

Predicting a vehicles velocity using dashcam footage and dense optical flow

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Abstract—In this report bla bla bla

Index Terms—deep learning, computer vision, velocity prediction, dense optical flow

I. INTRODUCTION

II. DATA COLLECTION, ANALYSIS AND PREPROCESSING

For our data set, we used the comma ai speedchallenge¹ data base. This data set provides two dashcam videos: a training video, (20400 frames, shoot at 20 frames per second) including ground truths and a testing video (10798 frames, shoot at 20 frames per second) without labels, which they use for applications to check how well a submitted model is able to generalize.

A. Data analysis

As we only have access to the labels of the test video frames, we decided to split the data by the 80/20 principle into training and testing subsets. Here we did not shuffle the data randomly, as we needed to always have two consecutive frames, to be able to calculate the optical flow and we wanted to test our model on unseen data, to measure how good our model is able to generalize.

To analyse the velocity distribution in the two subsets, we rounded down the given velocities and plotted the distribution in a histogram in figure REFERENCE MISSING.

Write down, what we expect from this distribution and mention how important brightness is (to possibly explain bad result).

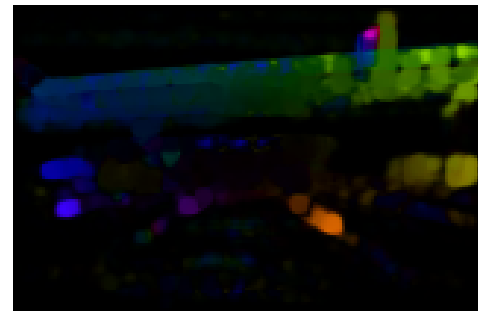
B. Preprocessing

Each of the provided frames has a size of (640, 480, 3) pixels. Due to computational limitations, we decided to cut off the last 60 pixels from the lower border, to remove a black frame inside the car, which did not have any effect on the optical flow. Furthermore, we cut the frame size in half and calculated the optical flow using the Farneback pyramid REFERENCE TO THE PAPER MISSING method with the



(a) Original frame

(b) Frame after down sampling



(c) Optical flow field, already down sampled

Fig. 1: Preprocessing of the video frames.

following parameters (WHY DID WE CHOOSE THEM LIKE THAT)

pyramid levels := 3

pyramid scaling := 0.5

window size := 6

pixel neighborhood size := 5

SD of the gaussian filter := 1.1

To decrease the training duration, we halved the size of the optical flow image again, resulting in a resolution of (160, 105, 3) pixels per frame. As we used a window size of 6, a comparison between the original optical flow and the down sampled one lead to the result, that we do not loose a lot information. The preprocessing pipeline is shown in figure REFERENCE MISSING. As we later on wanted to see if the model performs better using the dashcam frames as additional material, we did the same down sampling with the frames.

Explain, how we show the optical flow.

¹<https://github.com/commaai/speedchallenge>

III. METHOD SELECTION AND ARCHITECTURE

IV. RESULTS AND COMPARISON

V. FURTHER WORK

ACKNOWLEDGMENT

The preferred spelling of the word “acknowledgment” in America is without an “e” after the “g”. Avoid the stilted expression “one of us (R. B. G.) thanks ...”. Instead, try “R. B. G. thanks...”. Put sponsor acknowledgments in the unnumbered footnote on the first page.

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