

ViennaMesh

A Highly Flexible Meshing Framework

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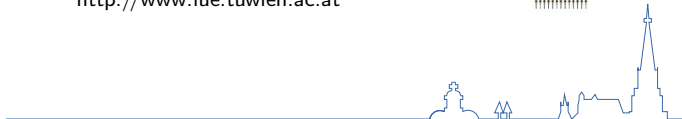
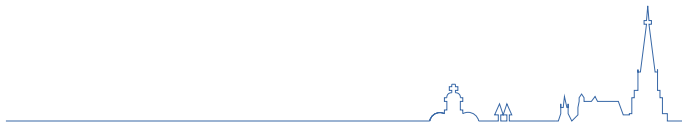


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What Is ViennaMesh?

Open source C++ meshing framework

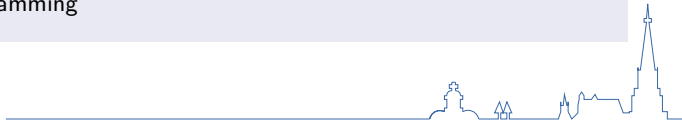
- LGPL

Based on a highly flexible data structure

- Focus on abstract topology and orthogonality

Abstract concepts enable uniform interfaces

- Generic programming



Problems Addressed by ViennaMesh

Simultaneous use of different meshing algorithms/libraries

- Challenging due to incompatible data structures and interfaces

Extensibility

- Most libraries are hard to extend

Reusability

- Code written against a library can hardly be reused with another library

Flexibility

- Data structure of libraries is often static and inflexible



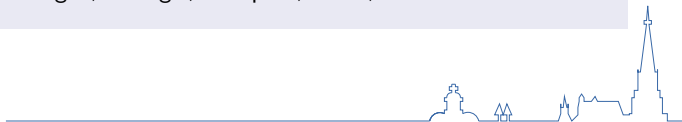
Framework Details

C++ library

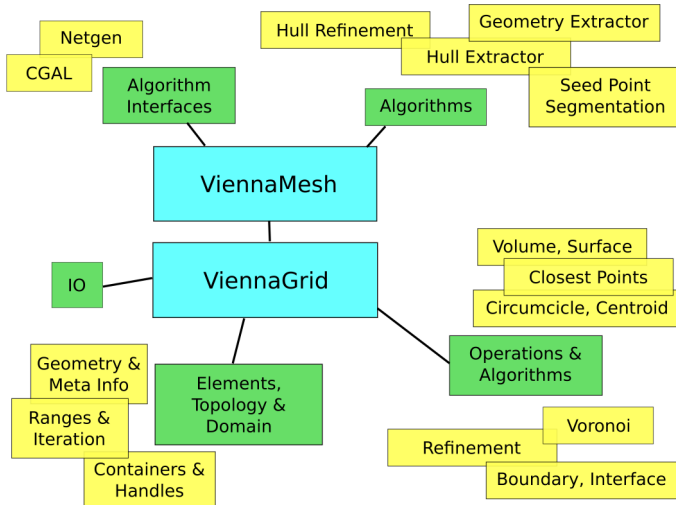
- Data structure and core functionality header-only
- C++11 support
- Cmake support

Interfaces to proven libraries

- Meshing: Netgen, CGAL, VERDICT
- Statistics: Boost.Accumulators
- More to come: Tetgen, Triangle, Mesquite, Metis, ...



Framework Overview



Framework Overview Explained

ViennaGrid

- Low level meshing data structure
- Central base of ViennaMesh
- Focus on topology, geometry as layer above topology

ViennaMesh Core

- Core Meshing functionality
- Abstract domain concept
- Abstract algorithm concept

ViennaMesh algorithms

- Interfaces to external libraries



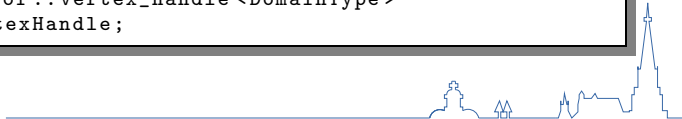
ViennaGrid - Types

Types are queried by result_of

- Similar to C++ result_of
- Tags represent element types

```
typedef result_of::element<DomainType, ElementTag>
    ::type ElementType;
typedef result_of::handle<DomainType, ElementTag>
    ::type ElementHandle;

typedef result_of::vertex<DomainType>
    ::type VertexType;
typedef result_of::vertex_handle<DomainType>
    ::type VertexHandle;
```



ViennaGrid - Elements

Elements represent topological entities

- Explicit storage of boundary elements
- Using handles to store boundary elements
- Co-Boundary and neighbour elements calculated when needed

Topological structures of arbitrary topological dimension

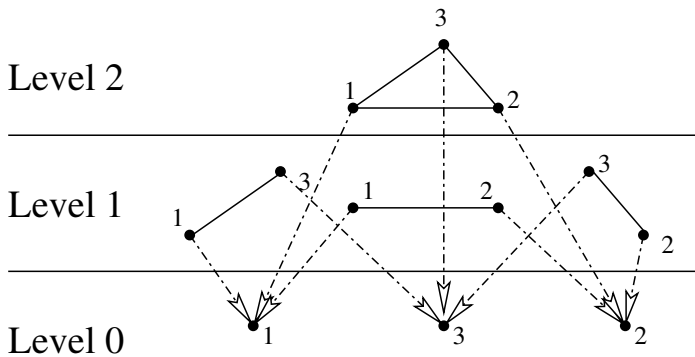
- Simplices
- Hypercubes

Dynamic types supported

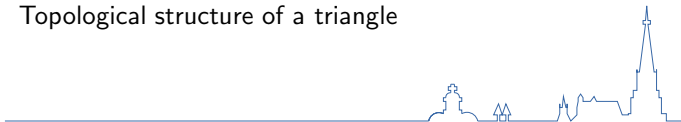
- Polygons and PLCs



ViennaGrid - Elements



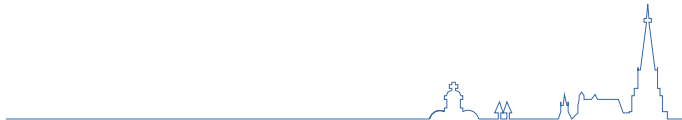
Topological structure of a triangle



ViennaGrid - Topology

Topological complex

- Set of elements
- Intersection of 2 elements \rightarrow empty or another element
- Same elements stored only once
- Non-conforming complexes supported (but with some restrictions)

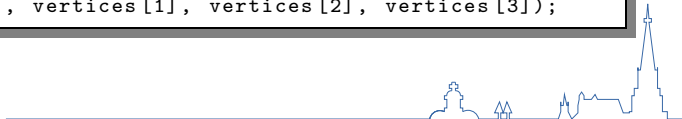


Example: Create Elements

```
typedef config::tetrahedral_3d_domain DomainType;  
  
DomainType domain;  
  
typedef result_of::element<DomainType, vertex_tag>  
    ::type VertexType;  
typedef result_of::element<DomainType, tetrahedron_tag>  
    ::type CellType;  
  
typedef result_of::handle<DomainType, vertex_tag>  
    ::type VertexHandle;  
typedef result_of::handle<DomainType, tetrahedron_tag>  
    ::type CellHandle;  
  
VertexHandle vertices[4];  
for (int i = 0; i < 4; ++i)  
    vertices[i]=create_element<VertexType>(domain);  
  
CellHandle cell=create_element<CellType>(domain, vertices);
```

Example: Create Elements

```
typedef config::tetrahedral_3d_domain DomainType;  
  
DomainType domain;  
  
typedef result_of::vertex_handle<DomainType>  
    ::type VertexHandle;  
typedef result_of::cell_handle<DomainType>  
    ::type CellHandle;  
  
VertexHandle vertices[4];  
for (int i = 0; i < 4; ++i)  
    vertices[i] = create_vertex(domain);  
  
CellHandle cell = create_tetrahedron(domain,  
    vertices[0], vertices[1], vertices[2], vertices[3]);
```



Meta Information

Default meta information: geometric point information

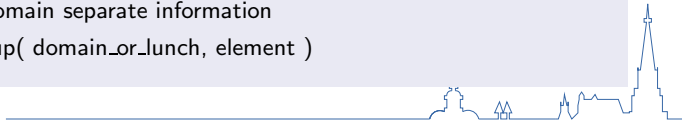
- Topology only stores vertices → Geometric information needed

Storage of Geometric information

- Within domain object
- Separate object

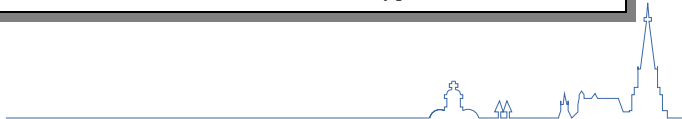
Same interface is used

- look_up for domain separate information
- Usage: look_up(domain_or_lunch, element)



Example: Meta Information

```
ElementType element;  
  
deque<double> scalar_values;  
map< result_of::id_type<ElementType>::type,  
    string > string_values;  
  
look_up(scalar_values, element) = 42.0;  
look_up(string_values, element) = "my_element";  
  
VertexType vertex;  
std::deque<PointType> geometric_container;  
  
point(domain, vertex) = PointType(0, 0, 1);  
point(geometric_container, vertex) = PointType(0, 1, 0);
```



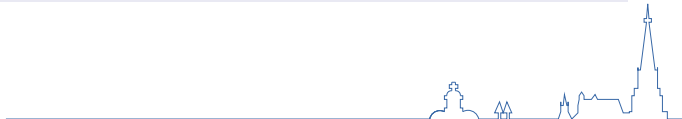
ViennaGrid - Domain, View

Domain object represents collection of elements

- Adds geometric information to topology
- Can be configured to work with any elements

View represents subsets of the domain

- Uses handle to store references
- Can be used to define segments



Example: Geometric Information

```
typedef config::tetrahedral_3d_domain DomainType;
typedef result_of::point_type<DomainType>::type PointType;

DomainType domain;

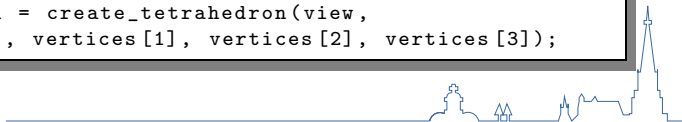
typedef result_of::vertex_handle<DomainType>
::type VertexHandle;
typedef result_of::cell_handle<DomainType>
::type CellHandle;

VertexHandle vertices[4];
for (int i = 0; i < 4; ++i)
{
    vertices[i] = create_vertex(domain);
    point( domain, vertices[i] ) = PointType(i, i*i, i*i*i);
}

CellHandle cell = create_tetrahedron(domain,
    vertices[0], vertices[1], vertices[2], vertices[3]);
```

Example: Create View

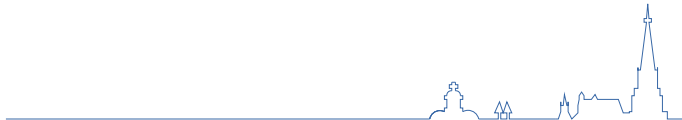
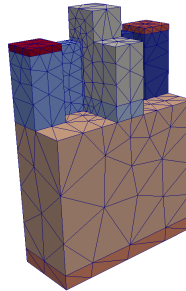
```
typedef config::tetrahedral_3d_domain DomainType;  
typedef config::tetrahedral_3d_view ViewType;  
  
DomainType domain;  
ViewType view = create_view( domain );  
  
typedef result_of::vertex_handle<DomainType>  
    ::type VertexHandle;  
typedef result_of::cell_handle<DomainType>  
    ::type CellHandle;  
  
VertexHandle vertices[4];  
for (int i = 0; i < 4; ++i)  
    vertices[i] = create_vertex(domain);  
  
CellHandle cell = create_tetrahedron(view,  
    vertices[0], vertices[1], vertices[2], vertices[3]);
```



ViennaMesh - Segment Support

Support for segments

- Subsets of the mesh
- Preserve interfaces through meshing process



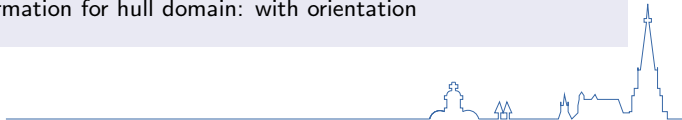
ViennaGrid - Segmentation

Segmentations with Views

- Using Views for segmentation
- One per segment
- Using seed points

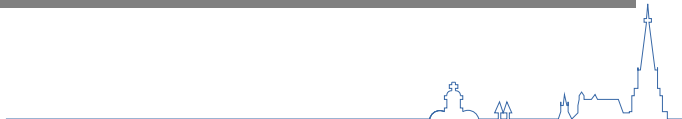
Segmentation object

- Stores segment information per element
- Trivial segment information: segment id
- Segment information for hull domain: with orientation



Example: Segmentation

```
typedef config::triangular_3d_domain DomainType;  
typedef config::triangular_3d_segmentation SegmentationType;  
  
DomainType domain;  
SegmentationType segmentation =  
    viennagrid::create_segmentation(domain);  
  
TriangleType triangle;  
  
segmentation.segment_info(triangle).  
    positive_orientation_segment_id = segment_id_0;  
segmentation.segment_info(triangle).  
    negative_orientation_segment_id = segment_id_1;
```



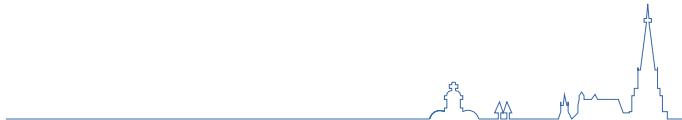
ViennaGrid - Containers, Handles and Ranges

Generic low level storage system

- Container and handle types are configurable
- Default container: `std::deque`
- Default handle: pointer to element

Range defines a set or subset of elements

- Needed for iteration



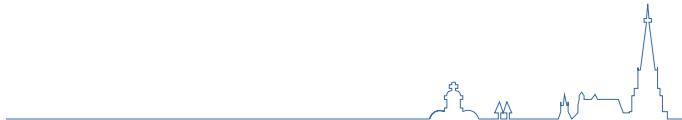
ViennaGrid - Iteration

Iteration is type-independent

- Easy access of associated elements
- Same source code for different types

Element Iteration

- Iterating over elements of a domain or view



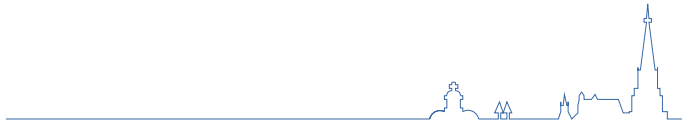
ViennaGrid - Iteration

Boundary Element Iteration

- Iterating over boundary elements of an element
- Same as element iteration

Co-Boundary Element Iteration

- Iterating over co-boundary elements of an element
- Scope domain or view is needed

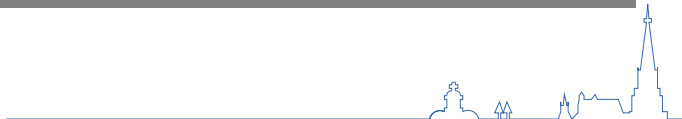


Example: Iteration Domain/View

```
DomainType domain;

typedef result_of::element_range<DomainType, vertex_tag>
    ::type VertexRangeType;
typedef result_of::iterator<VertexRangeType>
    ::type VertexRangeIterator;

VertexRangeType vertices = elements( domain );
for (VertexRangeIterator it = vertices.begin();
     it != vertices.end(); ++it)
{
    cout << point(domain, *it) << endl;
}
```

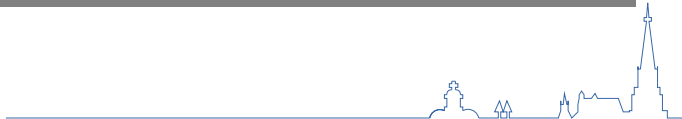


Example: Boundary Element Iteration

```
ElementType element;

typedef result_of::element_range<ElementType, vertex_tag>
    ::type VertexOnElementRangeType;
typedef result_of::iterator<VertexOnElementRangeType>
    ::type VertexOnElementRangeIterator;

VertexOnElementRangeType vertices = elements( element );
for (VertexOnElementRangeIterator it = vertices.begin();
     it != vertices.end(); ++it)
{
    cout << point(domain, *it) << endl;
}
```

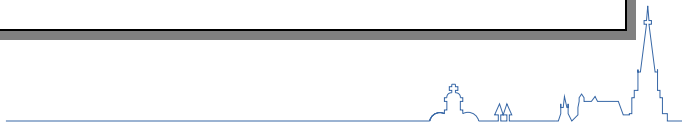


Example: Co-Boundary Element Iteration

```
DomainType domain;
VertexType vertex;

typedef result_of::coboundary_range<DomainType, triangle_tag>
    ::type TrianglesOfVertexRangeType;
typedef result_of::iterator<TrianglesOfVertexRangeType>
    ::type TrianglesOfVertexRangeIterator;

TrianglesOfVertexRangeType triangles =
    coboundary_elements( domain, vertex );
for (TrianglesOfVertexRangeIterator it = triangles.begin();
     it != triangles.end(); ++it)
{
    // do something with triangle *it
}
```



IO

Supported file reader

- VTK
- Netgen
- Tetgen poly (PLC)

Supported file writer

- VTK
- OpenDX

VTK reader and writer supports meta data

- support for vertices and cells



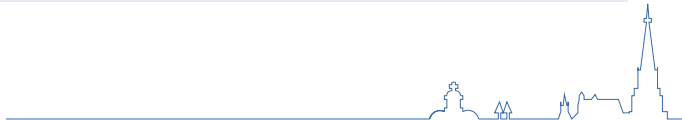
Overview ViennaGrid Operations and Algorithms

Element based operations and algorithms

- Use only local element information
- e.g. volume

Domain based algorithms

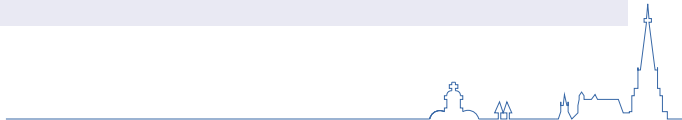
- Requires domain/view context
- e.g. refine



Element based operations and algorithms

More element operations and algorithms available

- Volume
- Surface
- Inner product
- Norm
- Cross product
- Centroid
- Circumcircle
- Closest points



Example: Volume data transfer

Transfer data from triangle to vertex

- value weighted with triangle volume

```
for (auto v : viennagrid::vertices( domain ) )
{
    numeric_type weighted_value = 0, total_volume = 0;

    for ( auto t : viennagrid::triangles( domain, v ) )
    {
        numeric_type current_volume = volume( domain, t );
        total_volume += current_volume;
        weighted_value += current_volume * value(t);
    }

    value(v) = weighted_value / total_volume;
}
```

Example: Volume data transfer

Type independent implementation

- to_tag and from_tag specify the types

```
for (auto v : viennagrid::elements<to_tag>( domain ) )
{
    numeric_type weighted_value = 0, total_volume = 0;

    for ( auto t : viennagrid::coboundary_elements<from_tag>(domain, v) )
    {
        numeric_type current_volume = volume( domain, t );
        total_volume += current_volume;
        weighted_value += current_volume * value(t);
    }

    value(v) = weighted_value / total_volume;
}
```


Domain based algorithms

Boundary

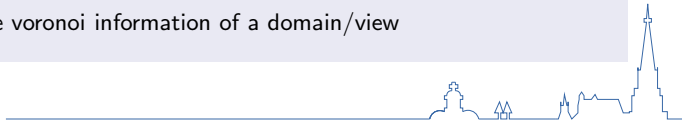
- Determines if the current element is a boundary element
- Requires domain/view context

Refine

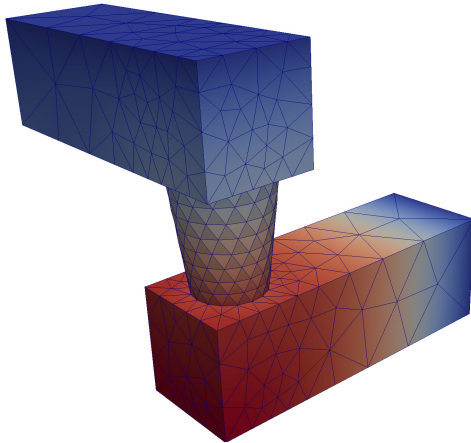
- Refines previously marked cells

Voronoi

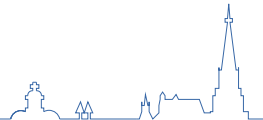
- Calculates the voronoi information of a domain/view



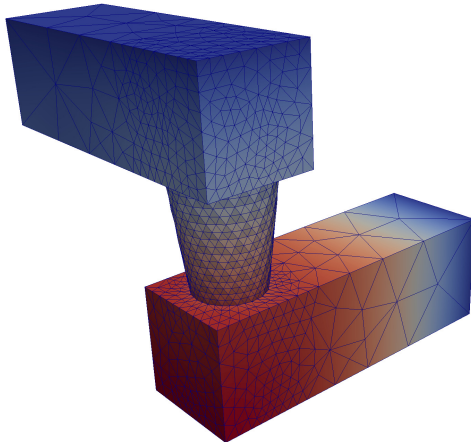
Example: Refinement



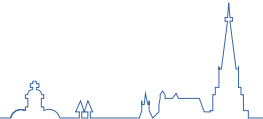
Before Refinement



Example: Refinement

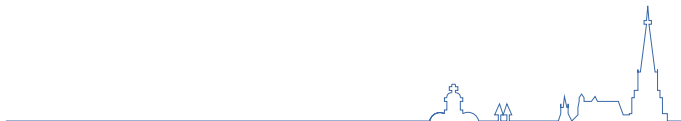


After Refinement



Example: Refinement

```
for (auto element : cells(domain) )  
{  
    if (to_refine(element))  
        tag_to_refine(element);  
}  
  
refine(domain, segments,  
        result_domain, result_segments,  
        local_refinement_tag() );
```

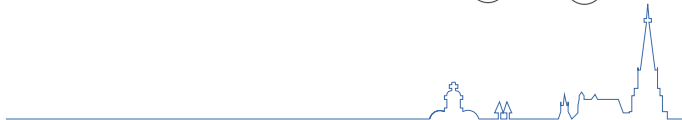
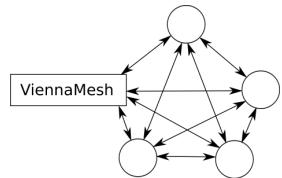


ViennaMesh Domain Concept

ViennaMesh aims to support external libraries

- Interfaces have to be provided

Each external library comes with its own data structure



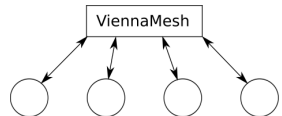
ViennaMesh Domain Concept

ViennaMesh aims to support external libraries

- Interfaces have to be provided

Each external library comes with its own data structure

- Conversions to and from ViennaGrid required
- Other conversions optional



ViennaMesh Algorithm Concept

ViennaMesh provides an uniform interface for complex algorithms

- Query algorithm information and settings object

Execution of algorithm is generic interface

- `viennamesh::run_algo<algorithm_tag>(source, destination, settings)`
- If required, source and destination is converted implicitly

Returns information of algorithm execution

- Execute time
- Success state
- Errors, warnings and informations



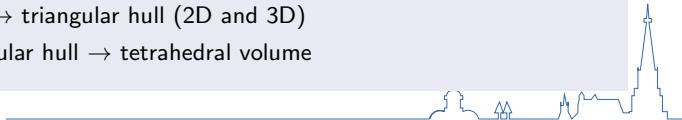
ViennaMesh Algorithms

Internal algorithms in ViennaMesh

- Extract Hull
- Extract PLC Geometry
- Seed point segment marking of hull meshes
- Multi-segment hull refinement
- Mesh doctor: 3D triangular hull

External algorithms with ViennaMesh interface

- Netgen: triangular hull → tetrahedral volume
- CGAL: PLC → triangular hull (2D and 3D)
- CGAL: triangular hull → tetrahedral volume

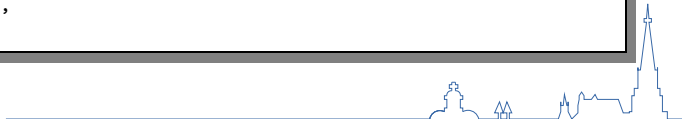


ViennaMesh Algorithms

External and internal algorithms share common interface

- data structure conversion if needed

```
InputDomainType  input_domain;  
OutputDomainType output_domain;  
viennamesh::result_of::settings<algorithm_tag>::type  
    settings;  
  
settings.cell_size = 1.0;  
  
viennamesh::run_algo< algorithm_tag >(  
    input_domain,  
    output_domain,  
    settings);
```

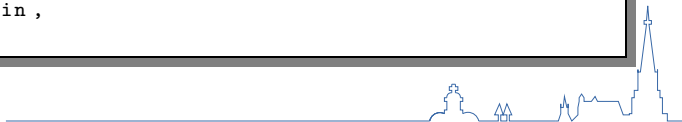


ViennaMesh Algorithms

External and internal algorithms share common interface

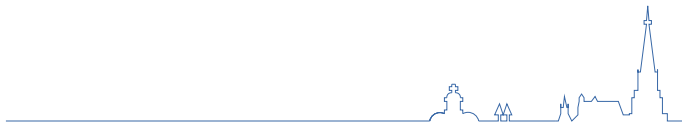
- Easy exchangeability of algorithms

```
InputDomainType  input_domain;  
OutputDomainType output_domain;  
viennamesh::result_of::settings< algorithm_tag >::type  
    settings;  
  
settings.cell_size = 1.0;  
  
viennamesh::run_algo< algorithm_tag >(  
    input_domain,  
    output_domain,  
    settings);
```



ViennaMesh Examples

Time for some detailed source code! :-)



Conclusion

Flexibility

- Abstract concepts → Write your code only once
- Common interface → Easily change meshing kernel
- High configurability → Use arbitrary topological structures
- High extensibility → Write your own meshing algorithm

Status

- Development release available at sourceforge
- <http://viennamesh.sourceforge.net>

