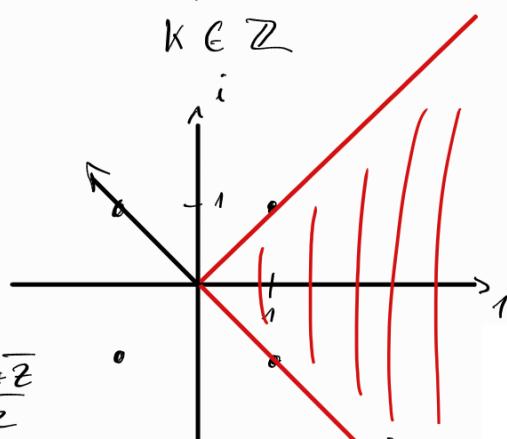


$$n e^{i\theta} \in QPSK$$

↳ $n > 0$

$$\theta \in \frac{\pi}{4} \times (2k+1)$$

$$k \in \mathbb{Z}$$



$$a = \frac{z + \bar{z}}{2}$$

$$b = \frac{z - \bar{z}}{2i}$$

$$\frac{b}{a} = \frac{z - \bar{z}}{(z + \bar{z})i}$$

$$a + ib \quad \left. \begin{array}{l} a > 0 \\ \text{et } b < a \\ \text{et } -b < a \end{array} \right\} |b| < a$$

$$n e^{i\theta} \times n' e^{i\varphi} = n n' e^{i(\theta+\varphi)}$$

pour rester dans le même quadrant du plan complexe (divisé en 4)

il faut $n' > 0$ et $\varphi \in]-\frac{\pi}{4}, \frac{\pi}{4}[$

i.e pour $n' e^{i\varphi} = a + ib$ implique
 $|a+ib| = \sqrt{a^2 + b^2} > 0$ $a > 0$

$$\theta = \begin{cases} \arccos\left(\frac{a}{r}\right) & \text{si } b \geq 0 \\ -\arccos\left(\frac{a}{r}\right) & \text{si } b < 0, \end{cases} \quad r = \sqrt{a^2 + b^2}$$

$$\theta = \begin{cases} \arcsin\left(\frac{b}{r}\right) & \text{si } a \geq 0 \\ \pi - \arcsin\left(\frac{b}{r}\right) & \text{si } a < 0, \end{cases}$$

et $\theta = \begin{cases} \arctan\left(\frac{b}{a}\right) & \text{si } a > 0 \\ \arctan\left(\frac{b}{a}\right) + \pi & \text{si } a < 0 \\ \operatorname{sgn}(b)\frac{\pi}{2} & \text{si } a = 0. \end{cases}$

fct angle matlab.

$$(a+ib)i = -b + ia = -b - ia$$

C2PO
avec rendement d

\Rightarrow pas pris en compte, mais l'initialisation MRT semble empêcher ce problème

$$x = H^\dagger \lambda ?$$

→ initialisation en ZF semble également empêcher ce pb, mais donne de moins bons résultats pour un grand SNR

à vérifier

→ contrainte de positivité peut-être non nécessaire.

amplification $D \in M_{n,n}(\mathbb{C})$, $d_j = r_j e^{i\phi_j}$

de limiter à $r_j \geq 0$ et $\phi_j \in]-\frac{\pi}{4}, \frac{\pi}{4}[$

pour écrire une solution en $\arg \underline{x} \leq 0$

$$d_j = r_j e^{i\phi_j} = a_j + i b_j$$

\Leftrightarrow de limiter à $a_j \geq 0$ et

$\begin{cases} \text{signal pas} \\ = 0 \text{ envoyé} \end{cases}$

$$b_j \leq a_j \quad -b_j \leq a_j$$

$\hookrightarrow ? a_j = b_j$ perte d'info

on pourrait ajouter un angle d'inclinaison $\lambda < 1$

$$b_j \in \lambda a_j$$

Convexité des fct's :

$$a_j \geq 0 \Leftrightarrow -a_j \leq 0$$

$$\text{avec } z = a + i b \in \mathbb{C} \quad f(z) = -a = -\left(\frac{z + \bar{z}}{2}\right)$$

$$\text{et } z_2 = c + i d$$

$$f\left(\begin{pmatrix} x_1 \\ x_2 \end{pmatrix}\right) = -x_1 = -\left(\frac{x_1 + x_2 + x_1 - x_2}{2}\right) = -x_1$$

$$\alpha \in [0,1] \quad f(\alpha z + (1-\alpha)z_2) = -\alpha a - (1-\alpha)c$$

$$\alpha f(z) + (1-\alpha)f(z_2) = -\alpha a - (1-\alpha)c$$

f convexe

$$b \leq a \Leftrightarrow \frac{b}{a} - 1 \leq 0 \quad \text{si } a \neq 0, \text{ sinon } a=b=0$$

$$f(z) = \frac{b}{a} - 1 = \frac{z - \bar{z}}{(z + \bar{z})_i} - 1 \quad \text{mauvais pt de départ}$$

$$f\left(\frac{x_1}{x_2}\right) = \frac{x_2}{x_1} - 1 = \frac{x_1 + x_2 - (x_1 - x_2)}{(x_1 + x_2 + x_1 - x_2)} - 1$$

$$\begin{aligned} \alpha \in [0;1] \quad f(\alpha z + (1-\alpha)z_2) &= f(\alpha a + i\alpha b + (1-\alpha)c + i(1-\alpha)d) \\ &= f(\alpha a + (1-\alpha)c + i(\alpha b + (1-\alpha)d)) \\ &= \frac{\alpha b + (1-\alpha)d}{\alpha a + (1-\alpha)c} - 1 = \frac{\alpha b + (1-\alpha)d - \alpha a - (1-\alpha)c}{\alpha a + (1-\alpha)c} \\ &= \frac{\alpha(b-a) + (1-\alpha)(d-c)}{\alpha a + (1-\alpha)c} = \frac{\alpha b - \alpha a - \alpha d + \alpha c + d - c}{\alpha a + c - \alpha c} \\ &= \frac{\alpha(b-a+c-d) + d - c}{\alpha(a-c) + c} \end{aligned}$$

espace de départ f

$$\begin{cases} a > 0 \\ b \leq a \\ -b \leq a \end{cases} \quad z = a + ib \in \mathbb{C}$$

$$\begin{aligned} \alpha a + (1-\alpha)c &> 0 \\ \text{car } a > 0, c > 0 \\ \text{et } \alpha \in [0;1] \end{aligned}$$

$$\left. \begin{aligned} \alpha(b-a) + (1-\alpha)(d-c) &\leq 0 \\ \geq 0 &\leq 0 \end{aligned} \right\} \leq 0$$

$$\begin{aligned} \alpha f(z) + (1-\alpha) f(z_2) &= \alpha \left(\frac{b}{a} - 1 \right) + (1-\alpha) \left(\frac{d}{c} - 1 \right) \\ &= \alpha \frac{b}{a} - \alpha + (1-\alpha) \frac{d}{c} - (1-\alpha) \\ &= \alpha \frac{b}{a} + (1-\alpha) \frac{d}{c} - 1 \\ &= \frac{\alpha bc + (1-\alpha)da - ac}{ac} = \frac{\alpha bc + da - \alpha da - ac}{ac} \end{aligned}$$

$$f\left(\frac{x_1}{x_2}\right) = \frac{x_2}{x_1} - 1$$

$$\frac{\partial f}{\partial x_1} = -\frac{x_2}{x_1^2}$$

$$\begin{aligned} z_1 &= a + ib \\ z_2 &= c + id \end{aligned}$$

$$\frac{\partial^2 f}{\partial x_1^2} = \frac{UV - UV'}{V^2} = \frac{x_2 x_2 x_1}{x_1^4} \cdot \frac{2x_2}{x_1^3}$$

$$\frac{\partial f}{\partial x_2} = \frac{1}{x_1}$$

$$\frac{1}{c} - 1 \geq \frac{b}{a} - 1 + \begin{pmatrix} -\frac{b}{a^2} \\ \frac{1}{a} \end{pmatrix} \cdot \begin{pmatrix} c-a \\ d-b \end{pmatrix}$$

$$\frac{\partial^2 f}{\partial x_2^2} = 0$$

$$\frac{\partial^2 f}{\partial x_1 \partial x_2} = -\frac{1}{x_1^2}$$

$$\frac{d}{c} - \frac{b}{a} + \frac{bc}{a^2} - \frac{d}{a} = \frac{da^2 - bac + bc^2 - dac}{a^2 c} > 0 \quad (1)$$

$$= \frac{b}{a} - 1 - \frac{bc}{a^2} + \cancel{\frac{b}{a}} + \frac{d}{a} - \cancel{\frac{d}{a}}$$

meilleur point de départ

$$|b| \leq a \Leftrightarrow \frac{|b|}{a} - 1 \leq 0 \quad \text{si } a \neq 0, \text{ sinon } a=b=0$$

$$\begin{aligned} f(z) = \frac{|b|}{a} - 1 &= \left| \frac{z-\bar{z}}{z_i} \right| \times \frac{z}{z+\bar{z}} - 1 \\ &= \frac{|z-\bar{z}|}{|z_i|} \times \frac{z}{z+\bar{z}} - 1 = \frac{|z-\bar{z}|}{z+\bar{z}} - 1 = \frac{|z-\bar{z}|(z+\bar{z})}{|z+\bar{z}|^2} - 1 \end{aligned}$$

$$\begin{aligned} \alpha \in [0; 1] : \quad f(\alpha z_1 + (1-\alpha)z_2) &= f(\alpha a + (1-\alpha)c + i(\alpha b + (1-\alpha)d)) \\ z_1 = a+ib & \quad (1) = \frac{|\alpha b + (1-\alpha)d|}{\alpha a + (1-\alpha)c} - 1 = \frac{|\alpha b + (1-\alpha)d| - \alpha a - (1-\alpha)c}{\alpha a + (1-\alpha)c} \\ z_2 = c+id & \end{aligned}$$

$$\begin{aligned} \alpha f(z_1) + (1-\alpha)f(z_2) &= \alpha \left(\frac{|b|}{a} - 1 \right) + (1-\alpha) \left(\frac{|d|}{c} - 1 \right) \\ (1) \leq (2) &= \frac{\alpha |b|}{a} - \alpha + \frac{(1-\alpha)|d|}{c} - 1 + \alpha \end{aligned}$$

$$(1) - (2) \quad (2) = \frac{\alpha |b|}{a} + \frac{(1-\alpha)|d|}{c} - 1$$

$$\begin{aligned} (1) - (2) &= \frac{|\alpha b + (1-\alpha)d|}{\alpha a + (1-\alpha)c} - \frac{\alpha |b|}{a} - \frac{(1-\alpha)|d|}{c} \\ &= \frac{ac |\alpha b + (1-\alpha)d| - \alpha |b| (1-\alpha)c - (1-\alpha)|d| (\alpha a + (1-\alpha)c)}{(\alpha a + (1-\alpha)c)ac} \\ &\quad \underbrace{\geq 0}_{\text{inégalité triangulaire}} \end{aligned}$$

$$\begin{aligned} ac |\alpha b + (1-\alpha)d| - \alpha |b| (1-\alpha)c - (1-\alpha)|d| (\alpha a + (1-\alpha)c) &\leq ac \alpha |b| + ac (1-\alpha) |d| \\ &\quad - \alpha |b| (\alpha a + (1-\alpha)c) c - (1-\alpha) |d| (\alpha a + (1-\alpha)c) a \\ &= \alpha |b| c \left[a - (\alpha a + (1-\alpha)c) \right] + a (1-\alpha) |d| \left[c - (\alpha a + (1-\alpha)c) \right] \\ &= ac \alpha |b| + ac (1-\alpha) |d| - \alpha^2 |b| ac - \alpha |b| (1-\alpha) c^2 - (1-\alpha) a^2 |d| a - (1-\alpha)^2 |d| ac \end{aligned}$$

$$f\left(\begin{pmatrix} x_1 \\ x_2 \end{pmatrix}\right) = \frac{|x_2|}{x_1} - 1 \quad \frac{\partial f}{\partial x_1} = -\frac{|x_2|}{x_1^2} \quad \frac{\partial f}{\partial x_2} = \frac{\text{sign}(x_2)}{x_1}$$

$$\frac{\partial^2 f}{\partial x_1^2} = \frac{2|x_2|}{x_1^3} \quad \frac{\partial^2 f}{\partial x_2^2} = \frac{\delta(x_2)}{x_1}$$

$$\frac{\partial^2 f}{\partial x_1 \partial x_2} = -\frac{\text{sign}(x_2)}{x_1^2} \quad \frac{\partial^2 f}{\partial x_2 \partial x_1} = -\frac{\text{sign}(x_2)}{x_1^2}$$

$\delta(x)$ fonction
disac $\begin{cases} \rightarrow +\infty \text{ en } 0 \\ 0 \text{ sinon} \end{cases}$

$$\text{Hess} : \begin{pmatrix} \frac{2|x_2|}{x_1^3} & -\frac{\text{sign}(x_2)}{x_1^2} \\ -\frac{\text{sign}(x_2)}{x_1^2} & \frac{\delta(x_2)}{x_1} \end{pmatrix}$$

$$\text{trace}(\text{Hess}) = \sum \lambda_i = \frac{2|x_2|}{x_1^3} + \frac{\delta(x_2)}{x_1}$$

≥ 0 car $x_1 > 0$ par déf
de l'espace d'entrée de f

$$\det(\text{Hes}) = \pi \lambda_i = \frac{2|x_2|}{x_1^4} \delta(x_2) - \left[\frac{\text{sign}(x_2)^2}{(x_1)^4} \right] \underset{x_1 x_2 \neq 0}{\leq} 0$$

non convexe car n'importe
de départ

amplification $D \in M_{n,n}(\mathbb{C})$, $d_j = r_j e^{i\varphi_j}$
se limiter à $r_j \geq 0$ et $\varphi_j \in J - \frac{\pi}{4}, \frac{\pi}{4} \left[$
pour écrire une solution en $\argmin_{\underline{x}} \|\underline{x}\|^2$

$$d_j = r_j e^{i\varphi_j} = a_j + i b_j$$

$$|b| < a$$

$$|b| - a < 0$$

$$f \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = |x_1| - x_2 \quad \frac{\partial f}{\partial x_1} = \text{sign}(x_1)$$

$$\frac{\partial f}{\partial x_2} = -1$$

$$\frac{\partial^2 f}{\partial x_1^2} = \delta(x_1) \quad \frac{\partial^2 f}{\partial x_1 \partial x_2} = 0$$

$$\frac{\partial^2 f}{\partial x_2^2} = 0$$

$$\text{Hes} = \begin{pmatrix} \delta(x_1) & 0 \\ 0 & 0 \end{pmatrix}$$

$$\text{trace} = \delta(x_1) = \sum \lambda_i = \begin{cases} r_j \text{ si } x_1 = 0 \\ 0 \text{ sinon} \end{cases}$$

$$\det(\text{Hes}) = \delta(x_1) = \pi \lambda_i = 0 \quad \forall x_1$$

$$\Leftrightarrow 1 \text{ des } \lambda_i = 0$$

donc Convexe

$$\underline{\sigma}^* = \arg\min \|\underline{\sigma} - \underline{R}\|_2^2$$

$$\sigma_j = r_j e^{i\varphi_j} \quad \forall j \in [r; k]$$

$$r_j > 0$$

$$\varphi_j \in \left]-\frac{\pi}{4}; \frac{\pi}{4}\right[$$

$$\begin{aligned} \|\underline{\sigma} - \underline{R}\|_2^2 &= \sum_{j=1}^k \left[\operatorname{Re}(\sigma_j s_j - R_j) \right]^2 + \left[\operatorname{Im}(\sigma_j s_j - R_j) \right]^2 \\ &= \sum_{j=1}^k \left[r_j \operatorname{Re}(e^{i\varphi_j} s_j) - \operatorname{Re}(R_j) \right]^2 + \left[r_j \operatorname{Im}(e^{i\varphi_j} s_j) - \operatorname{Im}(R_j) \right]^2 \\ \text{s.t. } & r_j > 0, \quad \varphi_j > -\frac{\pi}{4}, \quad \varphi_j < \frac{\pi}{4} \\ & -r_j < 0, \quad -\varphi_j - \frac{\pi}{4} < 0, \quad \varphi_j - \frac{\pi}{4} < 0 \end{aligned}$$

$$= \sum_{j=1}^K \left\{ r_j \left(\cos \varphi_j R_e(s_j) - \sin \varphi_j I_m(s_j) \right) \cdot R_e(R_j) \right\}^2 + \left[r_j \left(\cos \varphi_j I_m(s_j) + \sin \varphi_j R_e(s_j) \right) - I_m(R_j) \right]^2$$

$$\rho(r_1, \dots, r_K, \varphi_1, \dots, \varphi_K) = \| \underline{\partial} \otimes \underline{s} - \underline{R} \|_2^2 - \sum_{j=1}^K \lambda_j r_j - \sum_{j=1}^K \left(\varphi_j + \frac{\pi}{4} \right) \alpha_j + \sum_{j=1}^K \left(\varphi_j - \frac{\pi}{4} \right) \beta_j$$

$$\underbrace{\frac{\partial \rho(r, \varphi)}{\partial r_j}}_{\partial \varphi_j} = 2 R_e(e^{i\varphi_j} s_j) \left[r_j R_e(e^{i\varphi_j} s_j) - R_e(R_j) \right] + 2 I_m(e^{i\varphi_j} s_j) \left[r_j I_m(e^{i\varphi_j} s_j) - I_m(R_j) \right] - \lambda_j$$

$$\begin{aligned} \frac{\partial}{\partial \varphi_j} R_e(d_j s_j - R_j) &= \frac{\partial}{\partial \varphi_j} r_j \cos \varphi_j R_e(s_j) - r_j \sin \varphi_j I_m(s_j) \\ &= -r_j R_e(s_j) \sin \varphi_j - r_j I_m(s_j) \cos \varphi_j \\ &= -r_j I_m(e^{i\varphi_j}) \end{aligned}$$

$$\begin{aligned} \frac{\partial}{\partial \varphi_j} I_m(d_j s_j - R_j) &= \frac{\partial}{\partial \varphi_j} r_j \cos \varphi_j I_m(s_j) + r_j \sin \varphi_j R_e(s_j) \\ &= -r_j I_m(s_j) \sin \varphi_j + r_j R_e(s_j) \cos \varphi_j \\ &= r_j R_e(e^{i\varphi_j} s_j) \end{aligned}$$

$$\begin{aligned} \frac{\partial \rho(r, \varphi)}{\partial \varphi_j} &= -2 r_j I_m(e^{i\varphi_j}) \left[r_j R_e(e^{i\varphi_j} s_j) - R_e(R_j) \right] + \\ &\quad 2 r_j R_e(e^{i\varphi_j} s_j) \left[r_j I_m(e^{i\varphi_j} s_j) - I_m(R_j) \right] - \alpha_j + \beta_j \end{aligned}$$

$$\begin{aligned} \frac{\partial \rho(r, \varphi)}{\partial \varphi_j} = 0 &\Leftrightarrow \frac{\alpha_j}{2} = r_j \left(R_e(e^{i\varphi_j} s_j)^2 + I_m(e^{i\varphi_j} s_j)^2 \right) - R_e(e^{i\varphi_j} s_j) R_e(R_j) \\ &\quad - I_m(e^{i\varphi_j} s_j) I_m(R_j) \\ &\Leftrightarrow r_j = \frac{\frac{\alpha_j}{2} + R_e(e^{i\varphi_j} s_j) R_e(R_j) + I_m(e^{i\varphi_j} s_j) I_m(R_j)}{R_e(e^{i\varphi_j} s_j)^2 + I_m(e^{i\varphi_j} s_j)^2} \end{aligned}$$

$$\begin{aligned} -\alpha_j &= 0 \Rightarrow \begin{cases} \text{soit } \alpha_j = 0 \text{ et } \lambda \geq 0 \\ \lambda > 0 \end{cases} \\ &\quad \begin{cases} \text{soit } \lambda = 0 \text{ et } -\alpha_j \leq 0 \end{cases} \end{aligned}$$

$$\alpha f = \arctan \left(0, \left[\operatorname{Re}(e^{i\psi_{sl}}) \operatorname{Re}(R_f) + \operatorname{Im}(e^{i\psi_{sl}}) \operatorname{Im}(R_f) \right] \right)$$

$$\frac{\partial f(\alpha, \beta)}{\partial \beta} = 0 \Leftrightarrow -2 \alpha \operatorname{Im}(e^{i\psi_{sl}}) \left[\alpha \operatorname{Re}(e^{i\psi_{sl}}) \cdot \operatorname{Re}(R_f) \right] + 2 \alpha \operatorname{Re}(e^{i\psi_{sl}}) \left[\alpha \operatorname{Im}(e^{i\psi_{sl}}) - \operatorname{Im}(R_f) \right] - \alpha l + \beta_j = 0$$

$$\Leftrightarrow -2 \alpha^2 \operatorname{Im}(e^{i\psi_{sl}}) \operatorname{Re}(e^{i\psi_{sl}}) + 2 \alpha \operatorname{Im}(e^{i\psi_{sl}}) \operatorname{Re}(R_f) + 2 \alpha^2 \operatorname{Re}(e^{i\psi_{sl}}) \operatorname{Im}(e^{i\psi_{sl}}) - 2 \alpha \operatorname{Re}(e^{i\psi_{sl}}) \operatorname{Im}(R_f) - \alpha l + \beta_j = 0$$

$$\alpha l \operatorname{Im}(e^{i\psi_{sl}}) \operatorname{Re}(R_f) + \frac{\beta_j}{2} = \alpha l \operatorname{Re}(e^{i\psi_{sl}}) \operatorname{Im}(R_f) + \frac{\alpha l}{2}$$

Cf. shared phase

* si $\alpha f = 0$, alors ψ_{sl} n'est pas d'intérêt
 $(\Rightarrow \operatorname{Re}(e^{i\psi_{sl}}) \operatorname{Re}(R_f) + \operatorname{Im}(e^{i\psi_{sl}}) \operatorname{Im}(R_f) \leq 0)$

* sinon $\alpha f = \operatorname{Re}(e^{i\psi_{sl}}) \operatorname{Re}(R_f) + \operatorname{Im}(e^{i\psi_{sl}}) \operatorname{Im}(R_f)$
 et on a
 $= [\cos \psi \operatorname{Re}(sl) - \sin \psi \operatorname{Im}(sl)] \operatorname{Re}(R_f) + [\cos \psi \operatorname{Im}(sl) + \sin \psi \operatorname{Re}(sl)] \operatorname{Im}(R_f)$
 $= \cos \psi \alpha f + \sin \psi \beta_j$

$$\alpha l \operatorname{Im}(e^{i\psi_{sl}}) \operatorname{Re}(R_f) + \frac{\beta_j}{2} = \alpha l \operatorname{Re}(e^{i\psi_{sl}}) \operatorname{Im}(R_f) + \frac{\alpha l}{2}$$

$$\cos(2\psi_{sl}) \alpha f \beta_j + \frac{\beta_j}{2} = \frac{1}{2} \sin(2\psi_{sl}) (\alpha f^2 - \beta_j^2) + \frac{\alpha l}{2}$$

* si $\beta_j = 0$ et $\alpha f = 0$

$$\tan(2\psi_{sl}) = \frac{2 \alpha f \beta_j}{\alpha f^2 - \beta_j^2} = \frac{\operatorname{Im}(sl) \operatorname{Re}(sl) [\operatorname{Im}(R_f)^2 - \operatorname{Re}(R_f)^2]}{2 \operatorname{Re}(R_f) \operatorname{Im}(R_f) \operatorname{Re}(sl) \operatorname{Im}(sl)}$$

$$\psi_{sl} = \frac{1}{2} \arctan \left(\frac{2 \alpha f \beta_j}{\alpha f^2 - \beta_j^2} \right)$$

Cf page 12

$$\sim \left(\varphi_l + \frac{\pi}{4} \right) \alpha_l = 0 \Rightarrow \begin{cases} \alpha_l = 0 \text{ et } -\left(\varphi_l + \frac{\pi}{4} \right) \leq 0 \\ \text{ou} \\ -\left(\varphi_l + \frac{\pi}{4} \right) = 0 \text{ et } \alpha_l \geq 0 \\ \varphi_l = -\frac{\pi}{4} \end{cases}$$

$$\left(\varphi_l - \frac{\pi}{4} \right) \beta_l = 0 \Rightarrow \begin{cases} \beta_l = 0 \text{ et } \varphi_l - \frac{\pi}{4} \leq 0 \\ \text{ou} \\ \varphi_l - \frac{\pi}{4} = 0 \text{ et } \beta_l \geq 0 \\ \varphi_l = \frac{\pi}{4} \end{cases}$$

$$\varphi^* = \max \left(-\frac{\pi}{4}, \min \left(\frac{\pi}{4}, \varphi_l \right) \right)$$

X

$$\underline{\vartheta}^* = \arg \min \| \underline{\vartheta} \underline{s} - \underline{R} \|_2^2$$

$$\vartheta_j = a_j + i b_j \quad |b_j| \leq a_j$$

$$\| \underline{\vartheta} \underline{s} - \underline{R} \|_2^2 = \sum_{j=1}^k \operatorname{Re}(\vartheta_j s_j \cdot R_j)^2 + \operatorname{Im}(\vartheta_j s_j \cdot R_j)^2$$

$$\begin{aligned} \operatorname{Re}(is_j) &= \sum_{j=1}^k \left[\operatorname{Re}(a_j s_j + b_j is_j) - \operatorname{Re}(R_j) \right]^2 + \left[\operatorname{Im}(a_j s_j + b_j is_j) - \operatorname{Im}(R_j) \right]^2 \\ &\geq -\operatorname{Im}(s_j) \\ \operatorname{Im}(is_j) &= \sum_{j=1}^k \left[a_j \operatorname{Re}(s_j) + b_j \operatorname{Re}(is_j) - \operatorname{Re}(R_j) \right]^2 + \left[a_j \operatorname{Im}(s_j) + b_j \operatorname{Im}(is_j) - \operatorname{Im}(R_j) \right]^2 \\ &= \operatorname{Re}(s_j) \end{aligned}$$

s.t. $|b_j| \leq a_j \quad \forall j \in \{1, k\}$

$$|b_j| - a_j \leq 0$$

$$\begin{aligned} \mathcal{L}(a, b, \lambda) &= \sum_{j=1}^k \left[a_j \operatorname{Re}(s_j) - b_j \operatorname{Im}(s_j) - \operatorname{Re}(R_j) \right]^2 + \left[a_j \operatorname{Im}(s_j) + b_j \operatorname{Re}(s_j) - \operatorname{Im}(R_j) \right]^2 \\ &\quad + \lambda_j (|b_j| - a_j) \end{aligned}$$

$$\frac{\partial \mathcal{L}(a, b, \lambda)}{\partial a p} = 2 [a p R_e(s p) - b p I_m(\alpha) - R_e(R p)] R_e(s p) \\ + 2 [a p I_m(s p) + b p R_e(s p) - I_m(R p)] I_m(s p) \\ - \lambda p$$

$$\frac{\partial \mathcal{L}(a, b, \lambda)}{\partial b p} = 2 [a p R_e(s p) - b p I_m(\alpha) - R_e(R p)] (-I_m(\alpha)) \\ + 2 [a p I_m(s p) + b p R_e(s p) - I_m(R p)] R_e(\alpha) \\ + \lambda p \operatorname{sgn}(b p)$$

$$\lambda p (|b p| - a p) = 0 \Rightarrow \begin{cases} \lambda p = 0 & \text{et } |b p| - a p \leq 0 \\ |b p| \leq a p \\ |b p| - a p = 0 & \text{et } \lambda p \geq 0 \\ |b p| = a p \end{cases}$$

* soit $\lambda p = 0$

$$\frac{\partial \mathcal{L}(a, b, \lambda)}{\partial a} = 0 \Leftrightarrow 2 [a p R_e(s p) - b p I_m(\alpha) - R_e(R p)] R_e(s p) \\ + 2 [a p I_m(s p) + b p R_e(s p) - I_m(R p)] I_m(s p) \\ - \lambda p = 0$$

$$\Leftrightarrow a p R_e(\alpha)^2 - b p I_m(\alpha) R_e(s p) - R_e(R p) R_e(s p) + a p I_m(\alpha)^2 + b p R_e(s p) I_m(\alpha) \\ - I_m(R p) I_m(s p) = 0$$

$$a p (R_e(s p)^2 + I_m(s p)^2) = R_e(R p) R_e(s p) + R_e(R p) R_e(s p) \\ \underbrace{1 \text{ car } Q \text{-PSK sur cercle unité}}$$

$$\frac{\partial \mathcal{L}(\underline{a}, \underline{b}, \lambda)}{\partial b\ell} = 0 \iff \begin{aligned} & 2 \left[a\ell \operatorname{Re}(s\ell) - b\ell \operatorname{Im}(s\ell) - \operatorname{Re}(R\ell) \right] (-\operatorname{Im}(s\ell)) \\ & + 2 \left[a\ell \operatorname{Im}(s\ell) + b\ell \operatorname{Re}(s\ell) - \operatorname{Im}(R\ell) \right] \operatorname{Re}(s\ell) \\ & + \lambda \ell \underbrace{\operatorname{sign}(b\ell)}_{\text{1 can decide mintr}} = 0 \end{aligned}$$

$$\iff -a\ell \operatorname{Re}(s\ell) \operatorname{Im}(s\ell) + b\ell \operatorname{Im}(s\ell)^2 + \operatorname{Re}(R\ell) \operatorname{Im}(s\ell)$$

$$+ a\ell \operatorname{Re}(s\ell) \operatorname{Im}(s\ell) + b\ell \operatorname{Re}(s\ell)^2 - \operatorname{Im}(R\ell) \operatorname{Re}(s\ell) = 0$$

$$b\ell \left(\operatorname{Re}(s\ell)^2 + \operatorname{Im}(s\ell)^2 \right) = \operatorname{Re}(s\ell) \operatorname{Im}(R\ell) - \operatorname{Re}(R\ell) \operatorname{Im}(s\ell)$$

1 can decide mintr

$$a + ib = r e^{i\varphi}$$

$$= r \cos \varphi + i r \sin \varphi \implies a = r \cos \varphi$$

$$b = r \sin \varphi$$

$$r = \frac{a+ib}{e^{i\varphi}} = (a+ib) e^{-i\varphi} = (a+ib) (\cos(-\varphi) + i \sin(-\varphi))$$

$$= a \cos(\varphi) - i a \sin(\varphi) + i b \cos(\varphi) + b \sin(\varphi)$$

$$= a \cos(\varphi) + b \sin(\varphi) - i r \cos(\varphi) \sin(\varphi) + i r \sin(\varphi) \cos(\varphi)$$

d'au més resultats.

*

$$\text{soit } \lambda \ell \geq 0 \quad |b\ell| = a\ell$$

$$\frac{\partial \mathcal{L}(\underline{a}, \underline{b}, \lambda)}{\partial a} = 0 \iff \begin{aligned} & 2 \left[a\ell \operatorname{Re}(s\ell) - b\ell \operatorname{Im}(s\ell) - \operatorname{Re}(R\ell) \right] \operatorname{Re}(s\ell) \\ & + 2 \left[a\ell \operatorname{Im}(s\ell) + b\ell \operatorname{Re}(s\ell) - \operatorname{Im}(R\ell) \right] \operatorname{Im}(s\ell) \\ & - \lambda \ell = 0 \quad (1) \end{aligned}$$

$$a\ell \underbrace{\left[\operatorname{Re}(s\ell)^2 + \operatorname{Im}(s\ell)^2 \right]}_1 = \frac{\lambda \ell}{2} + \operatorname{Re}(R\ell) \operatorname{Re}(s\ell) + \operatorname{Im}(R\ell) \operatorname{Im}(s\ell)$$

$$\frac{\partial \mathcal{L}(\underline{a}, \underline{b}, \lambda)}{\partial b\ell} = 0 \iff \begin{aligned} & b\ell \underbrace{\left[\operatorname{Im}(s\ell)^2 + \operatorname{Re}(s\ell)^2 \right]}_{\approx 1} + \lambda \ell \underbrace{\operatorname{sign}(b\ell)}_{2} \\ & = \operatorname{Re}(s\ell) \operatorname{Im}(R\ell) - \operatorname{Im}(s\ell) \operatorname{Re}(R\ell) \quad (2) \end{aligned}$$

$$(1) \left\{ \begin{array}{l} al = \frac{\lambda l}{2} + Re(\lambda l)Re(sl) + Im(\lambda l)Im(sl) = \frac{\lambda l}{2} + al^* \quad |bl| = sign(bl) \times bl \\ bl + \frac{\lambda l \underbrace{sign(bl)}_{2}}{2} = Re(sl)Im(\lambda l) - Im(sl)Re(\lambda l) = bl^* \end{array} \right.$$

$$(3) \left| bl \right| = al \quad sign(0) \approx 0$$

$$(2) bl + (al - al^*)sign(bl) = bl^*$$

$$\Leftrightarrow bl + (sign(bl)bl - al^*)sign(bl) = bl^*$$

$$* \text{ si } bl = 0 \quad sign(bl) = 0$$

$$al = 0 = \frac{\lambda l}{2} + al^* \quad \text{et} \quad bl^* = 0$$

$$* \text{ si } bl \neq 0 \quad bl + bl \underbrace{sign(bl)^2}_{=1} - al^*sign(bl) = bl^*$$

$$\hookrightarrow \text{si } bl > 0 \quad sign(bl) = 1$$

$$2bl - al^* = bl^*$$

$$bl = \frac{al^* + bl^*}{2}$$

$$\frac{al^* + bl^*}{2} + \frac{\lambda l}{2} = bl^* \Rightarrow \lambda l = bl^* - al^*$$

$$al = \frac{bl^* - al^*}{2} + al^* = \frac{bl^* + al^*}{2} \quad \checkmark$$

$$\hookrightarrow \text{ si } bl < 0 \quad sign(bl) = -1$$

$$2bl + al^* = bl^*$$

$$bl = \frac{bl^* - al^*}{2}$$

$$\frac{bl^* - al^*}{2} - \frac{\lambda l}{2} = bl^* \Rightarrow bl^* - al^* = 2bl^* + \lambda l$$

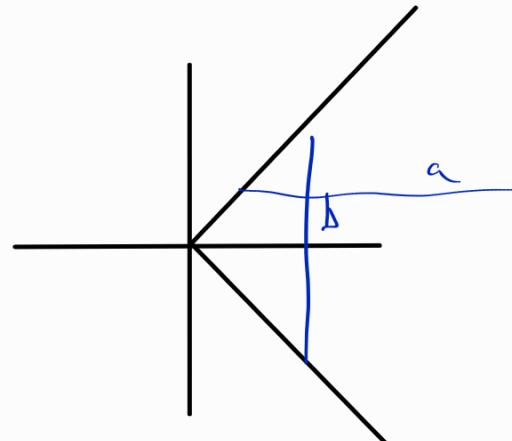
$$\lambda l = -bl^* - al^*$$

$$al = \frac{-bl^* - al^*}{2} + al^* = \frac{-bl^* + al^*}{2} \quad \checkmark$$

$$\left\{
 \begin{array}{l}
 \text{pos} = \begin{cases} a\ell = \operatorname{Re}(s\ell)\operatorname{Re}(R\ell) + \operatorname{Im}(s\ell)\operatorname{Im}(R\ell) & \text{si } |b\ell| < a\ell \\ b\ell = \operatorname{Re}(s\ell)\operatorname{Im}(R\ell) - \operatorname{Re}(R\ell)\operatorname{Im}(s\ell) & \end{cases} \\
 \text{neg} = \begin{cases} a\ell = b\ell = \frac{\operatorname{Re}(s\ell)\operatorname{Re}(R\ell) + \operatorname{Im}(s\ell)\operatorname{Im}(R\ell) + \operatorname{Re}(s\ell)\operatorname{Im}(R\ell) - \operatorname{Re}(R\ell)\operatorname{Im}(s\ell)}{2} & \text{si } b\ell = a\ell \\ a\ell = -b\ell = \frac{\operatorname{Re}(s\ell)\operatorname{Re}(R\ell) + \operatorname{Im}(s\ell)\operatorname{Im}(R\ell) - \operatorname{Re}(s\ell)\operatorname{Im}(R\ell) + \operatorname{Re}(R\ell)\operatorname{Im}(s\ell)}{2} & \text{si } b\ell = -a\ell \end{cases}
 \end{array}
 \right.$$

$$b\ell = \min \left(\text{pos}, \max \left(\text{neg}, \operatorname{Re}(s\ell)\operatorname{Im}(R\ell) - \operatorname{Re}(R\ell)\operatorname{Im}(s\ell) \right) \right)$$

$$a\ell = \max \left(b\ell, \operatorname{Re}(s\ell)\operatorname{Re}(R\ell) + \operatorname{Im}(s\ell)\operatorname{Re}(R\ell) \right)$$



i) a) Démontrer $\max(a;b) + \min(a;b) = a+b$

b) Démontrer $\max(a;b) - \min(a;b) = |a-b|$

i) Déduire $\min(a;b) = \frac{a+b-|a-b|}{2}$ et $\max(a;b) = \frac{a+b+|a-b|}{2}$

On unless $\forall j \in [1; N]$, $\delta_j = r_j e^{i\varphi_j} = r_j (\cos \varphi_j + i \sin \varphi_j)$

$$\text{onec } r_j = \max \left(C, \Re(e^{i\varphi_j}) \Re(R_j) + \Im(e^{i\varphi_j}) \Im(R_j) \right)$$

$$\text{et } \varphi_j = \max \left(-\frac{\pi}{4}, \min \left(\frac{\pi}{4}, \arctan \left[\frac{\Re(\delta_l) \Im(R_l) - \Im(\delta_l) \Re(R_l)}{\Re(\delta_l) \Re(R_l) + \Im(\delta_l) \Im(R_l)} \right] \right) \right)$$

* Si $\beta_\ell = \alpha_\ell = 0$ et $\alpha_l \neq 0$

$$\alpha_l \Im(e^{i\varphi_l}) \Re(R_l) + \frac{\beta_l}{2} = \alpha_l \Re(e^{i\varphi_l}) \Im(R_l) + \frac{\alpha_l}{2}$$

~~$$\alpha_l \Im(e^{i\varphi_l}) \Re(R_l) = \alpha_l \Re(e^{i\varphi_l}) \Im(R_l)$$~~

$$\left[\cos \varphi \Im(\delta_l) + \sin \varphi \Re(\delta_l) \right] \Re(R_l) = \left[\cos \varphi \Re(\delta_l) - \sin \varphi \Im(\delta_l) \right] \Im(R_l)$$

$$\sin \varphi \left[\Re(\delta_l) \Re(R_l) + \Im(\delta_l) \Im(R_l) \right] = \cos \varphi \left[\Re(\delta_l) \Im(R_l) - \Im(\delta_l) \Re(R_l) \right]$$

$$\tan(\varphi) = \frac{\Re(\delta_l) \Im(R_l) - \Im(\delta_l) \Re(R_l)}{\Re(\delta_l) \Re(R_l) + \Im(\delta_l) \Im(R_l)}$$

$$\varphi = \arctan \left[\frac{\Re(\delta_l) \Im(R_l) - \Im(\delta_l) \Re(R_l)}{\Re(\delta_l) \Re(R_l) + \Im(\delta_l) \Im(R_l)} \right]$$

onec $\min(x, y) = \frac{x + y - |x - y|}{2}$ $\max(0, x) = x \times U(x)$

$$U = \begin{cases} 1 & \text{si } x > 0 \\ 0 & \text{sinon} \end{cases}$$

$$\text{et } \max(x, y) = \frac{x + y + |x - y|}{2}$$

On cherche $\underline{x}^* = \underset{\underline{x}}{\operatorname{argmin}} \| \underline{\mathcal{D}} \otimes \underline{\mathcal{I}} - \underline{R} \|_2^2$ $\underline{R} = H \underline{x}$

$$R_i = \sum_{m=1}^M H_{ij_m} x_m$$

$$\begin{aligned} f(x) &= \sum_{i=1}^K \left(\alpha_i \left[\cos \varphi_i \Re(s_i) - \sin \varphi_i \Im(s_i) \right] - \Re(r_i) \right)^2 \\ &\quad + \left(\alpha_i \left[\cos \varphi_i \Im(s_i) + \sin \varphi_i \Re(s_i) \right] - \Im(r_i) \right)^2 \\ &= \sum_{i=1}^K \text{RMSE}_i^2 + \text{IMSE}_i^2 \end{aligned}$$

$$\frac{\partial f(x)}{\partial \operatorname{Re}(x)} = 2 \sum_{i=1}^n \operatorname{RMSE}_i \frac{\partial}{\partial \operatorname{Re}(x)} \operatorname{RMSE}_i + 2 \sum_{i=1}^n \operatorname{IMSE}_i \frac{\partial}{\partial \operatorname{Re}(x)} \operatorname{IMSE}_i$$

$$\begin{aligned} & \operatorname{Re}\left(e^{i \varphi_i} s_i\right) \operatorname{Re}(R_i) + \operatorname{Im}\left(e^{i \varphi_i} s_i\right) \operatorname{Im}(R_i) \\ &= \cos(\varphi_i) [\operatorname{Re}(s_i) \operatorname{Re}(R_i) + \operatorname{Im}(s_i) \operatorname{Im}(R_i)] + \sin(\varphi_i) [\operatorname{Re}(s_i) \operatorname{Im}(R_i) - \operatorname{Re}(R_i) \operatorname{Im}(s_i)] \\ &= \cos \varphi_i a_i + \sin \varphi_i b_i \end{aligned}$$

$$\operatorname{RMSE}_i = \max \left(0, \cos(\varphi_i a_i + \sin \varphi_i b_i)\left[\cos \varphi_i \operatorname{Re}(s_i) - \sin \varphi_i \operatorname{Im}(s_i)\right] - \operatorname{Re}(R_i)\right)$$

$$(*) \cancel{*} \quad \frac{\partial}{\partial \operatorname{Re}(x)} - \sum_{j=1}^M \operatorname{Re}(H_{i,j} x_j) = - \sum_{j=1}^M \frac{\partial}{\partial \operatorname{Re}(x)} \operatorname{Re}(H_{i,j}) \operatorname{Re}(x_j) - \operatorname{Im}(H_{i,j}) \operatorname{Im}(x_j) \\ = - \operatorname{Re}(H_{i,l}) = \frac{\partial}{\partial \operatorname{Re}(x)} - \operatorname{Re}(R_i)$$

$$\cancel{*} \quad \frac{\partial}{\partial \operatorname{Re}(x)} - \operatorname{Im}\left(\sum_{m=1}^M H_{i,m} x_m\right) \\ = - \frac{\partial}{\partial \operatorname{Re}(x)} \sum_{m=1}^M \operatorname{Re}(H_{i,m}) \operatorname{Im}(x_m) + \operatorname{Im}(H_{i,m}) \operatorname{Re}(x_m) \\ = - \operatorname{Im}(H_{i,l}) = \frac{\partial}{\partial \operatorname{Re}(x)} - \operatorname{Im}(R_i)$$

$$\cancel{*} \quad \frac{\partial}{\partial \operatorname{Re}(x)} a_i = \operatorname{Re}(s_i) \operatorname{Re}(H_{i,l}) + \operatorname{Im}(s_i) \operatorname{Im}(H_{i,l})$$

$$\cancel{*} \quad \frac{\partial}{\partial \operatorname{Re}(x)} b_i = \operatorname{Re}(s_i) \operatorname{Im}(H_{i,l}) - \operatorname{Im}(s_i) \operatorname{Re}(H_{i,l})$$

$$\cancel{*} \quad \frac{\partial}{\partial \operatorname{Re}(x)} \operatorname{arctan} \left(\left[\frac{\operatorname{Re}(s_i) \operatorname{Im}(R_i) - \operatorname{Im}(s_i) \operatorname{Re}(R_i)}{\operatorname{Re}(s_i) \operatorname{Re}(R_i) + \operatorname{Im}(s_i) \operatorname{Im}(R_i)} \right] \right) = \frac{\partial}{\partial \operatorname{Re}(x)} \operatorname{arctan} \left(\frac{b_i}{a_i} \right)$$

$$= \frac{1}{1 + \left(\frac{b_i}{a_i}\right)^2} \times \frac{\partial}{\partial \operatorname{Re}(x)} \frac{b_i}{a_i} = \frac{1}{1 + \left(\frac{b_i}{a_i}\right)^2} \times \left[\underbrace{\left(b_i/a_i - b_i/a_i\right)'}_{a_i^2} \right]$$

$$\cancel{\frac{\partial \varphi}{\partial \operatorname{Re}(z)}} = \frac{\partial}{\partial \operatorname{Re}(z)} \frac{\min\left(\frac{\pi}{4}, \arctan\left(\frac{b_i}{a_i}\right)\right) - \frac{\pi}{4} - \left|\min\left(\frac{\pi}{4}, \arctan\left(\frac{b_i}{a_i}\right)\right) + \frac{\pi}{4}\right|}{\frac{\arctan\left(\frac{b_i}{a_i}\right) + \frac{\pi}{4} - \left|\arctan\left(\frac{b_i}{a_i}\right) - \frac{\pi}{4}\right|}{2} - \frac{\pi}{4} - \left|\frac{\arctan\left(\frac{b_i}{a_i}\right) + \frac{\pi}{4} - \left|\arctan\left(\frac{b_i}{a_i}\right) - \frac{\pi}{4}\right|}{2} + \frac{\pi}{4}\right|}$$

$$= \frac{\partial}{\partial \operatorname{Re}(z)} \frac{\arctan\left(\frac{b_i}{a_i}\right) + \frac{\pi}{4}}{2} - \left| \frac{\arctan\left(\frac{b_i}{a_i}\right) - \frac{\pi}{4}}{2} \right| - \frac{\pi}{8} - \left| \frac{\arctan\left(\frac{b_i}{a_i}\right) + \frac{\pi}{4} - \left|\arctan\left(\frac{b_i}{a_i}\right) - \frac{\pi}{4}\right|}{2} + \frac{\pi}{8} \right|$$

$$P(g)' = g' P'(g)$$

$$(A) -\frac{1}{2} \frac{\partial}{\partial \operatorname{Re}(z)} \left| \arctan\left(\frac{b_i}{a_i}\right) - \frac{\pi}{4} \right| = -\frac{1}{2} \operatorname{sign}\left(\arctan\left(\frac{b_i}{a_i}\right) - \frac{\pi}{4}\right) \frac{\partial}{\partial \operatorname{Re}(z)} \left(\arctan\left(\frac{b_i}{a_i}\right) - \frac{\pi}{4} \right)$$

$$(B) -\frac{\partial}{\partial \operatorname{Re}(z)} \left| \frac{\arctan\left(\frac{b_i}{a_i}\right) - \left| \arctan\left(\frac{b_i}{a_i}\right) - \frac{\pi}{4} \right|}{2} + \frac{\pi}{4} \right| \\ = -\operatorname{sign}\left(\frac{\arctan\left(\frac{b_i}{a_i}\right) - \left| \arctan\left(\frac{b_i}{a_i}\right) - \frac{\pi}{4} \right|}{2} + \frac{\pi}{4}\right) \frac{\partial}{\partial \operatorname{Re}(z)} \frac{\arctan\left(\frac{b_i}{a_i}\right) - \left| \arctan\left(\frac{b_i}{a_i}\right) - \frac{\pi}{4} \right|}{2} + \frac{\pi}{4}$$

$$= -\operatorname{sign}\left(\frac{\arctan\left(\frac{b_i}{a_i}\right) - \left| \arctan\left(\frac{b_i}{a_i}\right) - \frac{\pi}{4} \right|}{2} + \frac{\pi}{4}\right) \left[\frac{1}{2} \frac{\partial}{\partial \operatorname{Re}(z)} \arctan\left(\frac{b_i}{a_i}\right) - \frac{1}{2} \operatorname{sign}\left(\arctan\left(\frac{b_i}{a_i}\right) - \frac{\pi}{4}\right) \frac{\partial}{\partial \operatorname{Re}(z)} \arctan\left(\frac{b_i}{a_i}\right) \right]$$

$$\cancel{\frac{\partial}{\partial \operatorname{Re}(z)} n_i} = \frac{\partial}{\partial \operatorname{Re}(z)} \max\left(0, \underbrace{\operatorname{Re}(e^{i\varphi_i} s_i) \operatorname{Re}(R_i) + \operatorname{Im}(e^{i\varphi_i} s_i) \operatorname{Im}(n_i)}_{= n_i \text{ tot}}\right)$$

$$= \frac{\partial}{\partial \operatorname{Re}(z)} n_i \text{ tot} \times V(n_i \text{ tot})$$

$$= n_i \text{ tot} \frac{\partial}{\partial \operatorname{Re}(z)} V(n_i \text{ tot}) + V(n_i \text{ tot}) \frac{\partial}{\partial \operatorname{Re}(z)} n_i \text{ tot}$$

$$= V(n_i \text{ tot}) \frac{\partial}{\partial \operatorname{Re}(z)} (\cos \varphi_i a_i + \sin \varphi_i b_i)$$

$$= V(n_i \text{ tot}) \left[\cos \varphi_i \frac{\partial a_i}{\partial \operatorname{Re}(z)} - a_i \sin \varphi_i \frac{\partial \varphi_i}{\partial \operatorname{Re}(z)} + \sin \varphi_i \frac{\partial b_i}{\partial \operatorname{Re}(z)} + b_i \cos \varphi_i \frac{\partial \varphi_i}{\partial \operatorname{Re}(z)} \right]$$

$$\cancel{*} \text{ Dem } \frac{\partial}{\partial \operatorname{Re}(x)} \operatorname{RMSE}_i = \frac{\partial}{\partial \operatorname{Re}(x)} \left[r_i \cos \varphi_i \operatorname{Re}(s_i) - r_i \sin \varphi_i \operatorname{Im}(s_i) \right] - \operatorname{Re}(R_i)$$

$$= \operatorname{Re}(s_i) \left[r_i \left(-\sin \varphi_i \frac{\partial \varphi_i}{\partial \operatorname{Re}(x)} + \cos \varphi_i \frac{\partial r_i}{\partial \operatorname{Re}(x)} \right) - \operatorname{Im}(s_i) \left[r_i \cos \varphi_i \frac{\partial \varphi_i}{\partial \operatorname{Re}(x)} + \sin \varphi_i \frac{\partial r_i}{\partial \operatorname{Re}(x)} \right] - \operatorname{Re}(H_i, l) \right]$$

$$\operatorname{IMSE}_i = r_i \left[\sin \varphi_i \operatorname{Re}(s_i) + \cos \varphi_i \operatorname{Im}(s_i) \right] - \operatorname{Im}(R_i)$$

$$\cancel{*} \text{ Dem } \frac{\partial}{\partial \operatorname{Re}(x)} \operatorname{IMSE}_i = \operatorname{Re}(s_i) \left[r_i \cos \varphi_i \frac{\partial \varphi_i}{\partial \operatorname{Re}(x)} + \sin \varphi_i \frac{\partial r_i}{\partial \operatorname{Re}(x)} \right] \\ + \operatorname{Im}(s_i) \left[r_i \left(-\sin \varphi_i \frac{\partial \varphi_i}{\partial \operatorname{Re}(x)} + \cos \varphi_i \frac{\partial r_i}{\partial \operatorname{Re}(x)} \right) - \operatorname{Im}(H_i, l) \right]$$

$$\cancel{*} \frac{\partial}{\partial \operatorname{Im}(x)} \| \underline{\operatorname{D}} - \underline{R} \|_2^2 = \frac{\partial}{\partial \operatorname{Im}(x)} \sum_{i=1}^k (\operatorname{RMSE}_i)^2 + (\operatorname{IMSE}_i)^2 \\ = \sum_{i=1}^k 2 \operatorname{RMSE}_i \frac{\partial \operatorname{RMSE}_i}{\partial \operatorname{Im}(x)} + 2 \operatorname{IMSE}_i \frac{\partial \operatorname{IMSE}_i}{\partial \operatorname{Im}(x)}$$

$$\operatorname{RMSE}_i = \max(0, \cos(\varphi_i a_i + \operatorname{Im}(\alpha_i)) \left[\cos \varphi_i \operatorname{Re}(s_i) - \sin \varphi_i \operatorname{Im}(s_i) \right] - \operatorname{Re}(R_i))$$

$$\cancel{*} \frac{\partial}{\partial \operatorname{Im}(x)} a_i = \operatorname{Re}(s_i) (-\operatorname{Im}(H_i, l)) + \operatorname{Im}(s_i) \operatorname{Re}(H_i, l)$$

$$\cancel{*} \frac{\partial}{\partial \operatorname{Im}(x)} b_i = \operatorname{Re}(s_i) \operatorname{Re}(H_i, l) + \operatorname{Im}(s_i) \operatorname{Im}(H_i, l)$$

$$\cancel{*} - \sum_{j=1}^n \operatorname{Re}(H_{i,j} x_j) = - \operatorname{Re}(R_i)$$

$$\frac{\partial}{\partial \operatorname{Im}(x)} C = - \sum_{j=1}^M \frac{\partial}{\partial \operatorname{Im}(x)} \operatorname{Re}(H_{i,j}) \operatorname{Re}(x_j) - \operatorname{Im}(H_{i,j}) \operatorname{Im}(x_j) \\ = - (-\operatorname{Im}(H_i, l)) = \operatorname{Im}(H_i, l)$$

$$\cancel{\frac{\partial}{\partial \text{Im}(x_l)} C} = - \frac{\partial}{\partial \text{Im}(x_l)} \sum_{m=1}^M \text{Im}(H_{i,m} x_m) = - \frac{\partial}{\partial \text{Im}(x_l)} \text{Im}(R_i)$$

$$= - \frac{\partial}{\partial \text{Im}(x_l)} \sum_{m=1}^M \text{Re}(H_{i,m}) \text{Im}(x_m) + \text{Im}(H_{i,m}) \text{Re}(x_m)$$

$$= - \text{Re}(H_{i,l})$$

$$\cancel{\frac{\partial}{\partial \text{Im}(x_l)} \arctan \left(\frac{b_i}{a_i} \right)}$$

$$= \frac{1}{1 + \left(\frac{b_i}{a_i} \right)^2} \times \frac{\partial}{\partial \text{Im}(x_l)} \frac{b_i}{a_i} = \frac{1}{1 + \left(\frac{b_i}{a_i} \right)^2} \times \left[\underbrace{\left(b_i \right)' a_i - b_i \left(a_i \right)' a_i^2}_{a_i^2} \right]$$

$$\cancel{\frac{\partial \Psi}{\partial \text{Im}(x_l)}} = \frac{\partial}{\partial \text{Im}(x_l)} \frac{\arctan \left(\frac{b_i}{a_i} \right)}{4} - \frac{1}{2} \text{sign} \left(\arctan \left(\frac{b_i}{a_i} \right) - \frac{\pi}{4} \right) \frac{\partial}{\partial \text{Im}(x_l)} \left(\arctan \left(\frac{b_i}{a_i} \right) - \frac{\pi}{4} \right)$$

$$- \text{sign} \left(\frac{\arctan \left(\frac{b_i}{a_i} \right) - \left| \arctan \left(\frac{b_i}{a_i} \right) - \frac{\pi}{4} \right| + \frac{\pi}{4}}{2} \right) \left[\frac{1}{2} \frac{\partial}{\partial \text{Im}(x_l)} \arctan \left(\frac{b_i}{a_i} \right) - \frac{1}{2} \text{sign} \left(\arctan \left(\frac{b_i}{a_i} \right) - \frac{\pi}{4} \right) \frac{\partial}{\partial \text{Im}(x_l)} \arctan \left(\frac{b_i}{a_i} \right) \right]$$

$$\cancel{\frac{\partial \gamma_i}{\partial \text{Im}(x_l)}}$$

$$= V_{(\gamma_i, \text{tot})} \left[\cos \gamma_i \frac{\partial \gamma_i}{\partial \text{Im}(x_l)} - \gamma_i \sin \gamma_i \frac{\partial \gamma_i}{\partial \text{Im}(x_l)} + \sin \gamma_i \frac{\partial \gamma_i}{\partial \text{Im}(x_l)} + \gamma_i \cos \gamma_i \frac{\partial \gamma_i}{\partial \text{Im}(x_l)} \right]$$

Donc $\frac{\partial}{\partial \text{Im}(x_l)} \text{RMSE}_i =$

$$= \text{Re}(\gamma_i) \left[\gamma_i (-\sin \gamma_i) \frac{\partial \gamma_i}{\partial \text{Im}(x_l)} + \cos \gamma_i \frac{\partial \gamma_i}{\partial \text{Im}(x_l)} \right] - \text{Im}(\gamma_i) \left[\gamma_i \cos \gamma_i \frac{\partial \gamma_i}{\partial \text{Im}(x_l)} + \sin \gamma_i \frac{\partial \gamma_i}{\partial \text{Im}(x_l)} \right] + \text{Im}(H_{i,l})$$

$$\frac{\partial}{\partial \text{Im}(x_l)} \text{IMSE}_i = \text{Re}(\gamma_i) \left[\gamma_i \cos \gamma_i \frac{\partial \gamma_i}{\partial R(x_l)} + \sin \gamma_i \frac{\partial \gamma_i}{\partial R(x_l)} \right]$$

$$+ \text{Im}(\gamma_i) \left[\gamma_i (-\sin \gamma_i) \frac{\partial \gamma_i}{\partial R(x_l)} + \cos \gamma_i \frac{\partial \gamma_i}{\partial R(x_l)} \right] - \text{Re}(H_{i,l})$$

$$\begin{aligned}
\hat{\underline{x}} &= \arg \min \| \underline{s} - H \underline{x} \|_2^2 \\
&= \left(\underline{s} - \underline{x}^\dagger H^\dagger \right)^\dagger \left(\underline{s} - H \underline{x} \right) \\
&= \underline{s}^\dagger \underline{s} - \underline{x}^\dagger H^\dagger \underline{s} - \underline{s}^\dagger H \underline{x} + \underline{x}^\dagger H^\dagger H \underline{x} \\
&\stackrel{\partial}{\cancel{\underline{x}}} = - \underline{s}^\dagger H + H^\dagger H \underline{x}
\end{aligned}$$