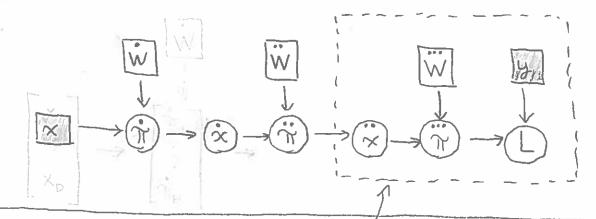
1) Recall the architecture for a feedforward neural network (here, using M=3 layers):



2) We've seen so far a cauple différent instances of his autput layer.

$$\begin{bmatrix} \ddot{x} \\ \vdots \\ \ddot{x} \\ \vdots \\ \ddot{x} \end{bmatrix} \rightarrow \begin{bmatrix} \ddot{x} \\ \ddot{x} \end{bmatrix} \rightarrow \begin{bmatrix} \ddot{x} \\ \ddot{x} \end{bmatrix}$$

$$\begin{bmatrix} \ddot{x}_{1} \\ \vdots \\ \ddot{x}_{H} \end{bmatrix} \rightarrow \begin{bmatrix} \ddot{\eta}_{1} \\ \vdots \\ + \log(1 + e^{-\ddot{\eta}_{1}}) \end{bmatrix}$$

(linear regression)

(logistic regression)

In the transfer of the second of the second

3) In each, we produce a single scalar it, and compare it to scalar response y, to compute loss L.

$$\begin{bmatrix} -50 \\ 2 \\ 1 \end{bmatrix} \qquad \begin{bmatrix} 182 \\ 24 \\ 150 \end{bmatrix} \rightarrow \begin{bmatrix} 148 \\ 148 \end{bmatrix} \rightarrow \begin{bmatrix} 182 \\ 148 \end{bmatrix}^{2}$$
(linear regression)

$$\begin{bmatrix} -150 \\ 0.1 \end{bmatrix}$$

$$\begin{bmatrix} 1 \\ 24 \\ 150 \end{bmatrix} \rightarrow \begin{bmatrix} 2.4 \end{bmatrix} \rightarrow log(1+e^{-2.4})$$

(logistic regression)

- 4) These autput layers address two distinct tasks:
 - regression: the autput variable is a real number (e.g. chalesteral level)
 - classification: the output variable is a
 Boolean value (e.g. whether
 you have high cholesteral or not)

But sometimes you want to classify something into one of several discrete categories. For instance, given an image of an animal, we might want to automatically identify whether it is a horse, a zebra, or a panda.

- multiway classification: the output variable is a member of a finite; unordered set (e.g. 2 horse, zebra, panda 3).

6 How do we represent the response variable y (n) for a multiway classification task? Strings aren't particularly convenient:

(evidence vector)	(response)
x ⁽²⁾ x ⁽³⁾ x ⁽⁴⁾ x ⁽⁵⁾	"Zebra" "Zebra" "Zebra" "panda" "horse"

because how do we compare a string with our output vector ii?

3) We could represent each response as its index in an ordered list of the possible categories, e.g. for < horse, zebra, panda>:

(evidence vector)	(response)
$\chi^{(1)}$ $\chi^{(2)}$	4
× (3)	2
(5)	3
X ⁽⁵⁾	

3) If we do this, then we end up comparing numbers to numbers, but in a way that's kind of weird.

Suppose this dofum is a panda

(index 3)

The loss needs to be some differentiable function of response y and adopt in. If this subject is a panda, then we want to reward panda predictions "i. Let's say we just use the simple loss:

$$L = (y - 77,)^2$$

9 That means we want it, to be close to 3 for panda images. That's ok, but it doesn't penalize horses and zebras equally. For a zebra, the loss is:

$$L = (3-2)^2 = 1$$

while for a horse, the loss is:

$$L = (3-1)^2 = 4$$

To Essentially, if we use the index of an arbitrarily ordered list to represent our response, we are implicitly saying that neighbors in the list (e.g. parda, whin are "closer" than elements that are further apart (e.g. parda and horse).

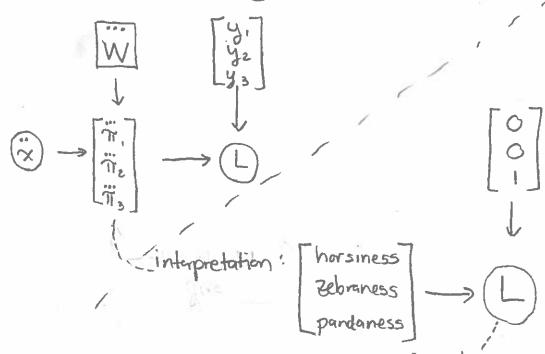
It's hard to imagine a loss function L that doesn't impose this bias, if we need L to be differentiable.

Back to the drawing board. How else could we represent the response? What if, again we provide an ordered list of the categories (e.g. < horse, zebra, panda>), but now we represent the response as a vector whose kth element is equal to 1 if the response is the kth element of the list?

(eridance vector)	(response)	
× ⁽¹⁾		"horse" vector
X ⁽²⁾	$\begin{bmatrix} 0 \\ 0 \end{bmatrix} \leftarrow$	'zebra'' vector
(4)		"zebra" vector
X(H)	00	"panda" vector
×(2)		"horse" vector

These are referred to as "one-hot" vectors.

12) If we go this route, then we'd want our output it to be a vector as well:



loss L should penalize outputs with a high horsiness or zebraness, and reward autputs with high pandaness

13) One straightforward implementation of this intuition is to take the output vector, replace its max value with 1, and replace the other values w. O:

$$\begin{bmatrix}
2.4 \\
4.2 \\
1.0
\end{bmatrix}
\rightarrow
\begin{bmatrix}
0 \\
1 \\
0
\end{bmatrix}
\begin{bmatrix}
1.2 \\
-2.5 \\
1.5
\end{bmatrix}
\rightarrow
\begin{bmatrix}
0 \\
1
\end{bmatrix}$$

Then, take the dot product of the resulting vector with the response:

e.g. [0]T[0] = 0 [0][0] = 1

This gives us a reward of the flee maximal value vontput by the neural network coincides with the ithre' category (and a reward of zero otherwise). To convert this into a loss function, we can just take I minus the reward.

$$\begin{array}{c} \begin{array}{c} \begin{array}{c} \begin{array}{c} \\ \\ \end{array} \end{array} \end{array} \begin{array}{c} \begin{array}{c} \\ \\ \end{array} \end{array} \begin{array}{c} \\ \\ \end{array} \begin{array}{c} \\ \\ \end{array} \begin{array}{c} \\ \end{array} \begin{array}{c} \\ \\ \\ \end{array} \begin{array}{c} \\ \\ \end{array} \begin{array}{c} \\ \\ \\ \end{array} \begin{array}{c} \\ \\ \end{array} \begin{array}{c} \\ \\ \end{array} \begin{array}{c} \\ \\ \\ \end{array} \begin{array}{c} \\ \\ \end{array} \begin{array}{c} \\ \\ \\ \end{array} \begin{array}{c} \\ \\ \end{array} \begin{array}{c} \\ \\ \\ \end{array} \begin{array}{c} \\ \\ \\ \end{array} \begin{array}{c} \\ \\ \end{array} \begin{array}{c} \\ \\ \\ \end{array} \begin{array}{c} \\ \\ \end{array} \begin{array}{c} \\ \\ \\ \end{array} \begin{array}{c} \\ \\ \\ \\ \end{array} \begin{array}{c} \\ \\ \\ \\ \end{array} \begin{array}$$

the 1055 is zero if this is the maximal output the loss is I if either of these are the maximal autput

(15) We can formalize this by defining onehot (k, d) to be the d-dimensional one-hot vector whose kth element is 1, e.g. onehot $(2,3) = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$, onehot $(1,3) = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$.

Then we define the loss as

L=11-yT. onehot (argmax ir, C)

where C is the number of categories (e.g. C=3 in our running example).

(6) There's only one problem. This loss function isn't differentiable. We can't compute $\frac{\partial L}{\partial n}$, so we can't compute $\frac{\partial L}{\partial n}$, and thus we can't use gradient descent to optimize the weights O.

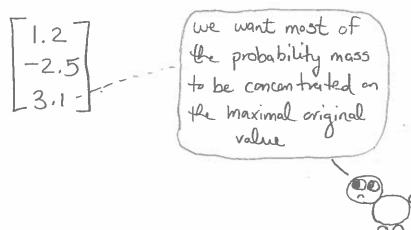
F) But can we find an alternative loss function that is similar in spirit, but which is differentiable?

First, observe that our "hard max" function is essentially mapping the vector in to a probability distribution:

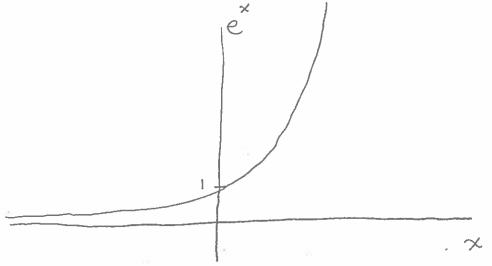
So one idea would be to map it to a probability distribution for which most of the probability mass is concentrated on one value, e.g.

$$\begin{bmatrix} 1.2 \\ -2.5 \\ 3.1 \end{bmatrix} \longrightarrow \begin{bmatrix} .130 \\ .003 \\ .867 \end{bmatrix}$$

How do we map a vector of reals into a probability distribution such that most of the probability mass is concentrated on the highest original value?



19 One cool trick is to notice that the exponential function maps the real numbers to strictly positive numbers:



It also does so in a way that magnifies the differences between the original numbers.

20) For instance, applying the exponential function; we get:

$$\begin{bmatrix} 1.2 \\ -2.5 \\ 3.1 \end{bmatrix}$$
 exponentiate $\begin{bmatrix} 3.32 \\ 0.08 \\ 22.2 \end{bmatrix}$

Now that we have a vector of positive numbers, we can simply normalize to get a probability distribution.

(21) This function is referred to as softmax:

$$Softmax \left(\begin{bmatrix} z_1 \\ \vdots \\ z_N \end{bmatrix} \right) = \begin{bmatrix} \frac{e^{z_1}}{\sum_{i=1}^{2n} e^{z_i}} \\ \frac{e^{z_1}}{\sum_{i=1}^{2n} e^{z_i}} \end{bmatrix}$$

22) Retrofitting our loss function from (5) to use softmax instead of hardmax, we get:

→ if output
$$\tilde{\pi} = \begin{bmatrix} 1.2 \\ -2.5 \\ 3.1 \end{bmatrix}$$
 and response $y = \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$

Hen:
$$L = 1 - [0 \ 0 \] [.130] = .133$$
 $[.867]$

if output
$$\tilde{\eta} = \begin{bmatrix} 1.2 \\ -2.5 \\ 3.1 \end{bmatrix}$$
 and response $y = \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}$

In other words, the 1055 is the total probability mass accorded to incorrect responses.

24) Of course, this is all for nothing if the 1055 isn't differentiable. And it is:

$$\frac{\partial L}{\partial \vec{n}_{i}} = \frac{\partial}{\partial \vec{n}_{i}} \left(-y^{T} \cdot softmax (\vec{n}) \right)$$

$$= \frac{\partial}{\partial \vec{n}_{i}} \left(-y^{T} \cdot softmax (\vec{n}) \right)$$

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$$= \frac{\partial}{\partial \vec{n}_{i}} \left(-y^{T} \cdot softmax (\vec{n}) \right)$$

$$= \frac{\partial}{\partial \pi_{L}} \left(\frac{-1}{\sum_{n} e^{\pi_{n}}} \right) y^{T} \cdot \begin{bmatrix} e^{\pi_{n}} \\ \vdots \\ e^{\pi_{n}} \end{bmatrix}$$

$$= y^{T} \cdot \begin{bmatrix} e^{i\pi} \\ \frac{\partial}{\partial \pi_{i}} \end{bmatrix} \frac{\partial}{\partial \pi_{i}} \left(\frac{1}{\sum_{e} i\pi_{n}} \right) + \frac{1}{\sum_{e} i\pi_{n}} \frac{\partial}{\partial \pi_{i}} \left(y^{T} \begin{bmatrix} e^{i\pi} \\ \frac{\partial}{\partial \pi_{n}} \end{bmatrix} \right)$$

$$= y^{T} \cdot \begin{bmatrix} e^{i\pi} \\ \frac{\partial}{\partial \pi_{n}} \end{bmatrix} \left(\frac{-e^{i\pi}}{\sum_{e} i\pi_{n}} \right)^{2} + \frac{y_{i}}{\sum_{e} i\pi_{n}}$$