

# **B3 - Paradigms Seminar**

B-PDG-300

# Day 07 - Afternoon



2.0





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language: C++



• The totality of your source files, except all useless files (binary, temp files, obj files,...), must be included in your delivery.

All your exercises will be compiled with g++ and the -std=c++20 -Wall -Wextra -Werror flags, unless specified otherwise.

All output goes to the standard output, and must be ended by a newline, unless specified otherwise.



None of your files must contain a main function, unless specified otherwise. We will use our own main functions to compile and test your code. It will include your header files.

For each exercise, the files must be turned-in in a separate directory called **exXX** where XX is the exercise number (for instance ex01), unless specified otherwise.



Read the examples CAREFULLY. They might require things that weren't mentioned in the subject...



The \*alloc, free, \*printf, open and fopen functions, as well as the using namespace keyword, are forbidden in C++.

By the way, friend is forbidden too, as well as any library except the standard one.

EPITECH.



## **UNIT TESTS**

It is highly recommended to test your functions as you implement them. It is common practice to create and use what are called **unit tests**.

From now on, we expect you to write unit tests for your functions (when possible). To do so, please follow the instructions in the "How to write Unit Tests" document on the intranet, available here.

For them to be executed and evaluated, put a Makefile at the root of your directory with the tests\_run rule as mentionned in the documentation linked above.





#### **EXERCISE O - MEEEEEEDIC**

Turn in: Skat.hpp, Skat.cpp
Forbidden features: pointers

Soldiers, welcome to the SKAT (Special Kreog And Tactical).

You are here because you want to protect our wonderful country, Australia, from the crawling brood that are **Dingos**.

This infamous rot won't rest until they undermine the core foundation of our wonderful country.

I am drill sergeant Hartog and I am in charge of making war dogs out of you.

However, you are now at level zero of your life on earth.

It's time for you to rack in some experience before you can show them what you've got.

Let's start the briefing.

As you will very likely get a bullet in your skin on the battlefield, our team of scientists have designed a special package that will save your butt more than you would think: the **stimpak**.

This stimpak can repair your bones, suture clean wounds, and so on.

As long as you have one left, you have a chance to stay alive and come back home.

#### Implement the following class:

```
class Skat
{
public:
    Skat(const std::string &name, int stimPaks);
    ~Skat();

    [...] stimPaks();
    const std::string &name();

    void shareStimPaks(int number, [...] stock);
    void addStimPaks(unsigned int number);
    void useStimPaks();
    void status();

private:
    [...]
}
```

A Skat has a name, represented by a string, and a number of stimpaks. By default, your Skat's name is **bob**, and it has 15 stimpaks.

The stimPaks member function returns the number of stimpaks your Skat currently has. It is possible to modify the number of stimpaks your unit has by calling this function.

The name member function returns your unit's name. It doesn't modify the calling instance.

The shareStimPaks member function lets you provide extra stimpaks to a teammate in need. It increments by number the stock of stimpaks.





After doing so, it decrements your stock by number stimpaks. If the number of stimpaks required is too big, print:

```
Don't be greedy
```

on the standard output, and do nothing.

Otherwise, print:

```
Keep the change.
```

The addStimPaks(unsigned int number) member function adds number stimpaks to your unit's collection. If number is equal to 0, it prints:

```
Hey boya, did you forget something?
```

Your unit can use stimpaks by calling the  ${\tt useStimPaks}()$  member function. It prints:

Time to kick some ass and chew bubble gum.

when possible.

Otherwise, it prints:

Mediiiiiic

You can query a unit's status at any point by calling its status member function. A unit communicates like so:

```
Soldier [NAME] reporting [NUMBER] stimpaks remaining sir!
```

where [NAME] is the name of the unit and [NUMBER] its number of stimpaks. This member function can be called on immutable Skats.

The following code must compile and display the following output:

```
int main()
{
    Skat s("Junior", 5);

    std::cout << "Soldier " << s.name() << std::endl;
    s.status();
    s.useStimPaks();

    return 0;
}</pre>
```

```
Terminal − + x

~/B-PDG-300> g++ -std=c++20 -Wall -Werror -Wextra *.cpp

~/B-PDG-300> ./a.out | cat -e

Soldier Junior$

Soldier Junior reporting 5 stimpaks remaining sir!$

Time to kick some ass and chew bubble gum.$
```





### **EXERCISE 1 - KOALABOT**

Turn in: KoalaBot.hpp, KoalaBot.cpp, Parts.hpp, Parts.cpp

Gentlemen, this is the **KoalaBot Kreog mk5** (the 4 previous versions have a tendency to burst into flames every now and then).

This new prototype will be your backup plan when the situation gets too tough for you (a recon mission in a mine field, for example).

The KoalaBot has 3 removable parts: arms, legs, and a head. I'll break the knees of the first of you to tell me the bot has 2 arms and legs.

All these parts are built according to the following model:

• Each class has a constructor with the following signature:

```
Constructor(std::string [...] serial, bool functional);
```

- They must have a serial represented by a string, as well as a boolean indicating whether or not it is functional:
  - The Arms class has a default serial of "A-O1".
  - The Legs class has a default serial of "L-O1".
  - The Head class has a default serial of "H-O1".

These classes are all functional by default.

- They should have the following public member functions:
  - bool isFunctional() indicates whether the piece is functional or not,
  - std::string serial() returns the part's serial,
  - void informations() prints:

```
[Parts] [PARTSTYPE] [SERIAL] status : {OK | KO}
```

preceded by a single tab, and followed by a newline.

[PARTSTYPE] must be replaced by the name of the class. [SERIAL] must be replaced by the object's serial. If the part is functional, print "OK". Otherwise, print "KO".



None of these member functions modify the calling instance.





Now that we have the various pieces, let's put them together. **Create the KoalaBot class**.

- it is composed of an instance of each of the previously created parts (Arms, Legs and Head),
- it has a serial, represented by a string, with a default value of "Bob-O1",
- it has a setParts member function that takes a reference to a constant part as parameter;



This function can be called with any class from the Parts.hpp file.

• it has a swapParts member function that takes a reference to a part as parameter. This part will be swapped with the KoalaBot's.



This function can be called with any class from the Parts.hpp file.

• it has a void informations() member function that prints:

[KoalaBot] [SERIAL]

followed by a newline,

[SERIAL] is the KoalaBot's serial, followed by information about each part of the KoalaBot, in the following order Arms, Legs then Head.



This member function does not modify the calling instance.

• it has a bool status() member function that returns true if all the parts of the KoalaBot are running, and false otherwise.



This member function does not modify the calling instance.





The following code must compile and print the following output:

```
int main()
{
    KoalaBot kb;

    std::cout << std::boolalpha << kb.status() << std::endl;
    kb.informations();
    return 0;
}</pre>
```

```
Terminal - + x

~/B-PDG-300> g++ -std=c++20 -Wall -Werror -Wextra *.cpp

~/B-PDG-300> ./a.out | cat -e

true$

[KoalaBot] Bob-01$

[Parts] Arms A-01 status : OK$

[Parts] Legs L-01 status : OK$

[Parts] Head H-01 status : OK$
```



## **EXERCISE 2 - HOUSTON, WE HAVE A PROBLEM**

Turn in: KreogCom.hpp, KreogCom.cpp

You are a team, and as such are closer than Parisians in the subway during rush hour.

This is true whether you are enjoying well-deserved R&R in the barracks, or deployed all over the jungle. In order to communicate, and more importantly locate your teammates, I introduce to you the pinnacle of our technology: the KreogCom.

This technological jewel locates your teammates in real-time.

The KreogCom works in the following way:

```
class KreogCom
{
public:
    KreogCom(int x, int y, int serial);
    ~KreogCom();

    void addCom(int x, int y, int serial);
    void removeCom();
    KreogCom *getCom();

    void ping();
    void locateSquad();

private:
    const int m_serial;
};
```

A KreogCom has a serial represented by a constant integer, as well as x and y coordinates.



It is up to you to add member data, but it must be private.

It has a constructor that lets you create a KreogCom by specifying its x and y coordinates, as well as its serial.

It has an addCom member function that creates a new KreogCom.

If the current KreogCom is not linked to any KreogCom, it is linked to the newly created one:

```
+----+ +------+
| this | --> | new KreogCom x, y, serial |
```

If the current KreogCom is already linked to another KreogCom, then the new KreogCom will replace it (see below):

It has a getCom member function that returns a pointer to the KreogCom linked to the current instance. If it is not linked, returns a null pointer.

It has a removeCom member function that removes the linked KreogCom.







Be careful not to break the communication chain.

It has a ping member function that prints the following information to the standard output:

KreogCom [SERIAL] currently at [X] [Y]

[SERIAL], [X] and [Y] are the member data of your KreogCom.



This member function doesn't modify the calling instance.

It has a locateSquad member function that prints information about all the linked KreogCom, and then the current instance's information:

[Displays info on linked KreogCom]
[Displays info on current KreogCom]



This member function doesn't modify the calling instance.



When destroying a KreogCom, the communication chain must not be broken.





The following code must compile and print the following output:

```
int main()
{
    KreogCom k(42, 42, 101010);
    k.addCom(56, 25, 65);
    k.addCom(73, 34, 51);

    k.locateSquad();
    k.removeCom();
    k.removeCom();
}
```

```
Terminal - + x

~/B-PDG-300> g++ -std=c++20 -Wall -Werror -Wextra *.cpp

~/B-PDG-300> ./a.out | cat -e

KreogCom 101010 initialized$

KreogCom 65 initialized$

KreogCom 51 initialized$

KreogCom 51 currently at 73 34$

KreogCom 65 currently at 56 25$

KreogCom 101010 currently at 42 42$

KreogCom 51 shutting down$

KreogCom 65 shutting down$

KreogCom 101010 shutting down$
```

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# **EXERCISE 3 - LOCK'N LOAD, BABY**

Turn in: Phaser.hpp, Phaser.cpp, Sounds.hpp

Now that you've gone through basic training, it's time to have some real fun.

This is the Phaser Kreog'o Blaster mk2, your new best friend.

From now on, you will train with it, eat with it and sleep with it.

This sweetheart has three different firing modes:

- REGULAR, for clean jobs
- PLASMA, to warm up the mood
- ROCKET, for surgical strikes

However, due to budget cuts, the weapon is being delivered in spare parts. It's time to roll up your sleeves and get to work, if you ever want to get blasting Dingos.

#### Implement the following class:

```
class Phaser
{
public:
    enum AmmoType
    { ... };
    Phaser(int maxAmmo, AmmoType type);
    ~Phaser();
    void fire();
    void ejectClip();
    void changeType(AmmoType newType);
    void reload();
    void addAmmo(AmmoType type);
    int getCurrentAmmos();
private:
    static const int Empty;
    [...]
```

The Sounds class must define the following constant class variables:

```
std::string Regular;
std::string Plasma;
std::string Rocket;
```



These variables must not be assigned within the files you turn in! That will be done in the correction main.





A Phaser has a maximum amount of ammunition, a number representing the amount of ammunition currently loaded, a sound for each type of firing mode, a magazine with ammunition and a default type of ammunition for the weapon.

A Phaser has a default magazine of 20 REGULAR bullets.

A Phaser is fully loaded upon creation.

The Empty variable represents an empty magazine. It is strongly recommended to use it in your program. You MUST initialize it with the value O.

When calling the fire member function, you must print

Clip empty, please reload

if the magazine is empty.

If not, you must print the sound of the ammunition loaded in the first case of the magazine. Once done, the size of the magazine is reduced by 1, to represent the round that was fired.

The ejectClip member function ejects the magazine in the weapon and reduces the amount of ammunition to O.

The change Type member function prints the following to the standard output:

Switching ammo to type: [TYPE]

where <code>[TYPE]</code> is the value of the parameter in lowercase (ex: <code>regular</code> for <code>REGULAR</code>). Calling this member function changes the default type for the <code>Phaser</code>.

The reload member function prints

Reloading...

and reloads the weapon with its default ammunition type.

The addAmmo member function adds a round with the type type at the end of the magazine. If the current amount of ammunition is equal to the maximum amount for the weapon, print

Clip full

to the standard output, and do nothing.

The getCurrentAmmos member function returns the amount of ammunition in the magazine.



The getCurrentAmmos member function can be called on immutable Phaser objects.





The following code must compile and print the following output:

```
int main()
{
    Phaser p(5, Phaser::ROCKET);

    p.fire();
    p.reload();

    std::cout << "Firing all ammunition" << std::endl;
    while (p.getCurrentAmmos() > 0)
        p.fire();

    return 0;
}
```

```
Terminal - + x

~/B-PDG-300> g++ -std=c++20 -Wall -Werror -Wextra *.cpp

~/B-PDG-300> ./a.out | cat -e

Booooooom$

Reloading...$

Firing all ammunitions$

Booooooom$

Booooooom$

Booooooom$

Booooooom$

Booooooom$

Booooooom$

Booooooom$

Booooooom$
```



In this example, the rocket sound is "Booooooom". It's up to you to find out how to initialize it.



#### **EXERCISE 4 - G-SQUAD**

Turn in: Skat.hpp/cpp, Phaser.hpp/cpp, Sounds.hpp, KreogCom.hpp/cpp, Squad.hpp/cpp

OK guys, you're all set.

I have nothing more to teach you.

However, before you go blasting Dingos, you have to get geared up.

A Skat has a Phaser and a KreogCom.

Thus, add a constructor with the following signature:

```
Skat(const std::string &name, int stimPaks, int serial, int x, int y, Phaser::AmmoType type);
```

The serial, x, y and type parameters are the information required to construct the Kreog Com and Phaser.

Each Skat gets a Phaser with 20 ammunition.



This class doesn't have a default constructor anymore.

Add the following member functions:

- void fire() so that the Skat opens fire
- void locate() gives the Skat's position
- void reload() so that the Skat reloads
- KreogCom &com() provides access to the Skat's communicator



It's up to you to figure out which of these member functions are constant.

Add the following member function to the KreogCom: void addCom(KreogCom \*com), which links the current KreogCom to com.



The correction won't call the removeCom member function, no need to modify it.

#### Good.

Now that you look like something decent, it's time to get organized.





#### Implement the following class:

Sounds from the Sounds class must be initialized in the Squad.cpp file, with the following values:

- Regular: "Bang"
- Plasma: "Fwooosh"
- Rocket: "Boouuuuum"

A squad is composed of size Skats. By default, a squad has 5 Skats.

The last teammate in a squad must be a null pointer.

Teammate's communicators serials are equivalent to the place of the Skat within the squad (Skat O -> com Skat N -> com

The first Skat is located at the posXBegin, posYBegin position.

The x position is incremented by 10 for each  $\mathtt{Skat}$  of the squad. The y position is incremented by 15 for each  $\mathtt{Skat}$  of the squad. For instance,

```
Skat 0 -> X = 0, Y = 0;

Skat 1 -> X = 10, Y = 15;

...;

Skat n -> X = (n) * 10, Y = (n) * 15
```

The communicator of the Skats are linked together, based on the following diagram:

```
+----+ +----+ +----+ +----+
| com Skat 0 | --> | com Skat 1 | --> | ... | --> | com Skat n |
+-----+ +-----+
```

The fire member function makes every squad member open fire.

The localisation member function prints the position of each squad member, starting from the FIRST member





The skats member function returns all the squad members

The at member function returns the Skat at the idx index. If idx is not valid, the function returns a null pointer

The size member function returns the size of the squad

In order to simplify squad interaction, **implement the following function**:

```
void foreach([...] beginIdx, [...] actionPtr)
```

in the files related to the squad.

This function takes as parameter an index representing the beginning of a group of Skats, as well as a pointer to a member function of the Skat class, taking no parameters and returning void.



This function will be called with all the member functions of the Skat class with no parameters and returning void.



Is a member function different from a const member function with the exact same signature? int class::fct() ==? int class::fct() const





The following code must compile and print the following:

```
int main()
{
    Squad s(0, 0, Phaser::REGULAR);
    s.fire();
    return 0;
}
```

```
Terminal
             g++ -std=g++20 -Wall -Werror -Wextra *.cpp
 /B-PDG-300> ./a.out | cat -e
KreogCom O initialized$
KreogCom 1 initialized$
KreogCom 2 initialized$
KreogCom 3 initialized$
KreogCom 4 initialized$
Bang$
Bang$
Bang$
Bang$
Bang$
KreogCom 0 shutting down$
KreogCom 1 shutting down$
KreogCom 2 shutting down$
KreogCom 3 shutting down$
KreogCom 4 shutting down$
```



That's it.

Break now private, and good luck for your mission.

