

## CameraControl

- + \_\_init\_\_()
- + run()
- + photo(settings: CamSettings | str): bytes
- + set\_settings(settings: CamSettings | str): CamSe
- + preview(settings: CamSettings | str = {}): bytes
- + focus(focus: float): str
- + aruco(): list[ArucoMarkerPos]
- + meta():None | Metadata
- + pause()
- + resume()
- + shutdown()
- + say\_moin()

## CameraInterface

- + \_\_init\_\_(folder: str)
- + make\_picture(settings: CamSettings = {}, preview
- + save\_picture(settings: CamSettingsWithFilename, aruco\_callback: None | Callable[[list[ArucoMark Metadata], None]): tuple[str, Metadata]
- + aruco\_search\_in\_background\_from\_file(filename: st metadata: Metadata aruco\_callback: Callable[[list[ArucoMarkerPos], Metadata], None]): None
- + aruco\_search\_in\_background(img: bytes, file: str, metadata: Metadata, aruco\_callback: Callable[[list[ArucoMarkerPos], Metadata], None]): None
- | + meta(): None | Metadata
- + find\_aruco(inform\_after\_picture: None | Callable[[], = None): list[ArucoMarkerPos]
- + pause()
- + resume()
- + set\_settings(settings: CamSettings): CamSettings
- + focus(focus: float): str

## CameraAruco

- + detect\_from\_rgb(image: bytes): list[ArucoN
- + detect(image: bytes): list[ArucoMarkerPos]