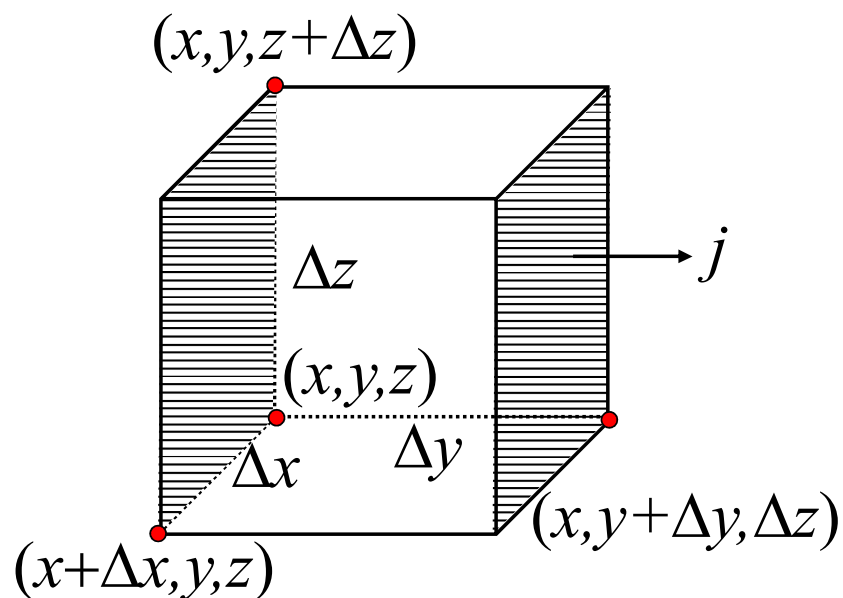


3. 扩散运动

物理图像：粒子在空间的运动



空间离散化，每一个粒子都在一个正方体中。不同时间从一个盒子转移到另一个盒子。

$$\rho_i(t) = N_i / \Delta V \quad \text{第} i \text{个盒子内粒子的密度}$$

质量能量守恒---粒子不能凭空产生也不能凭空消灭，只能从一个格子转移到另一个格子

$$\rho_i(t + \Delta t) - \rho_i(t) = (n_{x\uparrow} + n_{x\downarrow} + n_{y\uparrow} + n_{y\downarrow} + n_{z\uparrow} + n_{z\downarrow}) / \Delta V$$

第i个正方体格子内，粒子数量的变化等于6个方向进来的粒子数减去出去的粒子数

$$\frac{\rho_i(t + \Delta t) - \rho_i(t)}{\Delta t} = \frac{n_{x\uparrow}}{\Delta t} \frac{1}{\Delta V} + \dots$$

$$\frac{\rho_i(t + \Delta t) - \rho_i(t)}{\Delta t} = \frac{1}{\Delta t} \frac{n_{x\uparrow}}{\Delta S} \frac{\Delta S}{\Delta V} + \dots$$

$$\frac{\rho_i(t + \Delta t) - \rho_i(t)}{\Delta t} = \frac{(J_{x\uparrow} - J_{x\downarrow})}{\Delta x} + \dots$$

$$J = \frac{n}{\Delta S \Delta t} \quad \text{单位时间正向流过单位面积的粒子数}$$

扩散运动

连续性方程 $\rho_t(x, y, z, t) = \frac{\partial J(x, y, z, t)}{\partial x} + \dots = \nabla \cdot J(x, y, z, t)$

Fick's law $J = -k \nabla \cdot \rho$ 浓度高的区域向浓度低的区域
流动

$$\rho_t = -k \nabla \nabla \cdot \rho$$

数学物理方程的分类

波动方程wave equation : (双曲型方程)

描述现象: 声波、电磁波等波动

$$u_{tt} - a^2 \nabla^2 u = 0$$

输运方程Diffusion Equation : (抛物型方程)

描述现象: 热扩散、物质扩散等
扩散过程

$$u_t - a^2 \nabla^2 u = 0$$

稳恒状态方程: (椭圆型方程)

描述现象: 电势、稳定温度场
分布等与时间无关的稳定场。

$$\nabla^2 u = 0$$

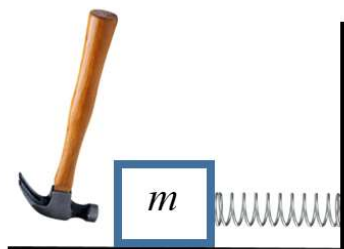
$$\rho u_{tt} = T u_{xx} - R u_t \implies T u_{xx} - R u_t = 0$$

定解条件

- 泛定方程和定解条件：
 - 泛定方程：

描述了系统内部具有代表性（一般性）的点处的运动规律的偏微分方程
 - 定解条件：
 - 边界条件：描述外界影响
 - 衔接条件：描述内部特殊点的运动规律
 - 初始条件：描述历史的作用

初始条件



$u(t=0)$ $t=0$, 小木块静止在平面上

$u'(t=0)$ $t=0$, 小木块速度为0

$$\frac{\partial^2 u(t)}{\partial t^2} = -\omega^2 u(t) + f_n(t)$$

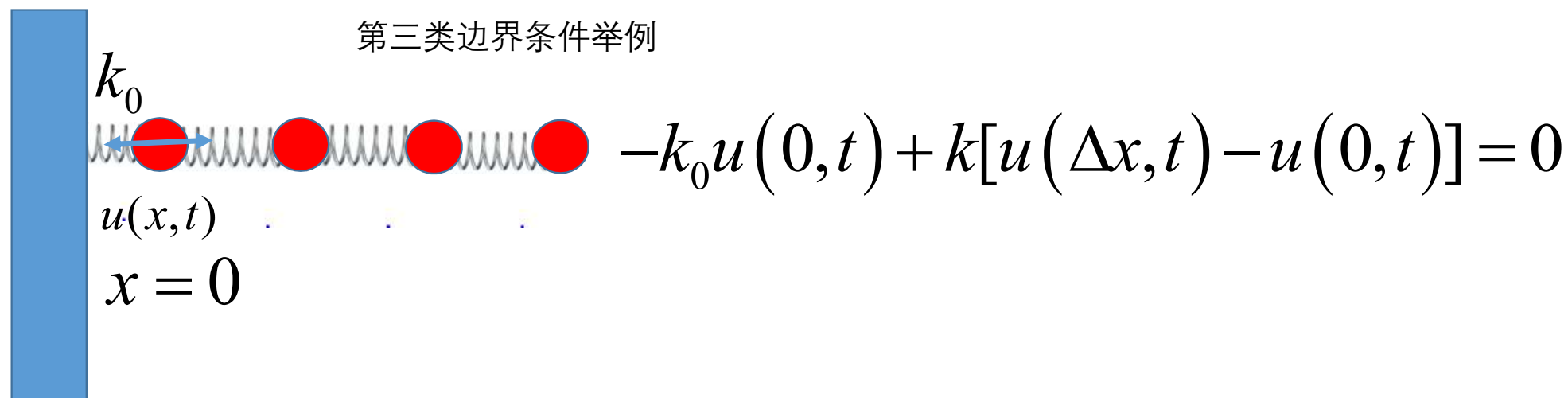
初始条件应当给出 $u(x, y, z, t_0)$
整个系统在 t_0 时刻的状态

边界条件

第一类：表征量在边界处的值 $u(x, t)|_{x \in S}$ Dirichlet boundary condition

第二类：其法向导数在边界处的值 $u_x(x, t)|_{x \in S}$ Neumann boundary condition

第三类：前两者的线性组合 $u(x, t) + Au_x(x, t)|_{x \in S}$



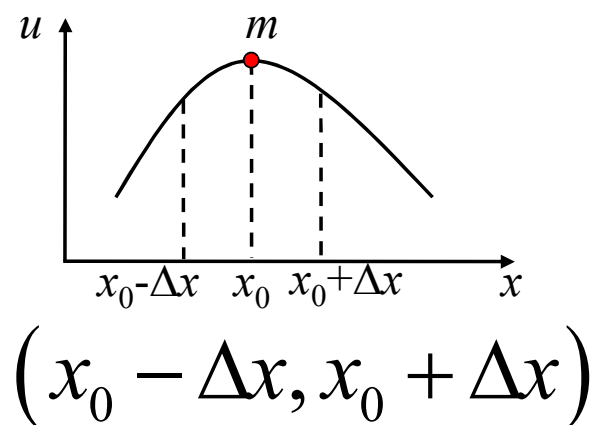
衔接条件

外界原因，体系在研究区域内出现突变点，使得该点处不满足泛定方程。

弦的横向运动, x_0 处受外力 $f(t)$ ，使得该点静止。

$$u(x_0 + 0, t) = u(x_0 - 0, t)$$

$$mu_{tt}(x_0, t) = T[u_x(x_0 + 0, t) - u_x(x_0 - 0, t)] - f(t) = 0$$



弦的自由横振动---行波法

$$\begin{cases} u_{tt} = a^2 u_{xx}, & |x| < \infty, t > 0 \\ u|_{t=0} = \phi(x), \quad u_t|_{t=0} = \psi(x), & |x| < \infty \end{cases}$$

弦的自由横振动---行波法

$$(\partial_t - a\partial_x)(\partial_t + a\partial_x)u = 0$$

做变换得到:

$$\begin{aligned}\partial_\xi &= \partial_t + a\partial_x \\ \partial_\eta &= \partial_t - a\partial_x\end{aligned}\quad \partial_\eta \partial_\xi u(\xi, \eta) = 0$$

$$t = ?$$

$$x = ?$$

弦的自由横振动---行波法

$$\begin{bmatrix} \xi \\ \eta \end{bmatrix} = T \begin{bmatrix} t \\ x \end{bmatrix} = \begin{bmatrix} T_{11} & T_{12} \\ T_{21} & T_{22} \end{bmatrix} \begin{bmatrix} t \\ x \end{bmatrix}$$

$$\begin{aligned} \partial_t &= \frac{\partial}{\partial \xi} \frac{\partial \xi}{\partial t} + \frac{\partial}{\partial \eta} \frac{\partial \eta}{\partial t} = T_{11} \frac{\partial}{\partial \xi} + T_{12} \frac{\partial}{\partial \eta} \\ \partial_x &= \frac{\partial}{\partial \xi} \frac{\partial \xi}{\partial x} + \frac{\partial}{\partial \eta} \frac{\partial \eta}{\partial x} = T_{12} \frac{\partial}{\partial \xi} + T_{22} \frac{\partial}{\partial \eta} \end{aligned} \quad \left. \vphantom{\begin{aligned} \partial_t \\ \partial_x \end{aligned}} \right\} (\partial_t - a\partial_x)(\partial_t + a\partial_x)u = 0$$

弦的自由横振动---行波法

$$\begin{aligned} & (\partial_t - a\partial_x)(\partial_t + a\partial_x)u \\ &= T_{11}^2 \left(\frac{\partial}{\partial \xi} \right)^2 + 2T_{12}T_{11} \frac{\partial}{\partial \eta} \frac{\partial}{\partial \xi} + T_{12}^2 \left(\frac{\partial}{\partial \eta} \right)^2 - a^2 T_{21}^2 \left(\frac{\partial}{\partial \xi} \right)^2 - 2a^2 T_{21}T_{22} \frac{\partial}{\partial \eta} \frac{\partial}{\partial \xi} - a^2 T_{22}^2 \left(\frac{\partial}{\partial \eta} \right)^2 \\ &= (T_{11}^2 - a^2 T_{21}^2) \left(\frac{\partial}{\partial \xi} \right)^2 + (2T_{12}T_{11} - 2a^2 T_{21}T_{22}) \frac{\partial}{\partial \eta} \frac{\partial}{\partial \xi} + (T_{12}^2 - a^2 T_{22}^2) \left(\frac{\partial}{\partial \eta} \right)^2 \end{aligned}$$

$$\frac{\partial}{\partial \eta} \frac{\partial}{\partial \xi} u = 0$$

弦的自由横振动---行波法

$$\partial_{\xi} = \partial_t + a\partial_x$$

$$\partial_{\eta} = \partial_t - a\partial_x$$

$$\partial_{\xi} = \frac{\partial}{\partial t} \frac{\partial t}{\partial \xi} + \frac{\partial}{\partial x} \frac{\partial x}{\partial \xi} = \partial_t + a\partial_x$$

$$\partial_{\eta} = \frac{\partial}{\partial t} \frac{\partial t}{\partial \eta} + \frac{\partial}{\partial x} \frac{\partial x}{\partial \eta} = \partial_t - a\partial_x$$

$$\frac{\partial t}{\partial \xi} = 1 \quad \frac{\partial x}{\partial \xi} = a \quad \frac{\partial t}{\partial \eta} = 1 \quad \frac{\partial x}{\partial \eta} = -a$$

$$\begin{cases} t = \xi + \eta \\ x = a(\xi - \eta) \end{cases}$$

弦的自由横振动---行波法

采用书上的变换：

$$\begin{cases} \xi = x + at \\ \eta = x - at \end{cases}$$

$$\frac{\partial}{\partial x} = \frac{\partial \xi}{\partial x} \frac{\partial}{\partial \xi} + \frac{\partial \eta}{\partial x} \frac{\partial}{\partial \eta} = \frac{\partial}{\partial \xi} + \frac{\partial}{\partial \eta}$$

$$\frac{\partial^2}{\partial x^2} = \left(\frac{\partial}{\partial \xi} + \frac{\partial}{\partial \eta} \right)^2 = \frac{\partial^2}{\partial \xi^2} + 2 \frac{\partial^2}{\partial \xi \partial \eta} + \frac{\partial^2}{\partial \eta^2}$$

$$\frac{\partial^2}{\partial t^2} = a^2 \left(\frac{\partial^2}{\partial \xi^2} - 2 \frac{\partial^2}{\partial \xi \partial \eta} + \frac{\partial^2}{\partial \eta^2} \right)$$

弦的自由横振动---行波法

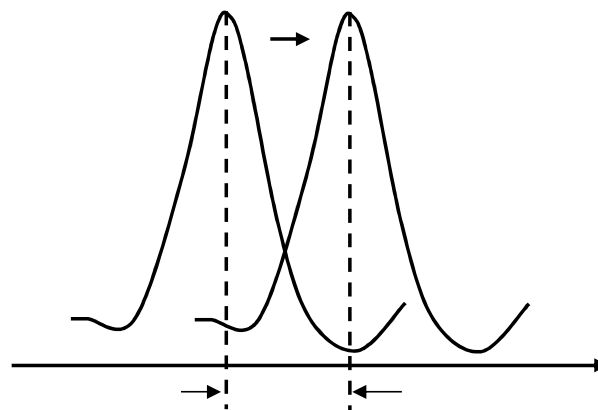
则泛定方程变为

$$u_{tt} - a^2 u_{xx} = -4a^2 u_{\xi\eta} = 0$$

求积分, 得 $u = \int f_1(\xi) d\xi + g(\eta) = f(\xi) + g(\eta)$

弦振动方程的通解

$$u = f(x + at) + g(x - at)$$



无界弦的自由横振动---行波法

$$\begin{cases} f(x) + g(x) = \phi(x) \\ \left[f_t(x+at) + g_t(x-at) \right] \Big|_{t=0} = \psi(x) \end{cases} \quad \text{代入初始条件}$$

$$\begin{cases} f(x) + g(x) = \phi(x) \\ af'(x) - ag'(x) = \psi(x) \end{cases}$$

定解问题的解（d'Alembert公式）

$$\begin{aligned} u(x, t) &= f(x + at) + g(x - at) = \frac{\phi(x + at) + \phi(x - at)}{2} + \frac{\Psi(x + at) + \Psi(x - at)}{2} \\ &= \frac{\phi(x + at) + \phi(x - at)}{2} + \frac{1}{2a} \int_{x-at}^{x+at} \psi(\xi) d\xi \end{aligned}$$

多元积分坐标变换

$$\begin{cases} x = r \cos \theta \sin \varphi \\ y = r \sin \theta \sin \varphi \\ z = r \cos \varphi \end{cases} \quad \begin{array}{l} r \geq 0 \\ 0 \leq \theta \leq 2\pi \\ 0 \leq \varphi \leq \pi \end{array}$$

$$\int f(x, y, z) dx dy dz$$

$$= \int f(r \cos \theta \cos \varphi, r \sin \theta \cos \varphi, r \sin \varphi) J(r, \theta, \varphi) dr d\theta d\varphi$$

球柱积分元

$$\begin{cases} x = r \cos \theta \sin \varphi \\ y = r \sin \theta \sin \varphi \\ z = r \cos \varphi \end{cases}$$

$$J = \begin{vmatrix} \frac{\partial x}{\partial r} & \frac{\partial x}{\partial \theta} \\ \frac{\partial y}{\partial r} & \frac{\partial y}{\partial \theta} \end{vmatrix} = \begin{vmatrix} \cos \theta & -r \sin \theta \\ \sin \theta & r \cos \theta \end{vmatrix} = r$$

$$J = \begin{vmatrix} \frac{\partial x}{\partial r} & \frac{\partial x}{\partial \theta} & \frac{\partial x}{\partial \varphi} \\ \frac{\partial y}{\partial r} & \frac{\partial y}{\partial \theta} & \frac{\partial y}{\partial \varphi} \\ \frac{\partial z}{\partial r} & \frac{\partial z}{\partial \theta} & \frac{\partial z}{\partial \varphi} \end{vmatrix} = \begin{vmatrix} \cos \theta \sin \varphi & -r \sin \theta \sin \varphi & r \cos \theta \cos \varphi \\ \sin \theta \sin \varphi & r \cos \theta \sin \varphi & r \sin \theta \cos \varphi \\ \cos \varphi & 0 & -r \sin \varphi \end{vmatrix} = r^2 \sin \varphi$$

场算符

$$\nabla = \mathbf{e}_x \frac{\partial}{\partial x} + \mathbf{e}_y \frac{\partial}{\partial y} + \mathbf{e}_z \frac{\partial}{\partial z}, \quad \nabla^2 = \frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} + \frac{\partial^2}{\partial z^2}$$

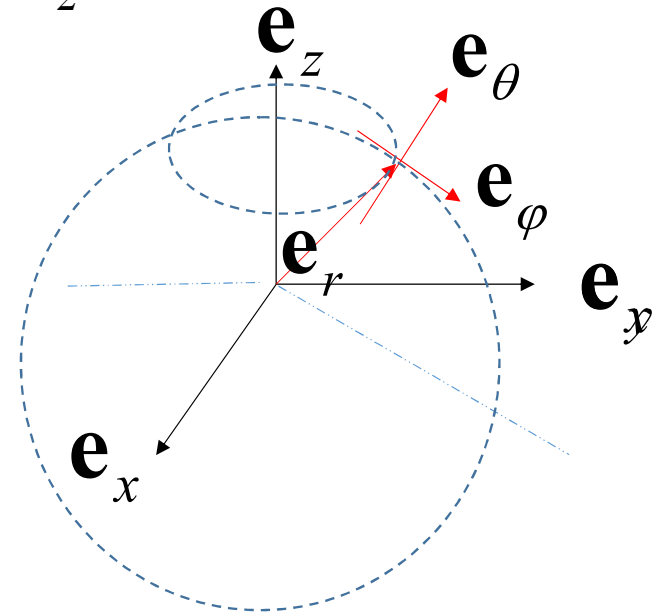
$$\mathbf{e}_i \cdot \mathbf{e}_j = \delta_{ij} \quad \left\{ \begin{array}{l} x = r \cos \theta \sin \varphi \\ y = r \sin \theta \sin \varphi \\ z = r \cos \varphi \end{array} \right.$$

坐标变换

$$\mathbf{e}_r = \frac{\mathbf{r}}{r} = \cos \theta \sin \varphi \mathbf{e}_x + \sin \theta \sin \varphi \mathbf{e}_y + \cos \varphi \mathbf{e}_z$$

$$\mathbf{e}_\theta = -\sin \theta \mathbf{e}_x + \cos \theta \mathbf{e}_y$$

$$\mathbf{e}_\varphi = \cos \theta \cos \varphi \mathbf{e}_x + \sin \theta \cos \varphi \mathbf{e}_y - \sin \varphi \mathbf{e}_z$$



$$\frac{\partial}{\partial x} = \frac{\partial r}{\partial x} \frac{\partial}{\partial r} + \frac{\partial \theta}{\partial x} \frac{\partial}{\partial \theta} + \frac{\partial \varphi}{\partial x} \frac{\partial}{\partial \varphi} = \cos \theta \sin \varphi \frac{\partial}{\partial r} - r \sin \theta \sin \varphi \frac{\partial}{\partial \theta} + r \cos \varphi \frac{\partial}{\partial \varphi}$$

$$\frac{\partial}{\partial y} = \sin \theta \sin \varphi \frac{\partial}{\partial r} + r \cos \theta \sin \varphi \frac{\partial}{\partial \theta} + r \cos \varphi \frac{\partial}{\partial \varphi}$$

$$\frac{\partial}{\partial z} = \cos \varphi \frac{\partial}{\partial r} - r \sin \varphi \frac{\partial}{\partial \varphi}$$

$$\mathbf{e}_x = \cos \theta \sin \varphi \mathbf{e}_r - \sin \theta \mathbf{e}_\theta + \cos \theta \cos \varphi \mathbf{e}_\varphi$$

$$\mathbf{e}_y = \sin \theta \sin \varphi \mathbf{e}_r + \cos \theta \mathbf{e}_\theta + \sin \theta \cos \varphi \mathbf{e}_\varphi$$

$$\mathbf{e}_z = \cos \varphi \mathbf{e}_r - \sin \varphi \mathbf{e}_\varphi$$

<http://mathworld.wolfram.com/SphericalCoordinates.html>

$$\nabla = \mathbf{e}_x \frac{\partial}{\partial x} + \mathbf{e}_y \frac{\partial}{\partial y} + \mathbf{e}_z \frac{\partial}{\partial z}$$

场算符

$$\nabla = \mathbf{e}_r \frac{\partial}{\partial r} + \frac{\mathbf{e}_\theta}{r} \frac{\partial}{\partial \theta} + \mathbf{e}_z \frac{\partial}{\partial z}$$

$$\nabla^2 = \frac{1}{r} \frac{\partial}{\partial r} \left(r \frac{\partial}{\partial r} \right) + \frac{1}{r^2} \frac{\partial}{\partial \theta^2} + \frac{\partial^2}{\partial z^2}$$

$$\nabla = \mathbf{e}_r \frac{\partial}{\partial r} + \frac{\mathbf{e}_\theta}{r \sin \varphi} \frac{\partial}{\partial \theta} + \frac{\mathbf{e}_\varphi}{r} \frac{\partial}{\partial \varphi}$$

$$\nabla^2 = \frac{1}{r^2} \frac{\partial}{\partial r} \left(r^2 \frac{\partial}{\partial r} \right) + \frac{1}{r^2 \sin \varphi} \frac{\partial}{\partial \varphi} \left(\sin \varphi \frac{\partial}{\partial \varphi} \right) + \frac{1}{r^2 \sin^2 \theta} \frac{\partial^2}{\partial \theta^2}$$

球面波

$$\begin{cases} u_{tt} = a^2 \nabla^2 u, \\ u|_{t=0} = \phi(r), \quad u_t|_{t=0} = \psi(r) \end{cases}$$

$$\begin{cases} u_{tt} = a^2 \frac{1}{r^2} \frac{\partial}{\partial r} \left(r^2 \frac{\partial u}{\partial r} \right), & r \geq 0, t > 0 \\ u|_{t=0} = \phi(r), \quad u_t|_{t=0} = \psi(r) \end{cases}$$

球面波

$$v = ru \quad \begin{cases} v_{tt} = a^2 v_{rr}, & r > 0, t > 0 \\ v|_{r=0} = 0, & t \geq 0 \\ v|_{t=0} = r\phi(r), \quad v_t|_{t=0} = r\psi(r) \end{cases}$$

通解为

$$v = f(r + at) + g(r - at)$$