

Simpler Computation of Minimal Removable Sets in 2-Edge-Connected Systems for Undirected Graphs

SHOTA, Kan HARAGUCHI, Kazuya

30th December 2025

1 Introduction

2 Preliminaries

2.1 Graphs

Throughout the paper, we assume that a graph is simple and undirected. We also assume that each vertex v is associated with a fixed integer identifier $\text{id}(v)$. These identifiers are given as part of the input graph and are preserved in all induced subgraphs.

For a graph $G = (V, E)$ with a vertex set V and an edge set E , we may abbreviate an edge $\{u, v\} \in E$ as uv (or equivalently vu) for simplicity. For a vertex $v \in V$, we denote by $N_G(v)$ the set of neighbours of v . Let $S \subseteq V$ be a subset of vertices. We denote by $N_G(S) = \bigcup_{v \in S} N_G(v) \setminus S$, the set of open neighbours of S in G . We denote by $G[S]$ the subgraph of G induced by S . We denote by $G - S$ the subgraph obtained by removing S and all edges incident to S , that is, $G - S = G[V - S]$. If $S = \{v\}$, then we simply write $G - v$ instead of $G - \{v\}$. A *degree-two segment* in G is a maximal path whose vertices all have degree two in G . Note that a degree-two segment may consist of a single vertex.

2.2 DFS-Trees and Related Notions

A *DFS-tree* of a connected undirected graph $G = (V, E)$ is a spanning tree T obtained by performing a depth-first search (DFS) on G . We root T at an arbitrary vertex $r \in V$. For each $v \in V$, we denote by T_v the subtree of T rooted at v .

An edge in E is called a *tree edge* if it appears in T , and a *back edge* otherwise. For $u, v \in V$, we say that u is an *ancestor* of v if u lies on the unique $r-v$ path in T . Moreover, if u is an ancestor of v and $u \neq v$, then we say that u is a *proper ancestor* of v , and v is correspondingly a (*proper*) *descendant* of u . If uv is a tree edge and u is an ancestor of v , then u is the *parent* of v ; we denote this by $\pi(v) = u$.

We may orient edges based on the DFS-tree T : for a tree edge $\pi(v)v$, we orient it from $\pi(v)$ to v ; and for a back edge xy , we orient it from the descendant to the ancestor. We

may write (u, v) and (x, y) to indicate the orientation of edge uv and xy , and refer to it as the *outgoing edge* from u or x and the *incoming edge* to v or y .

We say that a tree edge $\pi(v)v$ is *covered* by a back edge $e = (x, y)$ if x is a descendant of v and y is a proper ancestor of v (an ancestor of $\pi(v)$). In this case, e together with $\pi(v)v$ forms part of a cycle in G . Note that every tree edge is covered by at least one back edge if G is 2-edge-connected. For a tree edge uv , we denote by $Cov(uv) = \{(x, y) \in E \mid (x, y) \text{ is a back edge covering } uv\}$ the set of back edges that cover uv . We refer to $CovMult(uv) \triangleq |Cov(uv)|$ as the *cover multiplicity* of the tree edge uv .

In addition to cover multiplicity, we also consider aggregated identifiers of endpoints of covering back edges. For a tree edge uv and $i \in \{1, 2\}$, we define

$$AggDesc_i(uv) \triangleq \sum_{(x,y) \in Cov(uv)} (id(x))^i, \quad AggAnc_i(uv) \triangleq \sum_{(x,y) \in Cov(uv)} (id(y))^i.$$

We refer to these quantities as *aggregated identifiers*.

2.3 Graph Contraction and Suppression

Let $G = (V, E)$ be a graph. For $S \subseteq V$, the *contraction* of S in G is the graph obtained by merging all vertices in S into a single vertex s , removing all edges with both endpoints in S , and replacing each edge with one endpoint in S by an edge incident to s . For a vertex $v \in V$ with degree two, the *suppression* of v in G is the graph obtained by removing v and its two incident edges, and adding a new edge between the two neighbours of v . Equivalently, assuming that v has two neighbours u and w , we contract the set $\{u, v\}$ or $\{v, w\}$ in G .

3 Cover Information on DFS-Trees

For later use, we present efficient algorithms for computing various cover-related quantities in this section. In Section 3.1, we introduce a general technique, called *difference-based aggregation*, which efficiently supports path-based update operations on a rooted tree. In Section 3.2, we apply this technique to compute various cover-related quantities for all tree edges in a 2-edge-connected undirected graph in $O(n + m)$ time.

Before presenting the algorithms, we briefly illustrate how aggregated identifiers can be used to detect structural properties of covering back edges. For a tree edge uv , we can determine whether all covering back edges outgo from the same descendant or ingo to the same ancestor using the aggregated identifiers. In order to show this, we first prove a general lemma on sequences of real numbers.

Lemma 1 *Let $(\alpha_1, \alpha_2, \dots, \alpha_q)$ be a sequence of q real numbers. Then, all elements in the sequence are equal, i.e., $\alpha_1 = \alpha_2 = \dots = \alpha_q$, if and only if*

$$\left(\sum_{i=1}^q \alpha_i \right)^2 = q \sum_{i=1}^q (\alpha_i)^2.$$

PROOF: We have

$$\begin{aligned}
q \sum_{i=1}^q (\alpha_i)^2 - \left(\sum_{i=1}^q \alpha_i \right)^2 &= \sum_{i=1}^q (q-1) (\alpha_i)^2 - \sum_{i=1}^{q-1} \sum_{j=i+1}^q 2\alpha_i \alpha_j \\
&= \sum_{i=1}^q (q-i+i-1) (\alpha_i)^2 - \sum_{i=1}^{q-1} \sum_{j=i+1}^q 2\alpha_i \alpha_j \\
&= \sum_{i=1}^{q-1} \sum_{j=i+1}^q (\alpha_i)^2 + \sum_{i=2}^q \sum_{j=1}^{i-1} (\alpha_i)^2 - \sum_{i=1}^{q-1} \sum_{j=i+1}^q 2\alpha_i \alpha_j \\
&= \sum_{i=1}^{q-1} \sum_{j=i+1}^q \left[(\alpha_i)^2 - 2\alpha_i \alpha_j + (\alpha_j)^2 \right] = \sum_{i=1}^{q-1} \sum_{j=i+1}^q (\alpha_i - \alpha_j)^2.
\end{aligned}$$

Since each term in the last summation is nonnegative, the entire summation is equal to zero if and only if $\alpha_i = \alpha_j$ for all $i, j \in \{1, \dots, q\}$. \square

Using Lemma 1, we can prove the following lemma on aggregated identifiers.

Lemma 2 *Let $G = (V, E)$ be a 2-edge-connected undirected graph, T be a DFS-tree of G rooted at $r \in V$, and uv be a tree edge in T . Moreover, let $Cov(uv) = \{(x_1, y_1), \dots, (x_q, y_q)\}$ be the set of back edges covering uv , where $q = CovMult(uv)$. Then, the following two conditions hold:*

- $x_1 = x_2 = \dots = x_q$ if and only if $(AggDesc_1(uv))^2 = q \cdot AggDesc_2(uv)$; and
- $y_1 = y_2 = \dots = y_q$ if and only if $(AggAnc_1(uv))^2 = q \cdot AggAnc_2(uv)$.

PROOF: The conditions follow directly from Lemma 1 by setting $\alpha_i := id(x_i)$ for the descendant-side condition and $\alpha_i := id(y_i)$ for the ancestor-side condition. \square

3.1 Difference-Based Aggregation on a Rooted Tree

Let T be a rooted tree. Each edge e stores a value, say $A(e)$ (from \mathbb{Z} , \mathbb{R} , or, more generally, from an additive abelian group), and update operations add a constant value to all edges on a specified ancestor–descendant path in T .

Formally, update operations are specified by triples (x, y, α) , where y is an ancestor of x in T , and α is a value to be added to all edges on the x – y path. The goal is to compute the final value stored in each edge after performing a sequence of such update operations.

In order to achieve this goal efficiently, we use a difference-based approach. We associate each vertex v in T with an auxiliary value $\Delta(v)$, initially set to zero. For each update operation (x, y, α) , we perform:

$$\Delta(x) := \Delta(x) + \alpha, \quad \Delta(y) := \Delta(y) - \alpha.$$

Algorithm 1 Difference-Based Aggregation on a Rooted Tree

Input: A rooted tree T , an initial value $A(e)$ for all edges e in $E(T)$, and a sequence of update operations (x, y, α)

Output: The final values for all edges

```

1: Initialise  $\Delta(v) := 0$  for all  $v \in V(T)$  and  $value(e) := A(e)$  for all  $e \in E(T)$ ;
2: for each update operation  $(x, y, \alpha)$  do
3:    $\Delta(x) := \Delta(x) + \alpha$ ;  $\Delta(y) := \Delta(y) - \alpha$ 
4: end for;
5: for each child  $w$  of the root  $r$  in  $T$  do
6:   Execute AGGREGATE-DFS( $w$ )
7: end for;
8: output  $value(e)$  for all edges  $e$  in  $E(T)$ 
9:
10: procedure AGGREGATE-DFS( $v$ )
11:    $value(\pi(v)v) := value(\pi(v)v) + \Delta(v)$ ;
12:   for each child  $w$  of  $v$  in  $T$  do
13:     Execute AGGREGATE-DFS( $w$ );
14:      $value(\pi(v)v) := value(\pi(v)v) + value(vw)$ 
15:   end for
16: end procedure

```

Lemma 3 Let T be a rooted tree and each edge e store an initial value $A(e)$. After performing a sequence of update operations represented as triples (x, y, α) on a rooted tree T , for each edge $\pi(v)v$, the updated value is given by

$$A(\pi(v)v) + \sum_{w \in V(T_v)} \Delta(w).$$

PROOF: Consider a single update operation (x, y, α) . By the definition of Δ , the operation contributes $+\alpha$ to $\Delta(x)$ and $-\alpha$ to $\Delta(y)$. We examine how such an operation contributes to the sum $\sum_{w \in V(T_v)} \Delta(w)$.

If $x \in V(T_v)$ and $y \notin V(T_v)$, then the $x-y$ path passes through $\pi(v)v$, and the operation contributes $+\alpha$ to the sum. If both x and y belong to $V(T_v)$, then the $x-y$ path does not pass through $\pi(v)v$, and its $+\alpha$ and $-\alpha$ contributions cancel within T_v , yielding a total contribution of 0. If neither x nor y is in T_v , then the $x-y$ path does not pass through $\pi(v)v$, and again contributes 0 to the sum. Since y is a proper ancestor of x , the case with $x \notin V(T_v)$ and $y \in V(T_v)$ cannot occur.

Therefore, the only update operations that contribute a nonzero amount are those whose $x-y$ path passes through $\pi(v)v$, and each such operation contributes exactly $+\alpha$.

□

Lemma 4 *Given a rooted tree T with n vertices and a sequence of q update operations, Algorithm 1 computes the final values for all edges in $O(q + n)$ time.*

PROOF: By Lemma 3, it suffices to show that Algorithm 1 correctly computes $A(\pi(v)v) + \sum_{w \in V(T_v)} \Delta(w)$ for each edge $\pi(v)v$.

We first show the case with v being a leaf. In this case, since there is no child of v in T , the algorithm sets $\text{value}(\pi(v)v) = A(\pi(v)v) + \Delta(v)$.

Next, we consider the case other than the leaf case. We assume that, for any child w of v in T , $\text{AGGREGATE-DFS}(w)$ correctly computes the sum of the auxiliary values Δ for all vertices in T_w . Then, the algorithm computes

$$A(\pi(v)v) + \Delta(v) + \sum_{w: \text{child of } v} \sum_{z \in V(T_w)} \Delta(z) = A(\pi(v)v) + \sum_{z \in V(T_v)} \Delta(z)$$

that is the sum of the auxiliary values Δ for all vertices in T_v .

Since each update operation is processed in constant time, the total time for all q update operations is $O(q)$. We visit each vertex exactly once, and consider all edges exactly once, which means we can correctly compute the final values for all edges. Since we traverse only edges in T , we can execute the aggregation in $O(n)$ time. \square

3.2 Computation of Cover Information

Let $G = (V, E)$ be a 2-edge-connected undirected graph and T be a DFS-tree of G rooted at $r \in V$. As described in Section 2.2, every back edge (x, y) is oriented from a descendant x to a proper ancestor y .

Each back edge (x, y) covers all tree edges on the unique $y-x$ path in T . Therefore, we have a natural mapping from back edges to an update operation (x, y, α) on T , where α is chosen appropriately depending on the quantity to be computed.

Lemma 5 *Given a 2-edge-connected undirected graph $G = (V, E)$ with $n = |V|$ and $m = |E|$, and a DFS-tree T of G rooted at $r \in V$, we can compute the following quantities for all tree edges in T in $O(n + m)$ time:*

- Cover multiplicity $\text{CovMult}(uv)$;
- Aggregated identifiers $\text{AggDesc}_1(uv)$ and $\text{AggDesc}_2(uv)$; and
- Aggregated identifiers $\text{AggAnc}_1(uv)$ and $\text{AggAnc}_2(uv)$.

PROOF: By the definition of each quantity, we can represent the contribution of each back edge (x, y) as an update operation (x, y, α) on T , where α is set as follows:

- For $\text{CovMult}(uv)$, set $\alpha := 1$;
- For $\text{AggDesc}_i(uv)$, set $\alpha := (\text{id}(x))^i$ for $i \in \{1, 2\}$; and

- For $\text{AggAnc}_i(uv)$, set $\alpha := (\text{id}(y))^i$ for $i \in \{1, 2\}$.

Since there are $O(m)$ back edges in G , we can perform $O(m)$ update operations on T . By Lemma 4, we can compute the final values for all tree edges in $O(n + m)$ time. \square

4 Mathematical Properties and Computation of Minimal Removable Sets

In this section, we study structural properties of MinRSs and present an efficient algorithm for computing all MinRSs in a 2-edge-connected undirected graph.

MinRSs in a 2-edge-connected undirected graph have been studied in [1, 2]. In these works, they showed the following necessary condition for MinRSs.

Lemma 6 (Observation 3 in [1] and Lemma 7 in [2]) *Let $G = (V, E)$ be a 2-edge-connected undirected graph with $|V| \geq 3$. If a nonempty proper subset $S \subsetneq V$ is a MinRS of G , then,*

- S forms a degree-two segment in G ; or
- S is a singleton $\{v\}$, where $v \in V$.

By Lemma 6, we can list all candidates for MinRSs in $O(n + m)$ time by finding all degree-two segments in G and collecting all singleton vertex sets.

Based on Lemma 6, we classify MinRSs into several types to make them easier to handle with a DFS-tree T of G rooted at an arbitrary vertex $r \in V$:

- the MinRS containing the root of the DFS-tree;
- MinRSs containing at least one leaf of the DFS-tree;
- MinRSs consisting only of internal vertices of the DFS-tree that form a degree-two segment in G ; and
- MinRSs consisting of a single internal vertex of the DFS-tree with degree at least three in G .

The MinRS containing the root of the DFS-tree contains no leaf of the DFS-tree; this categorisation is mutually exclusive.

Lemma 7 *Let $G = (V, E)$ be a 2-edge-connected undirected graph with $|V| \geq 3$ and T be a DFS-tree of G rooted at $r \in V$. We can determine whether G has a MinRS containing r and find such a MinRS in $O(n + m)$ time.*

PROOF: By Lemma 6, if G has a MinRS containing r , then it is either $\{r\}$ (if $\deg_G(r) \geq 3$) or a degree-two segment P containing r (otherwise). All we have to do is to check $G - r$ or $G - P$ for 2-edge-connectivity, which can be done in $O(n + m)$ time. \square

In the rest of this section, we focus on MinRSs that do not contain the root of the DFS-tree. Before going into details, we show a basic property of degree-two segments not containing the root of the DFS-tree for the sake of simplifying discussions in the following subsections.

Lemma 8 *Let $G = (V, E)$ be a 2-edge-connected undirected graph with $|V| \geq 3$, T be a DFS-tree of G rooted at $r \in V$, and Let $P = v_1 \rightarrow v_2 \rightarrow \cdots \rightarrow v_k$ be a degree-two segment in G that does not contain r . Then, the following hold:*

- (i) *No internal vertex of T that is an endpoint of any back edge appears in P ; and*
- (ii) *The sequence v_1, v_2, \dots, v_k appears in this order or its reverse order on a root-to-leaf path in T .*
- (iii) *If P contains a leaf of T , then it is either v_1 or v_k , but not both.*

PROOF: (i) Since every internal vertex of T has the parent and at least one child, if an internal vertex of T is an endpoint of some back edge, then the degree in G is at least three. Thus, such a vertex cannot appear in P .

(ii) In the DFS traversal that constructs T , the vertices in P are visited one by one without visiting any other vertex in between. (iii) is immediate from (ii). \square

4.1 MinRSs Containing DFS-Tree Leaf

In this subsection, we consider MinRSs that consist of only leaves of a DFS-tree.

We first show a basic property of leaves in a DFS-tree of a 2-edge-connected undirected graph.

Lemma 9 *Let $G = (V, E)$ be a 2-edge-connected undirected graph with $|V| \geq 3$ and T be a DFS-tree of G rooted at $r \in V$. For any leaf $v \in V$ of T or any degree-two segment P containing a leaf of T , $G - v$ or $G - P$ is connected.*

PROOF: Since T is a spanning tree of G , every path in T also exists in G . For any leaf $v \in V$ of T or any degree-two segment P containing a leaf of T , $T - v$ or $T - P$ is connected. Thus, $G - v$ or $G - P$ is also connected. \square

Lemma 10 *Let $G = (V, E)$ be a 2-edge-connected undirected graph with $|V| \geq 3$ and T be a DFS-tree of G rooted at $r \in V$. Let $S \subsetneq V$ be a nonempty proper subset of V that is either a singleton consisting of a leaf of T or a degree-two segment containing a leaf of T ; let x denote the leaf of T in S and a denote the other endpoint of S . Note that $a = x$ if S is a singleton. Then, S is a MinRS of G if and only if, for any tree edge (u, v) with $v \notin S$, there exists a back edge outgoing from some vertex in $V \setminus S$ that covers (u, v) .*

PROOF: By Lemma 8, S contains exactly one leaf of T and S appears as a path from some vertex a to its descendant x in T . (If S is a singleton, then $a = x$.) By the definition of S , x is a leaf of T . Since G is 2-edge-connected, every tree edge is covered by at least one back edge. Thus, it suffices to consider only tree edges on the $y-\pi(a)$ path in T , where y is the most distant proper ancestor of x adjacent to x by a back edge.

(\Rightarrow) We show by contraposition. Suppose that there exists a tree edge (u, v) on the $y-\pi(a)$ path in T that is not covered by any back edge outgoing from a vertex other than those in S . Any vertex in $T_v - S$ cannot have a back edge to a proper ancestor of u in $G - S$, which means that uv is a bridge in $G - S$.

(\Leftarrow) By Lemma 6, it suffices to show that $G - S$ is 2-edge-connected. By Lemma 9, $G - S$ is connected. We show that there is no bridge in $G - S$. Every back edge $(x', y') \in E \setminus E(T)$ with $x', y' \notin S$ is not a bridge in $G - S$, since $x'y'$ and the $y'-x'$ path in T form a cycle in $G - S$. Next, we consider tree edges in $G - S$. For any tree edge not on the $y-\pi(a)$ -path in T , no covering back edge disappears by removing S from G , which means that such a tree edge is not a bridge in $G - S$. For any tree edge (u, v) on the $y-\pi(a)$ -path in T , by the assumption, there exists a back edge outgoing from a vertex in $T_v - S$ that covers (u, v) , which means that such a tree edge is not a bridge in $G - S$. Thus, there is no bridge in $G - S$, and hence, $G - S$ is 2-edge-connected. \square

Let $S \subsetneq V$ be a nonempty proper subset of V that is either a singleton consisting of a leaf of T or a degree-two segment containing a leaf of T ; let x denote the leaf of T . Since x is the only vertex in S that has back edges outgoing from it, then by Lemma 10, S is a MinRS of G if and only if, for any tree edge (u, v) with $v \notin S$, there exists a back edge outgoing from other vertex than x that covers (u, v) .

Theorem 1 *Given a 2-edge-connected undirected graph $G = (V, E)$ with $n = |V|$ and $m = |E|$, Algorithm 2 computes all MinRSs of G containing a leaf of a DFS-tree T in $O(n + m)$ time.*

PROOF: Note that we assume that a graph has no parallel edges throughout this paper. If $|V| < 3$, i.e., G consists of only one vertex, then G has no MinRS. Thus, we assume that $|V| \geq 3$. As the given graph is 2-edge-connected, each tree edge is covered by at least one back edge. Let $S \subsetneq V$ be a nonempty proper subset of V that is either a singleton consisting of a leaf of T or a degree-two segment containing a leaf of T ; let x denote the leaf of T in S . By the discussion before the theorem, S is a MinRS of G if and only if, for any tree edge (u, v) with $v \notin S$, there exists a back edge outgoing from other vertex than x that covers (u, v) ; which is equivalent to that for any tree edge (u, v) with $v \notin S$, $X_{uv} = \{x' \in V \mid \text{There is back edge } (x', y') \text{ covering } (u, v)\} \neq \{x\}$ holds. By Lemma 5, we can compute the aggregated identifiers $AggDesc_1$ and $AggDesc_2$ for all tree edges.

By Lemma 5, we can compute $AggDesc_1$ and $AggDesc_2$ for all tree edges in $O(n + m)$ time. For each tree edge (u, v) , we can compute the set X_{uv} from $AggDesc_1(uv)$ and $AggDesc_2(uv)$ in constant time. For each leaf l of T , we can check whether S is a MinRS

Algorithm 2 Computation of All MinRSs Containing a Leaf of a DFS-tree

Input: A 2-edge-connected undirected graph $G = (V, E)$ and its DFS-tree T rooted at $r \in V$

Output: All MinRSs of G containing a leaf of T

```

1: Compute  $AggDesc_1$  and  $AggDesc_2$  for all tree edges;
2: Initialise  $covering\_sets_l :=$  an array from leaves  $l$  of  $T$  to sets of tree edges;
3: for each tree edge  $(u, v)$  in  $E(T)$  do
4:   Compute the set  $X_{uv} := \{x' \in V \mid \text{There is back edge } (x', y') \text{ covering } (u, v)\}$  from
    $AggDesc_1(uv)$  and  $AggDesc_2(uv)$ ;
5:   Append  $(u, v)$  to  $covering\_sets_l$  if  $X_{uv}$  is a singleton  $\{l\}$  and  $l$  is a leaf of  $T$ 
6: end for;
7: Initialise  $\mathcal{Y} :=$  an empty set;
8: for each leaf  $l$  of  $T$  do
9:    $S := \begin{cases} \{l\} & \text{if } \deg_G(l) \geq 3, \\ \text{the vertex set of the degree-two segment containing } l & \text{otherwise;} \end{cases}$ 
10:  IS-MINRS := FALSE;
11:  for each tree edge  $(u, v)$  in  $covering\_sets_l$  do
12:    if  $u \notin S$  and  $v \notin S$  then
13:      IS-MINRS := TRUE                                 $\triangleright$  You can break the loop here
14:    end if
15:  end for;
16:   $\mathcal{Y} := \mathcal{Y} \cup \{S\}$  if IS-MINRS
17: end for;
18: output  $\mathcal{Y}$ 

```

of G in time proportional to the size of $covering_sets_l$. Since the total size of $covering_sets_l$ for all leaves l of T is at most $O(n)$, we can check all candidates S in $O(n)$ time. Thus, the total time complexity is $O(n + m)$. \square

4.2 Degree-Two Segment MinRSs but all Internal Vertices

In this section, we consider MinRSs that consist of only internal vertices of a DFS-tree and form a degree-two segment in G .

To simplify discussions, we introduce the *suppression* for degree-two segments. First, we show that the two neighbours of the endpoints of a degree-two segment not containing the root or any leaf of a DFS-tree are distinct.

Lemma 11 *Let $G = (V, E)$ be a 2-edge-connected undirected graph with $|V| \geq 3$, and P be a degree-two segment in G that does not contain the root or any leaf of a DFS-tree T of G . Then, $|N_G(V(P))| = 2$ holds.*

PROOF: Let $P = v_1 \rightarrow v_2 \rightarrow \dots \rightarrow v_k$, and let a, b denote the neighbours of v_1 and v_k not

on P if P is not a singleton; if P is a singleton, then let a and b denote the two neighbours of the only vertex in P . We show that $a \neq b$ holds. By Lemma 8(ii), P appears as the v_1-v_k path in T , and without loss of generality, we assume that v_1 is an ancestor of v_k in T . The DFS traversal visits in order a, v_1, v_2, \dots, v_k . If $a = b$, then $v_k b$ is a back edge, which means that b would be a leaf of T since v_k has degree 2 and b is its only neighbour other than v_{k-1} . This contradicts the assumption that P does not contain any leaf of T . \square

We fix a degree-two segment $P = v_1 \rightarrow v_2 \rightarrow \dots \rightarrow v_k$ in G , and let $\{a, b\} = N_G(V(P))$, where $a \neq b$ holds by Lemma 11. We define the *suppression* of P to be the graph G_P obtained from G by removing all vertices of P and adding a new edge $e_P = ab$, which means that the new edge e_P is not a self-loop. Note that G_P or the suppressed DFS-tree T_P may have parallel edges even if G has no parallel edges.

Lemma 12 *Let $G = (V, E)$ be a 2-edge-connected undirected graph with $|V| \geq 3$, T be a DFS-tree of G rooted at $r \in V$, and $P = v_1 \rightarrow v_2 \rightarrow \dots \rightarrow v_k$ be a degree-two segment in G that does not contain r or any leaf of T ; let a and b denote the neighbours of v_1 and v_k not on P . Then, T_P is a DFS-tree of G_P rooted at r , where T_P is the tree obtained from T by suppressing P . Moreover, e_P is a tree edge in T_P and $CovMult(e_P)$ in G_P equals any $CovMult(uv)$ in G for a tree edge (u, v) on the $a-b$ path in T .*

PROOF: Let $P = v_1 \rightarrow v_2 \rightarrow \dots \rightarrow v_k$, and let a, b denote the neighbours of v_1 and v_k not on P . By Lemmas 8(ii) and 11, P appears as the v_1-v_k path in T , and without loss of generality, we assume that v_1 is an ancestor of v_k in T . In the DFS traversal that constructs T , the vertices in order $a, v_1, v_2, \dots, v_k, b$ are visited one by one without visiting any other vertex in between. For DFS traversal on G_P , when we visit a , we can directly visit b via the new edge $e_P = ab$ without visiting any other vertex in between. Thus, T_P is a DFS-tree of G_P rooted at r .

By the construction of T_P , e_P is a tree edge in T_P . Next, we show that $CovMult(e_P)$ in G_P equals any $CovMult(uv)$ in G for a tree edge (u, v) on the $a-b$ path in T . No vertex in P is an endpoint of any back edge by Lemma 8(i). Thus, any back edge in G corresponds to a back edge in G_P and vice versa. Moreover, a back edge covers e_P in G_P if and only if it covers any tree edge (u, v) on the $a-b$ path in T in G . Thus, the cover multiplicities are equal. \square

Lemma 13 *Let $G = (V, E)$ be a 2-edge-connected undirected (multi)graph with $|V| \geq 3$, T be a DFS-tree of G rooted at $r \in V$, and $e = (u, v)$ be a tree edge in T . Then, e belongs to some 2-edge-cut if and only if $CovMult(e) = 1$ in G . Moreover, if e belongs to some 2-edge-cut, then there exists a unique tree edge $f \neq e$ such that $E(V(T_v)) = \{e, f\}$ holds.*

PROOF: Let $X := V(T_v)$. (\implies) Let $\{e, f\}$ be a 2-edge-cut containing e for some tree edge $f \neq e$. In $G - e$, X and $V \setminus X$ are connected separately. Since $G - \{e, f\}$ is disconnected,

the connected components of $G - \{e, f\}$ are exactly X and $V \setminus X$. Thus, f is the only back edge covering e in G , which means that $\text{CovMult}(e) = 1$.

(\Leftarrow) Suppose that $\text{CovMult}(e) = 1$. Let f be the unique back edge covering e in G . In $G - e$, X and $V \setminus X$ are connected separately. Since f is the only back edge covering e , $G - \{e, f\}$ is disconnected. Thus, $\{e, f\}$ is a 2-edge-cut containing e .

Moreover, if e belongs to some 2-edge-cut, then the above argument shows that there exists a unique tree edge $f \neq e$ such that $E_G(V(T_v)) = \{e, f\}$ holds. \square

Lemma 14 *Let $G = (V, E)$ be a 2-edge-connected undirected graph with $|V| \geq 3$, T be a DFS-tree of G rooted at $r \in V$, and P be a degree-two segment in G that does not contain r or any leaf of T . The following are equivalent:*

- (i) P is a MinRS of G ;
- (ii) $G_P - e_P$ is 2-edge-connected; and
- (iii) $\text{CovMult}(e_P) \geq 2$ in G_P .

PROOF: The equivalence between (i) and (ii) is immediate from the definition of MinRSs and the construction of G_P .

(ii) $\iff G_P - e_P$ has no bridge $\iff G_P$ has no 2-edge-cut containing $e_P \iff$ (iii), where the last equivalence follows by Lemma 13. \square

Theorem 2 *Given a 2-edge-connected undirected graph $G = (V, E)$ with $n = |V|$ and $m = |E|$, and its DFS-tree T rooted at $r \in V$, we can compute all MinRSs of G consisting of only internal vertices of T that form a degree-two segment in G in $O(n + m)$ time.*

PROOF: Let P be a degree-two segment in G that does not contain r or any leaf of T and v denote the vertex in P closest to r in T . By Lemmas 12 and 14, we can determine whether P is a MinRS of G by checking whether $\text{CovMult}(\pi(v)v) \geq 2$ in G_P . By Lemma 5, we can compute the cover multiplicities for all tree edges in $O(n + m)$ time. \square

4.3 Single Internal Vertex Degree At Least 3 MinRSs

Lemma 15 *Let $G = (V, E)$ be a 2-edge-connected undirected graph with $|V| \geq 3$ and $v \in V$. The graph $G - v$ has a bridge e if and only if there exists $X \subsetneq V \setminus \{v\}$ such that $E_G(X) = \{e\} \cup E_G(v, X)$.*

PROOF: (\Rightarrow) Let X be the vertex set of a connected component of $(G - v) - e$, where $E_{G-v}(X) = \{e\}$ holds. Since G is connected, all edges between X and $V \setminus X$ in G must be incident to v . Thus, $E_G(X) = \{e\} \cup E_G(v, X)$ holds.

(\Leftarrow) Suppose that there exists $X \subsetneq V \setminus \{v\}$ such that $E_G(X) = \{e\} \cup E_G(v, X)$. In $G - v$,

all edges between X and $V \setminus X$ are removed except for e . Thus, e is a bridge in $G - v$.

□

TODO

4.4 Reuse of DFS-tree and Covering Information

TODO

References

- [1] Taishu Ito, Yusuke Sano, Katsuhisa Yamanaka, and Takashi Hirayama. A polynomial delay algorithm for enumerating 2-edge-connected induced subgraphs. *IEICE Transactions on Information and Systems*, E105.D(3):466–473, 2022. doi: [10.1587/transinf.2021FCP0005](https://doi.org/10.1587/transinf.2021FCP0005).
- [2] Takumi Tada and Kazuya Haraguchi. A linear delay algorithm in SD set system and its application to subgraph enumeration. *Journal of Computer and System Sciences*, 152:103637, February 2025. doi: [10.1016/j.jcss.2025.103637](https://doi.org/10.1016/j.jcss.2025.103637).