«Script» Camera

- + conf: ConfigParser + cc: CameraControl
- + static_file(filename: PathLike[str] | str) -> Response
- + web_index()
- + web_pause()
- + web_resume()
- + photo_view()
- + web_shutdown()
- + stream()
- + photo(focus: float = -2)
- + settings(focus: float = -1)
- + preview(focus: float = -2)
- + focus(focus: float = -1)
- + aruco(id: str = "")
- + meta()
- + start_web()

CameraControl

- + ___init___()
- + run()
- + photo(settings: CamSettings | str): bytes
- + set_settings(settings: CamSettings | str): CamSettings
- + preview(settings: CamSettings | str = {}): bytes
- + focus(focus: float): str
- + aruco(): list[ArucoMarkerPos]
- + meta():None | Metadata
- + pause()
- + resume()
- + shutdown()
- + say_moin()

CameraAruco

- + detect_from_rgb(image: bytes): list[ArucoMarkerPos]
- + detect(image: bytes): list[ArucoMarkerPos]

CameraInterface

- + __init__(folder: str)
- + make_picture(settings: CamSettings = {}, preview=False): bytes
- + save_picture(settings: CamSettingsWithFilename, aruco_callback: None | Callable[[list[ArucoMarkerPos], Metadata], None]): tuple[str, Metadata]
- + aruco_search_in_background_from_file(filename: str, metadata: Metadata aruco_callback: Callable[[list[ArucoMarkerPos],

Metadata], None]): None

+ aruco_search_in_background(img: bytes, file: str, metadata: Metadata,

aruco_callback: Callable[[list[ArucoMarkerPos],

- Metadata], None]): None + meta(): None | Metadata
- + find_aruco(inform_after_picture: None | Callable[[], None] = None): list[ArucoMarkerPos]
- + pause()
- + resume()
- + set_settings(settings: CamSettings): CamSettings
- + focus(focus: float): str