

1 General definitions

1.1 Basic

- Sample variance

$$S_X^2 = \frac{1}{n-1} \sum_{i=1}^n (X_i - \bar{X})^2 \quad (1.1)$$

- Sample correlation coefficient

$$r_{X,Y} = \frac{\sum_{i=1}^n (X_i - \bar{X})(Y_i - \bar{Y})}{(n-1)\sqrt{(S_X^2 S_Y^2)}} \quad (1.2)$$

- QQ-plot for cumulative distribution function F is the set of points $(q_F(\frac{i}{n+1}), x_{(i)})$, where $q_F(\cdot)$ is the quantile function for the distribution.
- Mean Squared Error (MSE)

$$\text{MSE}(\theta; T(X), g(\theta)) = \mathbb{E}_\theta (T(X) - g(\theta))^2 \quad (1.3)$$

- Bias-variance decomposition

$$\text{MSE}(\theta; T(X)) = \text{var}_\theta T + (\mathbb{E}_\theta T(X) - g(\theta))^2 \quad (1.4)$$

- Empirical distribution function

$$\hat{F}_n(x) = \sum_{i=1}^n \mathbb{I}(X_i \leq x) \quad (1.5)$$

1.2 k -th order statistic $X_{(k)}$

$X_{(k)}$ — k -th order statistic distribution for n i.i.d. variables from continuous distribution F .

$$f_{(k)}(x) = \frac{n!}{(k-1)!(n-k)!} F(x)^{k-1} (1-F(x))^{n-k} f(x) \quad (1.6)$$

$$F_{(k)}(x) = \sum_{j=k}^n \binom{n}{j} F(x)^j (1-F(x))^{n-j} \quad (1.7)$$

$$\mathbb{E}F(X_{(k)}) = \frac{k}{n+1} \quad (1.8)$$

1.3 Time Series

Time series below are assumed to be *weakly stationary* in the following sense:

- Stochastic time series $X_t(\omega)$ are called *weakly stationary*, if $\mathbb{E}X_t$ and $\mathbf{cov}(X_t, X_s)$ are independent of time shifts; in particular, its first and second moments exist.
- For a weakly stationary time series X_t , the following functions are defined:

– *Autocovariance function*:

$$\gamma(h) = \mathbf{cov}(X_{t+h}, X_t) \quad (1.9)$$

– *Autocorrelation function*

$$\rho(h) = \frac{\gamma(h)}{\gamma(0)} \quad (1.10)$$

– *Partial autocorrelation function* $\varphi(h)$ is defined as the coefficient of linear regression of X_{t+h} on X_t when controlled for constant and $X_{t+1}, \dots, X_{t+h-1}$ (see Proposition 3.19). In particular, $\varphi(0) = 1$ and $\varphi(1) = \rho(1)$

2 Important distributions

- Student's t -distribution t_ν , $\nu \in \mathbb{R}_{>0}$

– pdf

$$\frac{\Gamma(\frac{\nu+1}{2})}{\sqrt{\pi\nu} \Gamma(\frac{\nu}{2})} \left(1 + \frac{x^2}{\nu}\right)^{-\frac{\nu+1}{2}} \quad (2.1)$$

– cdf

$$\frac{1}{2} + x \Gamma\left(\frac{\nu+1}{2}\right) \frac{{}_2F_1\left(\frac{1}{2}, \frac{\nu+1}{2}; \frac{3}{2}, -\frac{x^2}{\nu}\right)}{\sqrt{\pi\nu} \Gamma(\frac{\nu}{2})} \quad (2.2)$$

– t -distribution with $n \in \mathbb{N}$ degrees of freedom arises from the ratio of independent $N(0, 1)$ - and χ_n^2 -distributions

- Poisson distribution $\text{Poisson}(\lambda)$, $\lambda > 0$
 - λ is the average number of events per interval
 - pdf

$$p_\lambda(k) = e^{-\lambda} \frac{\lambda^k}{k!} \quad (2.3)$$

- Geometric distribution $G(\theta)$, $0 \leq \theta \leq 1$
 - pdf

$$f_\theta(k) = (1 - \theta)^{1-k} \theta \quad (2.4)$$

- cdf

$$F_\theta(k) = 1 - (1 - \theta)^k \quad (2.5)$$

- Exponential distribution $F(x; \lambda)$

- pdf

$$f_\lambda(x) = \lambda e^{-\lambda x} \quad (2.6)$$

- cdf

$$F_\lambda(x) = 1 - e^{-\lambda x} \quad (2.7)$$

- $\mathbb{E}_\lambda X = 1/\lambda$

- Beta distribution $B(\alpha, \beta)$, $\alpha, \beta > 0$

- pdf

$$f_{\alpha, \beta}(x) = \frac{x^{\alpha-1}(1-x)^{\beta-1}}{B(\alpha, \beta)}, \quad B(\alpha, \beta) \equiv \frac{\Gamma(\alpha)\Gamma(\beta)}{\Gamma(\alpha + \beta)} \quad (2.8)$$

- Weibull distribution

- α and λ are the “shape” and “inverse scale” parameters.

- pdf

$$f_{\lambda, \alpha}(x) = \lambda^\alpha \alpha x^{\alpha-1} e^{-(\lambda x)^\alpha} \quad (2.9)$$

- cdf

$$F_{\lambda, \alpha}(x) = 1 - e^{-(\lambda x)^\alpha} \quad (2.10)$$

- Gamma distribution $\Gamma(\alpha, \lambda)$, $\alpha > 0, \lambda > 0$

– α and λ are known as “shape” and “inverse scale” parameters.

– pdf

$$f_{\alpha,\lambda}(x) = \frac{x^{\alpha-1} \lambda^\alpha e^{-\lambda x}}{\Gamma(\alpha)} \quad (2.11)$$

– cdf (where $\gamma(s, x) = \int_0^x t^{s-1} e^{-t} dt$ — is the “incomplete gamma function”)

$$F_{\alpha,\lambda}(x) = \frac{\gamma(\alpha, x\lambda)}{\Gamma(\alpha)} \quad (2.12)$$

Definition 2.1. A family of probability densities p_θ that depends on a parameter θ is called a k -dimensional exponential family if there exist functions $c(\theta)$, $h(x)$, $Q_j(\theta)$, and $V_j(x)$ such that

$$p_\theta(x) = c(\theta)h(x)e^{\sum_{j=1}^k Q_j(\theta)V_j(x)}$$

3 Fundamental results

Theorem 3.1. Let X_1, \dots, X_n be an i.i.d. random variables from the $N(\mu, \sigma^2)$ distribution, then

1. \bar{X} is $N(\mu, \sigma^2/n)$ distributed;
2. $(n-1)S_X^2/\sigma^2$ is χ_{n-1}^2 -distributed (see 1.1);
3. \bar{X} and S_X^2 are independent;
4. $\sqrt{n}(\bar{X} - \mu)/\sqrt{S_X^2}$ has the t_{n-1} -distribution.

Proof. $\|X\|^2 - n\bar{X}^2 = (n-1)S_X^2$

Definition 3.2. Let X be a random variable defined on probability space $(\Omega, \mathbb{P}_\theta)$, $\theta \in \Theta$. Suppose that the likelihood function $\theta \mapsto \ell_\theta \stackrel{\text{def}}{=} \log p_\theta$ is differentiable for all $x \in \Omega$. The gradient

$$\dot{\ell}_\theta(x) = \frac{\partial}{\partial \theta} \ell_\theta(x)$$

is called the *score function*. The *Fisher information* is defined as the matrix

$$i_\theta = \mathbb{V}_\theta \dot{\ell}_\theta(X)$$

3.1 Reminder on different convergence types

Definition 3.3. Let X_n be a sequence of random variables defined on the probability space $(\Omega, \mathcal{F}, \mathbb{P})$:

- X_n is said to converge to X *almost surely* if $\mathbb{P}(\lim_{n \rightarrow \infty} (X_n = X)) = 1$
- convergence in probability
- weak convergence
- L_p convergence

Theorem 3.4. *If a sequence of random variables converges almost surely then it converges in probability.*

Proposition 3.5. *Assume $\sum_{n \in \mathbb{Z}} \mathbb{E}|X_n| < \infty$, then $\sum_{n \in \mathbb{Z}} X_n$ is defined as an almost sure limit and:*

$$\mathbb{E} \sum_{n \in \mathbb{Z}} X_n = \sum_{n \in \mathbb{Z}} \mathbb{E} X_n$$

Proof. Established using Monotone and Dominated Convergence theorems applied to partial sums of random variables.

Proposition 3.6. *Let $(a_n)_{n \in \mathbb{Z}}$ be an element of $l^1(\mathbb{Z})$, and let $(Z_t)_{n \in \mathbb{Z}}$ be a sequence of random variables satisfying $\mathbb{E}|Z_t| < C_1 \forall t$ for some constant C_1 . Then the convolution*

$$X_t = \sum_{n \in \mathbb{Z}} a_n Z_{t-n}$$

is defined almost surely $\forall t \in \mathbb{Z}$.

Moreover, if there exists a constant such that $\mathbb{E}Z_t^2 < C_2 \forall t$, then X_t is also a limit in L^2 -norm and $\mathbb{E}X_t^2 \leq \|a_n\|_1^2 C_2$.

Theorem 3.7. *Let $(a_n)_{n \in \mathbb{Z}}$ be an element of $l^2(\mathbb{Z})$. Let $Z_t = \sum_{n \in \mathbb{Z}} b_n e_{t-n}$, where b_n is absolutely summable and e_t is a sequence of uncorrelated $(0, \sigma^2)$ random variables.*

Then there exists a sequence of random variables X_t , such that:

1.

$$\lim_{n \rightarrow \infty} \mathbb{E} \left\{ \left(X_t - \sum_{n \in \mathbb{Z}} b_n Z_{t-n} \right)^2 \right\} = 0,$$

2.

$$\lim_{n \rightarrow \infty} \mathbb{E} \left\{ \left(X_t - \sum_{n \in \mathbb{Z}} c_n e_{t-n} \right)^2 \right\} = 0, \quad c_n = \sum_{j \in \mathbb{Z}} a_j b_{n-j},$$

3.

$$\mathbb{E}(X_t X_{t+h}) = \sum_{j \in \mathbb{Z}} c_j c_{j+h} \sigma^2$$

Corollary 3.8. *All statements of Theorem 3.7 are true if $(a_n)_{n \in \mathbb{Z}}$ is absolutely summable, and $(b_n)_{n \in \mathbb{Z}}$ is square summable.*

3.2 Estimator convergence via information matrix

Theorem 3.9. *Suppose that Θ is compact and convex and that θ is identifiable, and let $\hat{\theta}_n$ be the maximum likelihood estimator based on a sample of size n from the distribution with (marginal) probability density p_θ . Suppose, furthermore, that the map $\vartheta \mapsto \log p_\vartheta(x)$ is continuously differentiable for all x , with derivative $\dot{\ell}_\vartheta(x)$, such that $\|\dot{\ell}_\vartheta(x)\| \leq L(x)$ for every $\vartheta \in \Theta$, where $L(x)$ is a function with $\mathbb{E}_\theta L^2(X) < \infty$. If θ is an interior point of Θ and the function $\theta \mapsto i_\theta$ is continuous and positive, then under θ , $\sqrt{n}(\hat{\theta}_n - \theta)$ converges in distribution to a normal distribution with expectation 0 and variance i_θ^{-1} . Therefore, under θ , as $n \rightarrow \infty$, we have*

$$\sqrt{n}(\hat{\theta}_n - \theta) \rightarrow N(0, i_\theta^{-1})$$

Theorem 3.10. (Cramer-Rao) *Suppose $\theta \mapsto p_\theta(x)$ is differentiable for every x . Then under certain regularity conditions any unbiased estimator T for $g(\theta)$ satisfies:*

$$\mathbb{V}_\theta(T) \geq g'(\theta) I_\theta^{-1} g'(\theta)^T,$$

where I_θ denotes the full information matrix.

3.3 Sufficient Statistics and UMVU estimators

Definition 3.11. For a statistical model $(\Omega, \mathbb{P}_\theta)$, $\theta \in \Theta$, a statistic $V(x)$ is called *sufficient* (for r.v. X) if conditional distribution $f(x|V = v)$ is independent of V .

Theorem 3.12. *A statistic $V(x)$ is sufficient if there exist functions $h(x)$ and $g(v, \theta)$ such that*

$$p_\theta(x) = h(x)g(V(x), \theta)$$

Theorem 3.13. (Rao-Blackwell) *Let $V = V(X)$ be a sufficient statistic, and let $T = T(X)$ be an arbitrary real-valued estimator for $g(\theta)$. Then there exists an estimator $T^* = T^*(V)$ for $g(\theta)$ that depends only on V , such that $\mathbb{E}_\theta T^* = \mathbb{E}_\theta T$ and $\mathbb{V}_\theta T^* \leq \mathbb{V}_\theta T$ for all θ . In particular, we have $MSE(\theta; T^*) \leq MSE(\theta; T)$. This inequality is strict unless $\mathbb{P}_\theta(T^* = T) = 1$.*

Definition 3.14. For a statistical model $(\Omega, \mathbb{P}_\theta)$, $\theta \in \Theta$, a statistic $V(x)$ is called complete if $\mathbb{E}_\theta(f(V)) = 0$, $\forall \theta \in \Theta$ implies $f(V) = 0$ a.s.

Theorem 3.15. *Let $V(x)$ be sufficient and complete, and $T(V)$ be an unbiased estimator for $g(\theta)$. Then $T(V)$ is UMVU estimator (i.e. has smallest variance among all unbiased estimators $\forall \theta \in \Theta$).*

Theorem 3.16. *Suppose that for a k -dimensional exponential family (2.1) the set below contains an interior point:*

$$(Q_1(\theta), \dots, Q_k(\theta)), \theta \in \Theta$$

Then the random vector $(V_1(x), \dots, V_n(x))$ is sufficient and complete.

3.4 Time Series

Proposition 3.17. *Given the difference equation of order n :*

$$y_t + a_1 y_{t-1} + a_2 y_{t-2} + \dots + a_n y_{t-n} = r_t, \quad t = n, n+1, \dots \quad (3.1)$$

The solution $(y_n)_{n=0}^\infty$ can be expressed in the form:

$$y_t = \sum_{i=0}^t w_i r_{t-i}, \quad t = 0, 1, \dots$$

with $w_i \equiv 0$ for $i < 0$, and satisfying the homogeneous difference equation of (y_t) :

$$\sum_{i=0}^n a_i w_{t-i} = 0, \quad i = 1, 2, \dots \quad (3.2)$$

Proof. Using recursive formula (3.1) for y_t , any element of the sequence can be written in the form:

$$y_t = \sum_{i=0}^t w_i^{(t)} r_{t-i}$$

for some $w_i^{(t)}$ with $t \in \mathbb{Z}_{\geq 0}$, $0 \leq i \leq t$. Using inductive argument, we show that

1. $w_i^{(t)} \equiv w_i$ for some constant depending on i only
2. The sequence w_i satisfies equation (3.2)

Indeed, from the equation 3.1 it is immediate to see that $w_0 = 1$ and $w_1 = -a_1$. Assuming that the pair of statements above is shown for $s < t$, write:

$$y_t = r_t - \sum_{k=0}^n a_k^{(t)} y_{t-k} = r_t - \sum_{k=1}^t a_k \sum_{j=0}^{t-k} w_j r_{t-k-j} \quad (3.3)$$

By definition, we set w_t to be the coefficient of r_0 , that is, $w_t = -\sum_{i=1}^n a_i w_{t-i}$. Moreover, by rearranging terms in 3.3, we get:

$$y_t = - \sum_{j=0}^t r_j \sum_{k=1}^{t-j} a_k w_{t-j-k},$$

it follows that the coefficient $w_{t-j}^{(t)}$ of r_j , $j = 1, \dots, t$, is equal to w_{t-j} by induction assumption and it concludes the proof.

Theorem 3.18. *The real valued function $\rho(h)$ is the correlation function of a real valued stationary time series $X_t(\omega)$ with index set $t \in \mathbb{Z}$ if and only if it is representable in the form*

$$\rho(h) = \int_{-\pi}^{\pi} e^{ihx} dG(x),$$

where $G(x)$ is a symmetric distribution function.

Proposition 3.19. *Let X_t be weakly stationary time series:*

1. *The partial autocorrelation coefficient $\varphi(h)$ equals θ_{hh} in the linear regression:*

$$X_{t+h} = \theta_{0h} + \theta_{1h} X_{t+h-1} + \dots + \theta_{hh} X_t + a_{ht}$$

2. Let $\rho_{t+h,t,(t+1,\dots,t+h-1)}$ denote the partial correlation of X_{t+h} and X_t when controlled for $X_{t+1}, \dots, X_{t+h-1}$. The squared norm of the residual term in the regression above equals:

$$\mathbb{E}(a_{ht}^2) = \gamma(0) \prod_{i=1}^h (1 - \rho_{t+h,t+i-1,(t+i,\dots,t+h-1)}^2)$$

Proof. These statements follow from basic Euclidian geometry. Denote by P the projection onto the subspace spanned by $X_{t+i}, \dots, X_{t+h-1}$. Now consider sequentially orthogonal decompositions $X_{t+h} = P(X_{t+h}) + (1-P)(X_{t+h})$ and look at the component of the second summand along $(1-P)(X_{t+i})$.

4 Estimators

4.1 Maximum of n uniformly distributed statistics

Set up: X_1, X_2, \dots, X_n i.i.d. drawn from $U[0, \theta]$, where θ is the parameter of interest.

- $\hat{\theta} = 2\bar{X}_n$
 - method of moments estimator
 - *unbiased*
 - $\text{MSE}(\theta, \hat{\theta}) = \frac{\theta^2}{3n}$, see (1.6)
- $X_{(n)}$ — n -th order statistic, i.e. maximum.
 - $\mathbb{E}_\theta X_{(n)} = \frac{n}{n+1}\theta$, see (1.6)
 - $\text{MSE}(\theta, X_{(n)}) = \frac{2\theta^2}{(n+2)(n+1)}$
- $\frac{n+2}{n+1}X_{(n)}$
 - best estimator of the form $cX_{(n)}$
 - $\text{MSE}(\theta, \frac{n+2}{n+1}X_{(n)}) = \frac{\theta^2}{(n+1)^2}$

4.2 Univariate normal distribution

- $(\hat{\mu}, \hat{\sigma}^2) = \left(\bar{X}_n, \frac{1}{n} \sum_{i=1}^n (X_i - \bar{X}_n)^2 \right) = \left(\bar{X}_n, \frac{n-1}{n} S_X^2 \right)$
 - maximum likelihood estimator
 - method of moments estimator
 - $\hat{\mu}$ is *unbiased*
 - $\mathbb{E}_{(\mu, \sigma^2)} \hat{\sigma}^2 = \frac{n-1}{n} \sigma^2$

4.3 Empirical distribution function

Let X_1, \dots, X_n be an i.i.d. sample drawn from the distribution F .

- The empirical distribution function (ecdf) $\hat{F}(x) = \sum_{i=1}^n \mathbb{I}(X_i \leq x)$ (see 1.1)
 - *unbiased*
 - $\text{cov}_F(\hat{F}(u), \hat{F}(v)) = n^{-1}(F(\min(u, v)) - F(u)F(v))$ – positively correlated

4.4 Linear Regression

Theorem 4.1. (Ordinary Least Squares)

(i) In one-factor setting, maximum likelihood estimators for slope, intercept and variance are given by (see (1.1, 1.2)):

$$\hat{\beta} = \frac{S_{Y^T X, Y}}{S_X}, \quad \hat{\alpha} = \bar{Y} - \hat{\beta} \bar{X}, \quad \hat{\sigma}^2 = \frac{1}{n} \sum_{i=1}^n (Y_i - \hat{\beta} X_i - \hat{\alpha})^2$$

(ii) If the design matrix X in a multiple linear regression has full rank, then the maximum likelihood estimators are given by:

$$\hat{\beta} = (X^T X)^{-1} (X^T Y), \quad \hat{\sigma}^2 = \frac{\|Y - X\hat{\beta}\|^2}{n}$$

Theorem 4.2. (Weighted Least Squares/Heteroscedacity)

(i) Assume that error terms ε_i have variance as $\sigma_i^2 \equiv z_i \sigma^2$ for known constants z_i . Let $w_i \stackrel{\text{def}}{=} (z_i \sigma^2)^{-1}$, then maximum likelihood estimators for slope, intercept and variance are given by (see (1.1, 1.2)):

$$\begin{aligned}\tilde{\beta} &= \frac{\sum w_i(x - \tilde{x})(y - \tilde{y})}{\sum w_i(x - \tilde{x})^2} = \frac{\sum w_i \sum w_i x_i y_i - \sum w_i x_i \sum w_i y_i}{\sum w_i \sum w_i x_i^2 - (\sum w_i x_i)^2} \\ \tilde{\alpha} &= \tilde{y} - \tilde{\beta} \tilde{x} \\ \hat{\sigma}^2 &= n^{-1} \sum \frac{1}{z_i} (y_i - \tilde{\beta} x_i - \tilde{\alpha})^2\end{aligned}$$

(ii) For the multi-factor model, maximum likelihood estimators can be written in the form:

$$\tilde{\beta} = (X^T W X)^{-1} (X^T W Y)$$

Theorem 4.3. Let $V \stackrel{\text{def}}{=} \text{span}(X)$, and $V_0 \subset V$. Denote the projection onto V by P_V .

1. The likelihood ratio statistic for $H_0 : X\beta_0 \in V_0$ equals

$$2 \log \lambda_n(X, Y) = n \log \frac{\|(E - P_{V_0})Y\|^2}{\|(E - P_V)Y\|^2},$$

2. Under the null hypothesis, the following quantity has $F_{n-p, p-p_0}$ distribution:

$$\frac{\|(P_V - P_{V_0})Y\|^2 / (p - p_0)}{\|(E - P_V)Y\|^2 / (n - p)}$$

5 Statistical tests

5.1 t -tests

5.1.1 One-sample t -test

Let X_1, X_2, \dots, X_n be an i.i.d. sample from the $N(\mu, \sigma^2)$ -distribution with μ and σ^2 unknown. Given $\mu_0 \in \mathbb{R}$ we test:

$$H_0 : \mu \leq \mu_0 \text{ against } H_1 : \mu > \mu_0 \quad (5.1)$$

Test statistic:

$$T = \sqrt{n} \frac{\bar{X}_n - \mu_0}{S_X} \quad (5.2)$$

By Theorem 3.1, under $\mu = \mu_0$ the statistic has Student's t_{n-1} distribution, consequently we can use.

$$\sup_{\mu \leq \mu_0} \mathbb{P}(T \geq t_{n-1, 1-\alpha}) \leq \alpha \quad (5.3)$$

5.1.2 t-Test for paired observations

Let $(X_1, Y_1), (X_2, Y_2), \dots, (X_n, Y_n)$ be the i.i.d. sample of paired observations. We assume that $Z_i \stackrel{\text{def}}{=} X_i - Y_i$ is $N(\Delta, \sigma^2)$ is normally distributed, and the ordinary One-sample t -test can be used to test the null hypotheses $H_0 : \Delta \geq 0$. Note that if X_i and Y_i are strongly correlated then variance of Z_i decreases and this improves the power of the t -test.

5.1.3 Two-sample t -test

Let X_1, X_2, \dots, X_n and Y_1, Y_2, \dots, Y_m be two mutually independent i.i.d samples from $N(\mu, \sigma^2)$ and $N(\nu, \sigma^2)$. The test checks

$$H_0 : \mu - \nu \leq 0 \text{ against } H_1 : \mu - \nu > 0 \quad (5.4)$$

Test statistic:

$$T = \frac{\bar{X} - \bar{Y}}{S_{X,Y} \sqrt{\frac{1}{n} + \frac{1}{m}}} \quad (5.5)$$

$$S_{X,Y}^2 = \frac{1}{m+n-2} \left(\sum_{i=1}^n (X_i - \bar{X}_n)^2 + \sum_{j=1}^m (Y_j - \bar{Y}_m)^2 \right) \quad (5.6)$$

Theorem 3.1 implies that $S_{X,Y}^2$ follows $\sigma^2 \cdot \chi_{m+n-2}^2$ distribution.

5.2 Kolmogorov-Smirnov test

Given an i.i.d. sample X_1, \dots, X_n from some unknown distribution F , we want to test:

$$H_0 : F = F_0 \text{ against } H_1 : F \neq F_0 \quad (5.7)$$

The test statistic is given by

$$T = \sup_{x \in \mathbb{R}} |\hat{F}_n(x) - F(x)|, \quad (5.8)$$

where $\hat{F}_n(x)$ stands for the empirical distribution function (see 1.1). The distribution of T is the same for every continuous cdf F_0 . The following limit establishes the test:

$$\lim_{n \rightarrow \infty} \mathbb{P}_{F_0} \left(T > \frac{z}{n} \right) = 2 \sum_{j=1}^{\infty} (-1)^{j+1} e^{-j^2 z^2} \quad (5.9)$$