

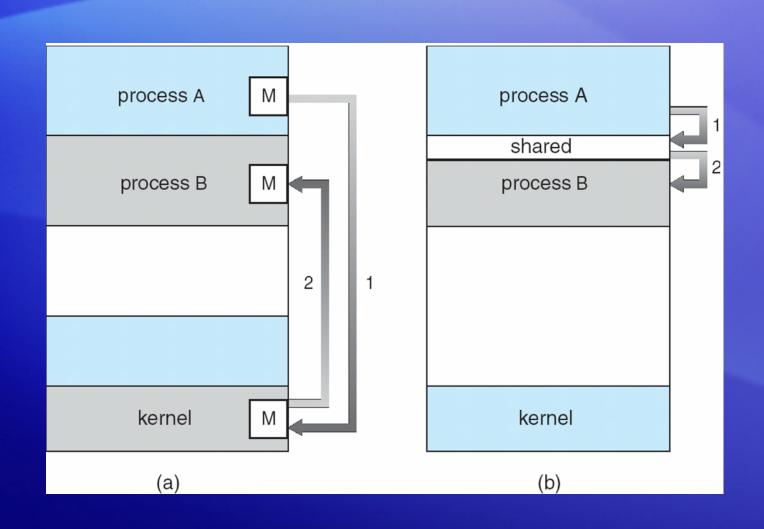
Operating Systems

Inter Process Communication

Interprocess Communication

- Processes within a system may be independent or cooperating
- Cooperating process can affect or be affected by other processes, including sharing data
- Reasons for cooperating processes:
 - Information sharing
 - Computation speedup
 - Modularity
 - Convenience
- Cooperating processes need interprocess communication (IPC)
- Two models of IPC
 - Shared memory
 - Message passing

Communications Models



Producer-Consumer Problem

- Paradigm for cooperating processes, producer process produces information that is consumed by a consumer process
- Unbounded-buffer places no practical limit on the size of the buffer
- Bounded-buffer assumes that there is a fixed buffer size

Bounded-Buffer – Shared-Memory Solution

```
Shared data

#define BUFFER_SIZE 10

typedef struct {
....
} item;

item buffer[BUFFER_SIZE];
int in = 0;
int out = 0;
```

Solution is correct, but can only use BUFFER_SIZE-1 elements

Bounded-Buffer - Producer

```
while (true) {
    /* Produce an item */
        while (((in = (in + 1) % BUFFER SIZE
count) == out)
        ;    /* do nothing -- no free buffers */
        buffer[in] = item;
        in = (in + 1) % BUFFER SIZE;
    }
```

Bounded Buffer - Consumer

```
while (true) {
        while (in == out)
               ; // do nothing --
nothing to consume
     // remove an item from the
buffer
     item = buffer[out];
     out = (out + 1) % BUFFER SIZE;
return item;
```

Interprocess Communication – Message Passing

- Mechanism for processes to communicate and to synchronize their actions
- Message system processes communicate with each other without resorting to shared variables
- IPC facility provides two operations:
 - **send**(*message*) message size fixed or variable
 - receive(message)
- If P and Q wish to communicate, they need to: establish a communication link between them exchange messages via send/receive
- Implementation of communication link physical (e.g., shared memory, hardware bus) logical (e.g., logical properties)

Implementation Questions

- How are links established?
- Can a link be associated with more than two processes?
- How many links can there be between every pair of communicating processes?
- What is the capacity of a link?
- Is the size of a message that the link can accommodate fixed or variable?
- Is a link unidirectional or bi-directional?

Direct Communication

- Processes must name each other explicitly:
 - send (P, message) send a message to process P
 - receive(Q, message) receive a message from process Q
- Properties of communication link
 - Links are established automatically
 - A link is associated with exactly one pair of communicating processes
 - Between each pair there exists exactly one link
 - The link may be unidirectional, but is usually bi-directional

Indirect Communication

- Messages are directed and received from mailboxes (also referred to as ports)
 - Each mailbox has a unique id
 - Processes can communicate only if they share a mailbox
- Properties of communication link
 - Link established only if processes share a common mailbox
 - A link may be associated with many processes
 - Each pair of processes may share several communication links
 - Link may be unidirectional or bi-directional

Indirect Communication

- Operations
 - create a new mailbox
 - send and receive messages through mailbox
 - destroy a mailbox
- Primitives are defined as:
 - send(A, message) send a message to mailbox
 - receive(A, message) receive a message from mailbox A

Indirect Communication

Mailbox sharing

 P_1 , P_2 , and P_3 share mailbox A P_1 , sends; P_2 and P_3 receive Who gets the message?

Solutions

Allow a link to be associated with at most two processes

Allow only one process at a time to execute a receive operation

Allow the system to select arbitrarily the receiver. Sender is notified who the receiver was.

Synchronization

- Message passing may be either blocking or nonblocking
- Blocking is considered synchronous
 - Blocking send has the sender block until the message is received
 - Blocking receive has the receiver block until a message is available
- Non-blocking is considered asynchronous
 - Non-blocking send has the sender send the message and continue
 - Non-blocking receive has the receiver receive a valid message or null

Buffering

- Queue of messages attached to the link; implemented in one of three ways
 - Zero capacity 0 messages
 Sender must wait for receiver (rendezvous)
 - Bounded capacity finite length of n messages
 Sender must wait if link full
 - Unbounded capacity infinite length Sender never waits

Examples of IPC Systems - POSIX

- POSIX Shared Memory
 - Process first creates shared memory segment

```
segment id = shmget(IPC PRIVATE, size, S IRUSR | S IWUSR);
```

- Process wanting access to that shared memory must attach to it
 shared memory = (char *) shmat(id, NULL, 0);
- Now the process could write to the shared memory
 sprintf(shared memory, "Writing to shared memory");
- When done a process can detach the shared memory from its address space

```
shmdt(shared memory);
```

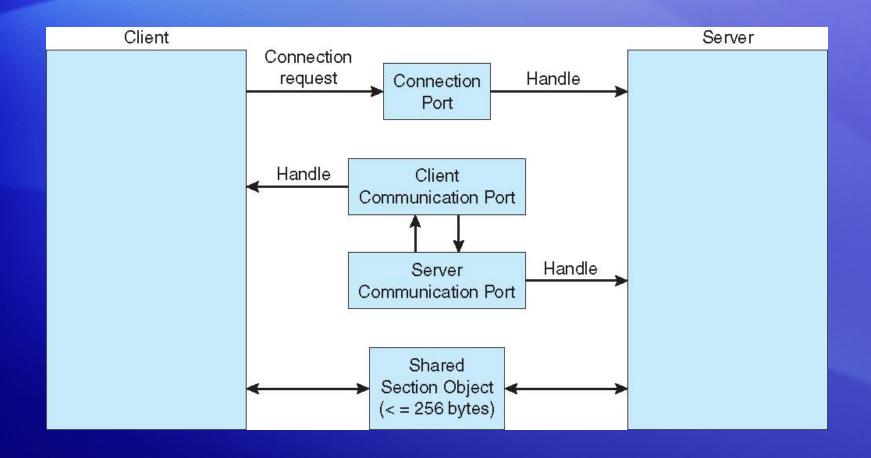
Examples of IPC Systems - Mach

- Mach communication is message based
 - Even system calls are messages
 - Each task gets two mailboxes at creation Kernel and Notify
 - Only three system calls needed for message transfer msg send(), msg receive(), msg rpc()
 - Mailboxes needed for commuication, created via port allocate()

Examples of IPC Systems – Windows XP

- Message-passing centric via local procedure call (LPC) facility
 - Only works between processes on the same system
 - Uses ports (like mailboxes) to establish and maintain communication channels
 - Communication works as follows:
 - The client opens a handle to the subsystem's connection port object.
 - The client sends a connection request.
 - The server creates two private communication ports and returns the handle to one of them to the client.
 - The client and server use the corresponding port handle to send messages or callbacks and to listen for replies.

Local Procedure Calls in Windows XP



Communications in Client-Server Systems

- Sockets
- Remote Procedure Calls
- Pipes
- Remote Method Invocation (Java)

Sockets

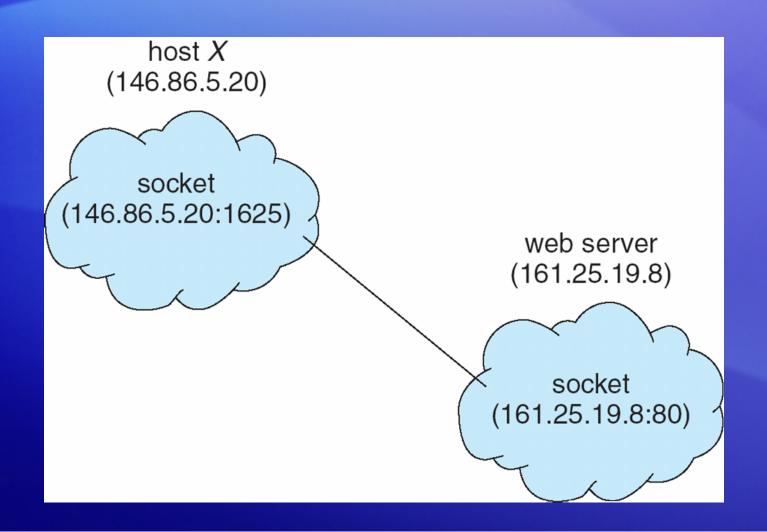
A socket is defined as an endpoint for communication

Concatenation of IP address and port

The socket **161.25.19.8:1625** refers to port **1625** on host **161.25.19.8**

Communication consists between a pair of sockets

Socket Communication



Remote Procedure Calls

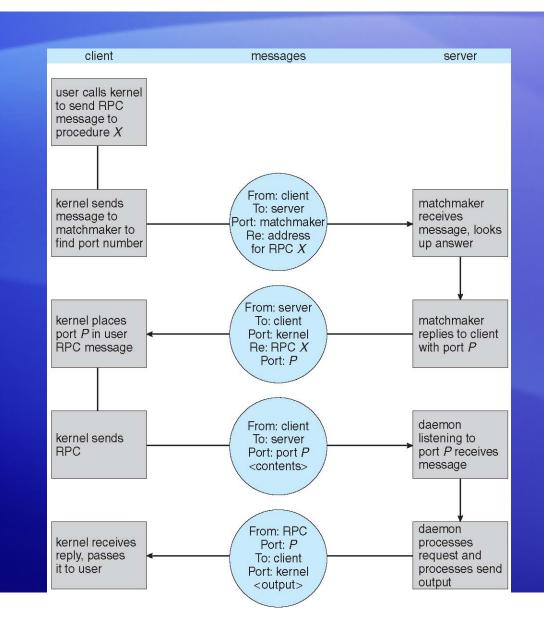
Remote procedure call (RPC) abstracts procedure calls between processes on networked systems

Stubs – client-side proxy for the actual procedure on the server

The client-side stub locates the server and *marshalls* the parameters

The server-side stub receives this message, unpacks the marshalled parameters, and performs the procedure on the server

Execution of RPC



Pipes

 Acts as a conduit allowing two processes to communicate

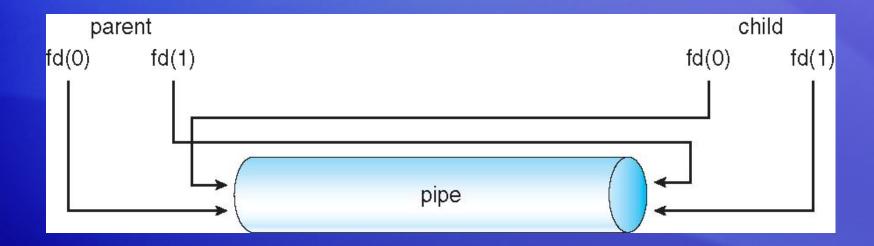
Issues

- Is communication unidirectional or bidirectional?
- In the case of two-way communication, is it half or full-duplex?
- Must there exist a relationship (i.e. parentchild) between the communicating processes?
- Can the pipes be used over a network?

Ordinary Pipes

- Ordinary Pipes allow communication in standard producer-consumer style
- Producer writes to one end (the write-end of the pipe)
- Consumer reads from the other end (the read-end of the pipe)
- Ordinary pipes are therefore unidirectional
- Require parent-child relationship between communicating processes

Ordinary Pipes



Named Pipes

- Named Pipes are more powerful than ordinary pipes
- Communication is bidirectional
- No parent-child relationship is necessary between the communicating processes
- Several processes can use the named pipe for communication
- Provided on both UNIX and Windows systems

Reference Book

"Operating System Concepts" by Silberchartz, Galvin, Gagne, Wiley India Publications.

