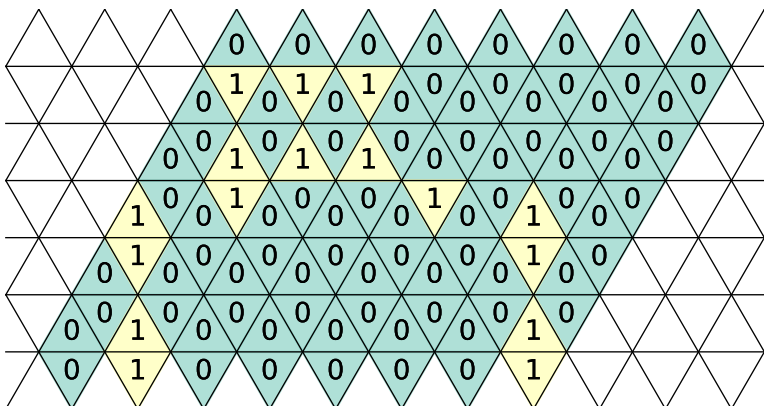
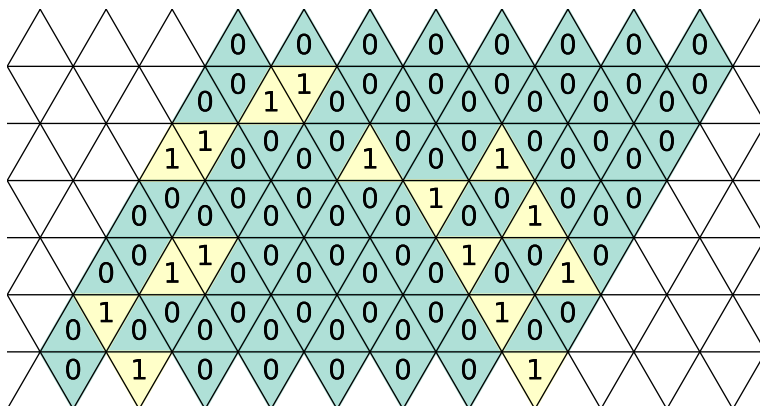


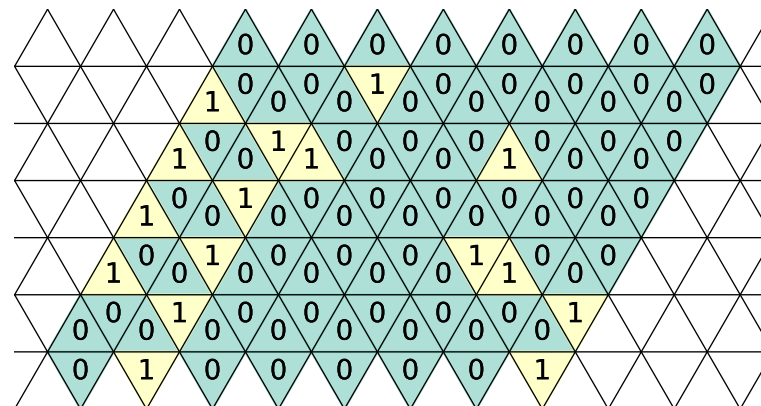
Channel: side 0



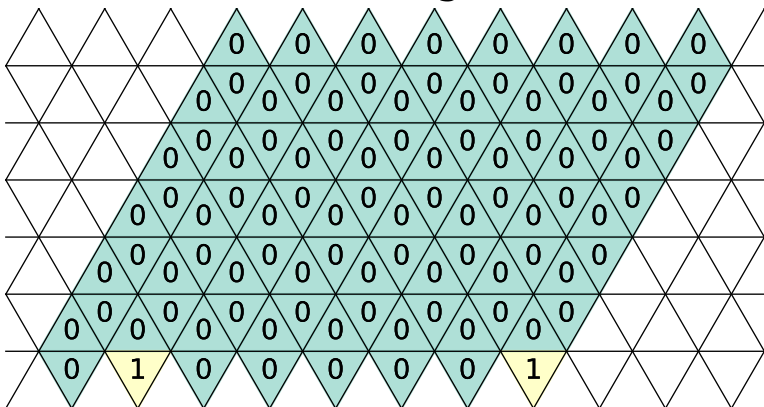
Channel: side 1



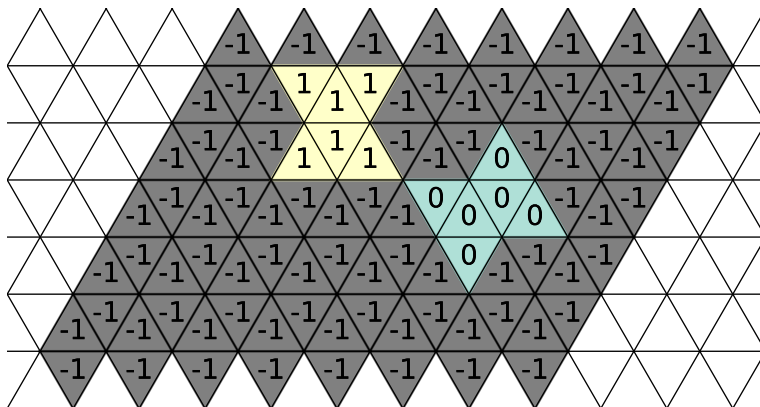
Channel: side 2



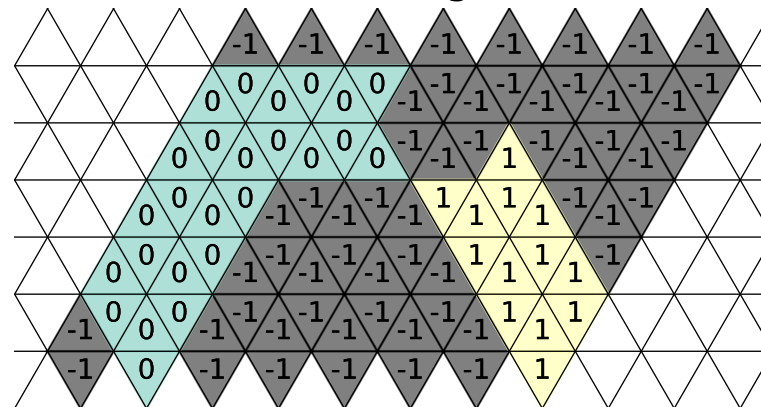
Channel: is ground



Channel: robot id



Channel: region id



Channel: is last

