

CameraControl

- + __init__()
- + run()
- + photo(settings: CamSettings | str): bytes
- + set_settings(settings: CamSettings | str): CamSettings
- + preview(settings: CamSettings | str = {}): bytes
- + focus(focus: float): str
- + aruco(): list[ArucoMarkerPos]
- + meta():None | Metadata
- + pause()
- + resume()
- + shutdown()
- + say_moin()

CameraInterface

- + __init__(folder: str)
- + make_picture(settings: CamSettings = {}, preview=False): bytes
- + save_picture(settings: CamSettingsWithFilename, aruco_callback: None | Callable[[list[ArucoMarkerPos],
 - Metadata], None]): tuple[str, Metadata]
- + aruco_search_in_background_from_file(filename: str,
 - metadata: Metadata
 - $aruco_callback: Callable [[list[ArucoMarkerPos],\\$
 - Metadata], None]): None
- + aruco_search_in_background(img: bytes, file: str,
 - metadata: Metadata,
 - aruco_callback: Callable[[list[ArucoMarkerPos],
 - Metadata], None]): None
- + meta(): None | Metadata
- + find_aruco(inform_after_picture: None | Callable[[], None] = None): list[ArucoMarkerPos]
- + pause()
- + resume()
- + set_settings(settings: CamSettings): CamSettings
- + focus(focus: float): str

CameraAruco

- + detect_from_rgb(image: bytes): list[ArucoMarkerPos]
- + detect(image: bytes): list[ArucoMarkerPos]