



# Aprendizado Automático



João Paulo Pordeus Gomes

A vertical decorative bar on the left side of the slide, consisting of a thin light blue line and a wider dark blue bar.

# Redes Neurais

# Redes Neurais

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- ▶ Funcionamento inspirado no neurônio biológico.
- ▶ Tarefas de Aprendizado de Máquina
  - ▶ Classificação
  - ▶ Regressão



# Neurônio Biológico x Neurônio Artificial

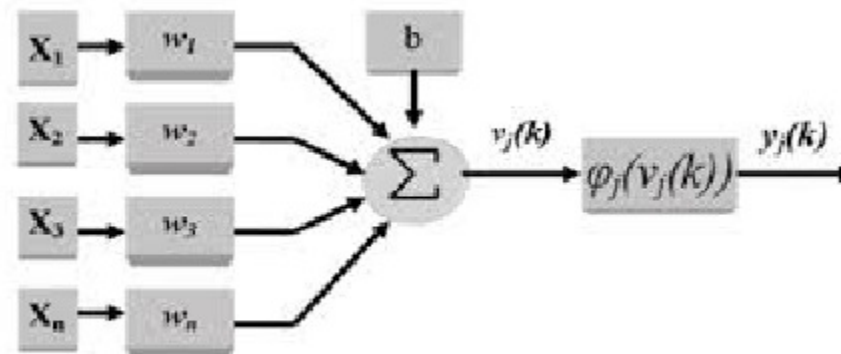


Figura 2: Representação do neurônio artificial.

# Neurônio Biológico x Neurônio Artificial



## McCulloch-Pitts

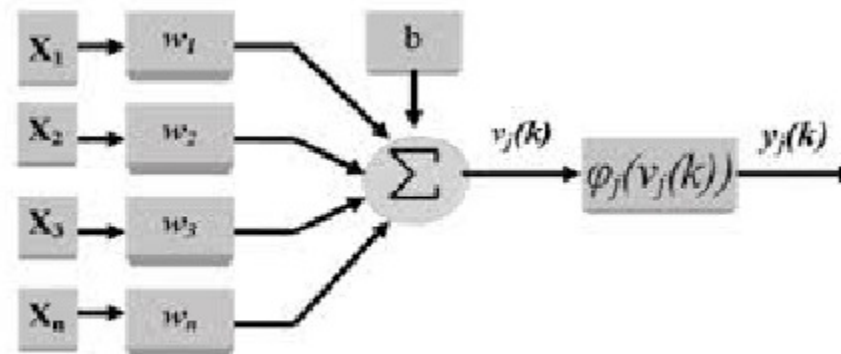


Figura 2: Representação do neurônio artificial.

# Modelo de McCulloch-Pitts

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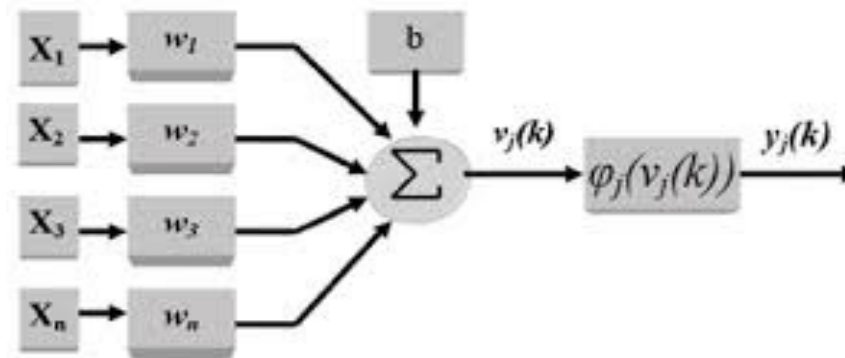


Figura 2: Representação do neurônio artificial.

$$v_j = w_1x_1 + w_2x_2 + \cdots - b$$

$$\varphi(v_j) = 1 \text{ se } v_j > 0$$

$$\varphi(v_j) = 0 \text{ se } v_j < 0$$



# Modelo de McCulloch-Pitts

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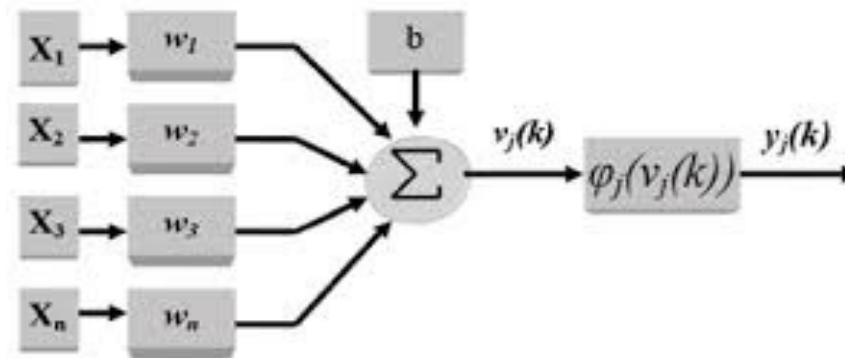


Figura 2: Representação do neurônio artificial.

$$v_j = w_1x_1 + w_2x_2 + \dots - w_0x_0 = \mathbf{w}^T \mathbf{x} \quad \text{onde } w_0 = -1 \text{ e } x_0 = b$$

$$\varphi(v_j) = 1 \text{ se } v_j > 0$$

$$\varphi(v_j) = 0 \text{ se } v_j < 0$$



# Perceptron

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- ▶ Modelo

- ▶  $\bar{y}_i = \varphi(\mathbf{w}^T \mathbf{x}_i)$

- ▶ Regra de Aprendizagem

- ▶  $\mathbf{w} = \mathbf{w} - \alpha \frac{\partial J}{\partial \mathbf{w}}$

- ▶  $\mathbf{w} = \mathbf{w} + \alpha \frac{1}{n} \sum_{i=1}^n e_i \mathbf{x}_i$



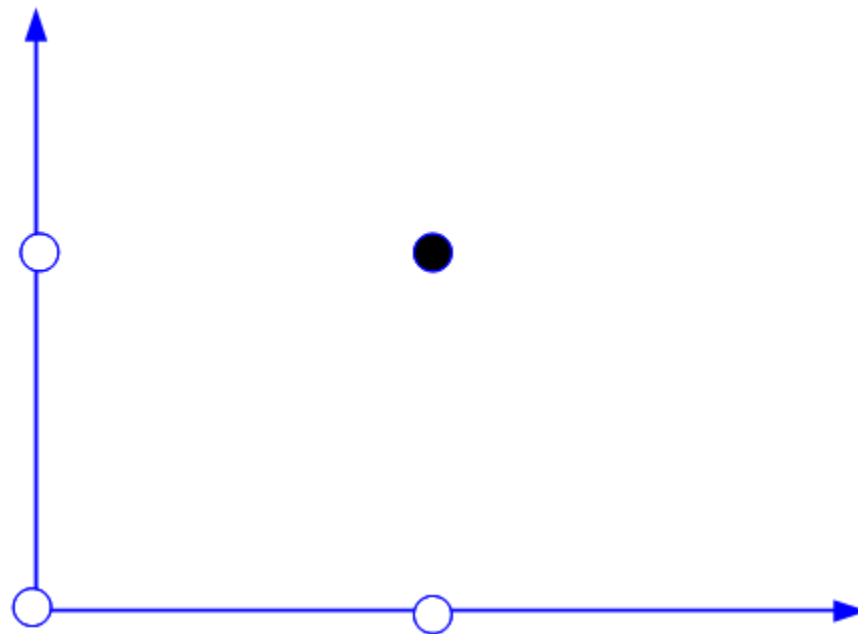


# Perceptron

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## ► Problemas linearmente separáveis

Entrada (x)	Saída (y)
0,0	0
0,1	0
1,0	0
1,1	1

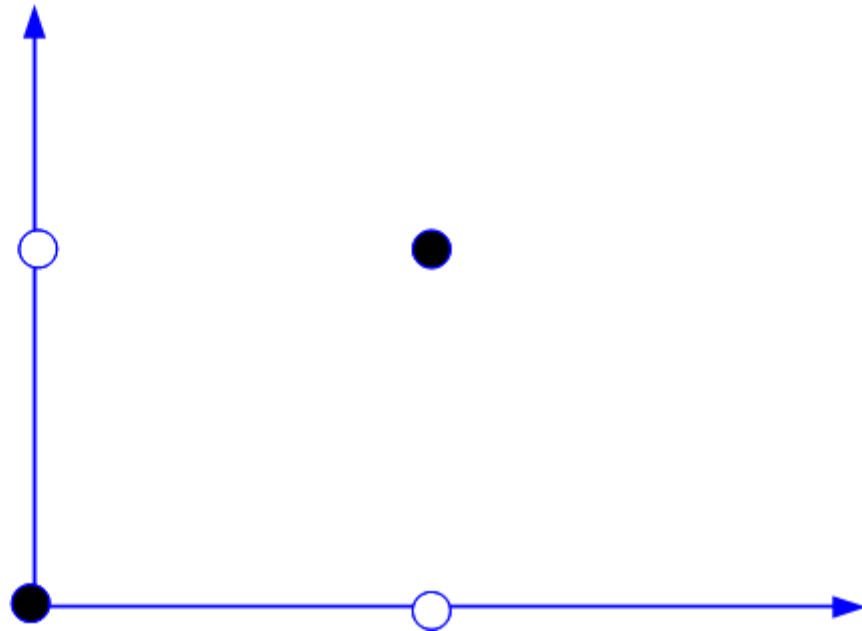


# Perceptron

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- ▶ Minsky e Papert (1969)
  - ▶ Problema ou-exclusivo

Entrada (x)	Saída (y)
0,0	0
0,1	1
1,0	1
1,1	0



# Perceptron

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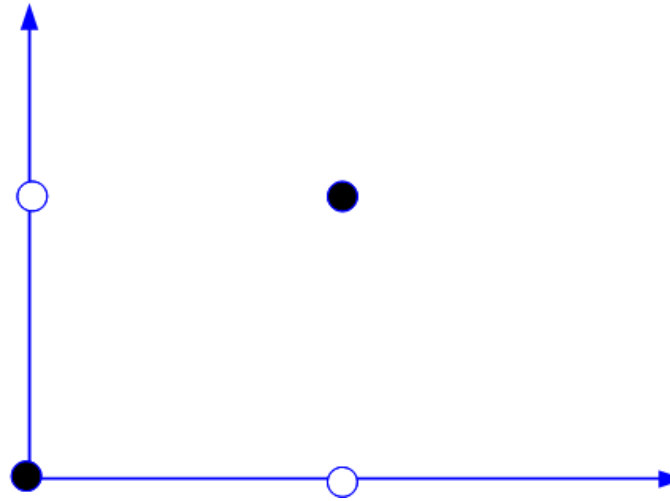
- ▶ Minsky e Papert (1969)
  - ▶ Problema ou-exclusivo
- ▶ Provaram que pode ser resolvido se for utilizada mais de uma camada de neurônios



# Perceptron

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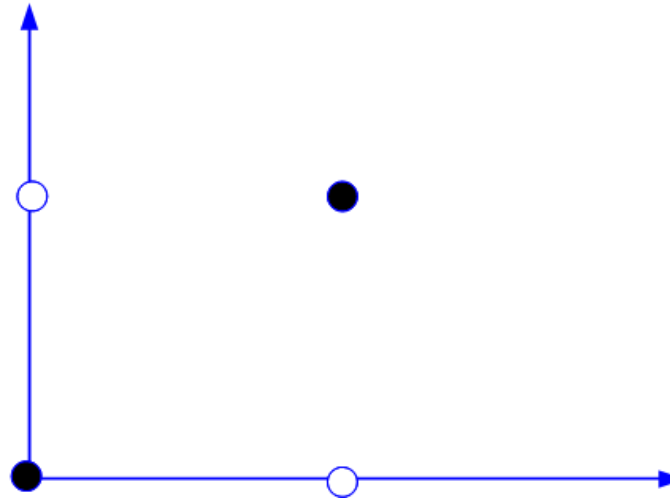
Entrada (x)	Saída (y)
0,0	0
0,1	1
1,0	1
1,1	0



# Perceptron

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Entrada (x)	Saída (y)
0,0	0
0,1	1
1,0	1
1,1	0



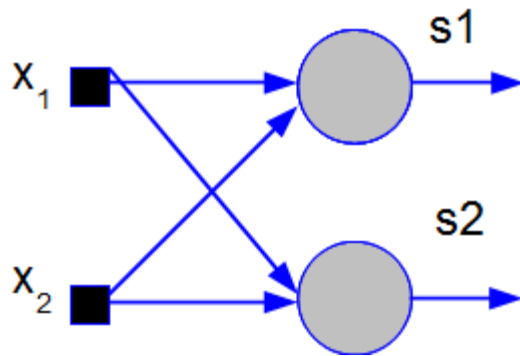
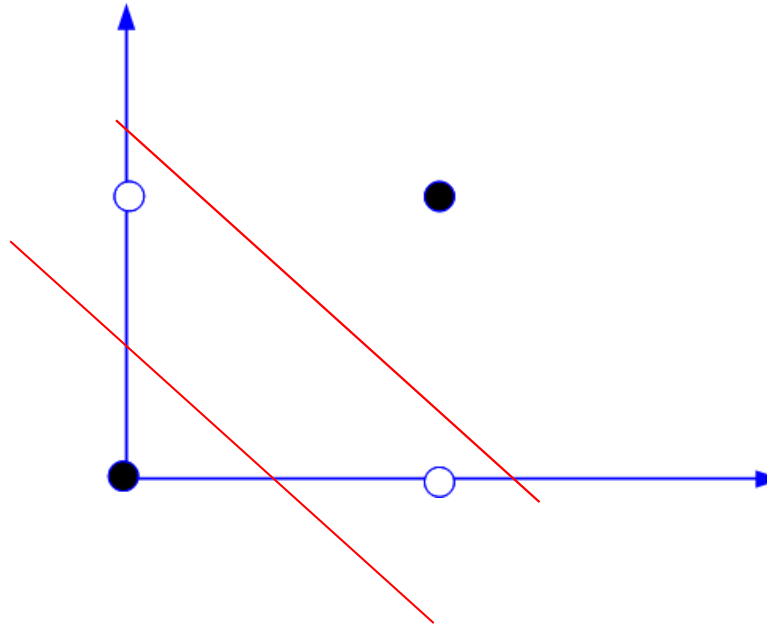
$x_1$  ■

$x_2$  ■



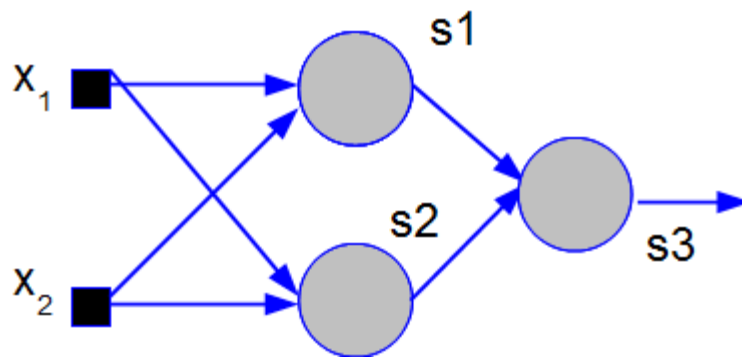
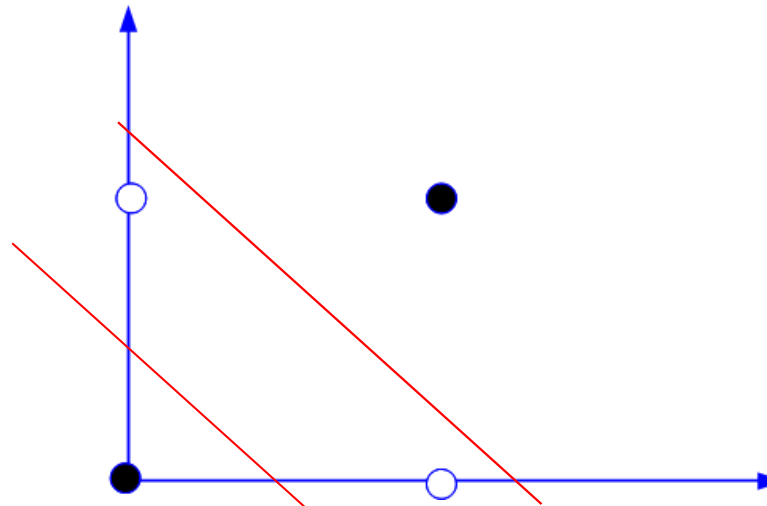
# Perceptron

Entrada (x)	Saída (y)
0,0	0
0,1	1
1,0	1
1,1	0



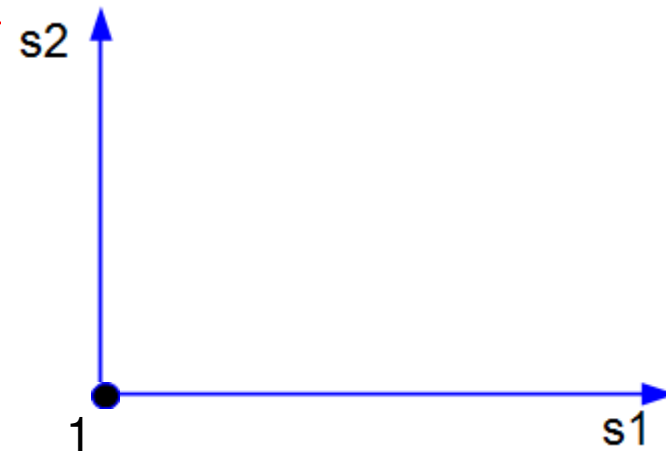
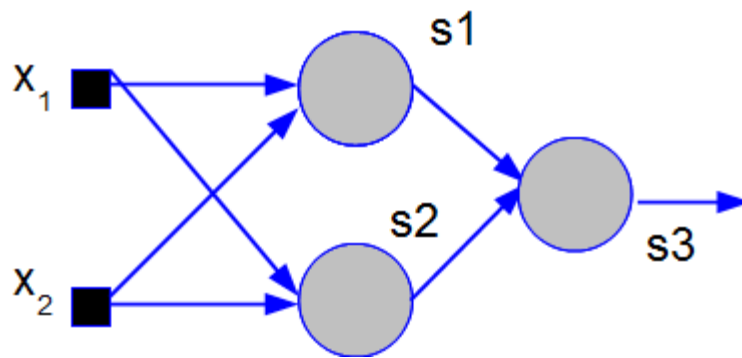
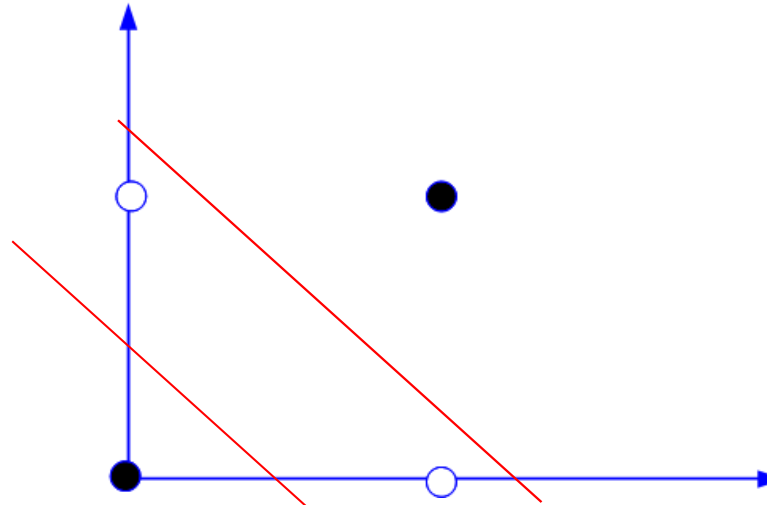
# Perceptron

Entrada (x)	Saída (y)
0,0	0
0,1	1
1,0	1
1,1	0



# Perceptron

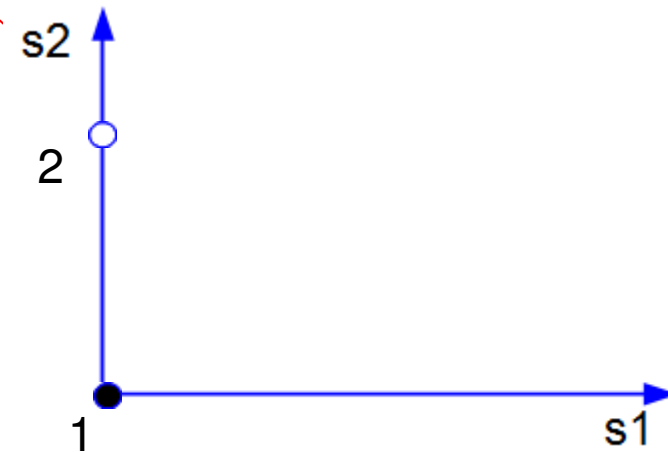
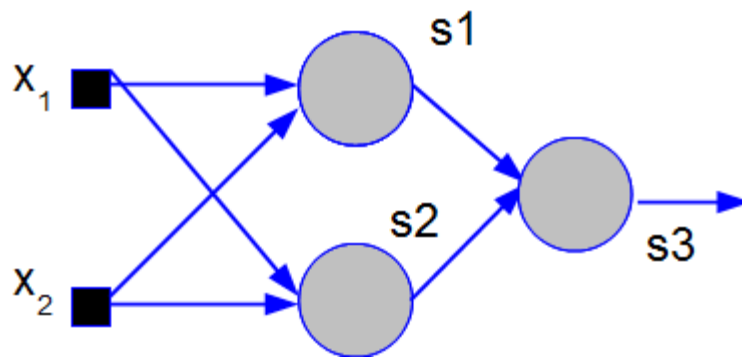
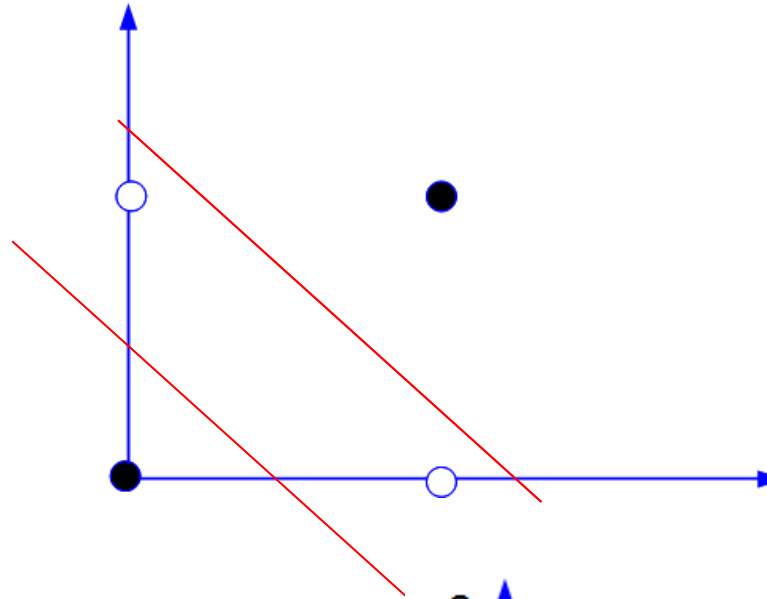
Entrada (x)	Saída (y)
0,0	0
0,1	1
1,0	1
1,1	0





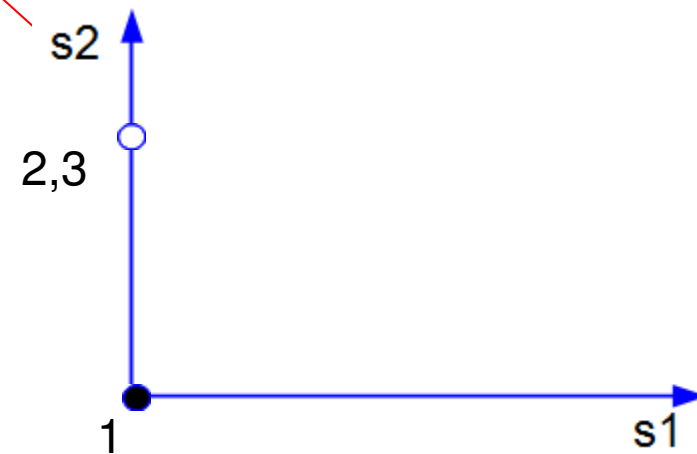
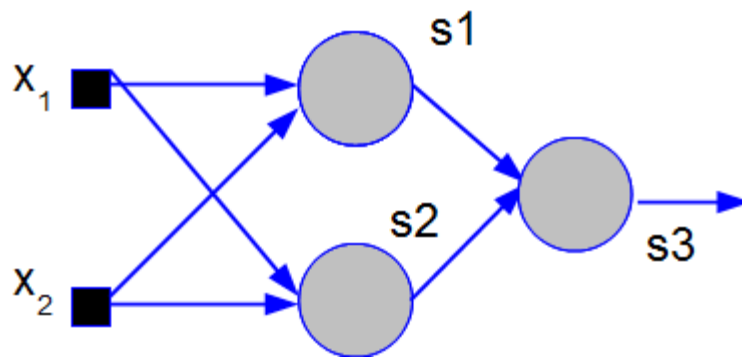
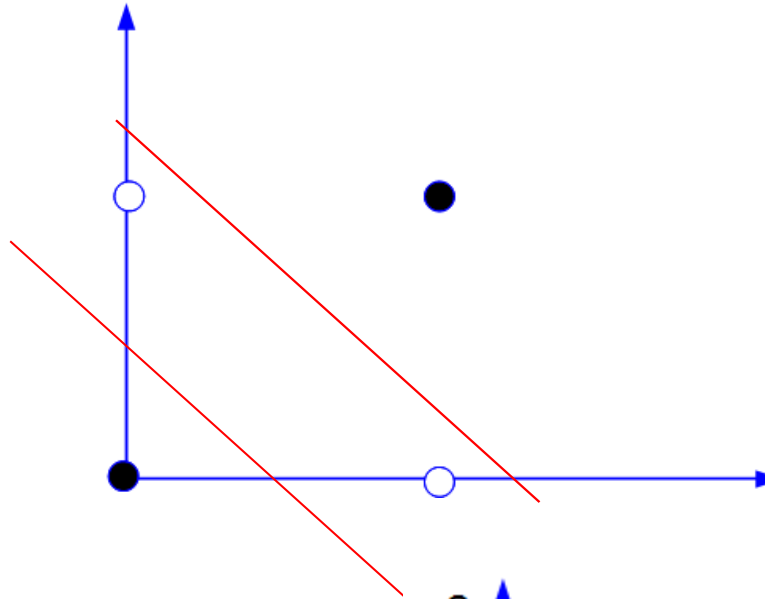
# Perceptron

Entrada (x)	Saída (y)
0,0	0
0,1	1
1,0	1
1,1	0



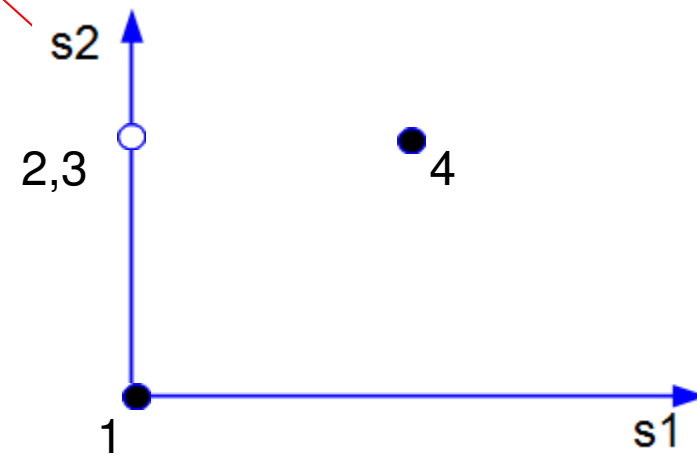
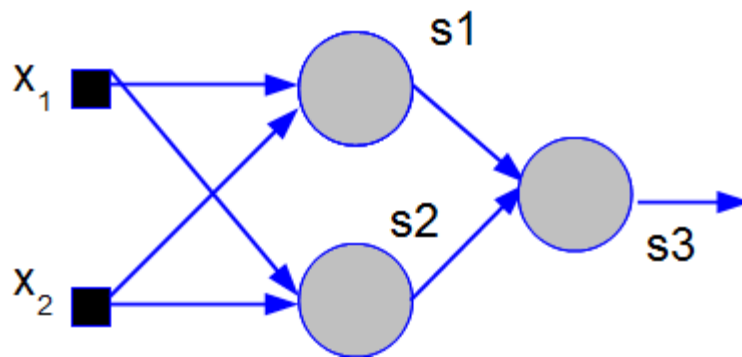
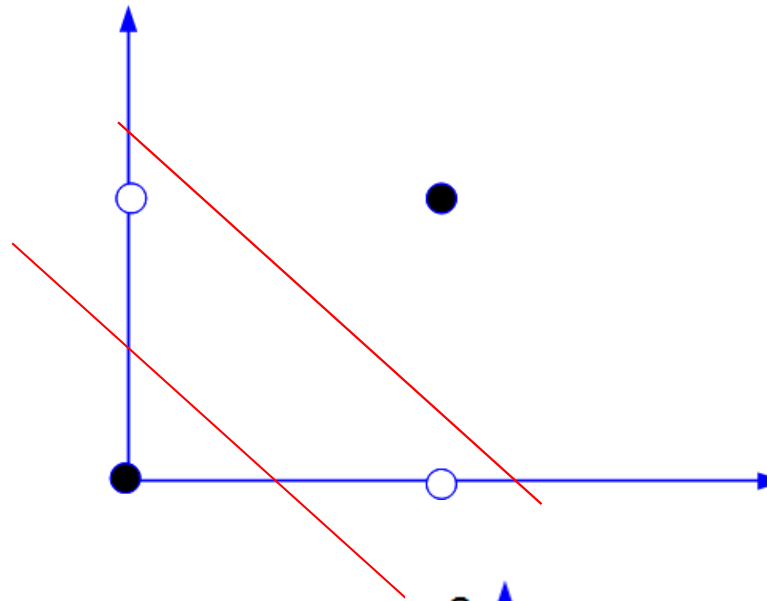
# Perceptron

Entrada (x)	Saída (y)
0,0	0
0,1	1
1,0	1
1,1	0



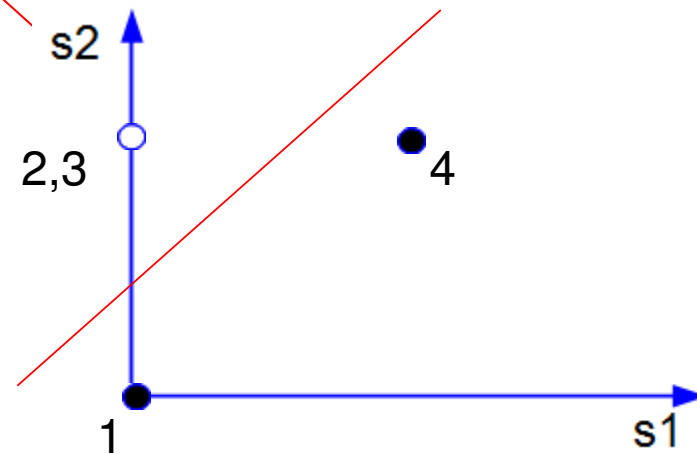
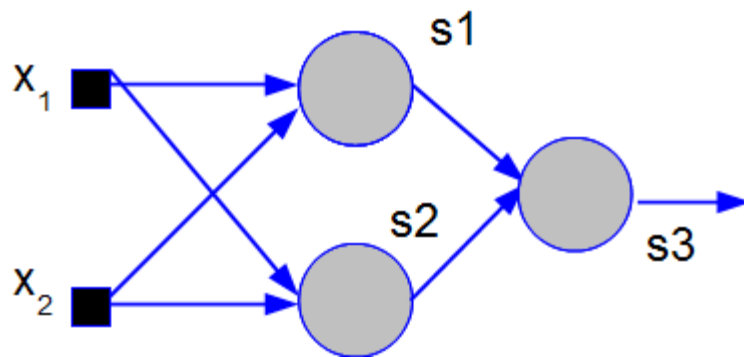
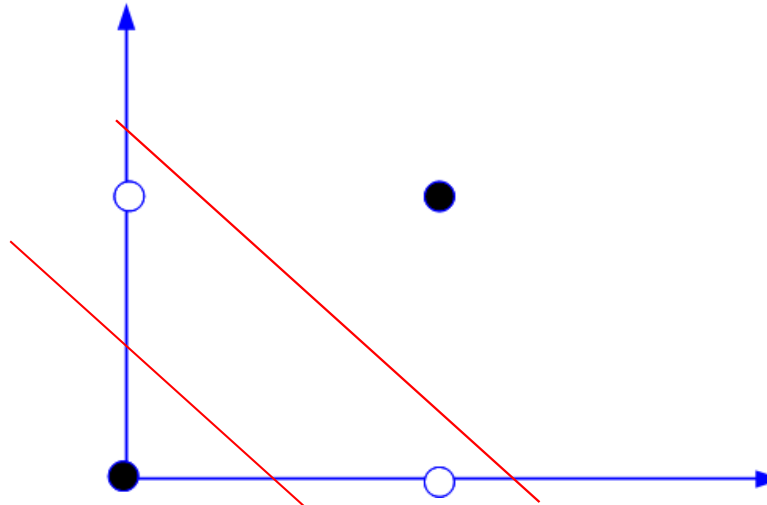
# Perceptron

Entrada (x)	Saída (y)
0,0	0
0,1	1
1,0	1
1,1	0



# Perceptron

Entrada (x)	Saída (y)
0,0	0
0,1	1
1,0	1
1,1	0



# Perceptron de Múltiplas Camadas

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- ▶ Rede MLP (MultiLayer Perceptron)
  - ▶ Problemas não linearmente separáveis



A vertical blue bar is located on the left side of the slide, partially enclosed by a thin white rectangular border.

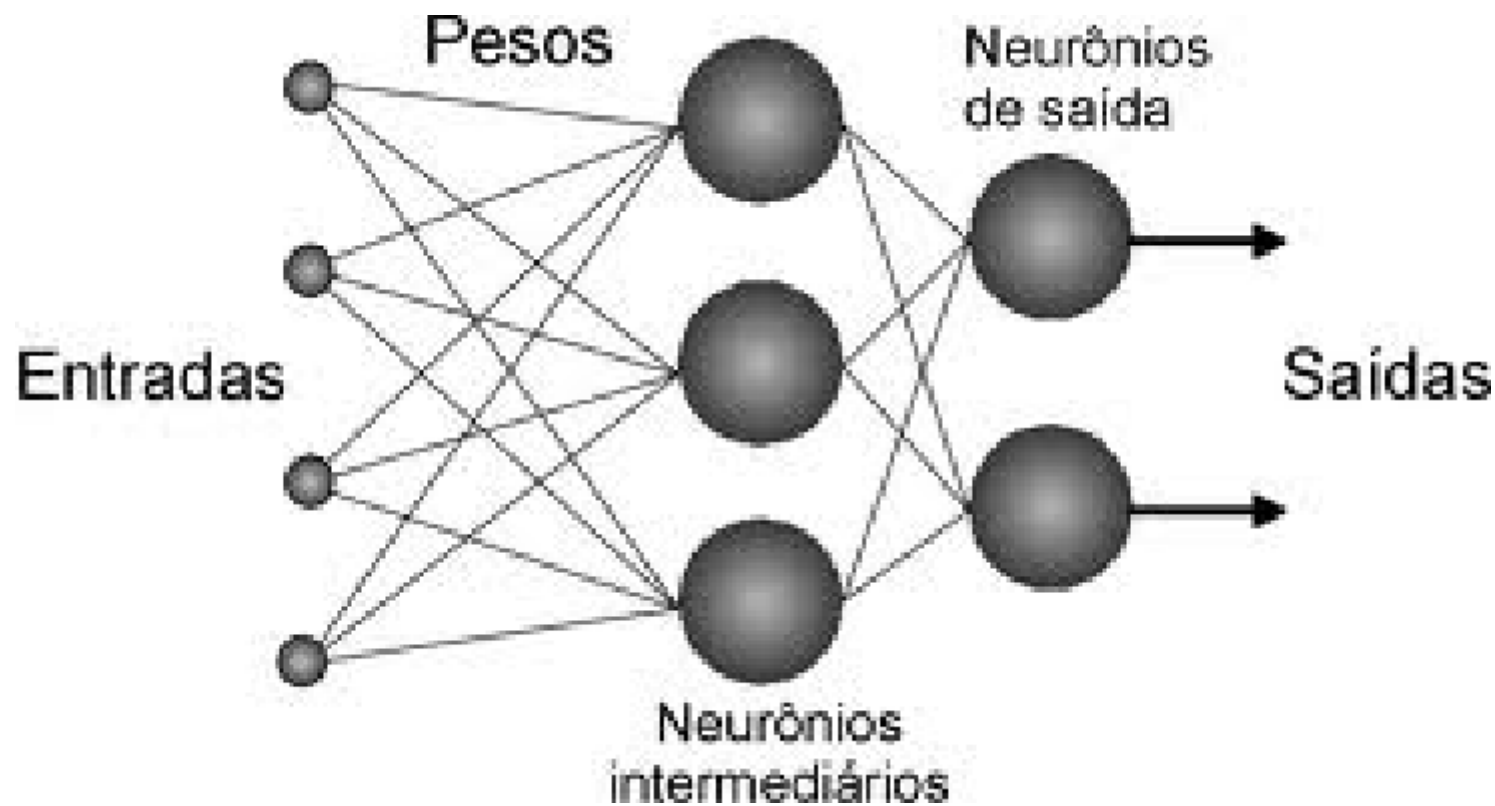
# Redes MLP

Redes Neurais

# Redes MLP

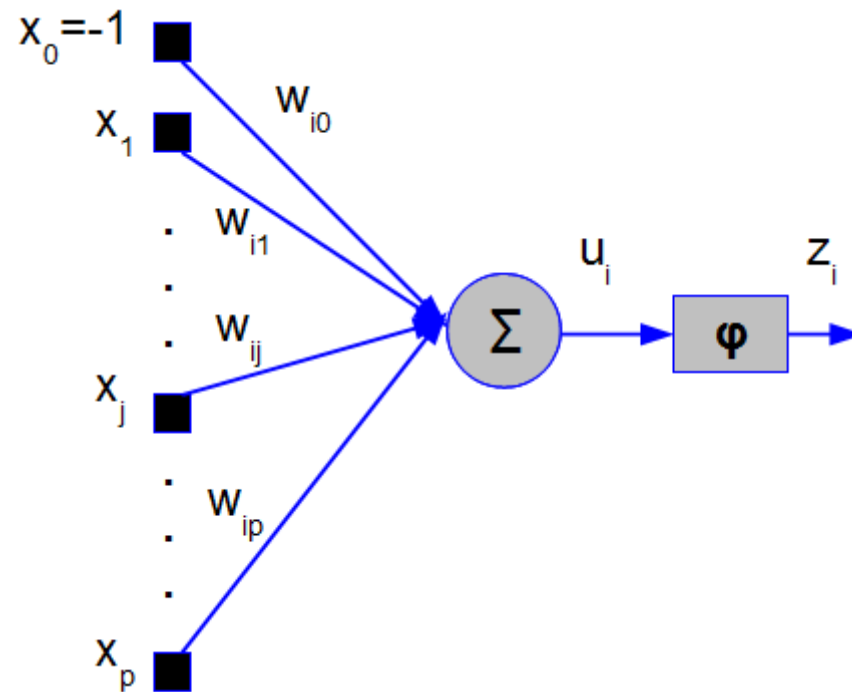
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- ▶ Redes com múltiplas camadas de neurônios artificiais



# Neurônio Artificial

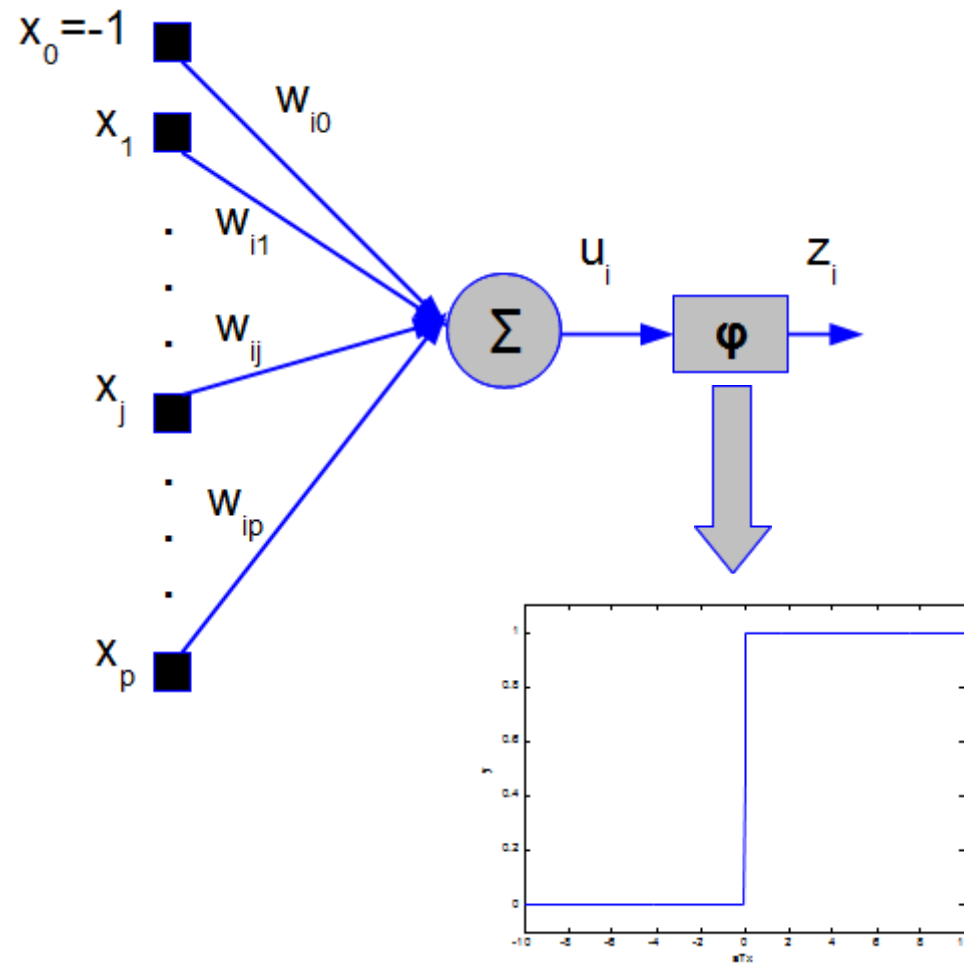
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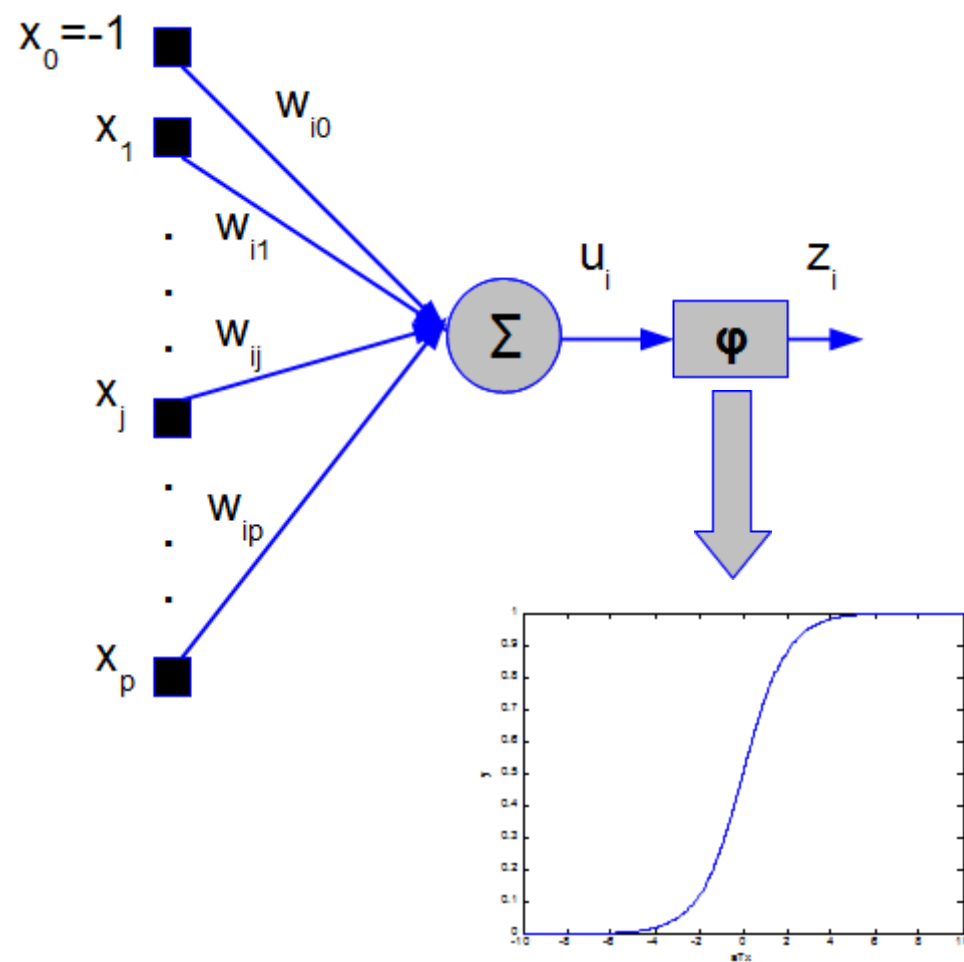
# Neurônio Artificial

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# Neurônio Artificial

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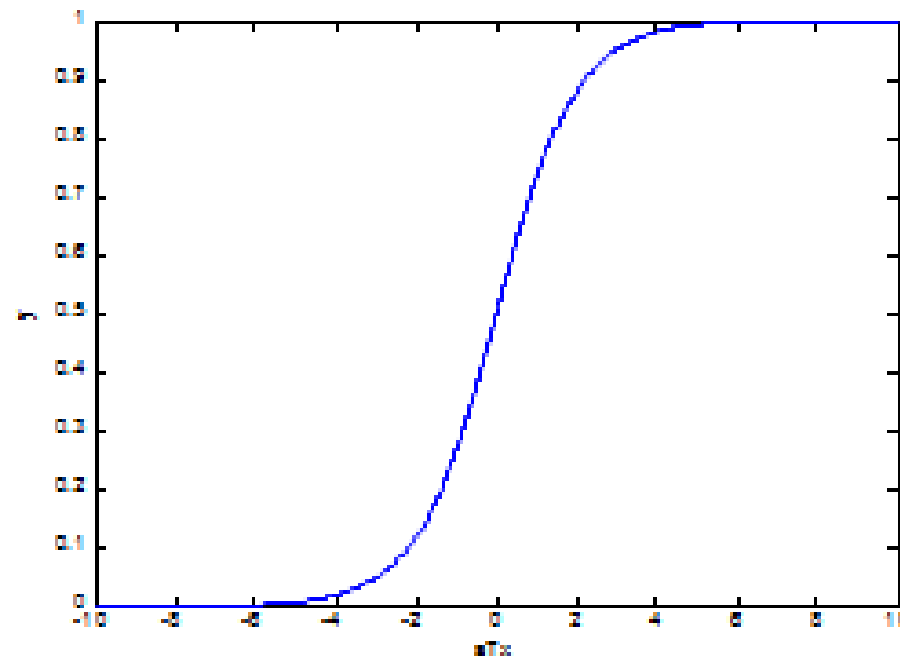


# Neurônio Artificial

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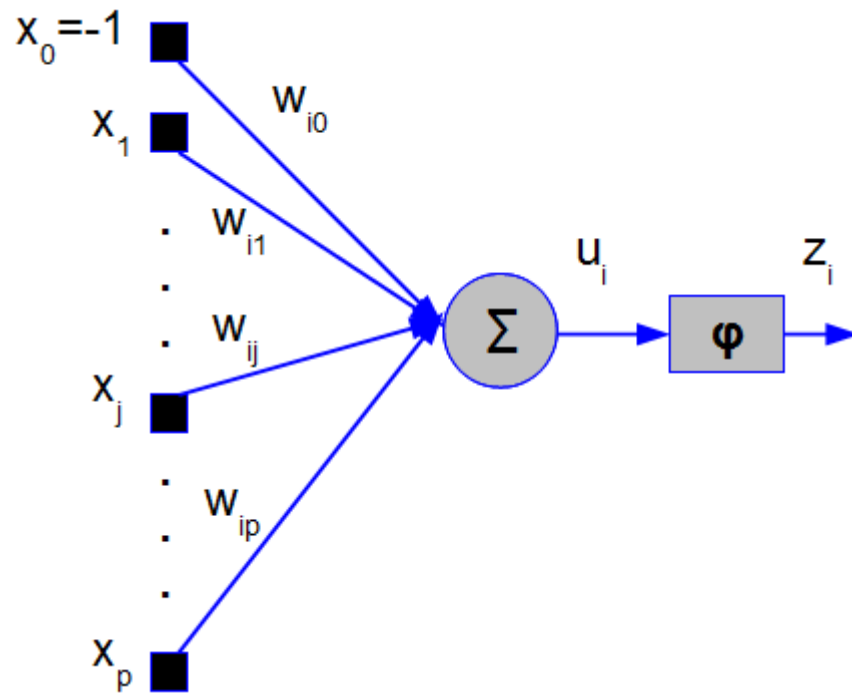
## ► Função Logística

- $f(x) = \frac{1}{1+e^{-x}}$
- $f'(x) = f(x)[1 - f(x)]$



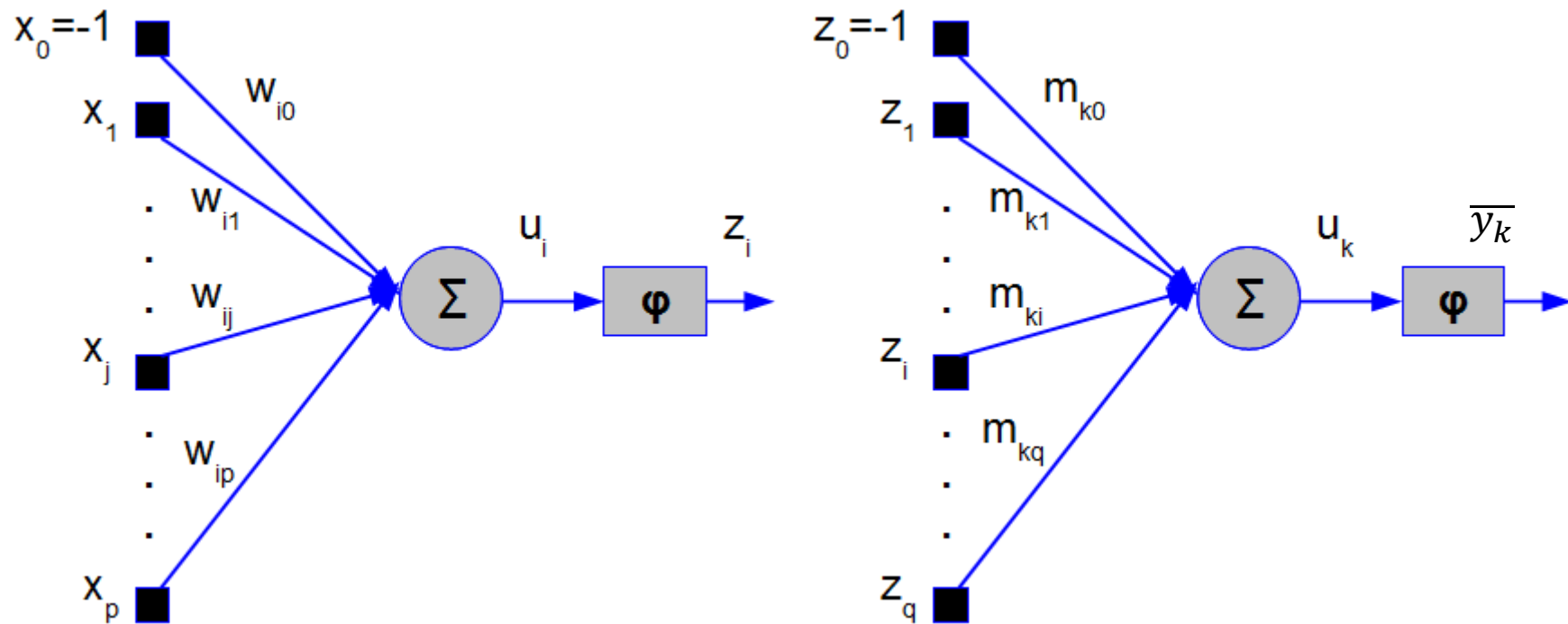
# Rede MLP

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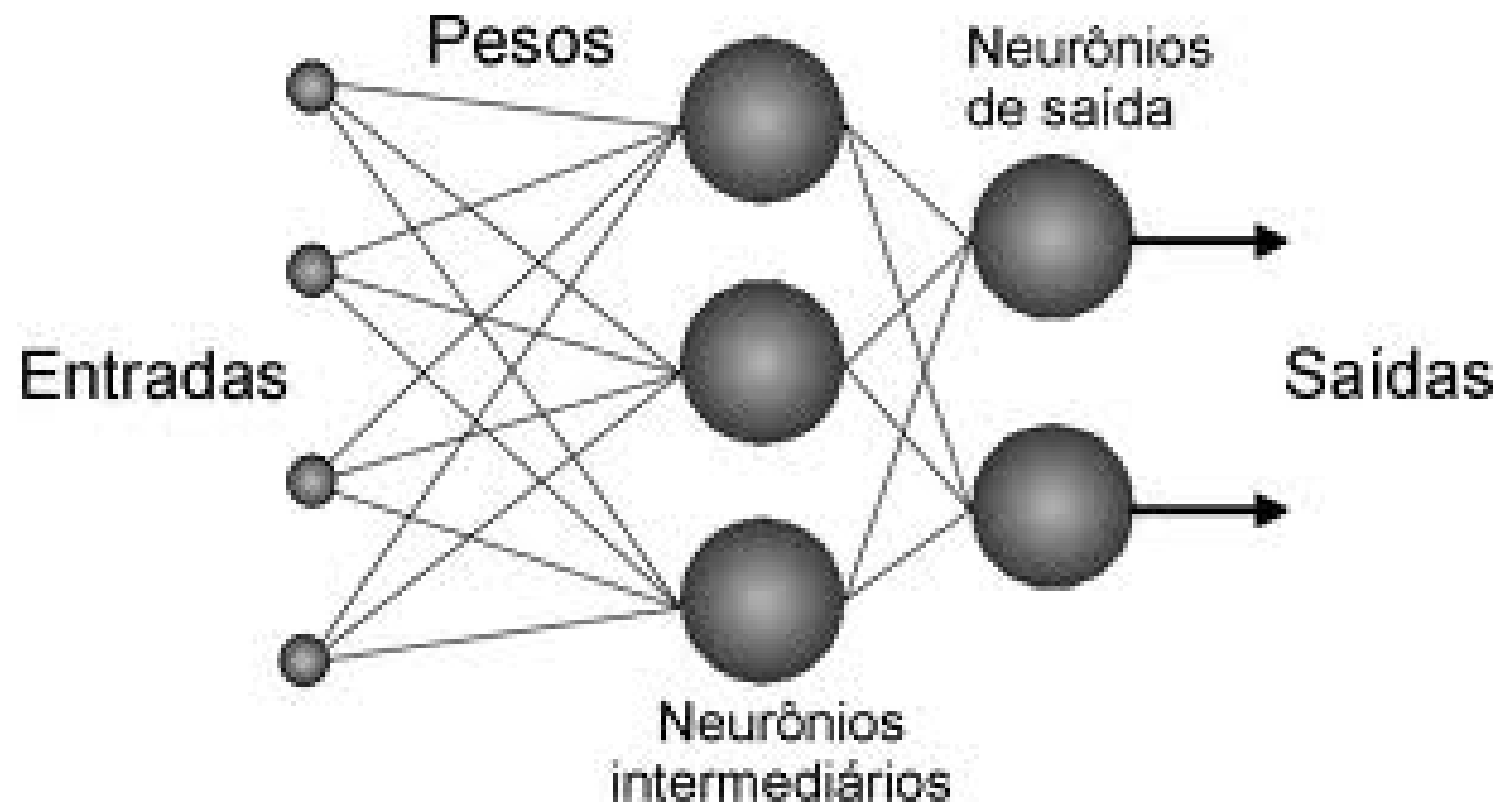
# Rede MLP

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# Rede MLP

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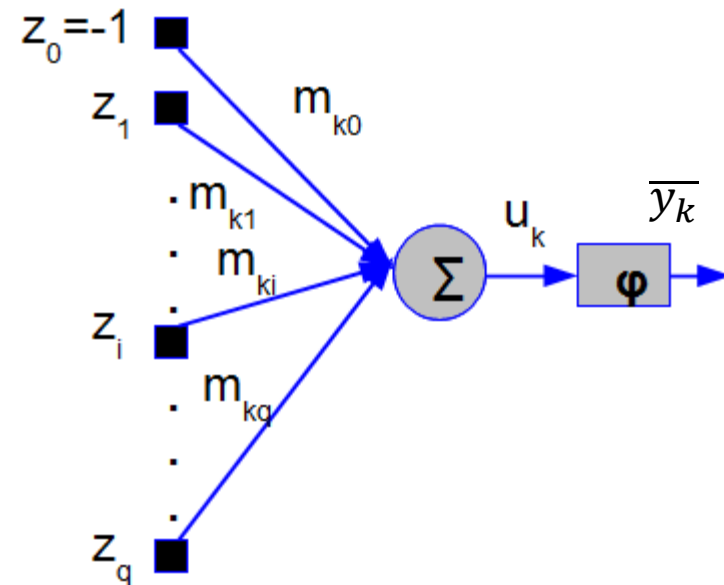
# Rede MLP

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- ▶ Atualização dos pesos da camada de saída

- ▶  $m = m - \alpha \frac{\partial J}{\partial m}$

- ▶  $J(m_{ki}) = \frac{1}{2} \{ [y_k - \overline{y}_k]^2 \}$



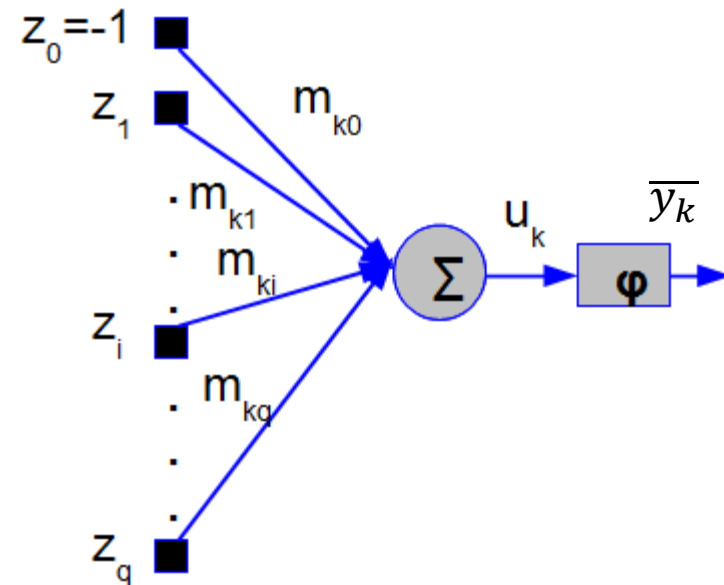
# Rede MLP

---

- Atualização dos pesos da camada de saída

- $m = m - \alpha \frac{\partial J}{\partial m}$

- $J(m_{ki}) = \frac{1}{2} \{ [y_k - \varphi(\sum_{i=0}^q m_{ki} z_i)]^2 \}$





# Rede MLP

---

- ▶ Atualização dos pesos da camada de saída

- ▶  $m = m - \alpha \frac{\partial J}{\partial m}$

- ▶  $J(m_{ki}) = \frac{1}{2} \{ [y_k - \varphi(\sum_{i=0}^q m_{ki} z_i)]^2 \}$

- ▶  $\frac{\partial J}{\partial m_{ki}} = \frac{1}{2} 2 [y_k - \varphi(\sum_{i=0}^q m_{ki} z_i)] [(-1) \varphi'(\sum_{i=0}^q m_{ki} z_i) z_i]$



# Rede MLP

---

- ▶ Atualização dos pesos da camada de saída

- ▶  $m = m - \alpha \frac{\partial J}{\partial m}$

- ▶  $J(m_{ki}) = \frac{1}{2} \{ [y_k - \varphi(\sum_{i=0}^q m_{ki} z_i)]^2 \}$

- ▶  $\frac{\partial J}{\partial m_{ki}} = \frac{1}{2} 2 [y_k - \varphi(\sum_{i=0}^q m_{ki} z_i)] [(-1) \varphi'(\sum_{i=0}^q m_{ki} z_i) z_i]$

- ▶  $\frac{\partial J}{\partial m_{ki}} = -e_k \varphi'(u_k) z_i$



# Rede MLP

---

- ▶ Atualização dos pesos da camada de saída

- ▶  $m = m - \alpha \frac{\partial J}{\partial m}$

- ▶  $J(m_{ki}) = \frac{1}{2} \{ [y_k - \varphi(\sum_{i=0}^q m_{ki} z_i)]^2 \}$

- ▶  $\frac{\partial J}{\partial m_{ki}} = \frac{1}{2} 2 [y_k - \varphi(\sum_{i=0}^q m_{ki} z_i)] [(-1) \varphi'(\sum_{i=0}^q m_{ki} z_i) z_i]$

- ▶  $\frac{\partial J}{\partial m_{ki}} = -e_k \varphi'(u_k) z_i$

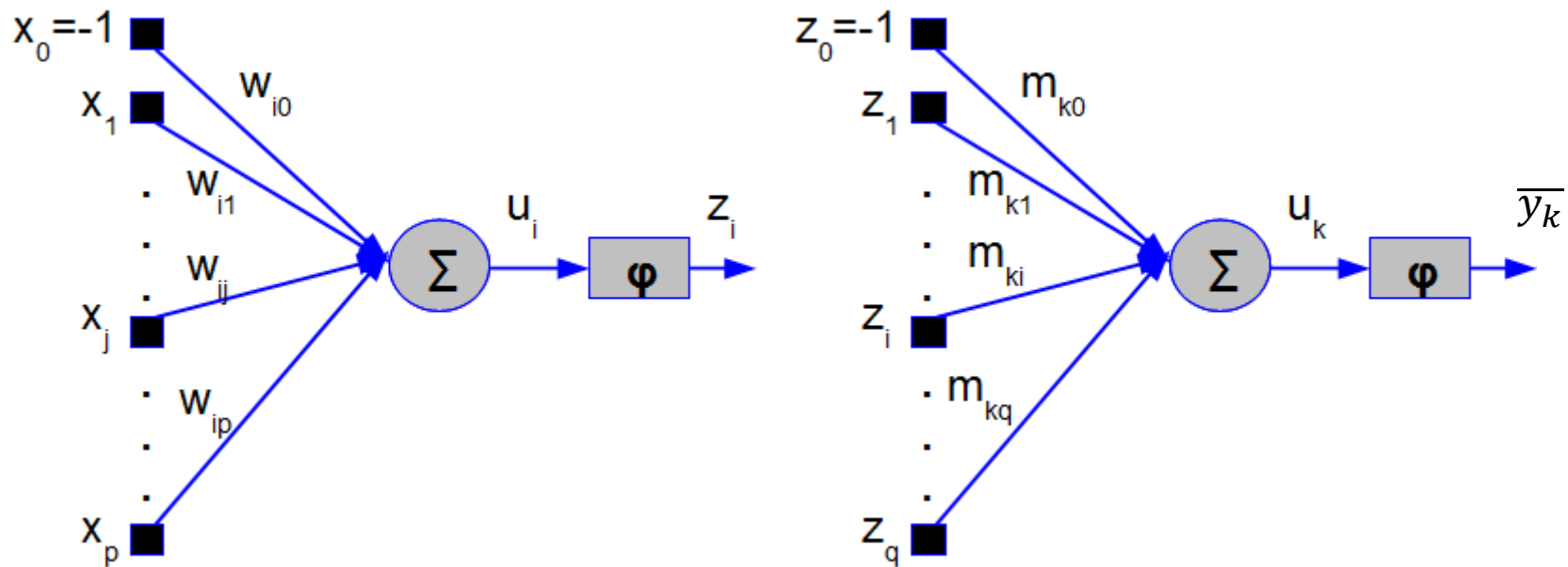
- ▶  $m_{ki} = m_{ki} + \alpha e_k \varphi'(u_k) z_i$



# Rede MLP

## ► Atualização dos pesos da camada oculta

- $w = w - \alpha \frac{\partial J}{\partial w}$
- $J(w_{ij}) = \frac{1}{2} [\sum_{k=1}^r (y_k - \overline{y_k})^2]$

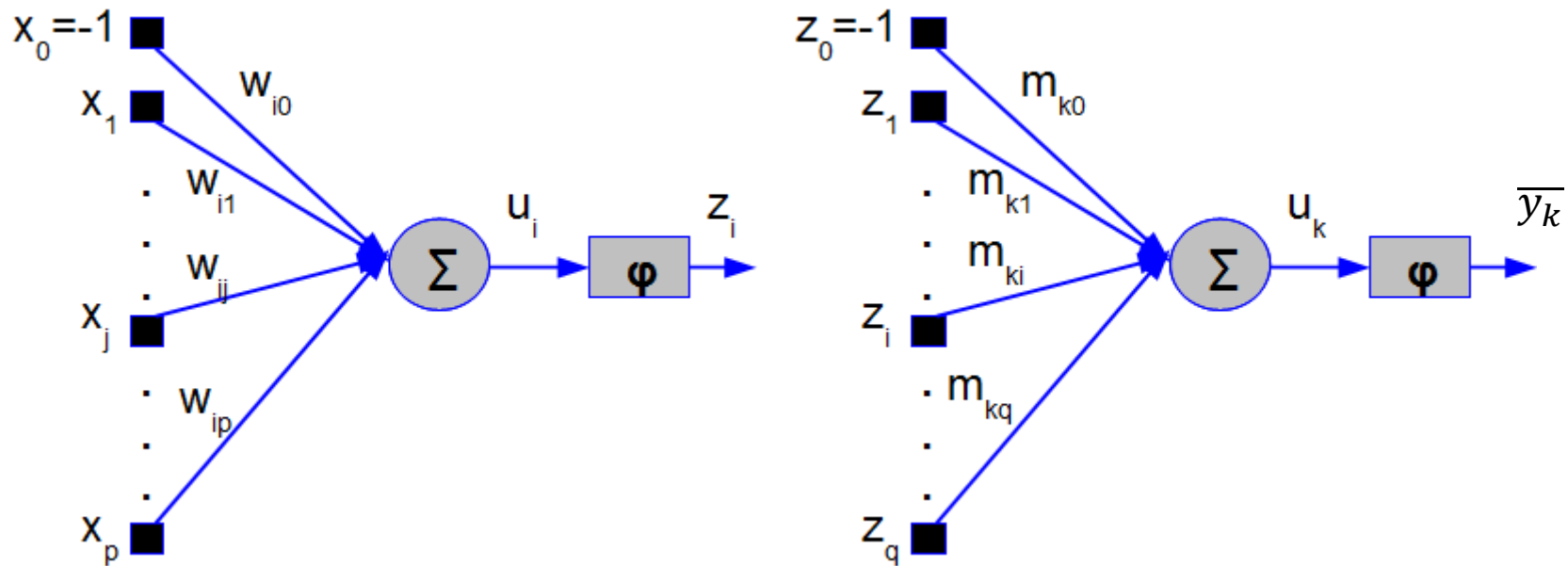


# Rede MLP

## ► Atualização dos pesos da camada oculta

►  $w = w - \alpha \frac{\partial J}{\partial w}$

►  $J(w_{ij}) = \frac{1}{2} \{ \sum_{k=1}^r [y_k - \varphi(\sum_{i=0}^q m_{ki} z_i)]^2 \}$

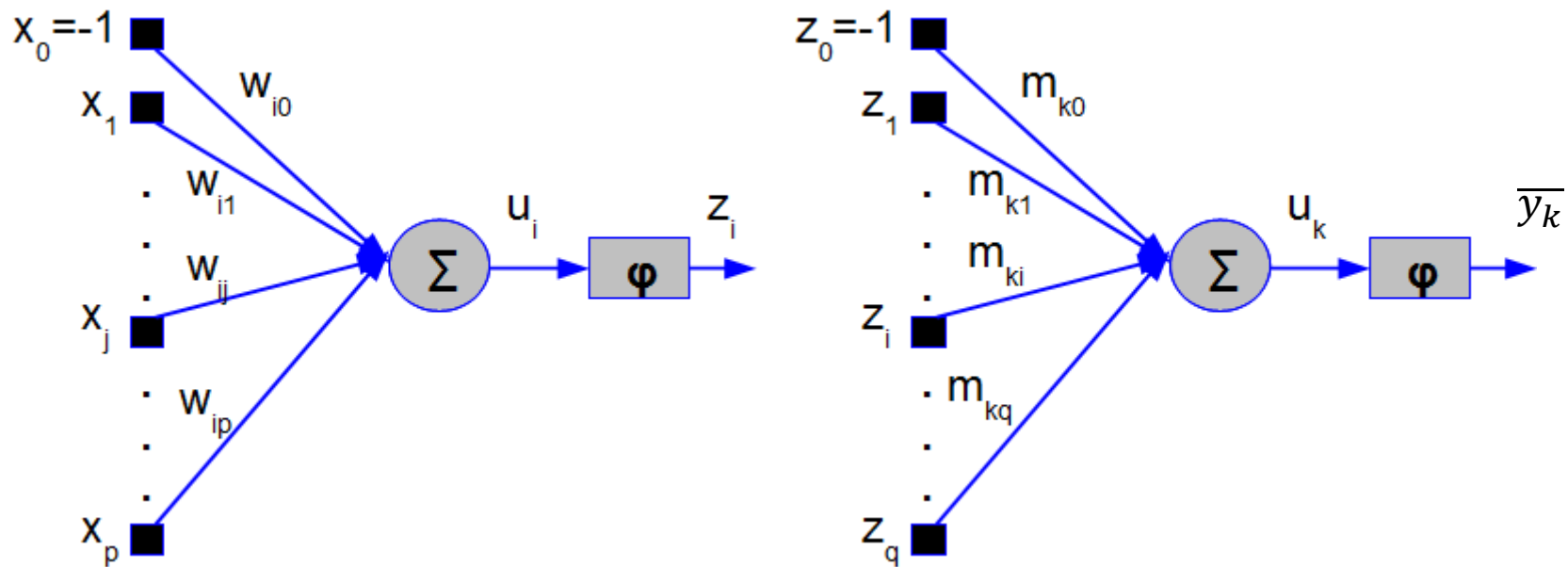


# Rede MLP

## ► Atualização dos pesos da camada oculta

►  $w = w - \alpha \frac{\partial J}{\partial w}$

►  $J(w_{ij}) = \frac{1}{2} \{ \sum_{k=1}^r [y_k - \varphi(\sum_{i=0}^q m_{ki} \varphi(u_i))]^2 \}$

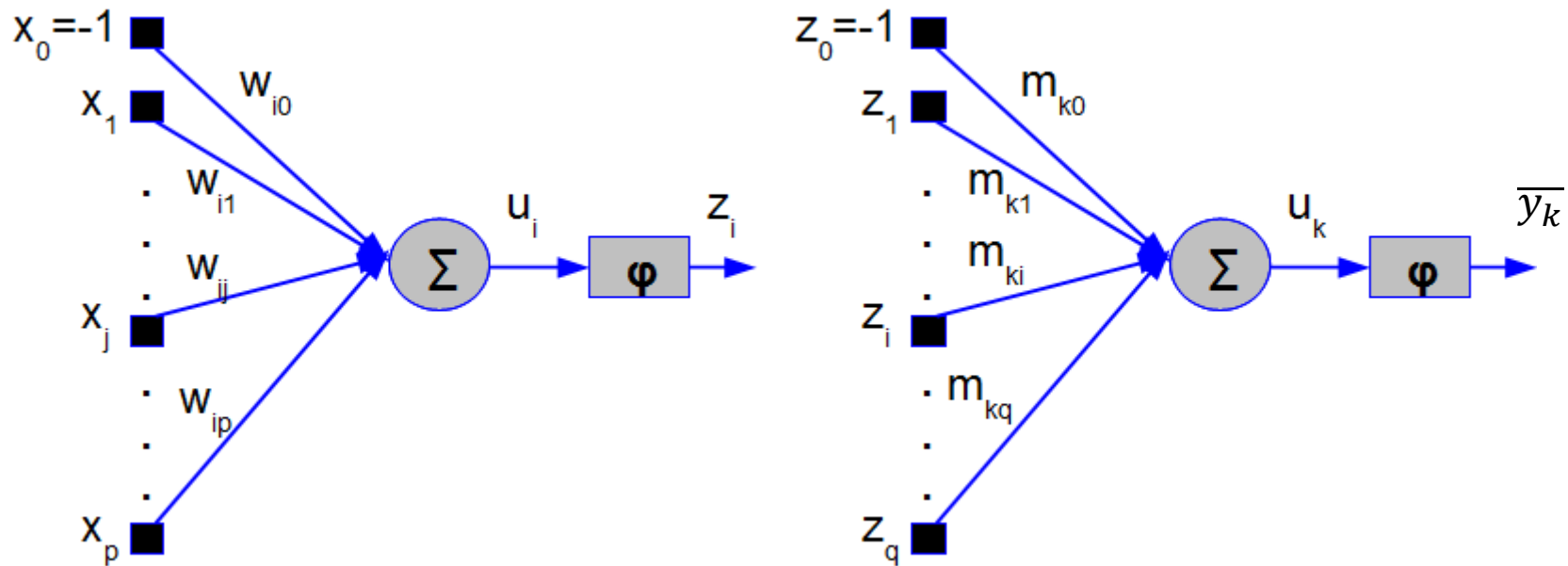


# Rede MLP

## ► Atualização dos pesos da camada oculta

►  $w = w - \alpha \frac{\partial J}{\partial w}$

►  $J(w_{ij}) = \frac{1}{2} \{ \sum_{k=1}^r [y_k - \varphi(\sum_{i=0}^q m_{ki} \varphi(\sum_{j=0}^p w_{ij} x_j))]^2 \}$



# Rede MLP

---

- ▶ Atualização dos pesos da camada oculta

- ▶  $w = w - \alpha \frac{\partial J}{\partial w}$

- ▶  $J(w_{ij}) = \frac{1}{2} \{ \sum_{k=1}^r [y_k - \varphi(\sum_{i=0}^q m_{ki} \varphi(\sum_{j=0}^p w_{ij} x_j))]^2 \}$

- ▶  $\frac{\partial J}{\partial w_{ij}} = -\varphi'(u_i) x_j \sum_{k=1}^r e_k \varphi'(u_k) m_{ki}$





# Rede MLP

---

- ▶ Atualização dos pesos da camada oculta

- ▶  $w = w - \alpha \frac{\partial J}{\partial w}$

- ▶  $J(w_{ij}) = \frac{1}{2} \{ \sum_{k=1}^r [y_k - \varphi(\sum_{i=0}^q m_{ki} \varphi(\sum_{j=0}^p w_{ij} x_j))]^2 \}$

- ▶  $\frac{\partial J}{\partial w_{ij}} = -\varphi'(u_i) x_j \sum_{k=1}^r e_k \varphi'(u_k) m_{ki}$

- ▶  $w_{ij} = w_{ij} + \alpha \varphi'(u_i) x_j \sum_{k=1}^r e_k \varphi'(u_k) m_{ki}$



# Backpropagation

---

- ▶  $w_{ij} = w_{ij} + \alpha \varphi'(u_i) x_j \sum_{k=1}^r e_k \varphi'(u_k) m_{ki}$
- ▶  $m_{ki} = m_{ki} + \alpha e_k \varphi'(u_k) z_i$



# Backpropagation

---

- ▶  $w_{ij} = w_{ij} + \alpha \varphi'(u_i) x_j \sum_{k=1}^r e_k \varphi'(u_k) m_{ki}$
- ▶  $m_{ki} = m_{ki} + \alpha e_k \varphi'(u_k) z_i$
- ▶ **Gradiente local**
  - ▶  $\delta_k = e_k \varphi'(u_k)$



# Backpropagation

---

- ▶  $w_{ij} = w_{ij} + \alpha \varphi'(u_i) x_j \sum_{k=1}^r \delta_k m_{ki}$
- ▶  $m_{ki} = m_{ki} + \alpha \delta_k z_i$
- ▶ **Gradiente local**
  - ▶  $\delta_k = e_k \varphi'(u_k)$



# Backpropagation

---

- ▶  $w_{ij} = w_{ij} + \alpha \varphi'(u_i) x_j \sum_{k=1}^r \delta_k m_{ki}$
- ▶  $m_{ki} = m_{ki} + \alpha \delta_k z_i$
- ▶ **Gradiente local**
  - ▶  $\delta_k = e_k \varphi'(u_k)$
  - ▶  $\delta_i = \varphi'(u_i) \sum_{k=1}^r \delta_k m_{ki}$



# Backpropagation

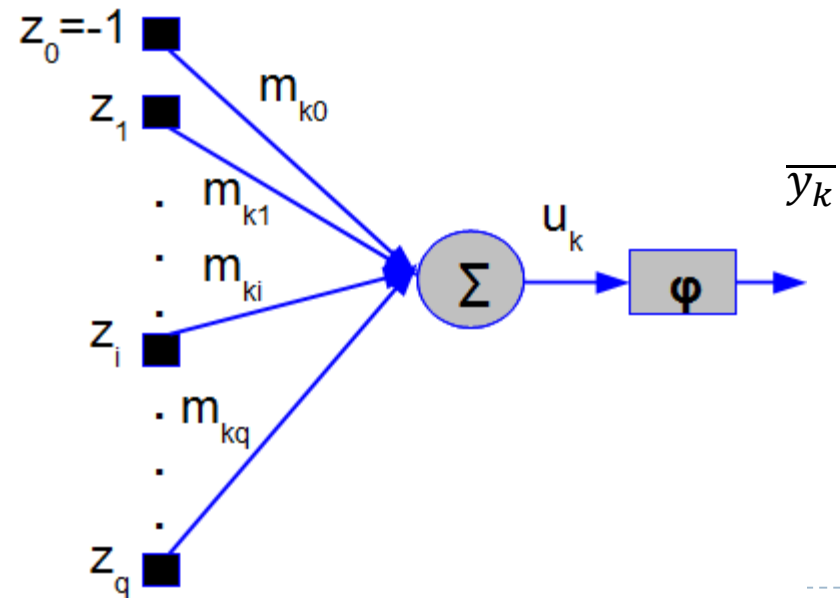
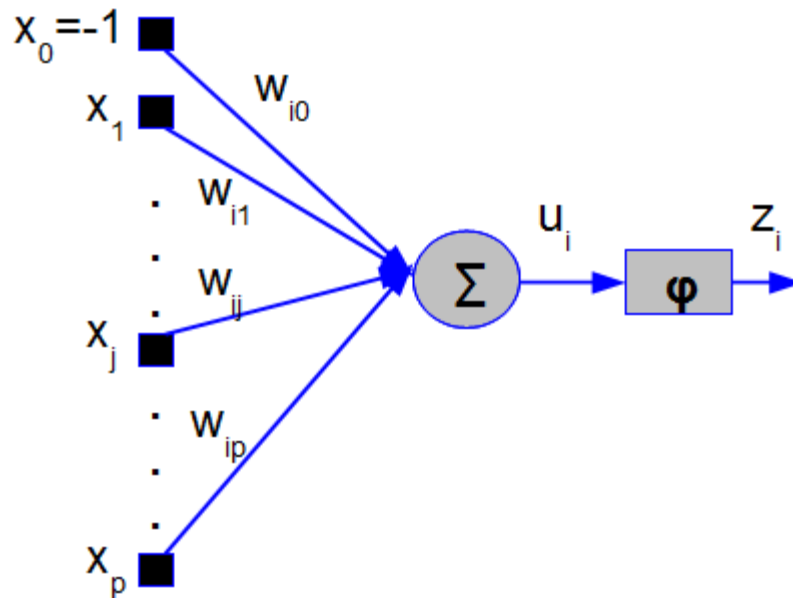
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- ▶  $w_{ij} = w_{ij} + \alpha \delta_i x_j$
- ▶  $m_{ki} = m_{ki} + \alpha \delta_k z_i$
- ▶ **Gradiente local**
  - ▶  $\delta_k = e_k \varphi'(u_k)$
  - ▶  $\delta_i = \varphi'(u_i) \sum_{k=1}^r \delta_k m_{ki}$



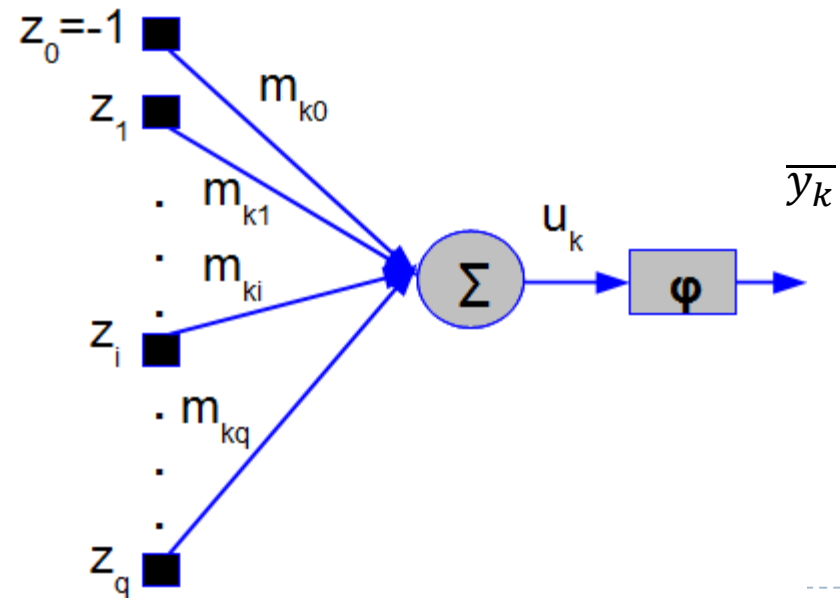
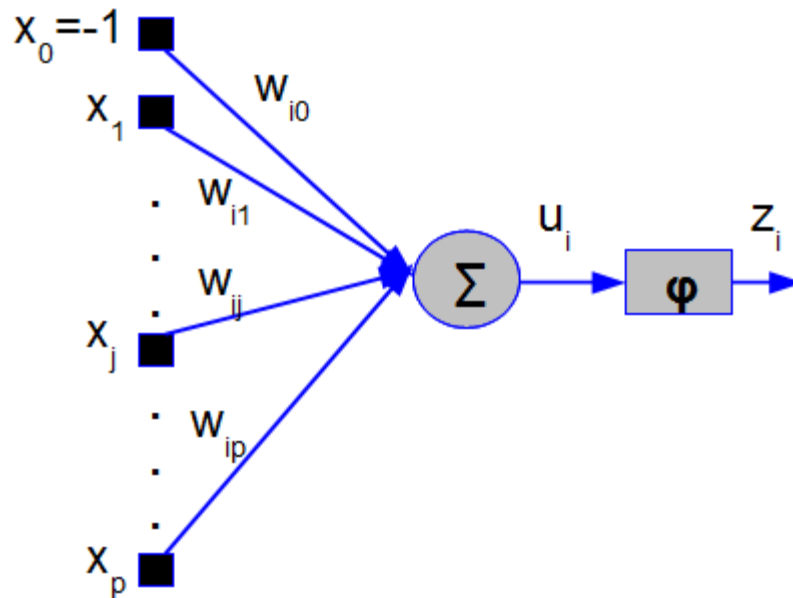
# MLP - Treinamento

- ▶ Inicializa os pesos com valores entre 0 e 1
- ▶ Duas fases
  - ▶ Sentido direto
  - ▶ Sentido inverso



# MLP - Treinamento

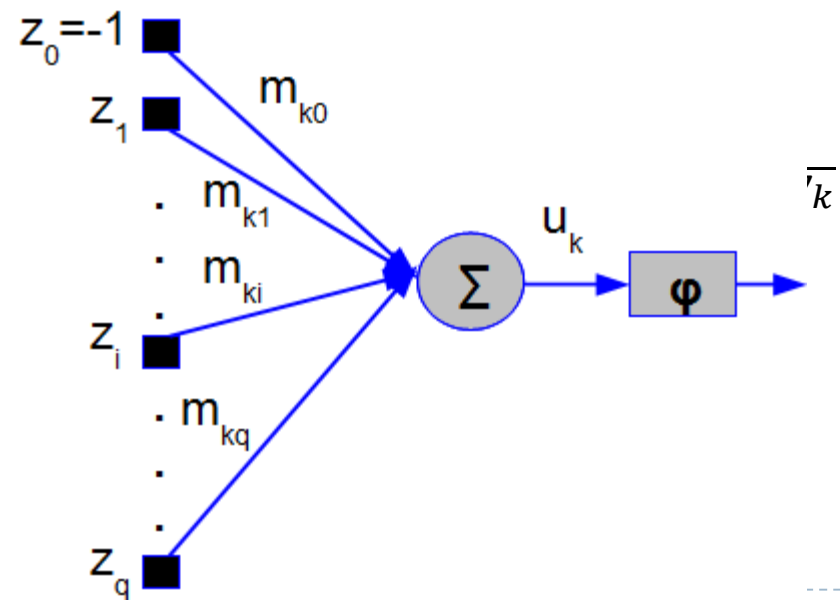
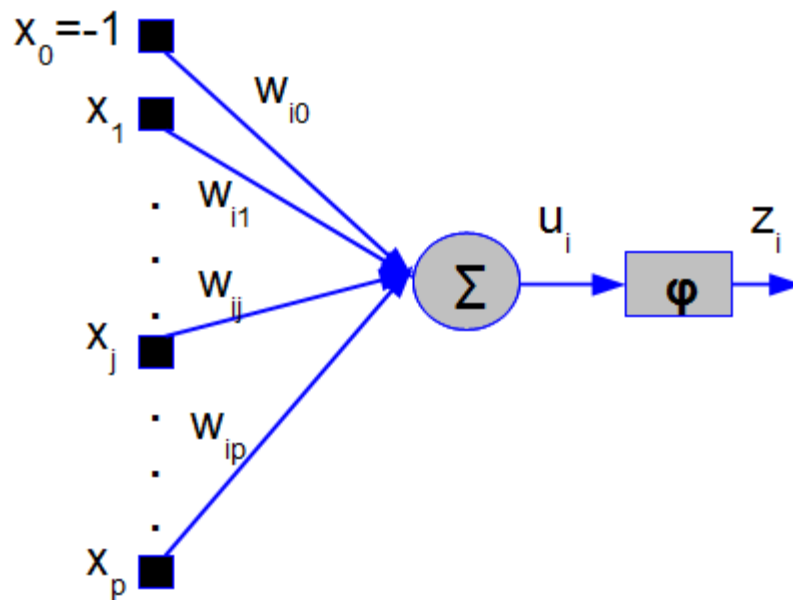
- ▶ Para cada amostra de treinamento
  - ▶ Sentido direto
  - ▶ Calcula  $\overline{y_k}$
  - ▶ Calcula  $e_k = y_k - \overline{y_k}$





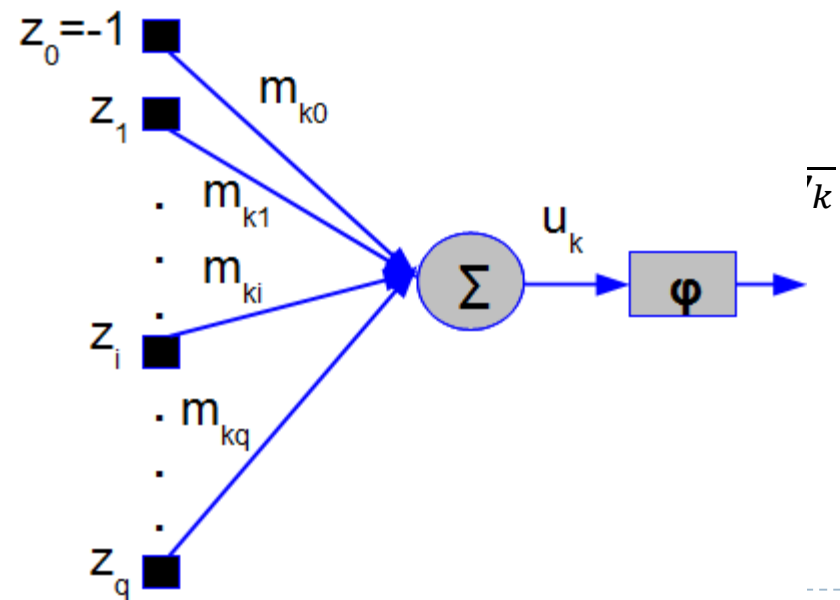
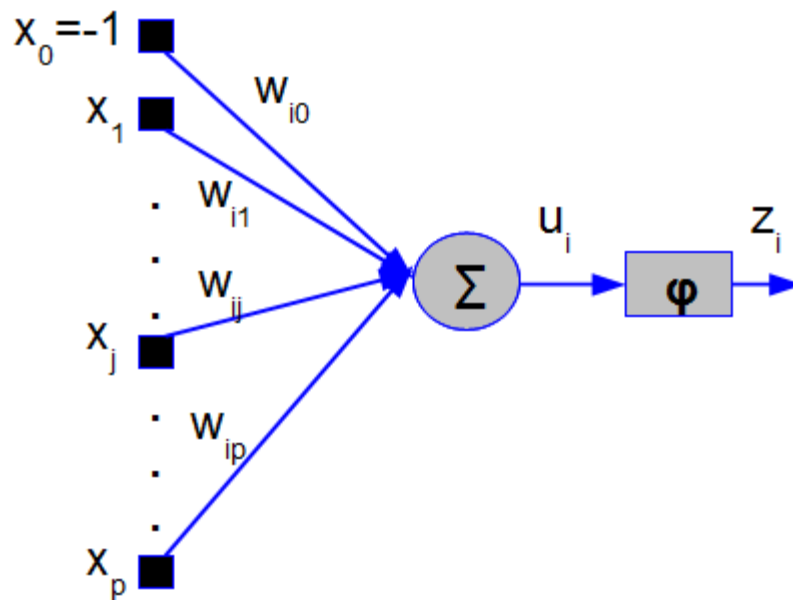
# MLP - Treinamento

- ▶ Para cada amostra de treinamento
  - ▶ Sentido inverso
  - ▶ Calcula os gradientes locais
    - ▶  $\delta_k = e_k \varphi'(u_k)$
    - ▶  $\delta_i = \varphi'(u_i) \sum_{k=1}^r \delta_k m_{ki}$



# MLP - Treinamento

- ▶ Para cada amostra de treinamento
  - ▶ Sentido inverso
  - ▶ Atualiza os pesos
    - ▶  $w_{ij} = w_{ij} + \alpha \delta_i x_j$
    - ▶  $m_{ki} = m_{ki} + \alpha \delta_k z_i$





Dúvidas ?