«Script» Camera + conf: ConfigParser + cc: CameraControl + static_file(filename: PathLike[str] | str) -> + web index() + web_pause() + web resume() + photo_view() + web shutdown() + stream() + photo(focus: float = -2) + settings(focus: float = -1) + preview(focus: float = -2) + focus(focus: float = -1) + aruco(id: str = "") + meta()

CameraControl

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+ __init__()
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- + run()
- + photo(settings: CamSettings | str): bytes
- + set_settings(settings: CamSettings | str): Cam\$
- + preview(settings: CamSettings | str = {}): byte
- + focus(focus: float): str
- + aruco(): list[ArucoMarkerPos]
- + meta():None | Metadata
- + pause()
- + resume()
- + shutdown()
- + say_moin()

CameraAruco

- + detect_from_rgb(image: bytes): list[ArucoN
- + detect(image: bytes): list[ArucoMarkerPos

CameraInterface

- + __init__(folder: str)
- + make_picture(settings: CamSettings = {}, preview
- + save_picture(settings: CamSettingsWithFilename, aruco_callback: None | Callable[[list[ArucoMark Metadata], None]): tuple[str, Metadata]
- + aruco_search_in_background(img: bytes, file: str, metadata: Metadata, aruco_callback: Callable[[list[ArucoMarkerPos],
 - aruco_callback: Callable[[list[ArucoMarkerPos Metadata], None]): None
- + meta(): None | Metadata
- + find_aruco(inform_after_picture: None | Callable[[], = None): list[ArucoMarkerPos]
- + pause()
- + resume()
- + set_settings(settings: CamSettings): CamSettings
- + focus(focus: float): str