BRS-AWD v1.32 Drive

Evolutions

Indice	Date	Description de l'évolution	Auteur

Rédacteur	Responsable	Qualité
FBR	FBR	FBR

1.0	01/08/2023	Création / POC	FBR
1.1	17/08/2023	POW	AVJ
1.2	20/08/2023	Release	FBR
1.32	11/09/2023	Manual 1.0 release	FBR

Etat	1.0	1.1	1.2
Statut	Fonctionnel POC	Fonctionnel, POW	Fonctionnel Release

INTRO:

The BRS-AWD Drives feature an integrated 4 motors solution, adaptable to ANY Vcore 3.x iteration, with or without enclosure, without any structural modification needed. The time to set it up will be between 1-2 hours depending the skill level.

This upgrade is based on high quality hardware, with a specific attention to the quality of the motion; Precision Shoulder bolts, ABEC 5-7 Bearings, and Precision GT2 pulleys! Motors are silent with the decoupling (you can use N17 dampers on this mod, like the M2 L3ver).

BOM :

Printed parts list

Lower part R (All variations)	X1
Lower part L (All variations)	X1
Upper Part R (All variations)	X1
Upper Part L (All variations)	X1
Bearing Lockers (All variations)	X3
Nema holder	X2
Nema Mount	X2

Hardware

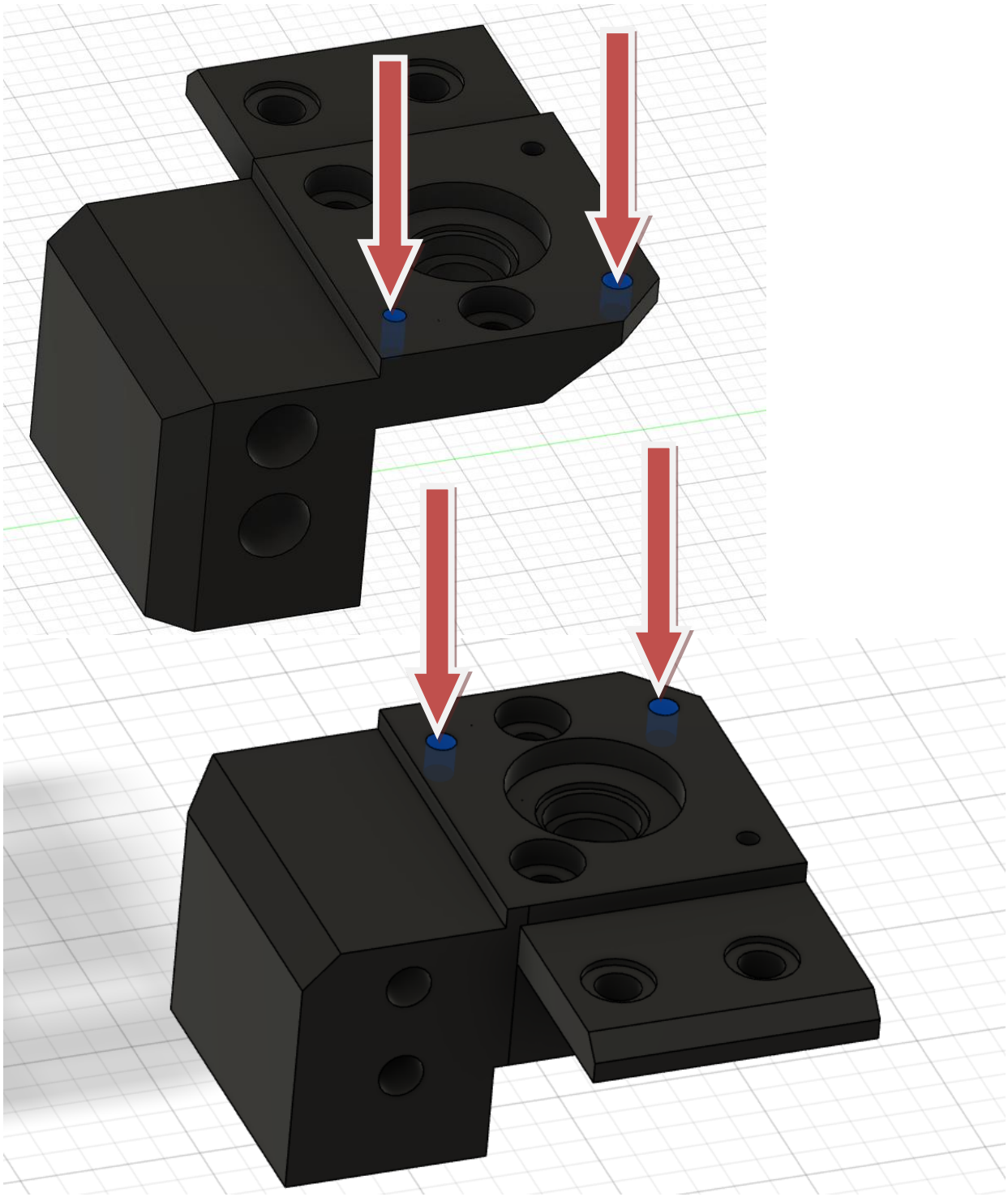
Heat inserts M4 Short	X4
Heat inserts M3 short	X16
M6x40 (For open version)	X4
Tnut M6	X16
F695-rs	X12
M3x12	X6
Shoulder bolt 5x35mm m4	X4
8x5x1mm microshim	X5
GT2 9mm Pulley	X2
5x65mm steel shaft	X4
Micro shim 1mm	X15
M6x14mm	X16
M3x30mm	X8
NEMA 17 (same as your back Nema)	X2
Driver (same as your back Nema)	X2
Nema Cable	X2

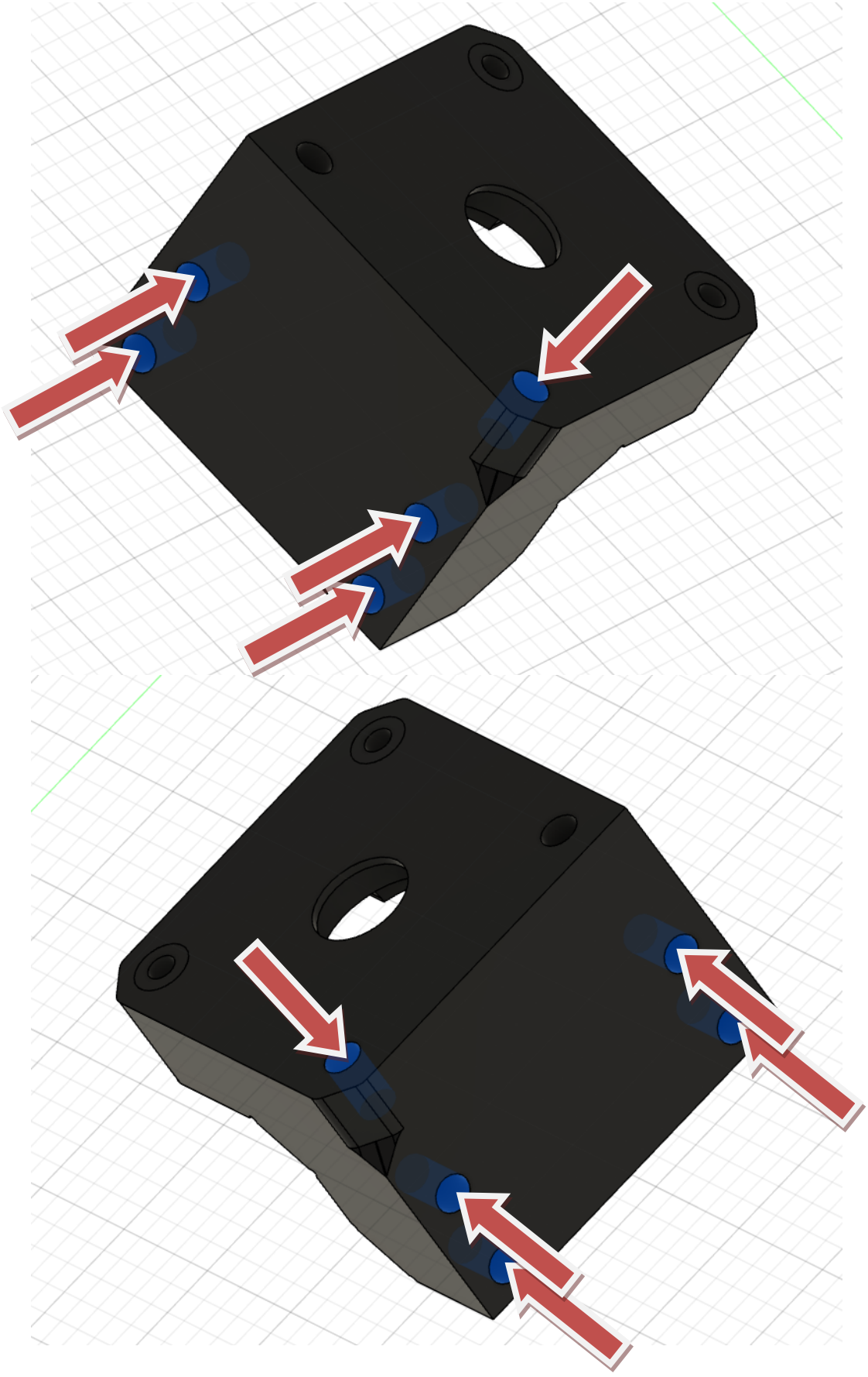
The Installation is the same regarding the Opened Frame, Closed frame, VC 3.0 and 3.1 iteration. Here for the sake of the example the manual is made upon the VC3.1 Opened version! I will track the R block here, the L block follow the exact same symmetrical assembly.

1-Part preparation

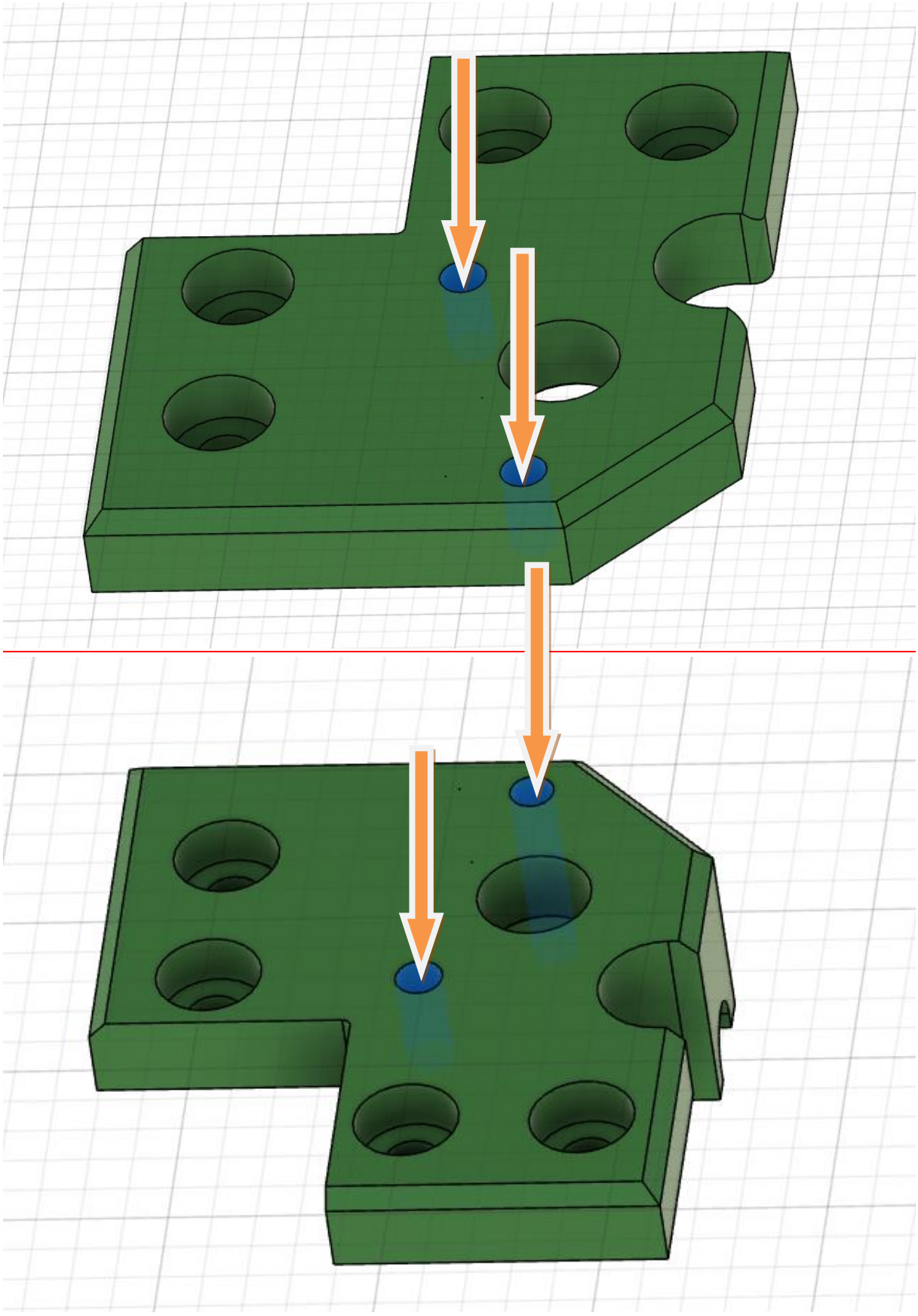
Before assembly, Install all heat inserts (for BRS Order it is already done)

Here All the M3

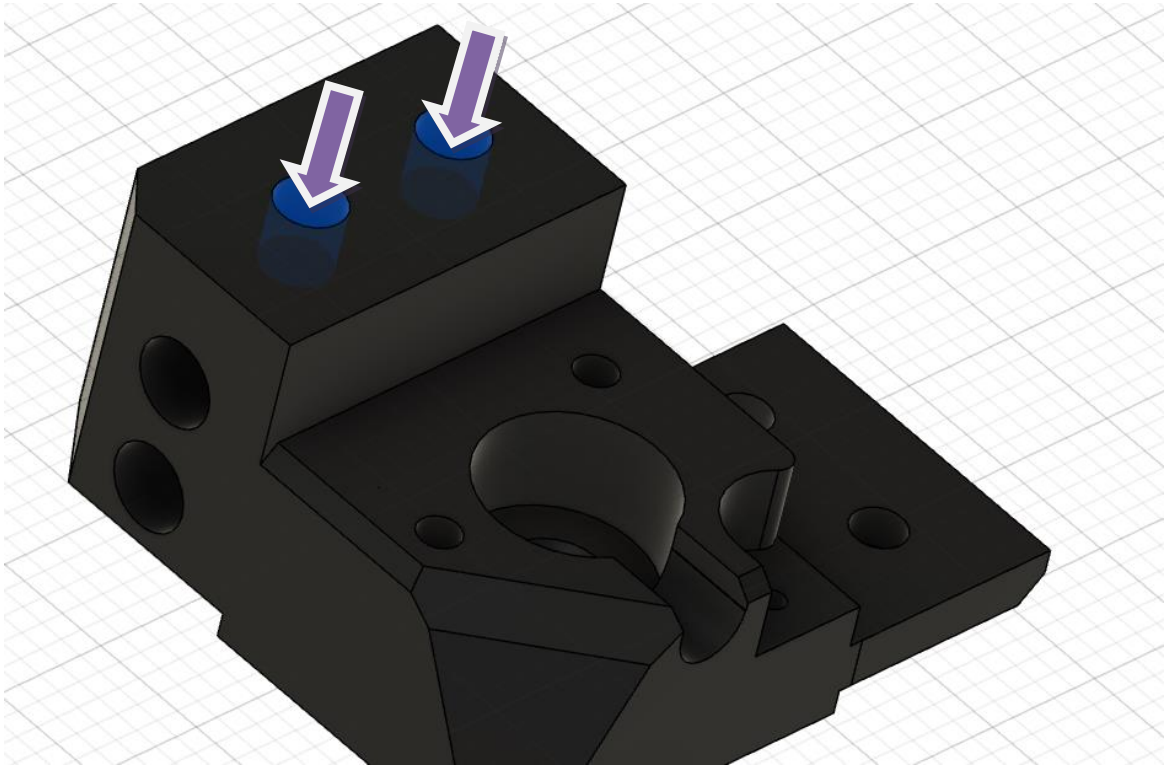


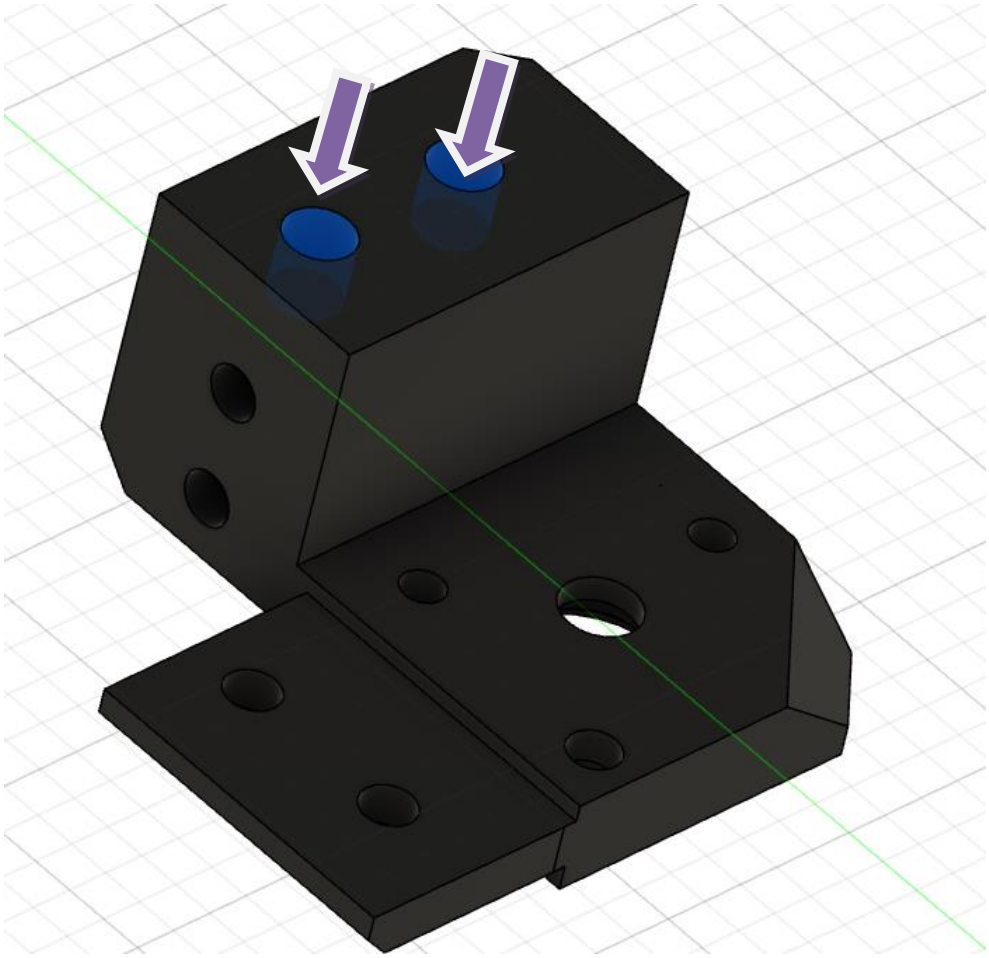


Here all the M4S (Short) **(Insertion FROM BELLOW)**

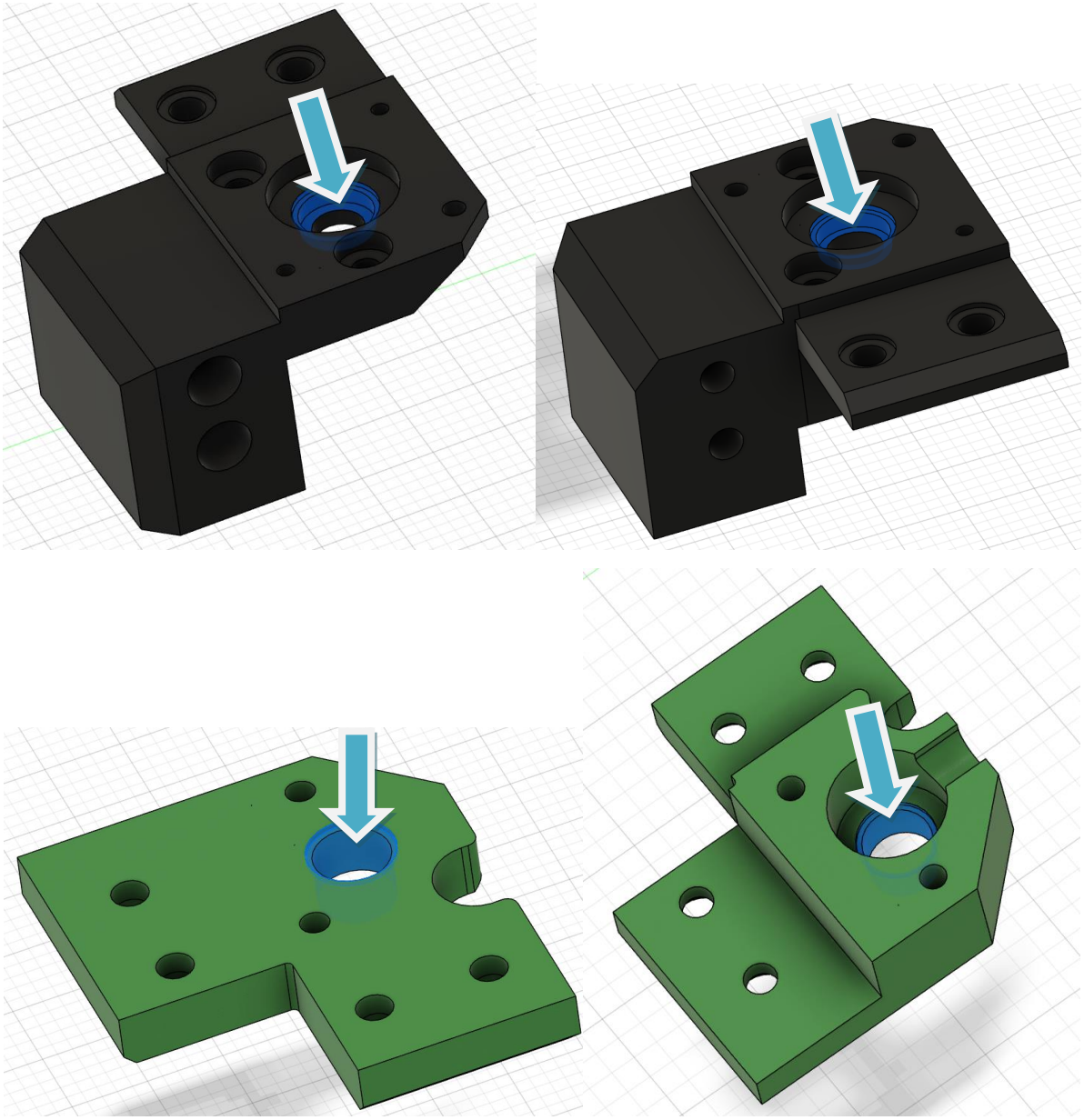


Here all the M6s (Short) (For open version ONLY)



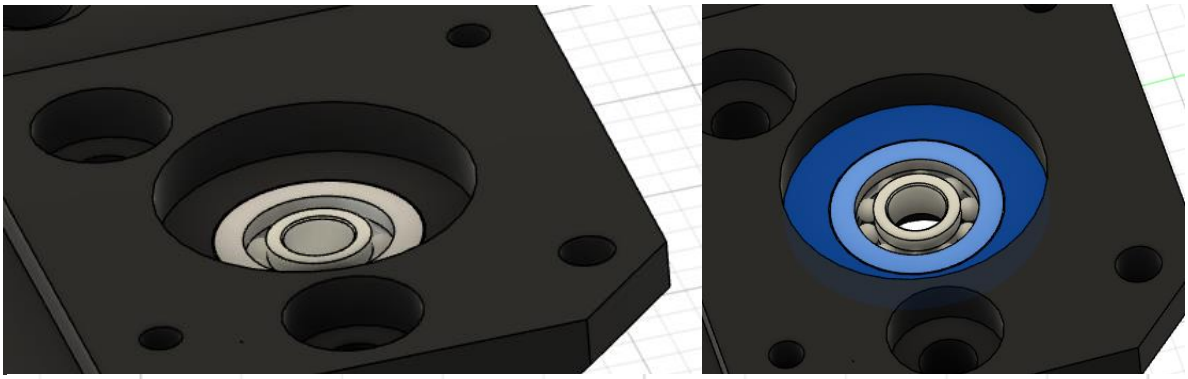


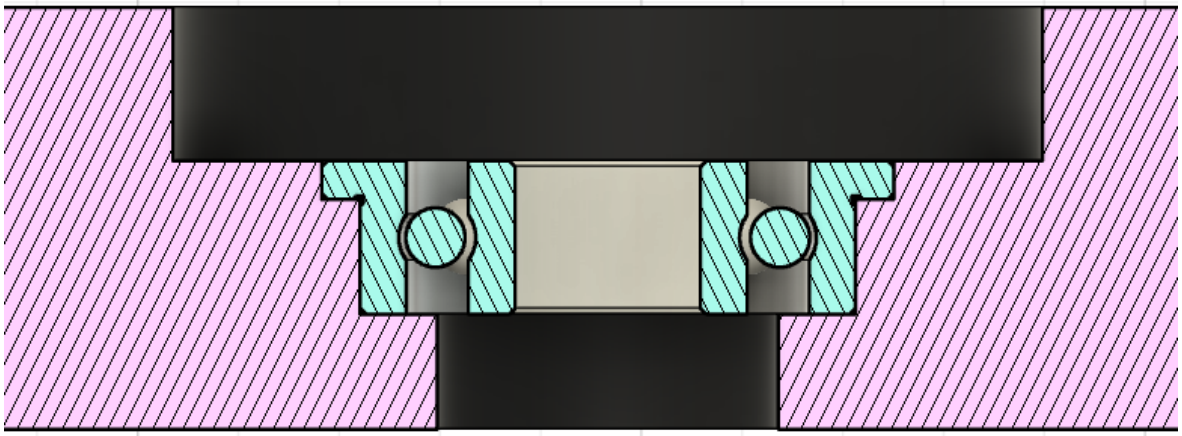
Bearings and Locks



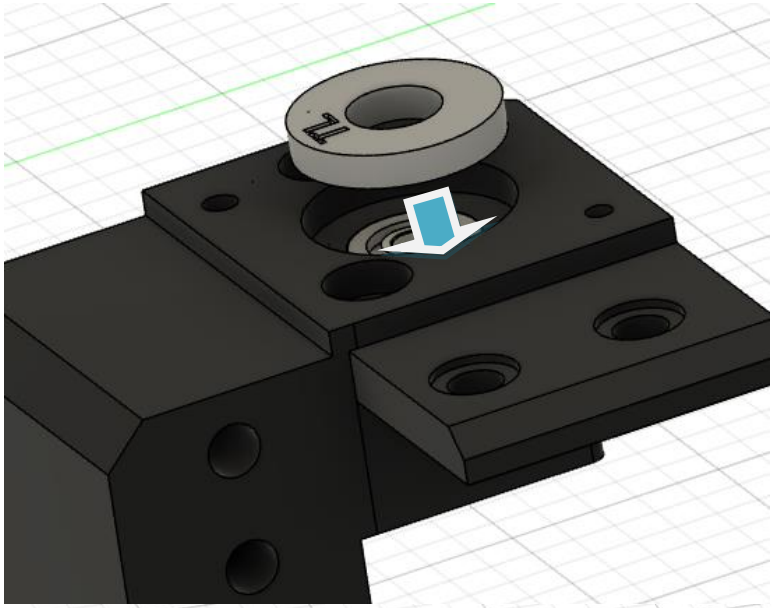
Each flanged spot on any Bottom and top parts need a F695 bearing installed here. You can use a 12mm cylindre tool (printed,...) to make the pressfit without damaging the bearings.

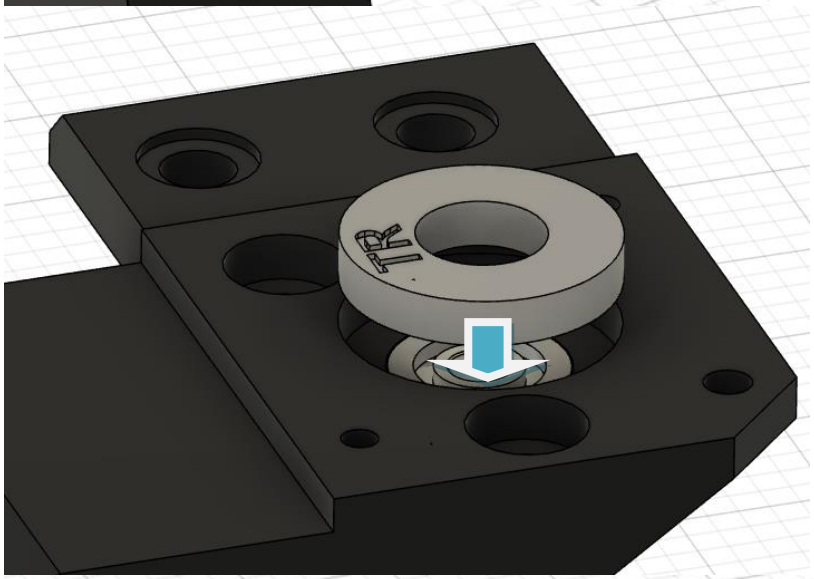
Bearing and laterial side must be flush in each parts

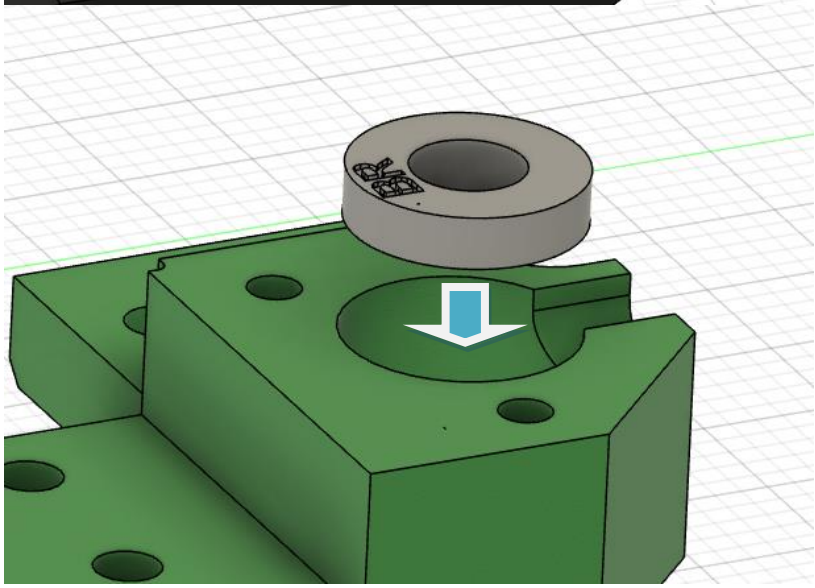




Once done you can install the Bearing locks, there is 3 of them



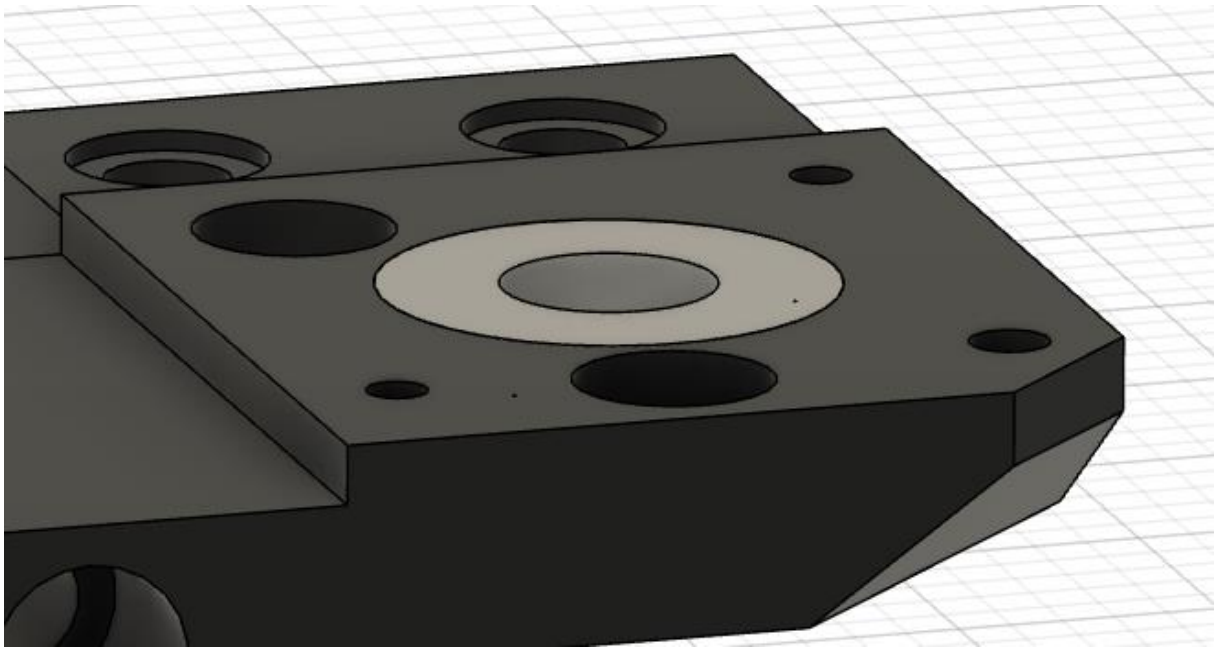


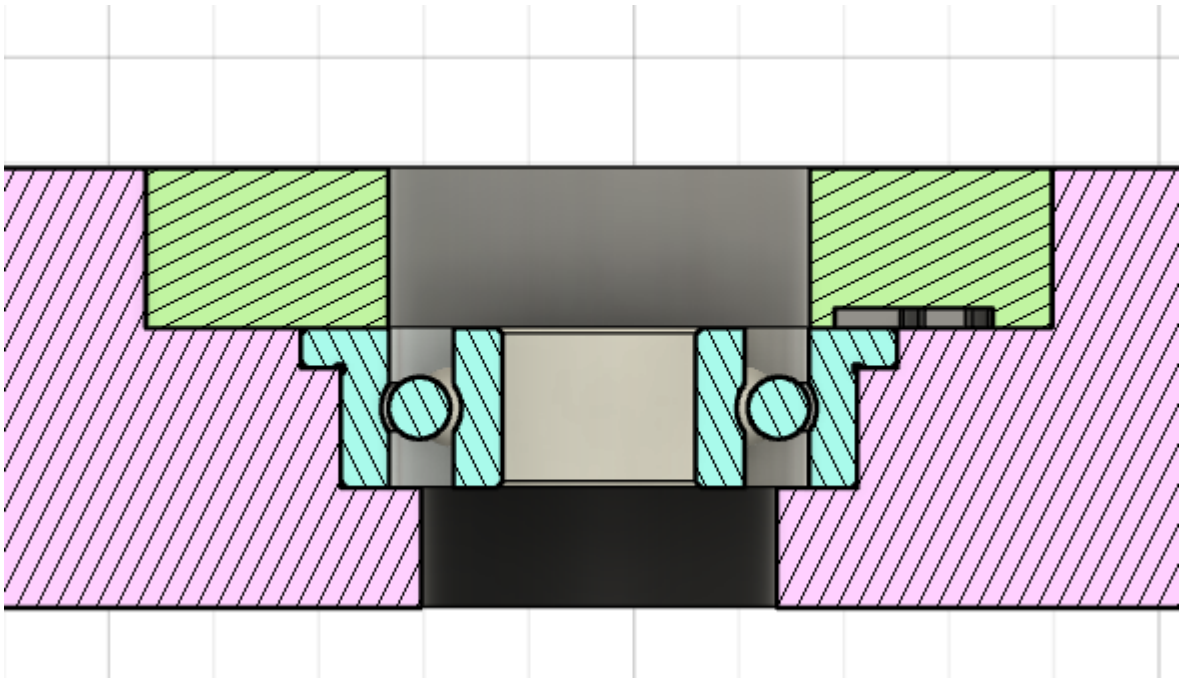


Now we need to pressfit them (Already done in all BRS orders)

Same logic, the top must be flush to the parts

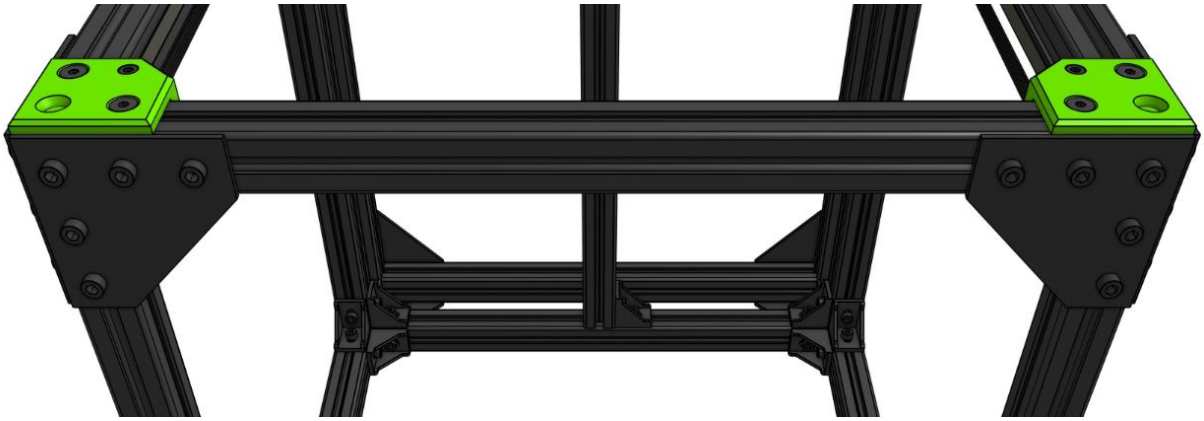
The goal here is to secure the bearing completely, I can be removed to make maintenance aftewards if necessary





Prepare the front of the Frame

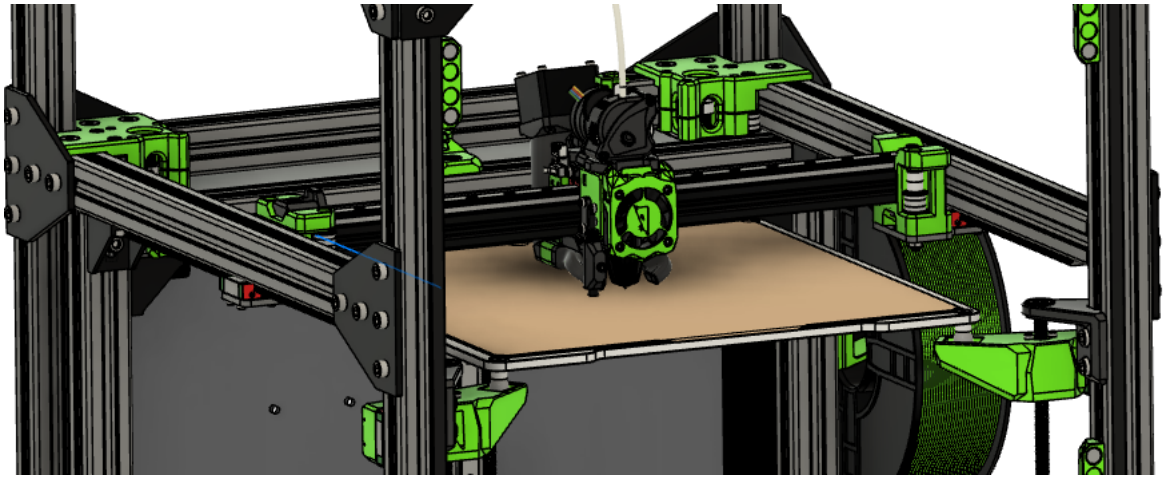
- For Vcore 3.0 you need to remove the corner idler assembly:



- For Vcore 3.1 and 2.0 frame extension, remove the idler in the front

- For the Z-Ugrade 2.0, remove the Top retainer parts + the idlers ensemble

2-General installation



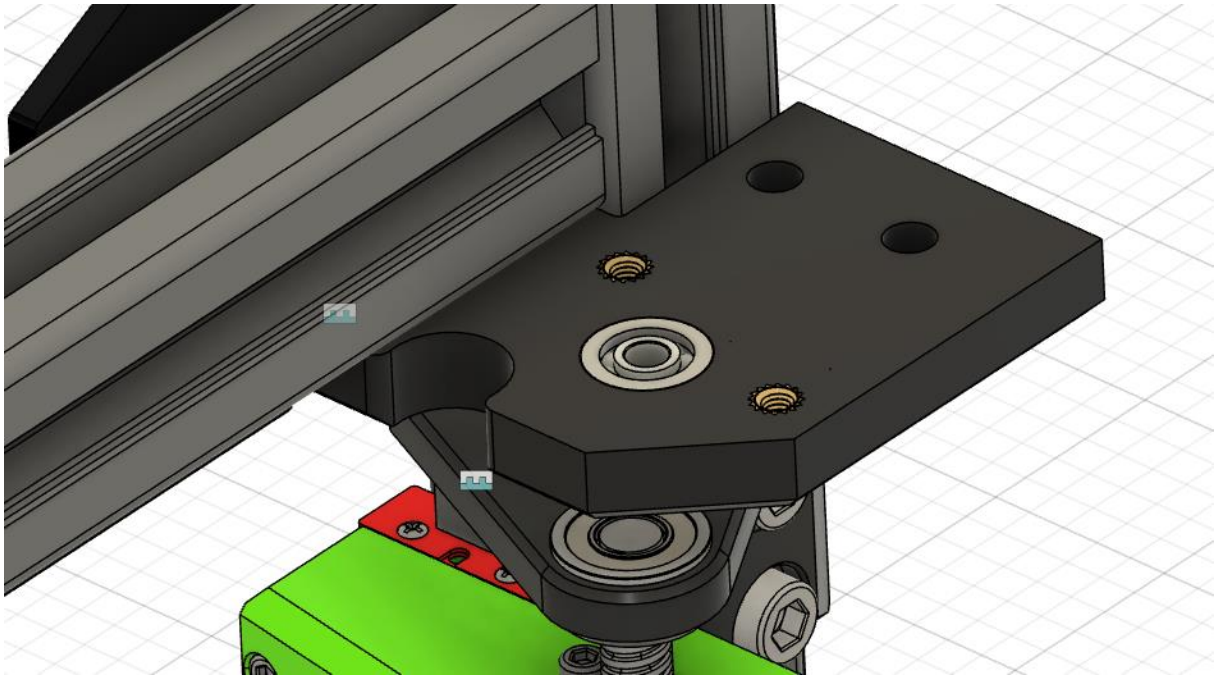
You should start with a clean empty front machine

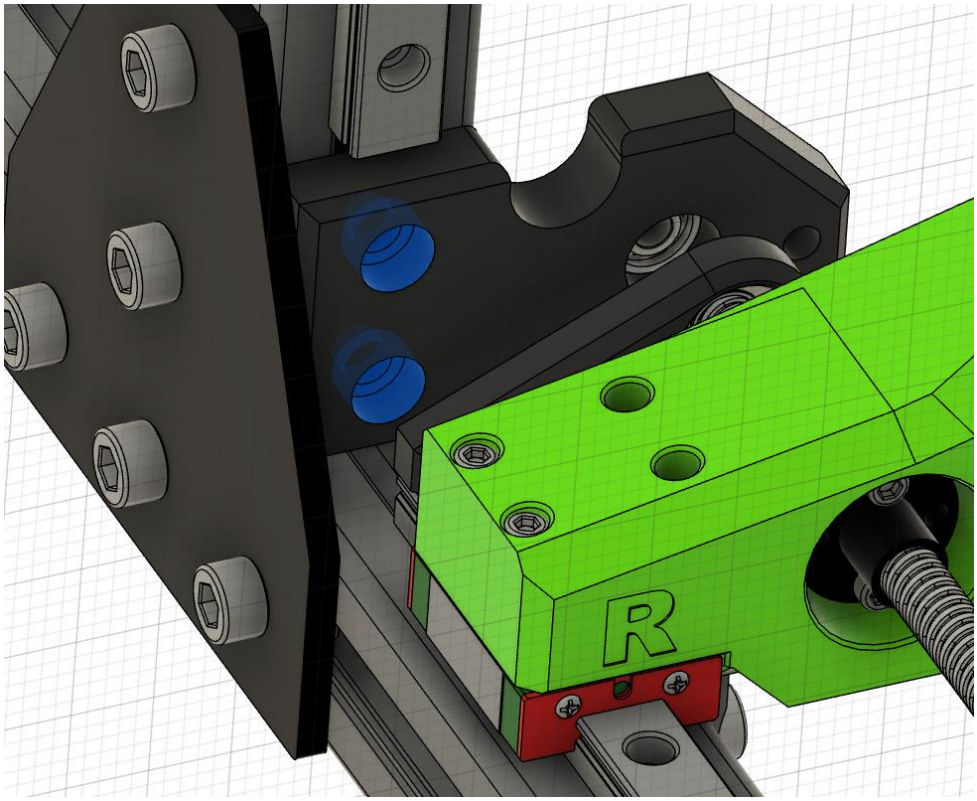
To ease the guide, I will remove some 3.1 part for a clear view

A/ Underplates

Slide the undeplate in the corner between the leadscrew retainer and the crossed frame join

Secure it with 2 M6 screws with according Tnuts

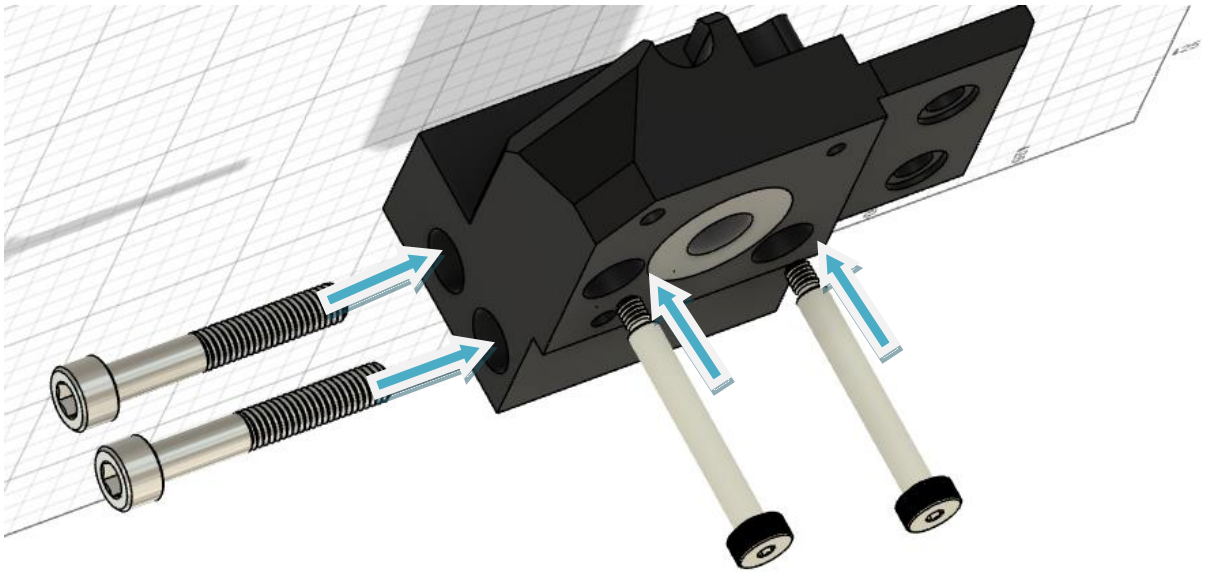


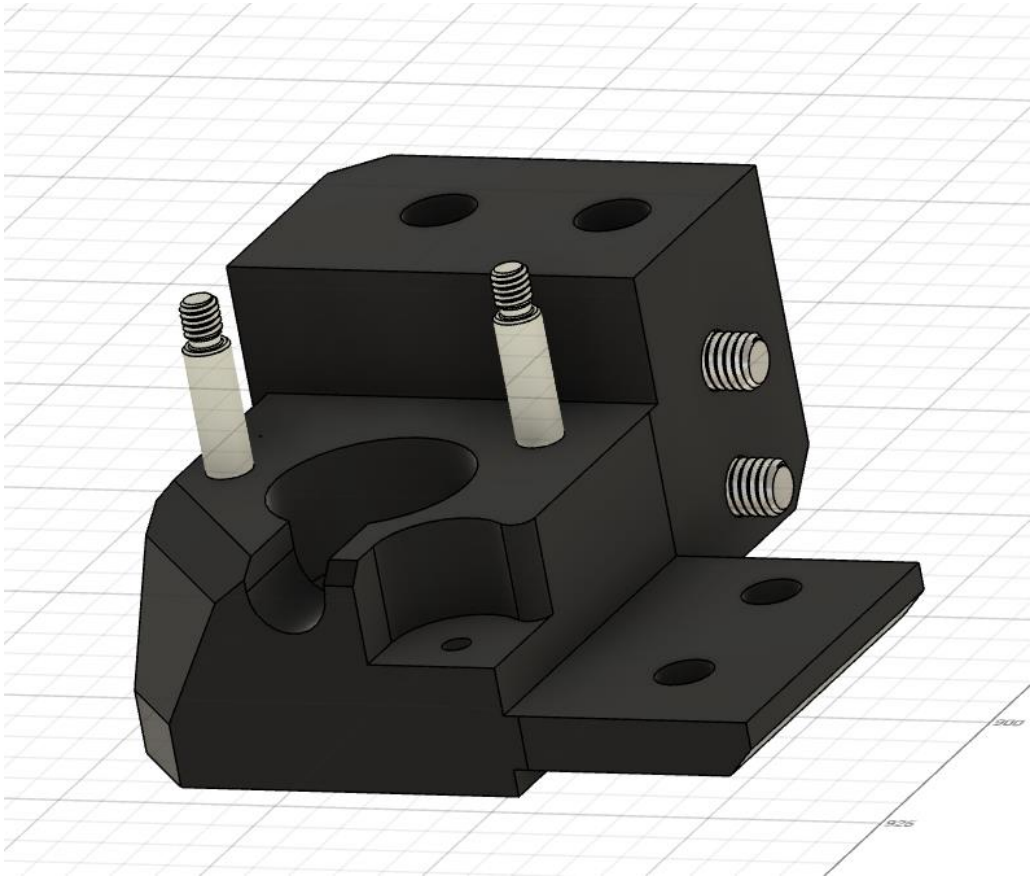


Repeat the operation for the L side

B/ Top parts

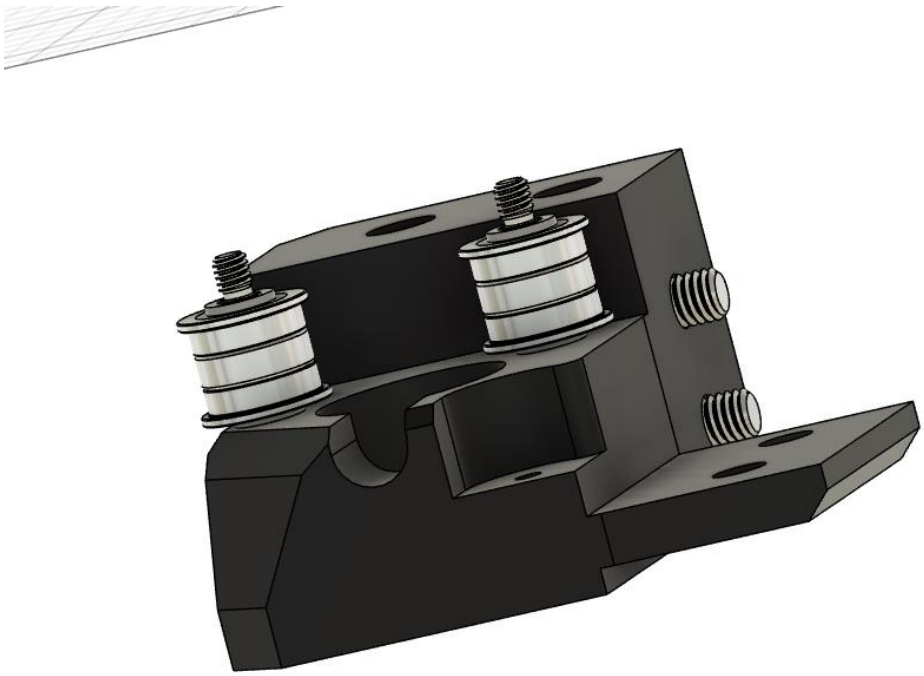
Here we need to install some Shoulderbolt and M6x40



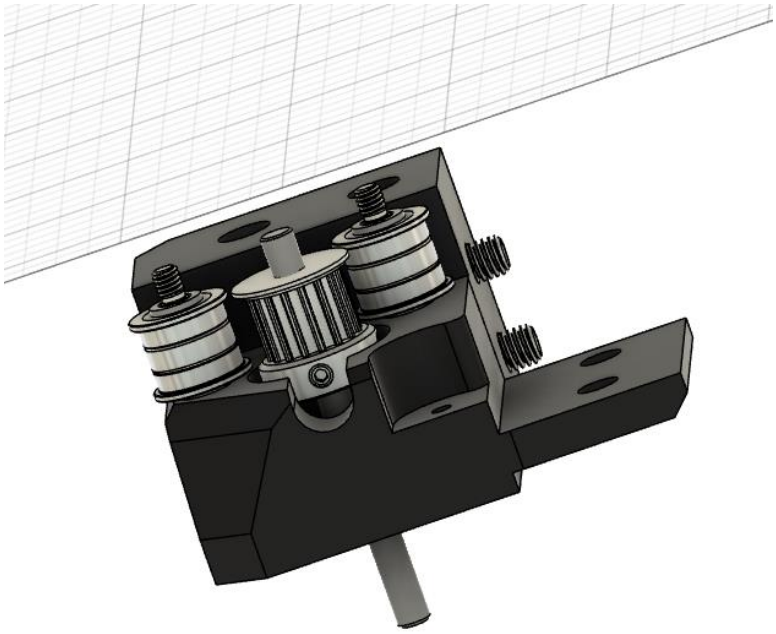


Install 2 Stacks of bearings

1 stack= microshim-F695-695-F695-microshim

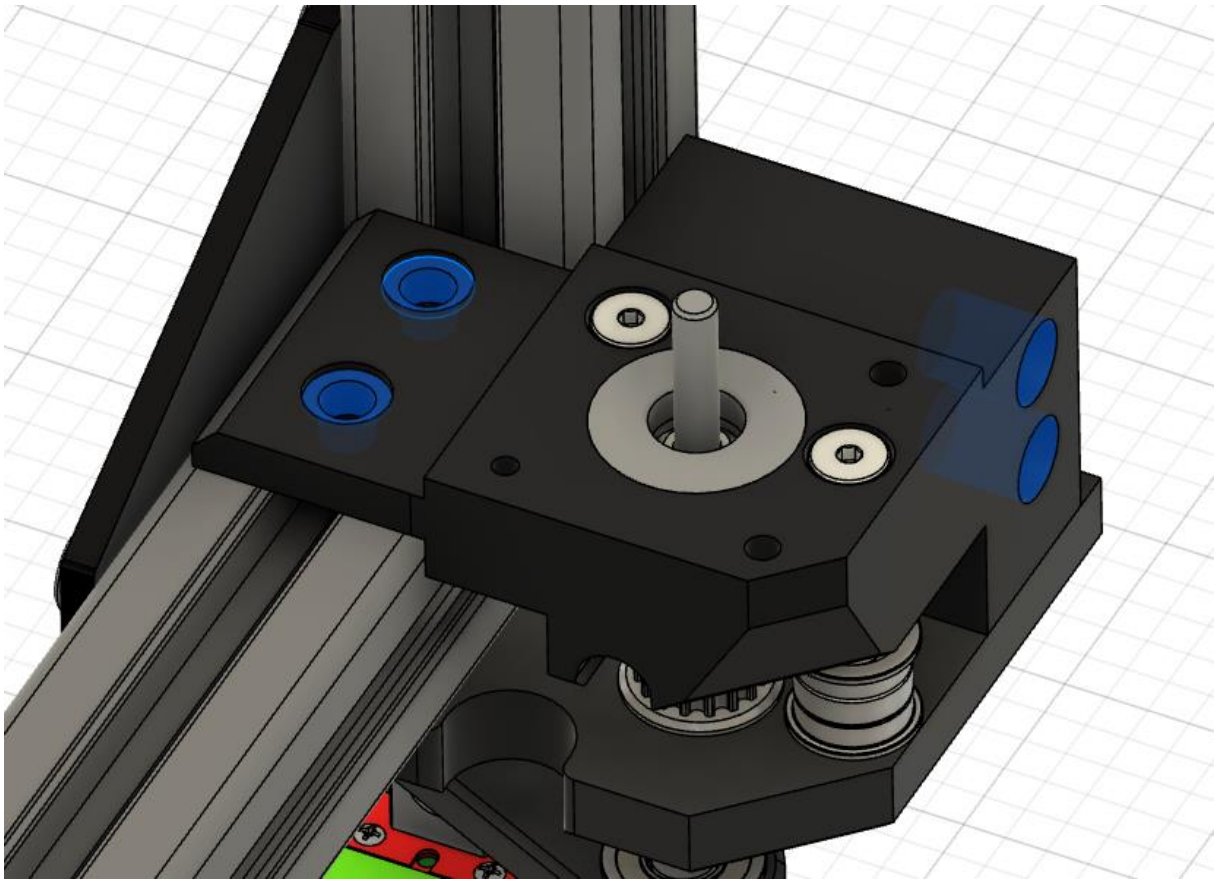


Install the 65mm shaft with the pulley



Place everything and secure the assembly with the 2x Shoulder bolts

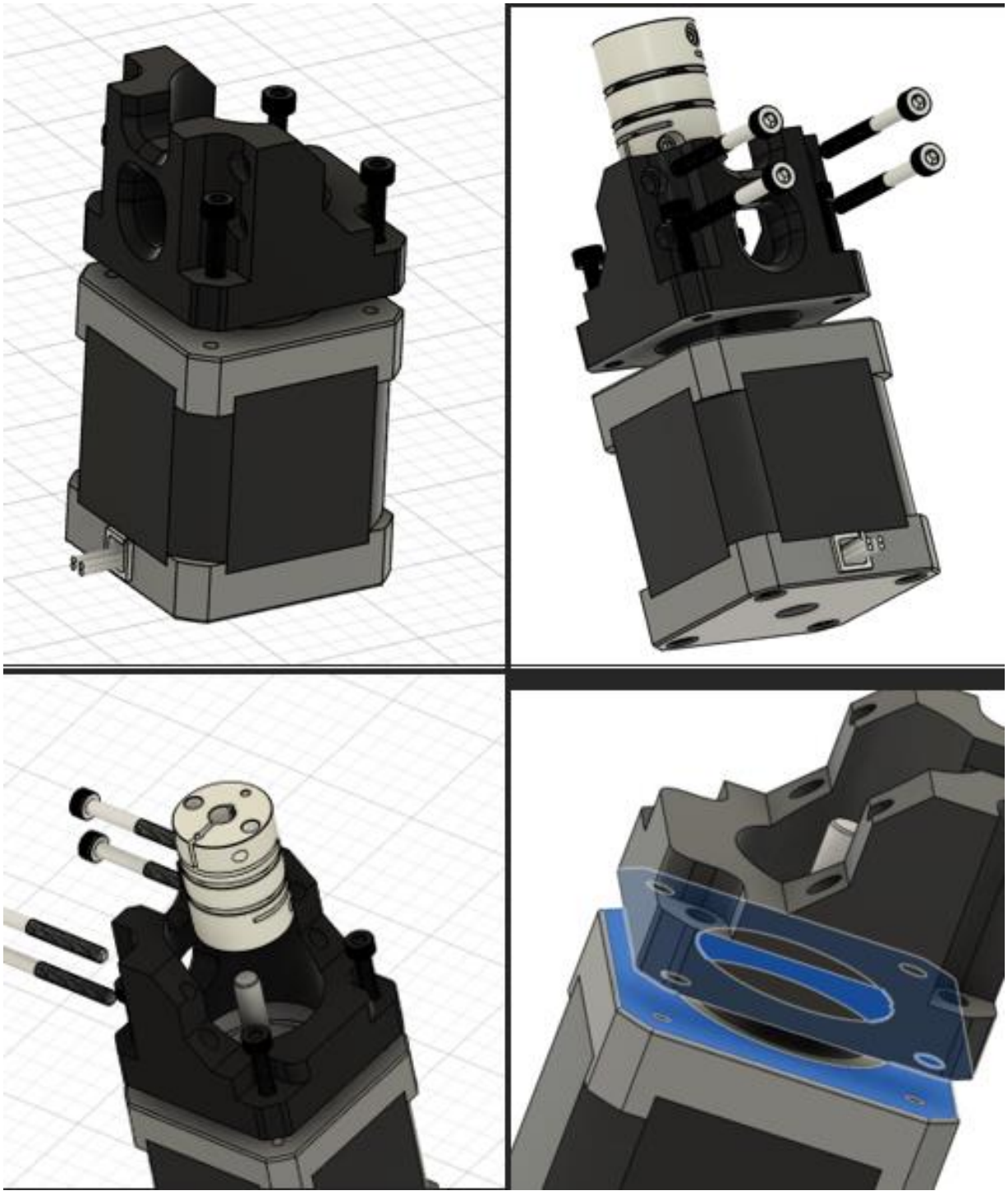
The 2x m6x40, and the 2x m6x14



C/ Nema mounts

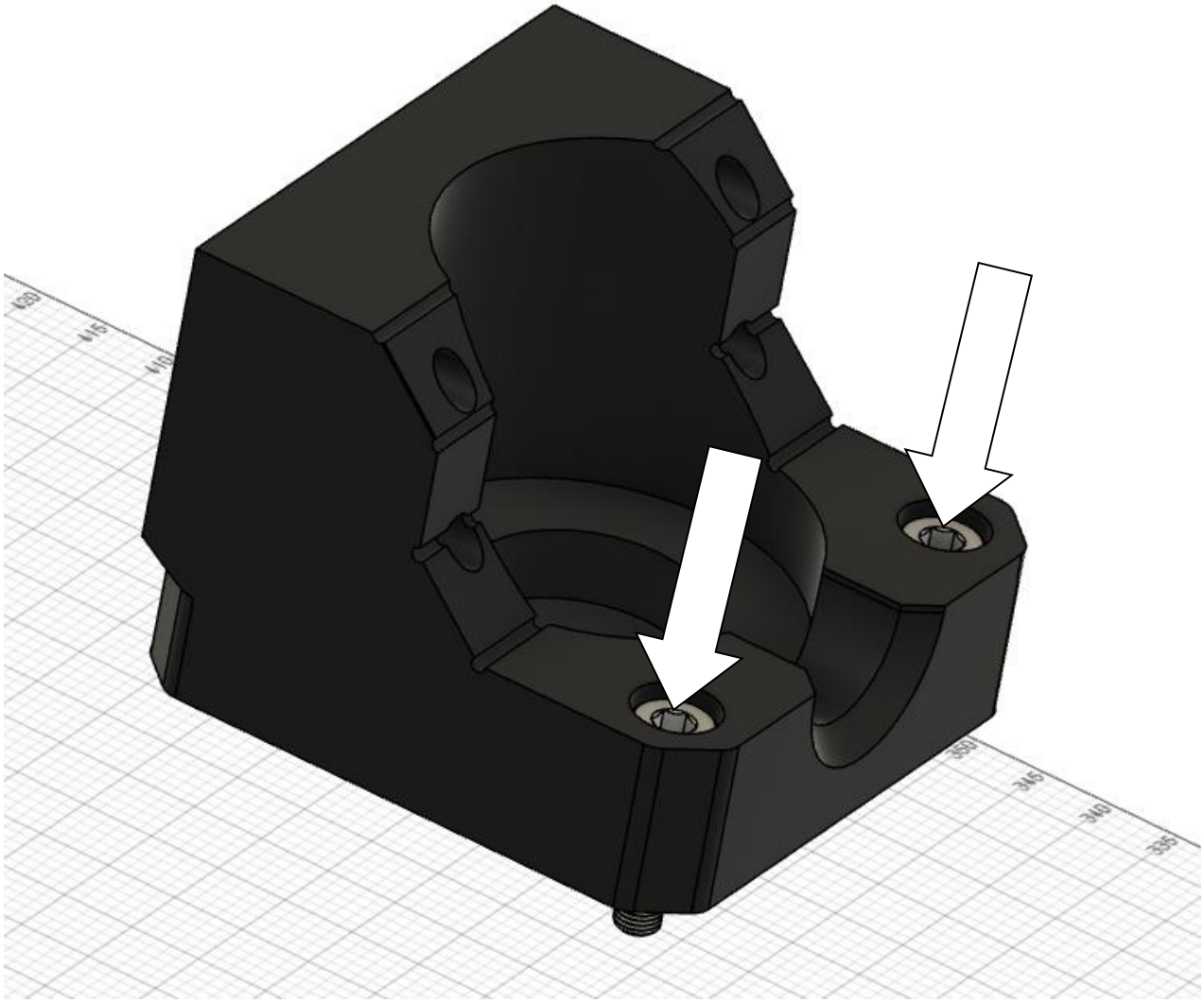
Install the Nema with the 4x m3x12mm

Preinstall the 4x m3x30mm



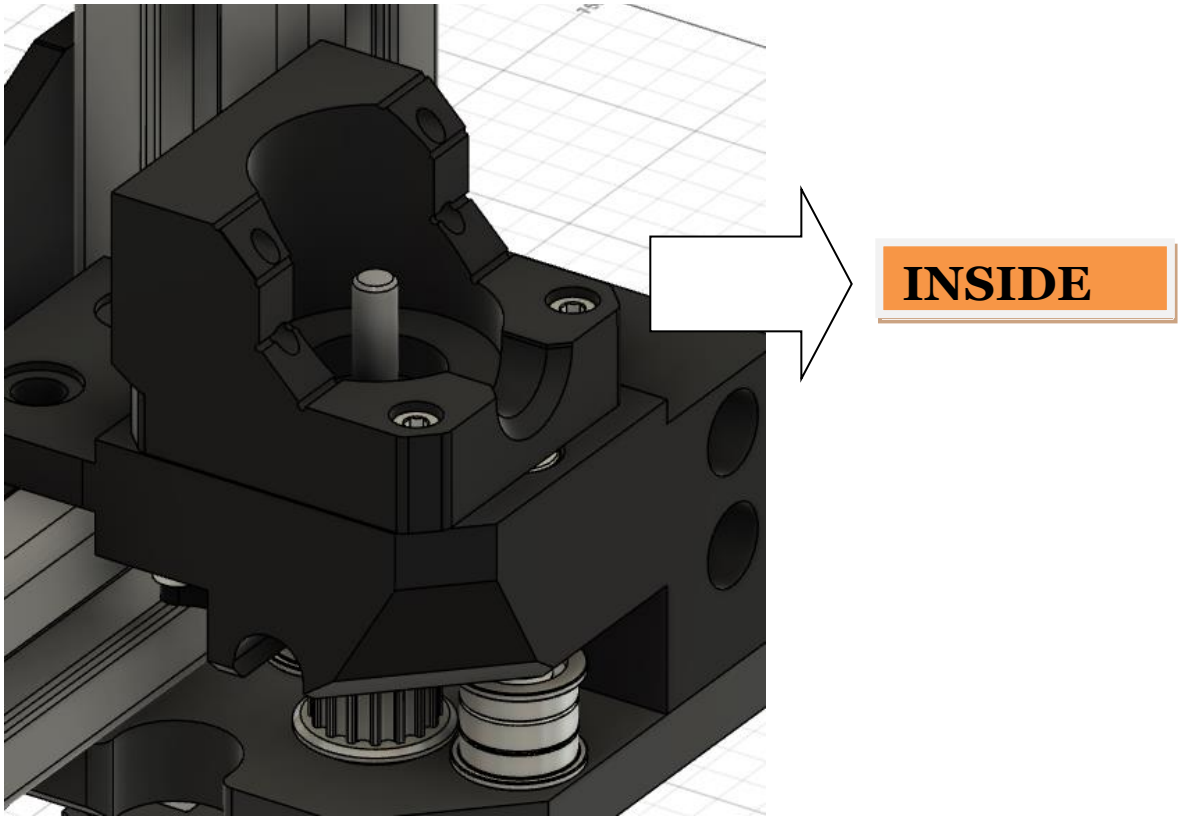
D/ Final assembly

Preinstall the Disk coupler on a shaft end (NEMA side or Block side)

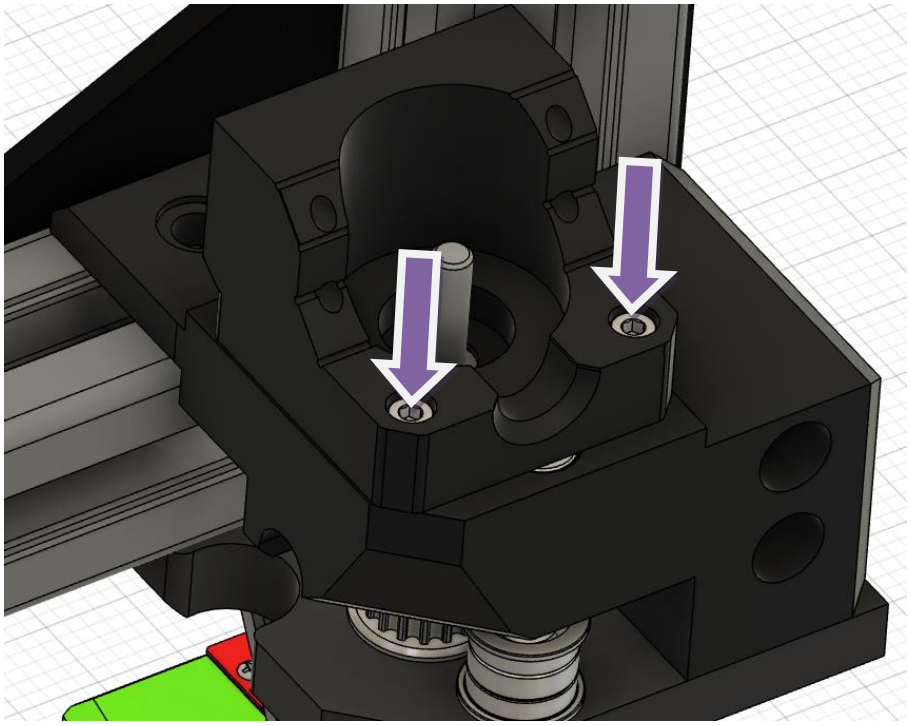


Install 2x m3x12mm in this part

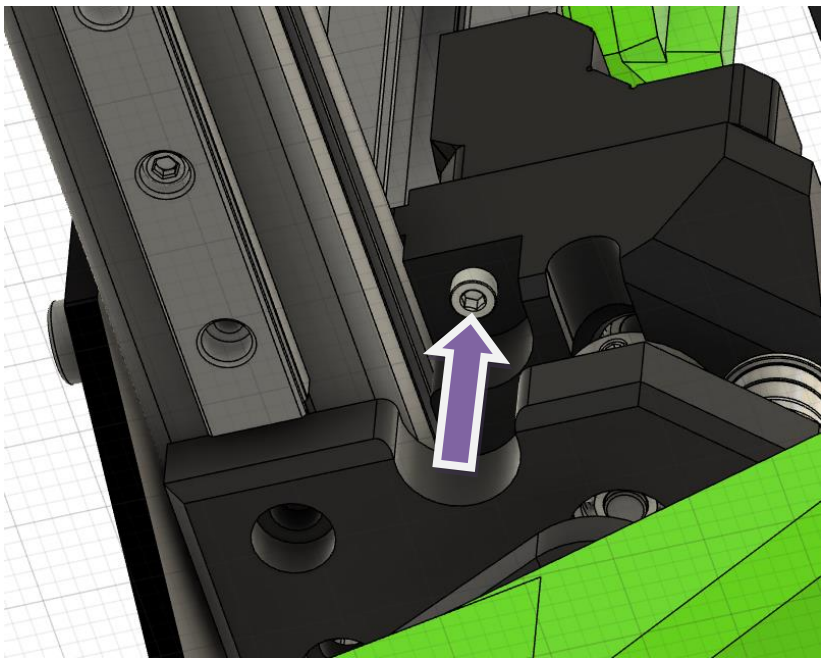
Recheck the 2 M4 Shoulderbolt, tightening them now for good is advised since it will not be available after without some disassembling.



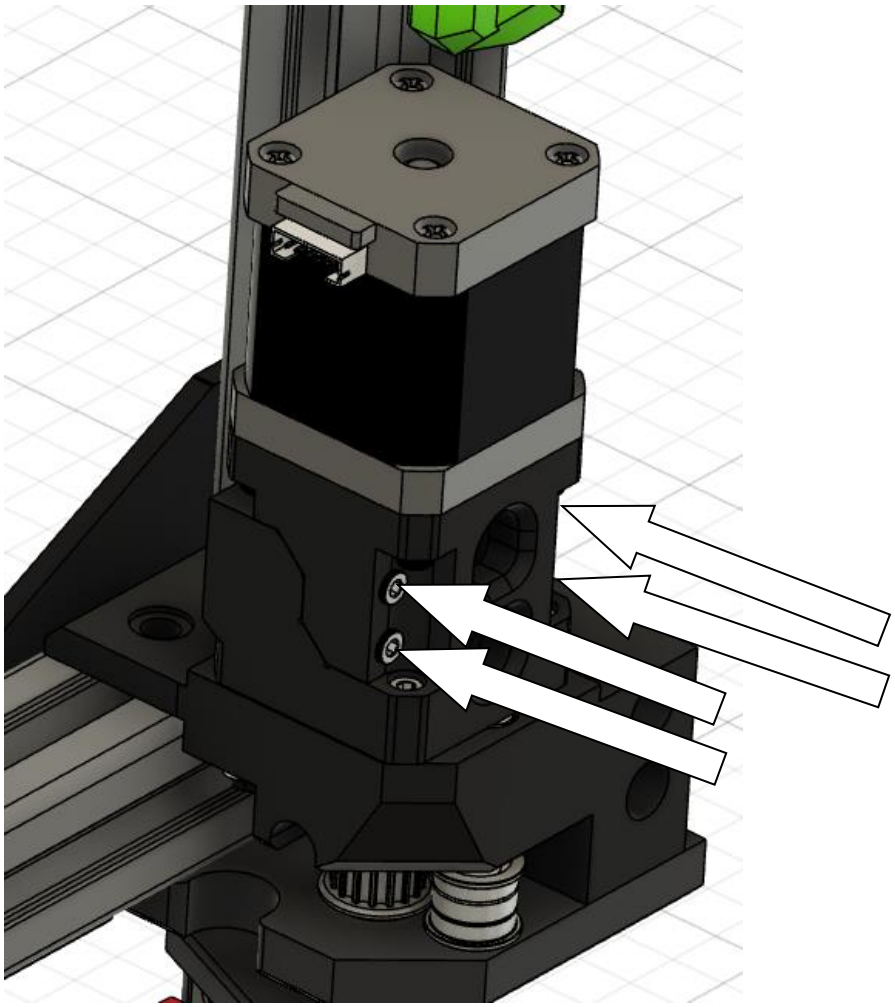
Then place it the opening toward the inner side of the machine



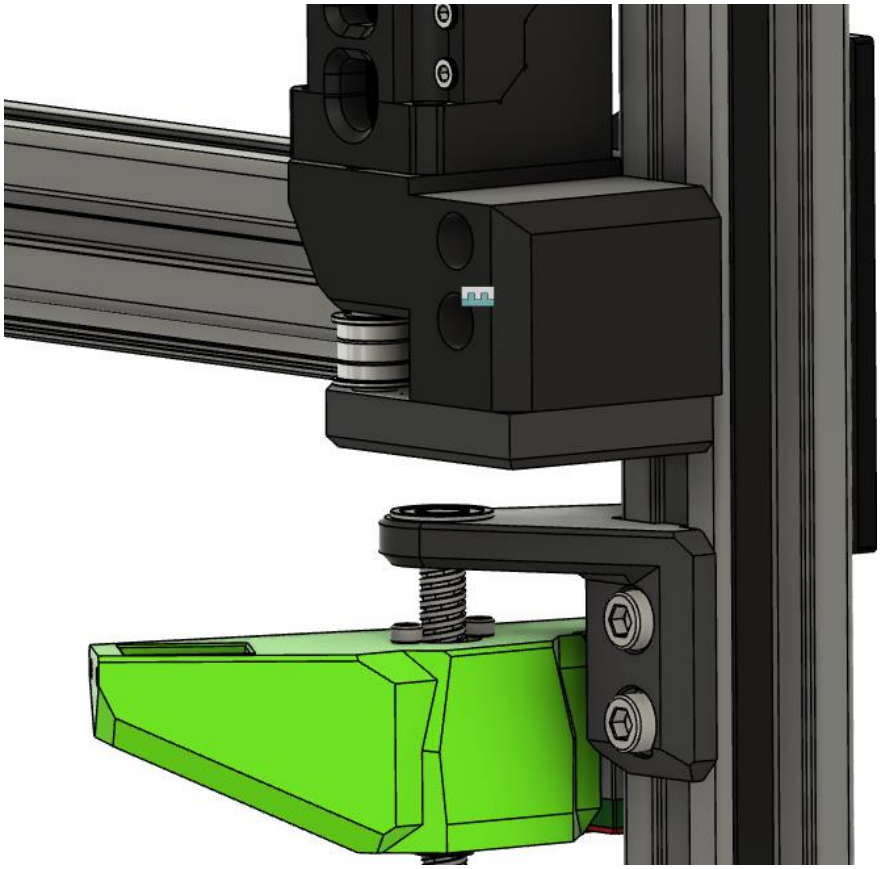
Secure the 2x m3x12mm



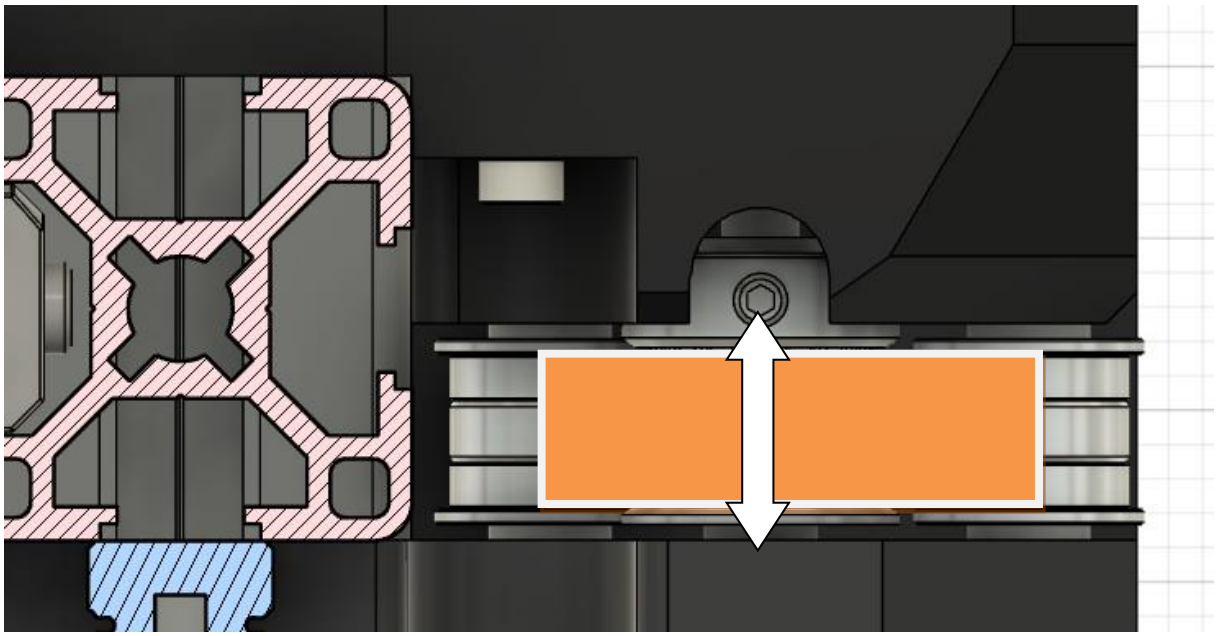
Add a m3x12mm from under, an opening has been made to access it easily



You can install the motor (Same mounting technique than the L3ver M2), secure the 4x m3x30



Check the clearances, and retight a bit the screws to secure the assembly.



Check the alignments, the pulley can be easily adjusted with the notches to access all the headless screws.

Here the Shaft are rounf without flat spot, It is a personal choice, but if you use a flat spot shaft, be sure it will need to be finer tuned to avoid so concentricity issues.

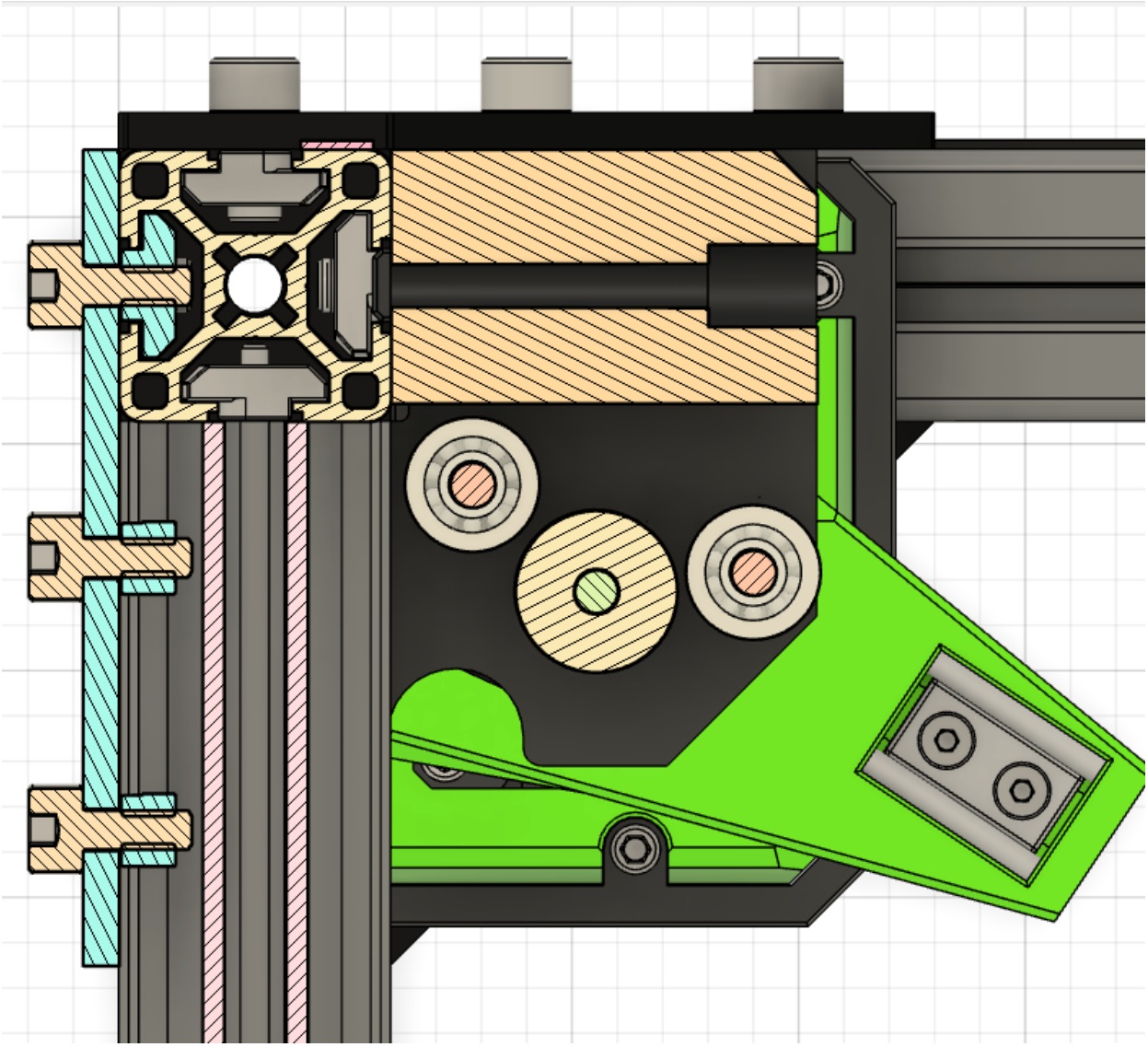
3-Belts routing :

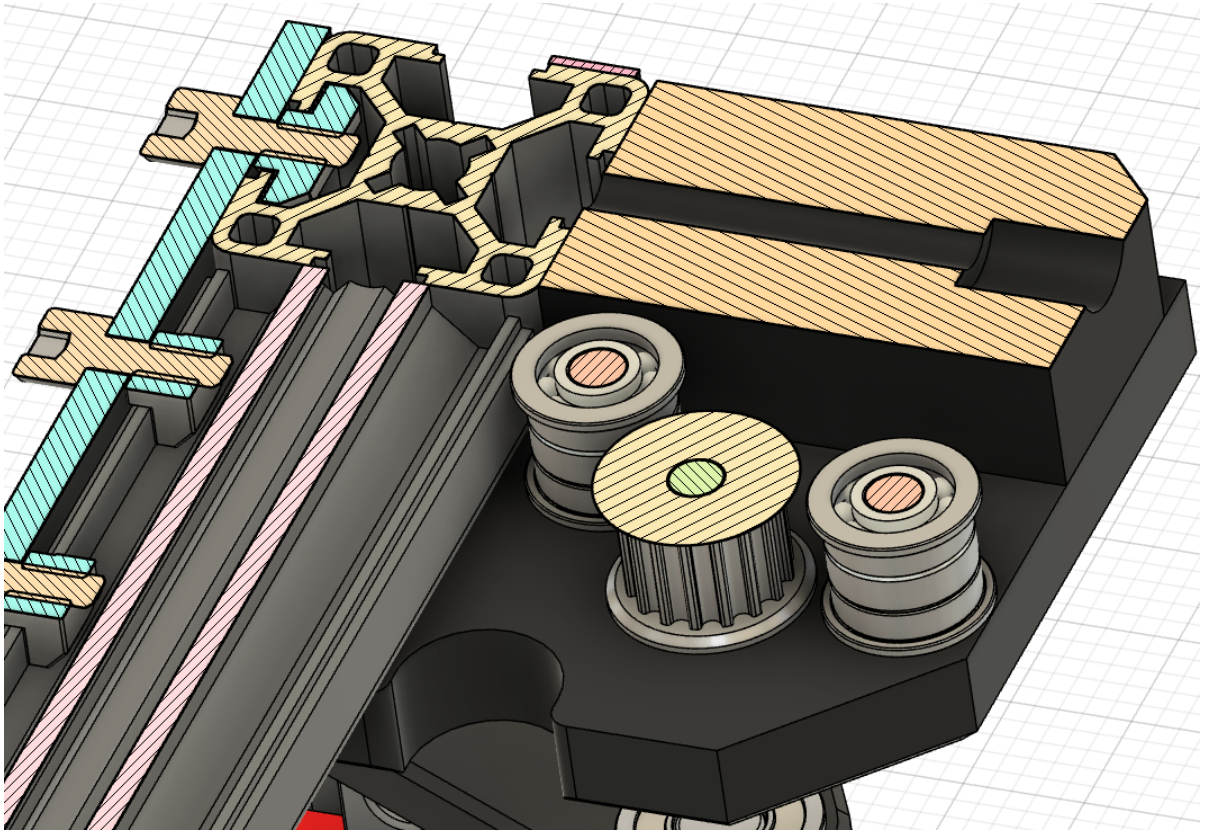
Belt routing on this mod has been made to maximize the grip and the torque transmission of the 9mm toothed pulley (90% compared to a 180 degrees rotation) without the need of a big block in the front and to keep the belt length as close as the stock one.

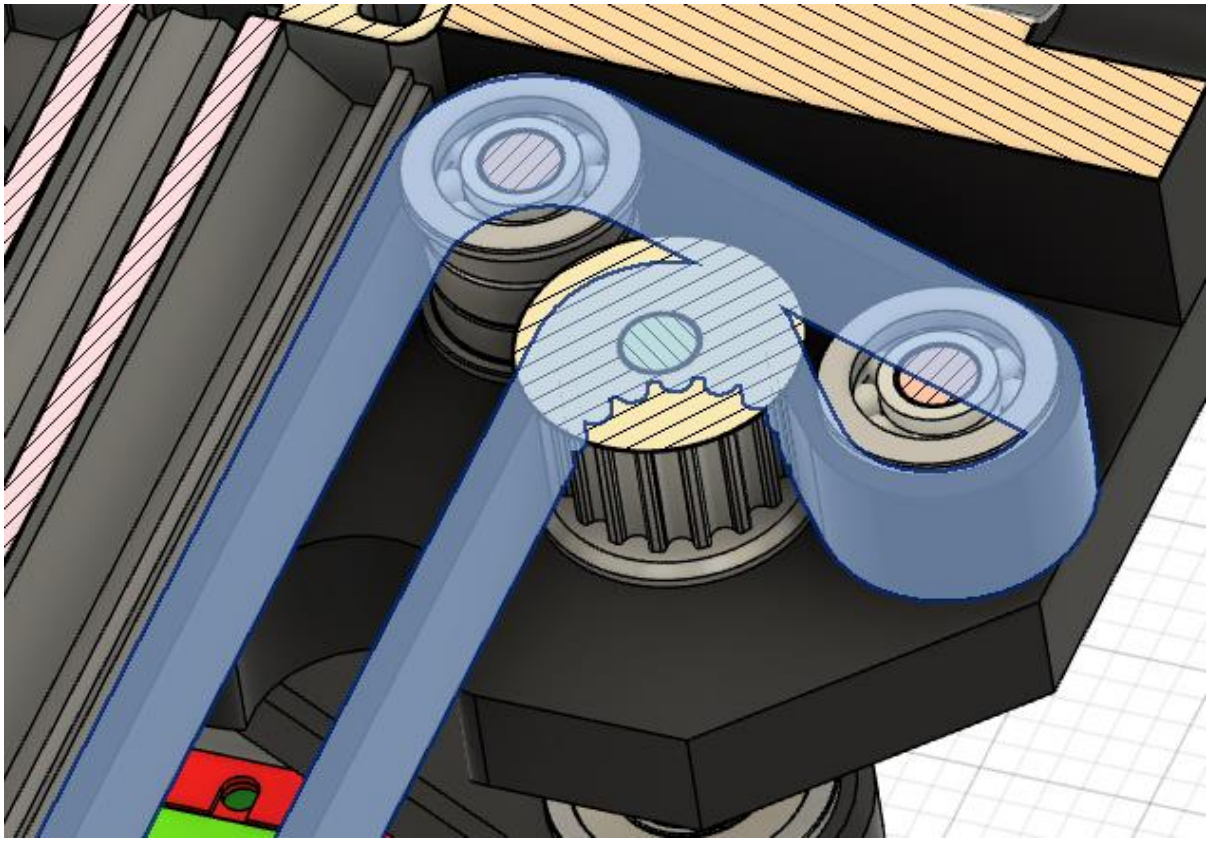
All this fact make it quite polyvalent for the usage we need:

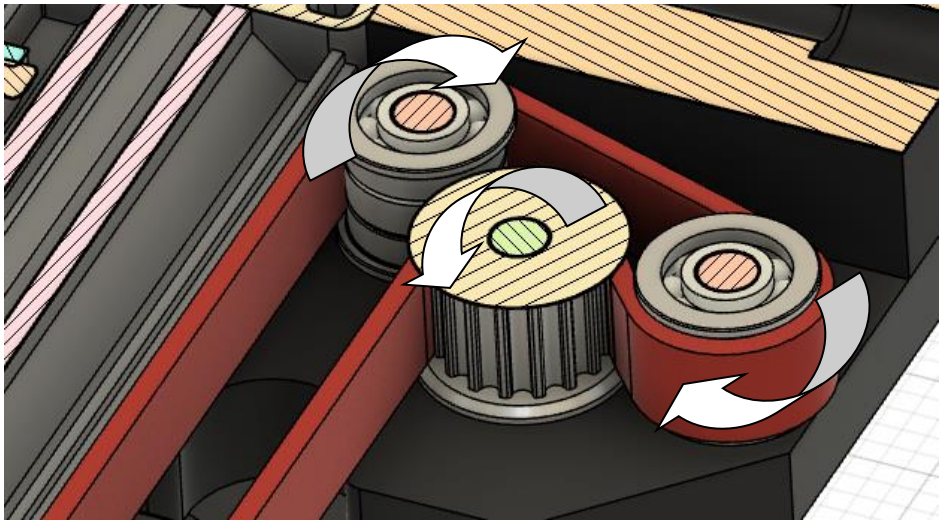
Enclosures are compatible, nothing outside, Printing volume clearances still at 100% (Vz toolhead)

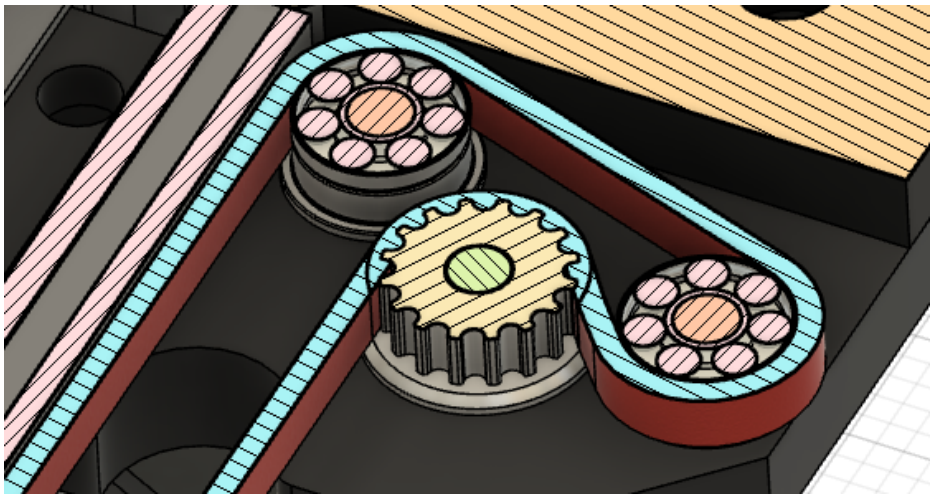
Here the layout we have to route the belt, no need to redo a full routing from the beginning, the mod adapt to any Vcore! As the assembly is done at this point, I advise the usage of a zip tie to help you routing the belt.

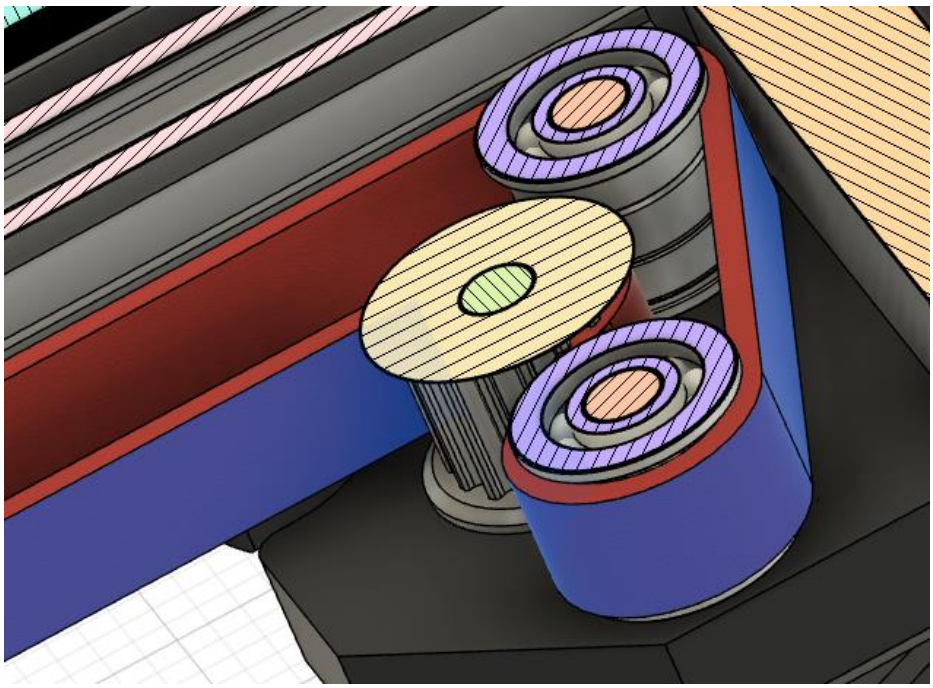












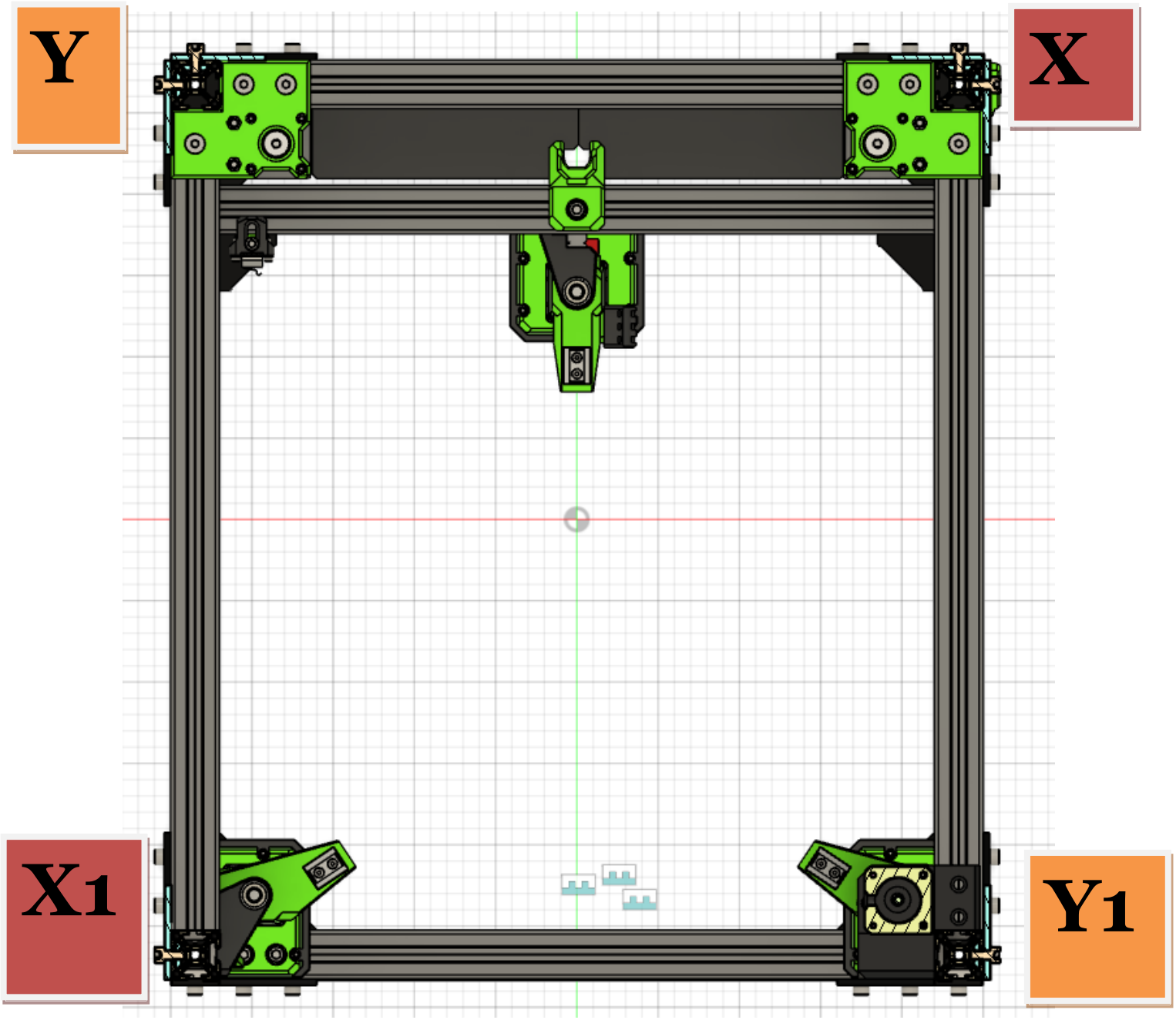
The blue face is the toothed face

Refer to the instruction to tune the Tension on the GITHUB Belt-tension.pdf

4-Wiring

You need to add the 2 drivers to your board, then make sure the wiring is correctly made to allow X and X1 to run in the same motion logic, same for Y and Y1

-Now the placement for each motor



5-Printer.cfg implementations

You will find here the template to accommodate the AWD in the CFG

https://github.com/FlorentBroise/BRS-Printers-Mod/blob/main/manuals/KlipperconfAWD.pdf

DON'T FORGET THAT ALL THE MOTORS NEED THE SAME ROTATION DISTANCES, SAME MICROSTEPPING SETUP, SAME TMC SETUP, If not you will be surprised by heavy noises and vibrations.

7-Motor Sync

To have a clear motion, we need to synchronize all the motors, this step is mandatory for a smooth running system.

I encourage you to make a specific macro to call this gcode arguments:

[gcode_macro enable_stepper]

gcode:

SET_STEPPER_ENABLE STEPPER=stepper_x ENABLE=1

SET_STEPPER_ENABLE STEPPER=stepper_x1 ENABLE=1

SET_STEPPER_ENABLE STEPPER=stepper_y ENABLE=1

SET_STEPPER_ENABLE STEPPER=stepper_y1 ENABLE=1

AND

[gcode_macro disable-steppers]

gcode:

m84

Step 1: Set belt tension like on a normal machine, following this documentation

Step 2: Loosen the grubscrews on one of each set of motors,

Step 3: Start up the printer and order "enable stepper".

Step 4: Then tighten the stepper grub screws and disable steppers again.

6-License :

Assistance

Like always, I provide an lifetime assistance;

As this manual is the first release, even after having made the assembly myself, I could have missed some specificities, don't hesitate to ask me if something seems wrong!

Any question or issue can be submited to Florent Broise on Facebook/Discord or at contact@brs-engineering.com