      (and (not (on ?x ?z))(clear ?z)))
20              )
21              (not (clear ?y))
22              (on ?x ?y)
23          )
24  )
25
26  (:action moveToTable
27      :parameters (?x - physob)
28      :precondition (and (not (ontable ?x)) (clear ?x))
29      :effect (and (ontable ?x)
```



```

30         (forall (?z – physob)
31             (when(on ?x ?z)
32                 (and (not (on ?x ?z))(clear ?z)))
33             )
34         )
35     )
36 )

```

blocks.pddl

```

1  (define (problem prob)
2  (:domain blocks)
3  (:objects A B C D E F – physob)
4  (:init (clear A)(on A B)(on B C)(ontable C) (ontable D)
5  (ontable F)(on E D)(clear E)(clear F)
6  )
7  (:goal (and (clear F) (on F A) (on A C) (ontable C)(clear E) (on E B)
8  (on B D) (ontable D)) )
9  )

```



Figure 3: Actions

Found Plan (

(move f a)
(move e f)
(movetotable e)
(movetotable f)
(move a f)
(move b e)
(move a c)
(move f a)
(move b d)
(move e b)

Figure 4: Results