Snapdesk

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Namespace Index

1.1 Namespace List

Here is a list of all namespaces with brief descriptions:

mpiler
tabase
coder
ecutable_tree
communicator

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Hierarchical Index

2.1 Class Hierarchy

This inheritance list is sorted roughly, but not completely, alphabetically:

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Class Index

3.1 Class List

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decoder::Body	
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This Function concatenates its arguments and	52
Nede that has a static value	54
Node that has a static value	ے ن

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File Index

4.1 File List

Here is a list of all files with brief descriptions:

includes/const.hpp
Contains all constant that are used in snapdesk
includes/compiler/compiler.hpp
includes/compiler/function_node.hpp
includes/compiler/node.hpp
This file contains base class of a executable tree
includes/database/core.hpp
Contains core classes to manipulate the database
includes/decoder/big_number.hpp
includes/decoder/frame.hpp
The file contains all basic frame class
includes/decoder/ie.hpp
Classes that permit to represent the IE of a frame's body
includes/decoder/management_body.hpp
includes/os_communicator/os_communicator.hpp
includes/os_communicator/os_communicator.hpp The os_communicator component handle all interaction between snapdesk and the current os 75
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Namespace Documentation

5.1 compiler Namespace Reference

Classes

· class Compiler

Tranform the source code into a executable tree.

5.2 database Namespace Reference

Classes

• class Csv

This class represent and operates a csv file.

class Database

This class provide a simple API to manipulate storage files.

Functions

• std::string hash (std::string str)

5.2.1 Function Documentation

5.2.1.1 hash()

5.3 decoder Namespace Reference

Classes

· class Beacon body

Is the body of a beacon frame.

· class Big_number

This class represent and manipulate indifined sized numbers using bytes.

· class Body

This class set the base of all frame's body possible.

class Frame

The class that represent the whole frame.

· class le_node

An element of a linked list of IEs.

5.4 executable tree Namespace Reference

Classes

· class Cut bit

This Function cut the bits of the first arg from the second arg of the size of the third arg.

class Cut_byte

This Function cut the bytes of the first arg fril the secong arg of the size of the third arg.

· class Function

Node that execute a function (that must be implemented as a child of Function class)

class Getter

Node that get dynamic information in the frame.

· class Node

Represents a node of the executable tree.

class Root

The node that represent the root of the executable tree, it does not do anything but have one child.

· class Sha256

This Function concatenates its arguments and.

class Value

Node that has a static value.

5.5 os_communicator Namespace Reference

Classes

class Communicator

The Communicator is the main class of the os_communicator component.

Class Documentation

6.1 decoder::Beacon_body Class Reference

Is the body of a beacon frame.

```
#include <management_body.hpp>
```

Inheritance diagram for decoder::Beacon_body:

Collaboration diagram for decoder::Beacon_body:

Public Member Functions

- Beacon_body (uint8_t *raw_body_buffer, size_t raw_buffer_size)
 - Construct a new Beacon_body object.
- ∼Beacon_body ()

Destroy the Beacon_body object.

• void print () const override

Print the content of the beacon body.

• Big_number get_value (string field) const override

Get the value of a specific field.

Additional Inherited Members

6.1.1 Detailed Description

Is the body of a beacon frame.

6.1.2 Constructor & Destructor Documentation

6.1.2.1 Beacon_body()

Construct a new Beacon_body object.

Parameters

raw_body_buffer	a buffer containing the exact beacon body
raw_buffer_size	the size of the buffer

6.1.2.2 \sim Beacon_body()

```
Beacon_body::\simBeacon_body ( )
```

Destroy the Beacon_body object.

6.1.3 Member Function Documentation

6.1.3.1 get_value()

Get the value of a specific field.

Parameters

field	the name of the field, or the element id corresponding to an IE
-------	-----------------------------------------------------------------

Returns

Big_number the value, or null if this do not exist

Implements decoder::Body.

6.1.3.2 print()

```
void Beacon_body::print ( ) const [override], [virtual]
```

Print the content of the beacon body.

Implements decoder::Body.

The documentation for this class was generated from the following files:

- includes/decoder/management_body.hpp
- src/decoder/management_body.cpp

6.2 decoder::Big_number Class Reference

This class represent and manipulate indifined sized numbers using bytes.

```
#include <big_number.hpp>
```

Public Member Functions

· bool is null () const

Look if the number is null or not.

void throw_if_null () const

Throw an error if the number is null.

• std::string hex_string () const

transform the number into a string containing the hex of it

• std::string char_string () const

transform the number into a string containing the char of it

• size_t to_size_t () const

Transform the number into a size_t number (only if the number can be contained in a size_t)

void cut_byte (size_t from, size_t size)

Cut the number to obtain only the given interval (unit byte)

void cut_bit (size_t from, size_t size)

Cut the number to obtain only the given interval (unit bit)

Big_number copy () const

Clone the Big_number object.

• Big_number & operator= (const Big_number _number)

Copy the value of a Big_number object into another.

Static Public Member Functions

• static Big number null ()

Create a instance of Big_number containing the null value.

- static Big_number from_buffer (const uint8_t *buffer, const size_t buffer_size, const size_t number_size)
 - Create a instance of Big_number containing the number from the given buffer.
- static Big_number from_buffer_inv (const uint8_t *buffer, const size_t buffer_size, const size_t number_size)

 Exactly the same as from buffer() but with inverted bytes.
- static Big_number from_hex_string (const std::string string)

Create a instance of Big_number containing the number from a given string.

6.2.1 Detailed Description

This class represent and manipulate indifined sized numbers using bytes.

6.2.2 Member Function Documentation

6.2.2.1 char_string()

```
std::string Big_number::char_string ( ) const
```

transform the number into a string containing the char of it

Returns

std::string the string containing the chars

6.2.2.2 copy()

```
Big_number Big_number::copy ( ) const
```

Clone the Big_number object.

Returns

Big_number the clone of the object

6.2.2.3 cut_bit()

Cut the number to obtain only the given interval (unit bit)

Parameters

from	the first bit of the new numbe	
size	the size of the new number	

6.2.2.4 cut_byte()

Cut the number to obtain only the given interval (unit byte)

Parameters

from	the first byte of the new numbe	
size	the size of the new number	

6.2.2.5 from_buffer()

Create a instance of Big_number containing the number from the given buffer.

Parameters

buffer	the buffer containing the number, starting at the first number byte	
buffer_size	the size of the buffer	
number_size	the size of the number inside the buffer	

Returns

Big_number the new instance with the value of the number in it

6.2.2.6 from_buffer_inv()

Exactly the same as from_buffer() but with inverted bytes.

Parameters

buffer	the buffer containing the number, starting at the first number byte	
buffer_size	the size of the buffer	
number_size	the size of the number inside the buffer	

Returns

Big_number the new instance containing the value of the buffer

6.2.2.7 from_hex_string()

Create a instance of Big_number containing the number from a given string.

Parameters

```
string the string containing the bytes in hex form
```

Returns

Big_number the new instance containing the value of the number

6.2.2.8 hex_string()

```
std::string Big_number::hex_string ( ) const
```

transform the number into a string containing the hex of it

Returns

std::string the string containing the hexs

6.2.2.9 is_null()

```
bool Big_number::is_null ( ) const
```

Look if the number is null or not.

Returns

true if the number is null false if the number is not null

6.2.2.10 null()

```
Big_number Big_number::null ( ) [static]
```

Create a instance of Big_number containing the null value.

Returns

Big_number the new instance

6.2.2.11 operator=()

Copy the value of a Big_number object into another.

Parameters

number	the Big_number object from where the value will be copied

Returns

Big_number& the Big_number where the value has been copied

6.2.2.12 throw_if_null()

```
void Big_number::throw_if_null ( ) const
```

Throw an error if the number is null.

6.2.2.13 to_size_t()

```
size_t Big_number::to_size_t ( ) const
```

Transform the number into a size_t number (only if the number can be contained in a size_t)

Returns

size_t the number corresponding to the Big_number

The documentation for this class was generated from the following files:

- includes/decoder/big_number.hpp
- src/decoder/big_number.cpp

6.3 decoder::Body Class Reference

This class set the base of all frame's body possible.

```
#include <frame.hpp>
```

Inheritance diagram for decoder::Body:

Public Member Functions

- Body (uint8_t *raw_body_buffer, size_t raw_buffer_size)
 - Construct a new Body object.
- virtual void print () const =0

Print the content of the body.

virtual Big_number get_value (string field) const =0

Get the value corresponding to the field.

Static Public Member Functions

• static Body * get_body (uint8_t *raw_body_buffer, size_t raw_buffer_size, size_t type, size_t sub_type)

Give the Body objects corresponding to the type and subtype.

Protected Member Functions

virtual void decode ()=0
 decode the body and fill the fields

Protected Attributes

```
    uint8_t * _raw_body_buffer
        The buffer that exactly contains the body.

    size_t _raw_buffer_size
        The size of the buffer.
```

6.3.1 Detailed Description

This class set the base of all frame's body possible.

6.3.2 Constructor & Destructor Documentation

6.3.2.1 Body()

Construct a new Body object.

Parameters

raw_body_buffer	a buffer containing the exact body
raw_buffer_size	the size of the buffer

6.3.3 Member Function Documentation

6.3.3.1 decode()

```
virtual void decoder::Body::decode ( ) [protected], [pure virtual]
```

decode the body and fill the fields

6.3.3.2 get_body()

Give the Body objects corresponding to the type and subtype.

Parameters

raw_body_buffer	a buffer containing the exact body
raw_buffer_size	the size of the buffer
type	the type of the frame (management, control, or data)
sub_type	the subtype of the frame

Returns

Body* the new body corresponding to args

6.3.3.3 get_value()

Get the value corresponding to the field.

Parameters

f	field	the name of the field or the element id corresponding to the value
---	-------	--------------------------------------------------------------------

Returns

Big_number the value or null if not found

Implemented in decoder::Beacon_body.

6.3.3.4 print()

```
virtual void decoder::Body::print ( ) const [pure virtual]
```

Print the content of the body.

Implemented in decoder::Beacon_body.

6.3.4 Member Data Documentation

6.3.4.1 _raw_body_buffer

```
uint8_t* decoder::Body::_raw_body_buffer [protected]
```

The buffer that exactly contains the body.

6.3.4.2 _raw_buffer_size

```
size_t decoder::Body::_raw_buffer_size [protected]
```

The size of the buffer.

The documentation for this class was generated from the following files:

- includes/decoder/frame.hpp
- src/decoder/frame.cpp

6.4 os communicator::Communicator Class Reference

The Communicator is the main class of the os_communicator component.

```
#include <os_communicator.hpp>
```

Public Member Functions

• Communicator (string file_name)

Construct a new Communicator object.

• bool exist ()

Say if the given file exist.

size_t in_buffer (uint8_t *buffer, const size_t buffer_size)

Copy the content of the file into the given buffer.

• string get_line (size_t line_number) const

Get the line number line_number from the file.

void add_line (string line)

Add a line at the end of the file.

• void replace_line (size_t line_number, string new_line)

Replace the line line_number with the line new_line.

• void new_file ()

Create an empty file.

Static Public Member Functions

• static string get_current_date ()

Get the current date.

• static void notify (string message)

Notify the user with a message.

• static void sleep (size_t seconds)

Pause the process for an amount of time.

• static void create_folder (string folder_name)

Create a folder.

• static size_t get_file_type (string name)

Get the type of a file (file, folder, nothing)

6.4.1 Detailed Description

The Communicator is the main class of the os communicator component.

6.4.2 Constructor & Destructor Documentation

6.4.2.1 Communicator()

Construct a new Communicator object.

Parameters

file_name The name of the file to interact with

6.4.3 Member Function Documentation

6.4.3.1 add_line()

Add a line at the end of the file.

Parameters

line the line to add to the end of the file

6.4.3.2 create_folder()

Create a folder.

Parameters

```
folder_name the name of the folder
```

6.4.3.3 exist()

```
bool os_communicator::Communicator::exist ( )
```

Say if the given file exist.

Returns

true if the file exist

false if the file does not exist

6.4.3.4 get_current_date()

```
string os_communicator::Communicator::get_current_date ( ) [static]
```

Get the current date.

Returns

string the current date

6.4.3.5 get_file_type()

Get the type of a file (file, folder, nothing)

Parameters

of the file

Returns

size_t the type of the file

6.4.3.6 get_line()

Get the line number line_number from the file.

Parameters

e_ <i>number</i> the	number of the line from file to get
----------------------	-------------------------------------

Returns

string the line

6.4.3.7 in_buffer()

Copy the content of the file into the given buffer.

Parameters

buffer	the buffer where the data will be copied
buffer_size	the size of the buffer

Returns

size_t the number of byte read

6.4.3.8 new_file()

```
void os_communicator::Communicator::new_file ( )
```

Create an empty file.

6.4.3.9 notify()

Notify the user with a message.

Parameters

message	the message that will be displayed
message	the message that will be displayed

6.4.3.10 replace_line()

Replace the line line_number with the line new_line.

Parameters

line_number	the number of the file to replace
new_line	the line that will replace the old one

6.4.3.11 sleep()

Pause the process for an amount of time.

Parameters

seconds	the number of seconds to pause the process

The documentation for this class was generated from the following files:

- includes/os_communicator/os_communicator.hpp
- src/os_communicator/os_communicator.cpp

6.5 compiler::Compiler Class Reference

Tranform the source code into a executable tree.

```
#include <compiler.hpp>
```

Public Member Functions

Compiler (const os_communicator::Communicator *communicator)

Construct a new Compiler object.

executable_tree::Node * get_executable_tree () const

Compile the source code to get the executable tree.

6.5.1 Detailed Description

Tranform the source code into a executable tree.

6.5.2 Constructor & Destructor Documentation

6.5.2.1 Compiler()

Construct a new Compiler object.

Parameters

6.5.3 Member Function Documentation

6.5.3.1 get_executable_tree()

```
executable_tree::Node * Compiler::get_executable_tree ( ) const
```

Compile the source code to get the executable tree.

Returns

executable_tree::Node* the executable tree corresponding to the source code

The documentation for this class was generated from the following files:

- includes/compiler/compiler.hpp
- src/compiler/compiler.cpp

6.6 database::Csv Class Reference

This class represent and operates a csv file.

```
#include <core.hpp>
```

Public Member Functions

• Csv (std::string file name)

Construct a new Csv object on a file that does exist.

• ∼Csv ()

Destroy the Csv object.

void push_row (std::vector< std::string > values)

Create a new entry in the file.

void replace_row (size_t row_number, std::vector< std::string > values)

Replace a row by another.

• std::string get_cell (size_t row_number, size_t column_number)

Get the value of a cell.

• size_t get_row_number (std::string key_value)

Get the row number of a given key value.

• size_t get_column_number (std::string column_name)

Get the column number from its name.

std::vector< std::string > get_all_keys ()

Get all key values of a file.

• std::vector< std::string > get_all_keys_with_value (size_t column_number, std::string value)

Get all key values that has a value on a given column.

Static Public Member Functions

static Csv * create (std::string file_name, std::vector< std::string > column_names, size_t key_column_

 number)

Construct a new Csv object on a file that does not exist.

6.6.1 Detailed Description

This class represent and operates a csv file.

6.6.2 Constructor & Destructor Documentation

6.6.2.1 Csv()

Construct a new Csv object on a file that does exist.

Parameters

e_name the name of the storage file (without exte	ns)
---------------------------------------------------	-----

6.6.2.2 ∼Csv()

```
database::Csv::~Csv ( )
```

Destroy the Csv object.

6.6.3 Member Function Documentation

6.6.3.1 create()

Construct a new Csv object on a file that does not exist.

Parameters

file_name	the filename of the new storage file (without extentions)
column_names	the names of the columns
key_column_number	the column number of the key

Returns

Csv* the new Csv instance of the new storage file

6.6.3.2 get_all_keys()

```
std::vector< std::string > database::Csv::get_all_keys ( )
```

Get all key values of a file.

Returns

std::vector<std::string> a vector containing all the key values

6.6.3.3 get_all_keys_with_value()

Get all key values that has a value on a given column.

Parameters

column_number	the number of the column to look for matches
value	the value to compare

Returns

std::vector<std::string> a vector containing all the key values

6.6.3.4 get_cell()

Get the value of a cell.

Parameters

row_number	the row number of the cell
column_number	the column number of the cell

Returns

std::string the value of the cell

6.6.3.5 get_column_number()

Get the column number from its name.

Parameters

column	name	the name of the column

Returns

size_t the column number, or -1 if not found

6.6.3.6 get_row_number()

Get the row number of a given key value.

Parameters

the value to match with the key	key_value
---------------------------------	-----------

Returns

size_t the row number of the given key value, or -1 if not found

6.6.3.7 push_row()

```
void database::Csv::push_row (  std::vector < std::string \, > \, values \, \, ) \\
```

Create a new entry in the file.

Parameters

6.6.3.8 replace_row()

Replace a row by another.

Parameters

row_number	the number of the row to replace
values	the vector of values that will replace

The documentation for this class was generated from the following files:

- includes/database/core.hpp
- src/database/csv.cpp

6.7 executable_tree::Cut_bit Class Reference

This Function cut the bits of the first arg from the second arg of the size of the third arg.

```
#include <function_node.hpp>
```

Inheritance diagram for executable_tree::Cut_bit:

Collaboration diagram for executable tree::Cut bit:

Public Member Functions

- std::string to_string (size_t depth) const override get the string representing the node
- std::string get_value (const decoder::Frame *target_frame) const override

 Get the value of the node.

Additional Inherited Members

6.7.1 Detailed Description

This Function cut the bits of the first arg from the second arg of the size of the third arg.

6.7.2 Member Function Documentation

6.7.2.1 get_value()

Get the value of the node.

Parameters

target_frame that is analysed by the executable tree

Returns

std::string the value returned by the node

Reimplemented from executable_tree::Node.

6.7.2.2 to_string()

get the string representing the node

Parameters

```
depth the depth of the node in the executable tree
```

Returns

std::string the string representing the node

Reimplemented from executable_tree::Node.

The documentation for this class was generated from the following files:

- includes/compiler/function_node.hpp
- src/compiler/function_node.cpp

6.8 executable_tree::Cut_byte Class Reference

This Function cut the bytes of the first arg fril the secong arg of the size of the third arg.

```
#include <function_node.hpp>
```

Inheritance diagram for executable_tree::Cut_byte:

Collaboration diagram for executable_tree::Cut_byte:

Public Member Functions

- std::string to_string (size_t depth) const override get the string representing the node
- std::string get_value (const decoder::Frame *target_frame) const override Get the value of the node.

Additional Inherited Members

6.8.1 Detailed Description

This Function cut the bytes of the first arg fril the secong arg of the size of the third arg.

6.8.2 Member Function Documentation

6.8.2.1 get_value()

Get the value of the node.

Parameters

target_frame that is analysed by the executable tree

Returns

std::string the value returned by the node

Reimplemented from executable_tree::Node.

6.8.2.2 to_string()

get the string representing the node

Parameters

depth the depth of the node in the executable tree

Returns

std::string the string representing the node

Reimplemented from executable_tree::Node.

The documentation for this class was generated from the following files:

- includes/compiler/function_node.hpp
- src/compiler/function_node.cpp

6.9 database::Database Class Reference

This class provide a simple API to manipulate storage files.

```
#include <core.hpp>
```

Public Member Functions

Database (std::string ssid, std::string code_file_name)

Construct a new Database object.

∼Database ()

Destroy the Database object.

• std::string get_cell (std::string key_value, std::string column_name)

Get a cell given the value of its key and its column number.

std::vector< std::string > get_key_of_entries (std::string column_name, std::string cell_value)

Get all keys values corresponding to a given cell value.

void add_entry (std::vector< std::string > values)

Add an entry to the storage file.

• void replace_entry (std::string key_value, std::vector< std::string > values)

Replace an entry by another.

6.9.1 Detailed Description

This class provide a simple API to manipulate storage files.

6.9.2 Constructor & Destructor Documentation

6.9.2.1 Database()

Construct a new Database object.

Parameters

ssid	The SSID of the analysed frames
code_file_name	The file name of the used code

6.9.2.2 ~ Database()

```
database::Database::~Database ( )
```

Destroy the **Database** object.

6.9.3 Member Function Documentation

6.9.3.1 add_entry()

Add an entry to the storage file.

Parameters

6.9.3.2 get_cell()

Get a cell given the value of its key and its column number.

Parameters

key_value	the value of the key
column_name	the column name of the cell

Returns

std::string the value of the cell

6.9.3.3 get_key_of_entries()

Get all keys values corresponding to a given cell value.

Parameters

column_name	the name of the column to compare
cell_value	the value to compare

Returns

std::vector<std::string> the vector of key values

6.9.3.4 replace_entry()

```
void database::Database::replace_entry ( std::string \ key\_value, \\ std::vector < std::string > values )
```

Replace an entry by another.

Parameters

key_value	the key value of the entry to replace
values	the vector of new values to replace the ols entry with

The documentation for this class was generated from the following files:

- includes/database/core.hpp
- src/database/database.cpp

6.10 decoder::Frame Class Reference

The class that represent the whole frame.

```
#include <frame.hpp>
```

Collaboration diagram for decoder::Frame:

Public Member Functions

Frame (os_communicator::Communicator *_communicator)

Construct a new Frame object.

• ∼Frame ()

Destroy the Frame object.

• bool get_is_decoded () const

Get the value of is_decoded.

void update_raw_data ()

Get a new frame from the character device and put it in raw_frame_buffer.

void print_raw_data ()

Print the raw_frame_buffer as hex bytes.

· virtual void decode ()

Decode the raw_frame_buffer to fill the different fields.

• virtual void print () const

Print the content of the decoded frame.

• Big_number get_value (string field) const

Get the value corresponding to the field.

Protected Attributes

• uint8_t * raw_frame_buffer

the buffer containing the frame that is not decoded

• size_t raw_buffer_size

the size of the buffer

• size_t raw_frame_size

the size of the frame in the buffer

· bool is decoded

true if the buffer is decoded, false if not

• bool has_raw_data

true if raw_frame_buffer is filled

- Big_number frame_control = Big_number::null()
- Big_number duration = Big_number::null()
- Big number destination address = Big number::null()
- Big_number source_address = Big_number::null()
- Big_number bssid = Big_number::null()
- Big_number sequence_control = Big_number::null()
- Big_number frame_check_sum = Big_number::null()
- Body * body = nullptr

the body of the frame

6.10.1 Detailed Description

The class that represent the whole frame.

6.10.2 Constructor & Destructor Documentation

6.10.2.1 Frame()

Construct a new Frame object.

Parameters

_communicator Communicator on the character device	,
------------------------------------------------------	---

6.10.2.2 ∼Frame()

```
Frame::\simFrame ( )
```

Destroy the Frame object.

6.10.3 Member Function Documentation

6.10.3.1 decode()

```
void Frame::decode ( ) [virtual]
```

Decode the raw_frame_buffer to fill the different fields.

6.10.3.2 get_is_decoded()

```
bool Frame::get_is_decoded ( ) const
```

Get the value of is_decoded.

Returns

```
true if is_decoded is true false if is_decoded is false
```

6.10.3.3 get_value()

Get the value corresponding to the field.

Parameters

field the name of the field that we want to get

Returns

Big_number the field value, or null if not found

6.10.3.4 print()

```
void Frame::print ( ) const [virtual]
```

Print the content of the decoded frame.

6.10.3.5 print_raw_data()

```
void Frame::print_raw_data ( )
```

Print the raw_frame_buffer as hex bytes.

6.10.3.6 update_raw_data()

```
void Frame::update_raw_data ( )
```

Get a new frame from the character device and put it in raw_frame_buffer.

6.10.4 Member Data Documentation

6.10.4.1 body

```
Body* decoder::Frame::body = nullptr [protected]
```

the body of the frame

6.10.4.2 bssid

```
Big_number decoder::Frame::bssid = Big_number::null() [protected]
```

6.10.4.3 destination_address

```
Big_number decoder::Frame::destination_address = Big_number::null() [protected]
```

6.10.4.4 duration

```
Big_number decoder::Frame::duration = Big_number::null() [protected]
```

6.10.4.5 frame_check_sum

```
Big_number decoder::Frame::frame_check_sum = Big_number::null() [protected]
```

6.10.4.6 frame_control

```
Big_number decoder::Frame::frame_control = Big_number::null() [protected]
```

6.10.4.7 has_raw_data

```
bool decoder::Frame::has_raw_data [protected]
```

true if raw_frame_buffer is filled

6.10.4.8 is_decoded

```
bool decoder::Frame::is_decoded [protected]
```

true if the buffer is decoded, false if not

6.10.4.9 raw_buffer_size

```
size_t decoder::Frame::raw_buffer_size [protected]
```

the size of the buffer

6.10.4.10 raw_frame_buffer

```
uint8_t* decoder::Frame::raw_frame_buffer [protected]
```

the buffer containing the frame that is not decoded

6.10.4.11 raw_frame_size

```
size_t decoder::Frame::raw_frame_size [protected]
```

the size of the frame in the buffer

6.10.4.12 sequence_control

```
Big_number decoder::Frame::sequence_control = Big_number::null() [protected]
```

6.10.4.13 source_address

```
Big_number decoder::Frame::source_address = Big_number::null() [protected]
```

The documentation for this class was generated from the following files:

- includes/decoder/frame.hpp
- src/decoder/frame.cpp

6.11 executable_tree::Function Class Reference

Node that execute a function (that must be implemented as a child of Function class)

```
#include <node.hpp>
```

Inheritance diagram for executable_tree::Function:

Collaboration diagram for executable_tree::Function:

Public Member Functions

• ∼Function ()

Destroy the Function object.

• void add_node (Node *arg) override

Add a child node to the current node.

• std::string to_string (size_t depth) const override

get the string representing the node

Protected Attributes

std::vector< Node * > args

The vector of arguments of the function.

6.11.1 Detailed Description

Node that execute a function (that must be implemented as a child of Function class)

6.11.2 Constructor & Destructor Documentation

6.11.2.1 ∼Function()

```
executable_tree::Function::~Function ( ) [inline]
```

Destroy the Function object.

6.11.3 Member Function Documentation

6.11.3.1 add_node()

Add a child node to the current node.

Parameters

```
arg The node to add
```

Reimplemented from executable_tree::Node.

6.11.3.2 to_string()

get the string representing the node

Parameters

depth the depth of the node in the executable tree

Returns

std::string the string representing the node

Reimplemented from executable_tree::Node.

6.11.4 Member Data Documentation

6.11.4.1 args

```
std::vector<Node*> executable_tree::Function::args [protected]
```

The vector of arguments of the function.

The documentation for this class was generated from the following files:

- includes/compiler/node.hpp
- src/compiler/node.cpp

6.12 executable tree::Getter Class Reference

Node that get dynamic information in the frame.

```
#include <node.hpp>
```

Inheritance diagram for executable tree::Getter:

Collaboration diagram for executable_tree::Getter:

Public Member Functions

• Getter (const std::string field_name)

Construct a new Getter object.

• std::string get_value (const decoder::Frame *target_frame) const override

Get the value of the node.

• void add_node (Node *arg) override

Add a child node to the current node.

• std::string to_string (size_t depth) const override

get the string representing the node

6.12.1 Detailed Description

Node that get dynamic information in the frame.

6.12.2 Constructor & Destructor Documentation

6.12.2.1 Getter()

Construct a new Getter object.

Parameters

field_name the name of the field where to get information

6.12.3 Member Function Documentation

6.12.3.1 add_node()

Add a child node to the current node.

Parameters

arg The node to add

Reimplemented from executable_tree::Node.

6.12.3.2 get_value()

Get the value of the node.

Parameters

target_frame that is analysed by the executable tree

Returns

std::string the value returned by the node

Reimplemented from executable_tree::Node.

6.12.3.3 to_string()

get the string representing the node

Parameters

depth	the depth of the node in the executable tree
-------	----------------------------------------------

Returns

std::string the string representing the node

Reimplemented from executable_tree::Node.

The documentation for this class was generated from the following files:

- includes/compiler/node.hpp
- src/compiler/node.cpp

6.13 decoder::le_node Class Reference

An element of a linked list of IEs.

```
#include <ie.hpp>
```

Public Member Functions

```
• le_node (uint8_t element_id, Big_number value)
```

Construct a new le_node object.

• \sim le_node ()

Destroy the le_node object.

void add (le_node *new_element)

Add a node to the linked list.

• Big_number get_value (std::string field) const

Get the value of corresponding to a field.

• void print ()

Print the IE.

6.13.1 Detailed Description

An element of a linked list of IEs.

6.13.2 Constructor & Destructor Documentation

6.13.2.1 le_node()

Construct a new le_node object.

Parameters

element <i>⊷</i> _id	the element id of the new IE
value	the value of the new IE

6.13.2.2 ~le_node()

```
{\tt Ie\_node::}{\sim} {\tt Ie\_node \ (\ )}
```

Destroy the le_node object.

6.13.3 Member Function Documentation

6.13.3.1 add()

Add a node to the linked list.

Parameters

```
new_element | the new node to add
```

6.13.3.2 get_value()

Get the value of corresponding to a field.

Parameters

field	the name of the field or its element id
-------	-----------------------------------------

Returns

Big_number the value that correcpond to the field or null if none

6.13.3.3 print()

```
void Ie_node::print ( )
```

Print the IE.

The documentation for this class was generated from the following files:

- includes/decoder/ie.hpp
- src/decoder/ie.cpp

6.14 executable_tree::Node Class Reference

Represents a node of the executable tree.

```
#include <node.hpp>
```

Inheritance diagram for executable_tree::Node:

Public Member Functions

- virtual std::string get_value (const decoder::Frame *target_frame) const
 Get the value of the node.
- virtual void add_node (Node *arg)

Add a child node to the current node.

 virtual std::string to_string (size_t depth) const get the string representing the node

6.14.1 Detailed Description

Represents a node of the executable tree.

6.14.2 Member Function Documentation

6.14.2.1 add_node()

Add a child node to the current node.

Parameters

```
arg The node to add
```

 $Reimplemented \ in \ executable_tree:: Function, \ executable_tree:: Value, \ and \ executable_tree:: Getter.$

6.14.2.2 get_value()

Get the value of the node.

Parameters

target_frame	the frame that is analysed by the executable tree
--------------	---------------------------------------------------

Returns

std::string the value returned by the node

Reimplemented in executable_tree::Sha256, executable_tree::Cut_bit, executable_tree::Cut_byte, executable_tree::Root, executable_tree::Value, and executable_tree::Getter.

6.14.2.3 to_string()

get the string representing the node

Parameters

depth the depth of the node in the executable tree

Returns

std::string the string representing the node

Reimplemented in executable_tree::Sha256, executable_tree::Cut_bit, executable_tree::Cut_byte, executable_tree::Root, executable_tree::Function, executable_tree::Value, and executable_tree::Getter.

The documentation for this class was generated from the following files:

- includes/compiler/node.hpp
- src/compiler/node.cpp

6.15 executable_tree::Root Class Reference

The node that represent the root of the executable tree, it does not do anything but have one child.

```
#include <node.hpp>
```

Inheritance diagram for executable_tree::Root:

Collaboration diagram for executable_tree::Root:

Public Member Functions

∼Root ()

Destroy the Root object.

• std::string get_value (const decoder::Frame *target_frame) const override

Get the value of the node.

• void add_node (Node *arg) override

Add a child node to the current node.

std::string to_string (size_t depth) const override

get the string representing the node

6.15.1 Detailed Description

The node that represent the root of the executable tree, it does not do anything but have one child.

6.15.2 Constructor & Destructor Documentation

6.15.2.1 ∼Root()

```
executable_tree::Root::~Root ( ) [inline]
```

Destroy the Root object.

6.15.3 Member Function Documentation

6.15.3.1 add_node()

Add a child node to the current node.

Parameters

```
arg The node to add
```

Reimplemented from executable_tree::Node.

6.15.3.2 get_value()

Get the value of the node.

Parameters

target_frame that is analysed by the executable tree

Returns

std::string the value returned by the node

Reimplemented from executable_tree::Node.

6.15.3.3 to_string()

get the string representing the node

Parameters

```
depth the depth of the node in the executable tree
```

Returns

std::string the string representing the node

Reimplemented from executable_tree::Node.

The documentation for this class was generated from the following files:

- includes/compiler/node.hpp
- src/compiler/node.cpp

6.16 executable tree::Sha256 Class Reference

This Function concatenates its arguments and.

```
#include <function_node.hpp>
```

Inheritance diagram for executable_tree::Sha256:

Collaboration diagram for executable_tree::Sha256:

Public Member Functions

- std::string to_string (size_t depth) const override get the string representing the node
- std::string get_value (const decoder::Frame *target_frame) const override Get the value of the node.

Additional Inherited Members

6.16.1 Detailed Description

This Function concatenates its arguments and.

6.16.2 Member Function Documentation

6.16.2.1 get_value()

Get the value of the node.

Parameters

target_frame that is analysed by the executable tree

Returns

std::string the value returned by the node

Reimplemented from executable_tree::Node.

6.16.2.2 to_string()

get the string representing the node

Parameters

depth the depth of the node in the executable tree

Returns

std::string the string representing the node

Reimplemented from executable_tree::Node.

The documentation for this class was generated from the following files:

- includes/compiler/function_node.hpp
- src/compiler/function_node.cpp

6.17 executable tree::Value Class Reference

Node that has a static value.

```
#include <node.hpp>
```

Inheritance diagram for executable_tree::Value:

Collaboration diagram for executable_tree::Value:

Public Member Functions

• Value (std::string value)

Construct a new Value object.

- $std::string \ get_value \ (const \ decoder::Frame \ *target_frame) \ const \ override$
 - Get the value of the node.
- void add node (Node *arg) override

Add a child node to the current node.

• std::string to_string (size_t depth) const override

get the string representing the node

6.17.1 Detailed Description

Node that has a static value.

6.17.2 Constructor & Destructor Documentation

6.17.2.1 Value()

Construct a new Value object.

Parameters

value the fixed value of the Node

6.17.3 Member Function Documentation

6.17.3.1 add_node()

Add a child node to the current node.

Parameters

```
arg The node to add
```

Reimplemented from executable_tree::Node.

6.17.3.2 get_value()

Get the value of the node.

Parameters

target_frame that is analysed by the executable tree

Returns

std::string the value returned by the node

Reimplemented from executable_tree::Node.

6.17.3.3 to_string()

get the string representing the node

Parameters

depth the depth of the node in the executable tree

Returns

std::string the string representing the node

Reimplemented from executable_tree::Node.

The documentation for this class was generated from the following files:

- includes/compiler/node.hpp
- src/compiler/node.cpp

Chapter 7

File Documentation

7.1 includes/compiler/compiler.hpp File Reference

```
#include "os_communicator/os_communicator.hpp"
#include "compiler/node.hpp"
#include "compiler/function_node.hpp"
#include "decoder/frame.hpp"
```

Include dependency graph for compiler.hpp: This graph shows which files directly or indirectly include this file:

Classes

· class compiler::Compiler

Tranform the source code into a executable tree.

Namespaces

· namespace compiler

7.2 compiler.hpp

Go to the documentation of this file.

```
1 #ifndef COMPILER HPF
2 #define COMPILER_HPP
# #include "os_communicator/os_communicator.hpp"
# #include "compiler/node.hpp"
# #include "compiler/function_node.hpp"
# #include "decoder/frame.hpp"
9 namespace compiler {
   class Compiler {
16
          private:
                 const os_communicator::Communicator *_communicator;
18
                 // return the next line to read and fill the current_node
19
                 size_t read_line(executable_tree::Node *current_node, size_t next_line) const;
                 Compiler(const os_communicator::Communicator *communicator)
35
                 : _communicator(communicator) {
36
37
                      if(!_communicator)
                           throw invalid_argument("No communicator given");
39
40
46
                 executable_tree::Node *get_executable_tree() const;
47
        };
48 }
50 #endif
```

58 File Documentation

7.3 includes/compiler/function_node.hpp File Reference

```
#include "compiler/node.hpp"
#include "decoder/big_number.hpp"
#include <openssl/evp.h>
#include <string>
```

Include dependency graph for function_node.hpp: This graph shows which files directly or indirectly include this file:

Classes

• class executable_tree::Sha256

This Function concatenates its arguments and.

class executable_tree::Cut_bit

This Function cut the bits of the first arg from the second arg of the size of the third arg.

• class executable_tree::Cut_byte

This Function cut the bytes of the first arg fril the secong arg of the size of the third arg.

Namespaces

• namespace executable_tree

7.3.1 Detailed Description

Author

Pagano Florian

Version

0.1

Date

2025

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7.4 function_node.hpp 59

7.4 function_node.hpp

Go to the documentation of this file.

```
11 #ifndef FUNCTION_NODE_HPP
12 #define FUNCTION_NODE_HPP
13
14 #include "compiler/node.hpp"
15 #include "decoder/big_number.hpp"
17 #include <openssl/evp.h>
18 #include <string>
19
20 namespace executable_tree{
     class Sha256 : public Function {
27
         public:
28
               std::string to_string(size_t depth) const override;
29
               std::string get_value(const decoder::Frame *target_frame) const override;
30
31
     } ;
32
      class Cut_bit : public Function {
       public:
38
               std::string to_string(size_t depth) const override;
39
40
              std::string get_value(const decoder::Frame *target_frame) const override;
41
42
     } ;
43
48
      class Cut_byte : public Function {
49
         public:
               std::string to_string(size_t depth) const override;
50
51
              std::string get_value(const decoder::Frame *target_frame) const override;
52
       } ;
54 }
56 #endif
```

7.5 includes/compiler/node.hpp File Reference

This file contains base class of a executable tree.

```
#include "decoder/frame.hpp"
#include <vector>
#include <string>
```

Include dependency graph for node.hpp: This graph shows which files directly or indirectly include this file:

Classes

class executable_tree::Node

Represents a node of the executable tree.

· class executable tree::Root

The node that represent the root of the executable tree, it does not do anything but have one child.

· class executable tree::Function

Node that execute a function (that must be implemented as a child of Function class)

class executable_tree::Value

Node that has a static value.

class executable_tree::Getter

Node that get dynamic information in the frame.

Namespaces

namespace executable_tree

60 File Documentation

7.5.1 Detailed Description

This file contains base class of a executable tree.

Author

Pagano Florian

Version

0.1

Date

2025

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7.6 node.hpp

Go to the documentation of this file.

```
11 #ifndef EXECUTABLE_TREE_HPP
12 #define EXECUTABLE_TREE_HPP
13
14 #include "decoder/frame.hpp"
15
16 #include <vector>
17 #include <string>
18
19 namespace executable_tree{
25     class Node {
          public:
26
33
               virtual std::string get_value(const decoder::Frame *target_frame) const;
40
               virtual void add_node(Node* arg);
41
48
               virtual std::string to_string(size_t depth) const;
49
       };
50
       class Root : public Node {
58
               Node* _first_node = nullptr;
59
60
           public:
65
               ~Root(){
                   if (_first_node)
                        delete _first_node;
68
69
70
                std::string get_value(const decoder::Frame *target_frame) const override;
71
72
               void add_node(Node* arg) override;
73
74
75
                std::string to_string(size_t depth) const override;
       } ;
76
       class Function : public Node {
82
83
           protected:
               std::vector<Node*> args;
86
           public:
               ~Function(){
91
92
                    for (Node* arg : args)
93
                        delete arg;
```

```
args.clear();
97
98
               void add_node(Node* arg) override;
99
100
                std::string to_string(size_t depth) const override;
101
       };
102
108
       class Value : public Node {
109
           private:
               std::string value;
110
111
112
           public:
118
               Value(std::string value) : value(value) {};
119
120
               std::string get_value(const decoder::Frame *target_frame) const override;
121
               void add node (Node* arg) override;
122
123
124
                std::string to_string(size_t depth) const override;
125
126
       class Getter : public Node {
132
133
           private:
134
               const std::string field_name;
135
136
142
              Getter(const std::string field_name)
143
                    : field_name(field_name){};
144
145
               std::string get_value(const decoder::Frame *target_frame) const override;
146
147
               void add_node(Node* arg) override;
148
149
               std::string to_string(size_t depth) const override;
150
151 }
153 #endif
```

7.7 includes/const.hpp File Reference

Contains all constant that are used in snapdesk.

This graph shows which files directly or indirectly include this file:

Macros

• #define FRAME_HEADER_MIN_LENGTH 24

The min length of the header of a frame.

• #define FRAME_HEADER_MAX_LENGTH 36

The max length of the header of a frame.

#define BEACON_FRAME_MAX_LENGTH 2346

The max length of a beacon frame.

• #define BEACON_FRAME_BODY_MIN_LENGTH 12

The min length of the body of a beacon frame.

#define FRAME_MAX_LENGTH BEACON_FRAME_MAX_LENGTH

The max length of a frame.

• #define DATABASE_ROOT "database"

The root directory name where logs will be saved.

File Documentation

7.7.1 Detailed Description

Contains all constant that are used in snapdesk.

Author

Pagano Florian

Version

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Date

2025

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7.7.2 Macro Definition Documentation

7.7.2.1 BEACON_FRAME_BODY_MIN_LENGTH

#define BEACON_FRAME_BODY_MIN_LENGTH 12

The min length of the body of a beacon frame.

7.7.2.2 BEACON_FRAME_MAX_LENGTH

#define BEACON_FRAME_MAX_LENGTH 2346

The max length of a beacon frame.

7.7.2.3 DATABASE_ROOT

#define DATABASE_ROOT "database"

The root directory name where logs will be saved.

7.8 const.hpp 63

7.7.2.4 FRAME_HEADER_MAX_LENGTH

```
#define FRAME_HEADER_MAX_LENGTH 36
```

The max length of the header of a frame.

7.7.2.5 FRAME_HEADER_MIN_LENGTH

```
#define FRAME_HEADER_MIN_LENGTH 24
```

The min length of the header of a frame.

7.7.2.6 FRAME_MAX_LENGTH

```
#define FRAME_MAX_LENGTH BEACON_FRAME_MAX_LENGTH
```

The max length of a frame.

7.8 const.hpp

Go to the documentation of this file.

```
1
2 #ifndef CONST_HPP
13 #define CONST_HPP
14
15 #define FRAME_HEADER_MIN_LENGTH 24
16 #define FRAME_HEADER_MAX_LENGTH 36
17
18 #define BEACON_FRAME_MAX_LENGTH 2346
19 #define BEACON_FRAME_BODY_MIN_LENGTH 12
20
21 // To change whith true value
22 #define FRAME_MAX_LENGTH BEACON_FRAME_MAX_LENGTH
23
24 #define DATABASE_ROOT "database"
25
26 #endif
```

7.9 includes/database/core.hpp File Reference

Contains core classes to manipulate the database.

```
#include <string>
#include <vector>
#include <algorithm>
#include <openssl/evp.h>
#include "os_communicator/os_communicator.hpp"
#include "const.hpp"
```

Include dependency graph for core.hpp: This graph shows which files directly or indirectly include this file:

Classes

· class database::Csv

This class represent and operates a csv file.

• class database::Database

This class provide a simple API to manipulate storage files.

Namespaces

• namespace database

Macros

```
• #define HEADER_SIZE 1
```

- #define DELIMITER ";"
- #define DATA_EXTENTION ".csv"
- #define METADATA_EXTENTION ".metadata"
- #define KEY_LINE_NUMBER 0
- #define COLUMN_NUMBER_LINE_NUMBER 1
- #define COLUMN_NAMES {"output", "creation_date", "last_date"}
- #define KEY COLUMN NUMBER 0

7.9.1 Detailed Description

Contains core classes to manipulate the database.

Author

Pagano Florian

Version

0.1

Date

2025

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7.9.2 Macro Definition Documentation

7.9.2.1 COLUMN_NAMES

```
#define COLUMN_NAMES {"output", "creation_date", "last_date"}
```

7.9.2.2 COLUMN_NUMBER_LINE_NUMBER

#define COLUMN_NUMBER_LINE_NUMBER 1

7.9.2.3 DATA_EXTENTION

#define DATA_EXTENTION ".csv"

7.9.2.4 DELIMITER

#define DELIMITER ";"

7.9.2.5 HEADER SIZE

#define HEADER_SIZE 1

7.9.2.6 KEY_COLUMN_NUMBER

#define KEY_COLUMN_NUMBER 0

7.9.2.7 KEY_LINE_NUMBER

#define KEY_LINE_NUMBER 0

7.9.2.8 METADATA_EXTENTION

#define METADATA_EXTENTION ".metadata"

7.10 core.hpp

Go to the documentation of this file.

```
11 #ifndef CORE_HPP
12 #define CORE_HPP
13
14 #include <string>
15 #include <vector>
16 #include <algorithm>
18 #include <openssl/evp.h>
19
20 #include "os_communicator/os_communicator.hpp"
21 #include "const.hpp"
23 // Number of line that are not raw data
24 #define HEADER_SIZE 1
25 #define DELIMITER ";"
26 #define DATA_EXTENTION ".csv"
27 #define METADATA_EXTENTION ".metadata"
28 #define KEY_LINE_NUMBER 0
29 #define COLUMN_NUMBER_LINE_NUMBER 1
30 #define COLUMN_NAMES {"output", "creation_date", "last_date"}
31 #define KEY_COLUMN_NUMBER 0
32
33 namespace database{
39     class Csv{
40
          private:
               size_t _number_of_columns;
41
                size_t _key_column_number;
43
                os_communicator::Communicator *_c_metadata;
44
               os_communicator::Communicator *_c_data;
45
                void _test_values_size(std::vector<std::string> values);
                size_t _get_key_position(std::string key_value);
                static std::string _values_to_line(std::vector<std::string> values);
73
                size_t _get_column_position_from_header(std::string header, std::string column_name);
                static std::string _get_cell_from_row(std::string row, size_t column_number);
size_t _string_to_size_t(std::string number);
81
88
89
96
                Csv(std::string file_name);
101
                 ~Csv();
                static Csv *create(std::string file_name, std::vector<std::string> column_names, size_t
110
      key_column_number);
111
117
                 void push_row(std::vector<std::string> values);
                 void replace_row(size_t row_number, std::vector<std::string> values);
124
132
                 std::string get_cell(size_t row_number, size_t column_number);
139
                 size_t get_row_number(std::string key_value);
146
                 size_t get_column_number(std::string column_name);
                std::vector<std::string> get_all_keys();
std::vector<std::string> get_all_keys_with_value(size_t column_number, std::string value);
152
160
161
162
168
        class Database(
          private:
169
                std::string _ssid;
170
171
                 std::string _code_file_name;
172
                 std::string _code_hash;
173
                 Csv *_csv;
174
175
            public:
182
                Database(std::string ssid, std::string code_file_name);
187
                 ~Database();
188
196
                 std::string get_cell(std::string key_value, std::string column_name);
204
                 std::vector<std::string> get_key_of_entries(std::string column_name, std::string
      cell_value);
210
                void add_entry(std::vector<std::string> values);
                void replace_entry(std::string key_value, std::vector<std::string> values);
217
218
219 };
220
221 #endif
```

7.11 includes/decoder/big_number.hpp File Reference

```
#include <vector>
#include <cstdint>
```

7.12 big_number.hpp 67

```
#include <cstddef>
#include <stdexcept>
#include <string>
```

Include dependency graph for big_number.hpp: This graph shows which files directly or indirectly include this file:

Classes

· class decoder::Big_number

This class represent and manipulate indifined sized numbers using bytes.

Namespaces

· namespace decoder

7.11.1 Detailed Description

Author

Florian Pagano

Version

0.1

Date

2025

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7.12 big_number.hpp

Go to the documentation of this file.

```
11 #ifndef BIG_NUMBER_HPP
12 #define BIG_NUMBER_HPP
14 #include <vector>
15 #include <cstdint>
16 #include <cstddef>
17 #include <stdexcept>
18 #include <string>
20
21 namespace decoder{
     class Big_number {
27
        private:
28
               std::vector<uint8_t> number;
30
              bool _is_null = false;
38
              Big_number& operator=(const std::vector<uint8_t> _number);
39
          public:
40
47
              bool is_null() const;
               void throw_if_null() const;
```

```
std::string hex_string() const;
                 std::string char_string() const;
70
                 size_t to_size_t() const;
                 void cut_byte(size_t from, size_t size);
void cut_bit(size_t from, size_t size);
Big_number copy() const;
77
84
90
                 /* Operators */
93
100
                  Big_number& operator=(const Big_number _number);
101
                  /* Constructors */
102
103
                  static Big_number null();
118
                  static Big_number from_buffer(const uint8_t *buffer, const size_t buffer_size, const size_t
127
                  static Big_number from_buffer_inv(const uint8_t *buffer, const size_t buffer_size, const
      size_t number_size);
134
                 static Big_number from_hex_string(const std::string string);
135
136 }
137
138 #endif
```

7.13 includes/decoder/frame.hpp File Reference

The file contains all basic frame class.

```
#include <cstdint>
#include <const.hpp>
#include <string>
#include <vector>
#include "os_communicator/os_communicator.hpp"
#include "decoder/big_number.hpp"
```

Include dependency graph for frame.hpp: This graph shows which files directly or indirectly include this file:

Classes

· class decoder::Body

This class set the base of all frame's body possible.

class decoder::Frame

The class that represent the whole frame.

Namespaces

· namespace decoder

7.13.1 Detailed Description

The file contains all basic frame class.

Author

Pagano Florian

69 7.14 frame.hpp

Version

0.1

Date

2025

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7.14 frame.hpp

Go to the documentation of this file.

```
11 #ifndef FRAME_HPP
12 #define FRAME_HPP
14 #include <cstdint>
15 #include <const.hpp>
16 #include <string>
17 #include <vector>
18
19 #include "os_communicator/os_communicator.hpp"
20 #include "decoder/big_number.hpp"
21
22 using namespace std;
2.3
24 namespace decoder{
       class Body {
30
           protected:
31
               uint8_t *_raw_body_buffer;
32
                size_t _raw_buffer_size;
33
               virtual void decode() = 0;
38
39
           public:
40
47
                Body(uint8_t *raw_body_buffer, size_t raw_buffer_size);
48
                virtual void print() const = 0;
53
                virtual Big_number get_value(string field) const = 0;
60
61
                static Body *get_body(uint8_t *raw_body_buffer, size_t raw_buffer_size, size_t type, size_t
      sub_type);
72
73
79
       class Frame{
80
           private:
                os_communicator::Communicator *communicator;
           protected:
83
                uint8_t *raw_frame_buffer;
84
                size_t raw_buffer_size;
85
                size_t raw_frame_size;
                bool is_decoded;
86
                bool has_raw_data;
88
89
                // Header
90
                Big_number frame_control = Big_number::null();
                Big_number duration = Big_number::null();
Big_number destination_address = Big_number::null();
91
92
                Big_number source_address = Big_number::null();
Big_number bssid = Big_number::null();
93
95
                Big_number sequence_control = Big_number::null();
                Big_number frame_check_sum = Big_number::null();
96
97
98
                // Body
                Body *body = nullptr;
100
            public:
101
107
                Frame(os_communicator::Communicator *_communicator);
112
                 ~Frame();
113
120
                 bool get_is_decoded() const;
125
                 void update_raw_data();
```

7.15 includes/decoder/ie.hpp File Reference

Classes that permit to represent the IE of a frame's body.

```
#include <cstdint>
#include <stdexcept>
#include <map>
#include "decoder/big_number.hpp"
Include dependency graph for ie.hpp: This graph shows which files directly or indirectly include this file:
```

Classes

• class decoder::le_node

An element of a linked list of IEs.

Namespaces

· namespace decoder

Macros

```
• #define P_SSID 0
     element id 0 is the SSID
• #define P SUPPORTED RATES 1
     element id 1 is the supported rated

 #define P_FH 2

     element id 2 is the FH parameter set
• #define P DS 3
     element id 3 is the DS parameter set
• #define P_CF 4
     element id 4 is the CF parameter set
• #define P_TIM 5
     element id 5 is the TIM
• #define P_IBSS 6
     element id 6 is the IBSS
• #define P_Challenge_text 16
     element 16 is the challenge text
```

7.15.1 Detailed Description

Classes that permit to represent the IE of a frame's body.

Author

Pagano Florian

Version

0.1

Date

2025

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7.15.2 Macro Definition Documentation

7.15.2.1 P_CF

#define P_CF 4

element id 4 is the CF parameter set

7.15.2.2 P_Challenge_text

#define P_Challenge_text 16

element 16 is the challenge text

7.15.2.3 P_DS

#define P_DS 3

element id 3 is the DS parameter set

7.15.2.4 P_FH

#define P_FH 2

element id 2 is the FH parameter set

7.15.2.5 P_IBSS

#define P_IBSS 6

element id 6 is the IBSS

7.15.2.6 P_SSID

#define P_SSID 0

element id 0 is the SSID

7.15.2.7 P_SUPPORTED_RATES

#define P_SUPPORTED_RATES 1

element id 1 is the supported rated

7.15.2.8 P_TIM

#define P_TIM 5

element id 5 is the TIM

7.16 ie.hpp 73

7.16 ie.hpp

Go to the documentation of this file.

```
11 #ifndef BEACON_ELEMENT_HPP
12 #define BEACON_ELEMENT_HPP
13
15 #include <stdexcept>
16 #include <stdexcept>
17 #include <map>
18 #include "decoder/big_number.hpp"
20 #define P_SSID 0
21 #define P_SUPPORTED_RATES 1
22 #define P_FH 2
23 #define P_DS 3
24 #define P_CF 4
25 #define P_TIM 5
26 #define P_IBSS 6
27 #define P_Challenge_text 16
29 namespace decoder{
35
      class Ie_node {
36
          private:
                uint8_t element_id;
                Big_number element_value;
39
                Ie_node *next_element;
40
               bool is_valid_hex(const std::string str) const;
48
49
50
               Ie_node(uint8_t element_id, Big_number value);
~Ie_node();
63
69
                void add(Ie_node *new_element);
                Big_number get_value(std::string field) const;
76
                void print();
83 }
85 #endif
```

7.17 includes/decoder/management_body.hpp File Reference

```
#include <cstdint>
#include <const.hpp>
#include <string>
#include "decoder/frame.hpp"
#include "decoder/ie.hpp"
#include "decoder/big_number.hpp"
```

Include dependency graph for management_body.hpp: This graph shows which files directly or indirectly include this file:

Classes

· class decoder::Beacon_body

Is the body of a beacon frame.

Namespaces

namespace decoder

7.17.1 Detailed Description

Author

Pagano Florian

Version

0.1

Date

2025

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7.18 management_body.hpp

Go to the documentation of this file.

```
11 #ifndef MANAGEMENT_BODY_HPP
12 #define MANAGEMENT_BODY_HPP
13
14 #include <cstdint>
15 #include <const.hpp>
16 #include <string>
17 #include "decoder/frame.hpp"
18 #include "decoder/ie.hpp"
19 #include "decoder/big_number.hpp"
20
21 using namespace std;
22
23 namespace decoder{
29
        class Beacon_body : public Body {
30
             private:
                   Big_number _timestamp;
Big_number _beacon_interval;
Big_number _capabilities_information;
Ie_node *_first_ie = nullptr;
31
32
33
34
40
                   void decode() override;
                    void add_ie(uint8_t element_id, uint8_t element_length, size_t start_position);
48
49
50
             public:
                    Beacon_body(uint8_t *raw_body_buffer, size_t raw_buffer_size);
                    ~Beacon_body();
                    void print() const override;
Big_number get_value(string field) const override;
68
7.5
76
         };
77 }
79 #endif
```

7.19 includes/os_communicator/os_communicator.hpp File Reference

The os_communicator component handle all interaction between snapdesk and the current os.

```
#include <cstddef>
#include <cstdint>
#include <stdexcept>
#include <string>
#include <fstream>
#include <ctime>
#include <iomanip>
#include <chrono>
#include <thread>
#include <filesystem>
```

Include dependency graph for os_communicator.hpp: This graph shows which files directly or indirectly include this file:

Classes

· class os_communicator::Communicator

The Communicator is the main class of the os_communicator component.

Namespaces

• namespace os_communicator

Macros

```
#define F_NONE 0

A file that does not exist.
#define F_FILE 1

A file.
#define F_FOLDER 2

A folder.
```

7.19.1 Detailed Description

The os_communicator component handle all interaction between snapdesk and the current os.

Author

Pagano Florian

Version

0.1

Date

2025

Copyright

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7.19.2 Macro Definition Documentation

7.19.2.1 F_FILE

```
#define F_FILE 1
```

A file.

7.19.2.2 F_FOLDER

```
#define F_FOLDER 2
```

A folder.

7.19.2.3 F NONE

```
#define F_NONE 0
```

A file that does not exist.

7.20 os_communicator.hpp

Go to the documentation of this file.

```
12 #ifndef OS_COMMUNICATOR_HPP
13 #define OS_COMMUNICATOR_HPP
14
15 #include <cstddef>
16 #include <cstdint>
17 #include <stdexcept>
18 #include <string>
19 #include <fstream>
20 #include <ctime>
21 #include <iomanip>
22 #include <chrono>
23 #include <thread>
24 #include <filesystem>
26 #define F_NONE 0
27 #define F_FILE 1
28 #define F_FOLDER 2
30 using namespace std;
32 namespace os_communicator{
33
39
      class Communicator{
          private:
40
41
                 string _file_name;
43
          public:
49
                 Communicator(string file_name);
50
                 bool exist();
                 size_t in_buffer(uint8_t *buffer, const size_t buffer_size);
```

```
string get_line(size_t line_number) const;
               void add_line(string line);
              void replace_line(size_t line_number, string new_line);
90
              void new_file();
91
              static string get_current_date();
              static void notify(string message);
103
109
               static void sleep(size_t seconds);
110
              static void create_folder(string folder_name);
116
              static size_t get_file_type(string name);
123
124
125 }
127 #endif
```

7.21 src/compiler/compiler.cpp File Reference

```
#include "compiler/compiler.hpp"
Include dependency graph for compiler.cpp:
```

7.22 src/compiler/function_node.cpp File Reference

```
#include "compiler/function_node.hpp"
Include dependency graph for function_node.cpp:
```

7.23 src/compiler/node.cpp File Reference

```
#include "compiler/node.hpp"
Include dependency graph for node.cpp:
```

7.24 src/database/csv.cpp File Reference

```
#include "database/core.hpp"
Include dependency graph for csv.cpp:
```

Namespaces

· namespace database

7.25 src/database/database.cpp File Reference

```
#include "database/core.hpp"
Include dependency graph for database.cpp:
```

Namespaces

namespace database

Functions

• std::string database::hash (std::string str)

7.26 src/decoder/big_number.cpp File Reference

```
#include "decoder/big_number.hpp"
Include dependency graph for big number.cpp:
```

7.27 src/decoder/frame.cpp File Reference

```
#include "decoder/frame.hpp"
#include "decoder/management_body.hpp"
Include dependency graph for frame.cpp:
```

7.28 src/decoder/ie.cpp File Reference

```
#include "decoder/ie.hpp"
Include dependency graph for ie.cpp:
```

7.29 src/decoder/management_body.cpp File Reference

```
#include "decoder/management_body.hpp"
Include dependency graph for management body.cpp:
```

7.30 src/main.cpp File Reference

This is the main file. It contains the main loop of snapdesk.

```
#include "decoder/frame.hpp"
#include "os_communicator/os_communicator.hpp"
#include "compiler/node.hpp"
#include "compiler/function_node.hpp"
#include "compiler/compiler.hpp"
#include "database/core.hpp"
Include dependency graph for main.cpp:
```

Macros

- #define CHARACTER_DEVICE_FILE "/dev/beacon-sniffer-0"
- #define SCRIPT_FILE "./snappy.txt"
- #define PERIOD 1

Functions

• int run ()

The true main function. This exist to permit the program to rerun itself when crashing.

• int main (int argc, char *argv[])

7.30.1 Detailed Description

This is the main file. It contains the main loop of snapdesk.

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Version

0.1

Date

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Copyright

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7.30.2 Macro Definition Documentation

7.30.2.1 CHARACTER_DEVICE_FILE

```
#define CHARACTER_DEVICE_FILE "/dev/beacon-sniffer-0"
```

7.30.2.2 PERIOD

#define PERIOD 1

7.30.2.3 SCRIPT_FILE

```
#define SCRIPT_FILE "./snappy.txt"
```

7.30.3 Function Documentation

7.30.3.1 main()

```
int main (
          int argc,
          char * argv[] )
```

7.30.3.2 run()

```
int run ()
```

The true main function. This exist to permit the program to rerun itself when crashing.

Returns

int: The same return than the main function

7.31 src/os_communicator/os_communicator.cpp File Reference

#include "os_communicator/os_communicator.hpp"
Include dependency graph for os_communicator.cpp:

Namespaces

• namespace os_communicator

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