
Project 8 - SF2520

GOYENS Florentin & WEICKER David

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Problem description

Blabla
bla

1 dimension

- 1) on explique la discretisation
- 2) on explique que sauf pour le first step, on a

$$f(U) = A * U$$

et on **défini la matrice A**. Cela because en gros
For any index t ,

$$\begin{aligned} f(U_i) &= \frac{\nu}{r_i} \frac{(U_{i+1} - U_{i-1}))}{h_x} + \nu \frac{U_{i+1} - 2U_i + U_{i-1}}{h_x * h_x} - \frac{\nu}{r_i^2} U_i \\ &= \frac{\nu}{h_x} \left(\frac{1}{h_x} - \frac{1}{r_i} \right) U_{i-1} - \nu \left(\frac{2}{h_x^2} + \frac{1}{r_i^2} \right) U_i + \frac{\nu}{h_x} \left(\frac{1}{h_x} + \frac{1}{r_i} \right) U_{i+1} \end{aligned}$$

So we can now write the Crank-Nicolson method as

$$\begin{aligned} U^{t+1} &= U^t + 0.5 * h_t \left(f(U^t) + f(U^{t+1}) \right) \\ &= U^t + 0.5 * h_t \left(A * U^t + A * U^{t+1} \right) \end{aligned}$$

Therefore,

$$\left(Id - 0.5 * h_t * A \right) U^{t+1} = \left(Id + 0.5 * h_t * A \right) U^t$$

This is a linear system that can easily be solved for U^{t+1} .

TODO: jacobien est minus donc c'est stiff, analyser la condition CFL pour voir si les pas choisis ont du sens etc

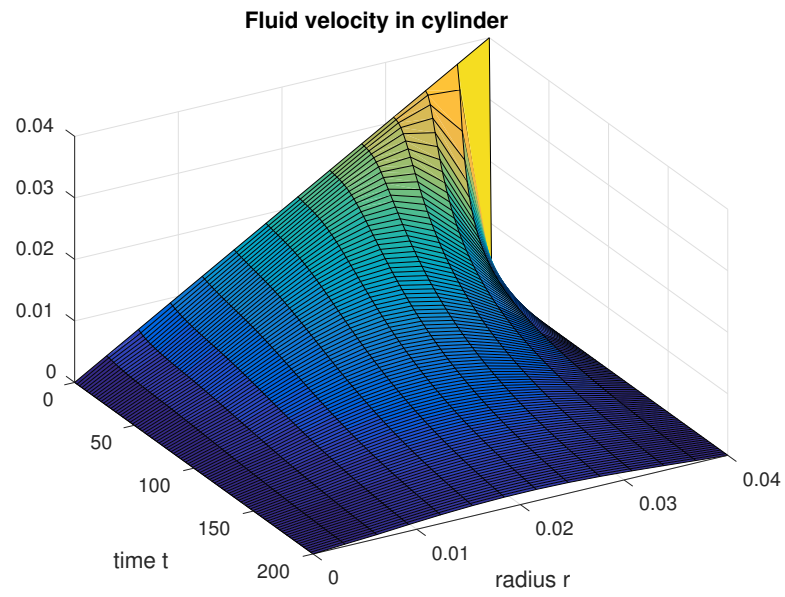


Figure 1: Solution for one dimension

2 dimension

TODO

Matlab codes