ATHAM-Fluidity: How to Install and Run

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# Downloading the ATHAM-Fluidity repository from GitHub

ATHAM-Fluidity is part of the Fluidity project (<http://fluidityproject.github.io/>). Fluidity is an open source, general purpose, multiphase computational fluid dynamics code capable of numerically solving the Navier-Stokes equation and accompanying field equations on arbitrary unstructured finite element meshes in one, two and three dimensions. Fluidity has been used in a number of different scientific areas including geophysical fluid dynamics, computational fluid dynamics, ocean modelling and mantle convection. ATHAM-Fluidity is a development of the main Fluidity project better suited for high resolution atmospheric processes. The ATHAM-Fluidity repository can be found on GitHub at <https://github.com/FluidityProject/ATHAM-Fluidity>. To download the repository onto a Linux machine (that has git installed), open up a terminal window and navigate to the directory under which you wish to store your local copy of ATHAM-Fluidity, e.g. $HOME/ATHAM-Fluidity. Then type the following command (after the command prompt `$'):

$ git clone https://github.com/FluidityProject/ATHAM-Fluidity.git

# Dependencies and environment variables

ATHAM-Fluidity requires a certain number of dependencies (external packages and libraries) to be installed before it can be compiled. An essential step before compiling ATHAM-Fluidity is therefore to make sure that all these dependencies are present and can be reached by the code. There are three possible ways to achieve this, depending on the system you are using:

* Install the fluidity-dev package. This installs all the dependencies automatically, using default versions and install locations. This procedure is described in Section 2.1
* Self-installation. Each dependency can be installed separately if desired (e.g. if the user wants to install non-default versions of the dependencies or choose different install locations). This procedure is described in Section 2.2
* Loading modules. This procedure can be followed if you are running ATHAM-Fluidity on a cluster that uses environment modules, and the dependencies have already been centrally built by a system administrator. This procedure is described in Section 2.3

## Installing the fluidity-dev package

With the Ubuntu operating system, the fluidity-dev package can be installed from the terminal window by issuing the following three commands (assuming that the user has administrative “sudo'” privileges):

$ sudo apt-add-repository -y ppa:fluidity-core/ppa

$ sudo apt-get update

$ sudo apt-get install fluidity-dev

Note that Fluidity (and thus ATHAM-Fluidity) is only supported for use with the GNU Compiler Collection (GCC) and OpenMPI executables. It is possible that a different compiler collection (e.g. Intel, Portland Group, etc.) is set up as the default on your system. Use of the supported executables can be ensured by setting the following environment variables:

$ export CC=gcc

$ export CXX=g++

$ export CPP=cpp

$ export FC=gfortran

$ export F90=gfortran

$ export F77=gfortran

$ export PATH=/usr/bin:$PATH

It is recommended that you add the above line (minus the command prompt) to your .bashrc fille, which is located in your home directory, so that these environment variables are remembered for every login session.

## Self-installation

The following section describes the installation of the ATHAM-Fluidity dependencies on a Linux machine that was running Ubuntu 16.04 LTS (Xenial Xerus). However, it is expected that the same procedure will apply on a machine running Ubuntu 14.04 LTS (Trusty Tahr). It is assumed that the user has administrative `sudo' privileges.

When newer versions of the dependencies are released, it takes time for their compatibility to be fully tested by the model developers, and so version support often lags behind the most recent versions of these dependencies. For this reason, it is recommended to install the dependencies from source code, with versions that are known to be stable, rather than using a package management tool (e.g. `apt-get install' on Ubuntu) which will install the most recent version of the dependency by default. It is recommended to install each dependency in a separate sub-directory, under a location that can be reached by all users. Here, we will install each dependency in a sub-directory under /usr/local/fluidity/. The first step is therefore to create this directory:

$ sudo mkdir /usr/local/fluidity

### GNU compilers

The GNU Compiler Collection (GCC) should come pre-installed with Ubuntu. You can check the version (and existence) of GCC installed on your system by typing:

$ gcc –version

Here, we are using gcc 4.8.4. It is possible that another compiler collection (e.g. Intel, Portland Group, etc.) is set up as the default on your system; see Section 2.1 for instructions on how to ensure that the GCC compilers are always used.

### Python

Python should also come pre-installed with Ubuntu. Again, you can check the (default) version on your system by typing `python --version' at the command prompt. Here, we are using Python 2.7.6. Note that Python 3 is not yet supported - you may therefore have to change the symbolic link /usr/bin/python to point to an earlier version of the python executable, e.g. python2.7. There are also a number of Python packages that are required for ATHAM-Fluidity to build. Again, these packages are typically installed by default. One important package is NumPy. It is possible to check whether NumPy is installed by typing the following at the command line:

$ python -c "import numpy; print numpy. version "

Here, we are using NumPy 1.8.2. If you see an import error, you should install the NumPy package manually.

### OpenMPI

ATHAM-Fluidity must be built with MPI support, even if the model will only be run on a single processor rather than in parallel. It is recommended to install OpenMPI. Here, we install OpenMPI 1.6.5. The source code can be download from <https://www.openmpi.org/software/ompi/v1.6/> (choose the gzipped tar file, i.e. openmpi-1.6.5.tar.gz). Untar the file somewhere locally and move into the untarred directory. Also, create a sub-directory under /usr/local/fluidity ready for installation:

$ tar -xzvf openmpi-1.6.5.tar.gz

$ cd openmpi-1.6.5

$ sudo mkdir /usr/local/fluidity/openmpi-1.6.5

OpenMPI is then built by issuing the following three commands:

$ ./configure --prefix=/usr/local/fluidity/openmpi-1.6.5

$ make

$ sudo make install

Once installation is complete, you may (if you wish) delete the local openmpi-1.6.5 directory and tar file. In order that the OpenMPI executables can be found when building ATHAM-Fluidity (as well as some of the dependencies below), you will need to issue the following command (and add it to your .bashrc file if you want the same behaviour for every login session):

$ export PATH=/usr/local/fluidity/openmpi-1.6.5/bin:$PATH

### BLAS and LAPACK

The linear algebra solvers BLAS and LAPACK are both required by the model. Netlib provide an implementation of these packages. The source codes can be downloaded from [http://www.netlib.org/blas/](http://www.netlib.org/blas/%20) and [http://www.netlib.org/lapack/](http://www.netlib.org/lapack/%20), respectively. Here, we download and install BLAS 3.6.0 (blas-3.6.0.tgz) and LAPACK 3.4.2 (lapack-3.4.2.tgz). First, untar BLAS locally, move into the untarred directory, and prepare an install directory:

$ tar -xzvf blas-3.6.0.tgz

$ cd BLAS-3.6.0

$ sudo mkdir /usr/local/fluidity/BLAS-3.6.0

Next, open the file make.inc using your preferred text editor (e.g. gedit) and modify the variables OPTS and BLASLIB so that they read:

OPTS = -O3 -fPIC

BLASLIB = /usr/local/fluidity/BLAS-3.6.0/libblas.a

The BLAS library is then installed by issuing the following command:

$ sudo make

Now untar LAPACK locally, move into the untarred directory, and prepare an install directory:

$ tar -xzvf lapack-3.4.2.tgz

$ cd lapack-3.4.2

$ sudo mkdir /usr/local/fluidity/lapack-3.4.2

Next, make a copy of the file make.inc.example, calling it make.inc, i.e. type:

$ cp make.inc.example make.inc

Open make.inc using your preferred text editor and modify the following lines so that they read:

OPTS = -O2 -fPIC

LOADOPTS = -fPIC

CFLAGS = -O3 -fPIC

BLASLIB = /usr/local/fluidity/BLAS-3.6.0/libblas.a

The LAPACK library file is then built by issuing the `make' command, after which the file must be manually copied into the install directory:

$ make

$ sudo cp liblapack.a /usr/local/fluidity/lapack-3.4.2/.

Note that no environment variables need to be set for BLAS and LAPACK - you will tell ATHAM-Fluidity where to find these libraries directly in the configure command.

### PETSc

PETSc is used to provide matrix solvers in ATHAM-Fluidity. Here, we install PETSc 3.5.4. The source code can be downloaded from http://www.mcs.anl.gov/petsc/download/ (petsc- 3.5.4.tar.gz). Untar this file locally, move into the untarred directory, and prepare an install directory:

$ tar -xzvf petsc-3.5.4.tar.gz

$ cd petsc-3.5.4

$ sudo mkdir /usr/local/fluidity/petsc-3.5.4

PETSc has some dependencies of its own that need to be installed before configuring and installing PETSc itself. Of these dependencies, those that are most likely not on your system by default are cmake, bison and flex. It should be OK to install the latest releases of these dependencies, and so the command line package management tool can be used. On Ubuntu, you would issue the following commands:

$ sudo apt-get update

$ sudo apt-get install cmake bison flex

Next, issue the following command to configure PETSc:

$ ./configure --prefix=/usr/local/fluidity/petsc-3.5.4 --download-fblaslapack=1 \

--download-blacs=1 --download-scalapack=1 --download-ptscotch=1 \

--download-mumps=1 --download-hypre=1 --download-suitesparse=1 \

--download-ml=1 --with-fortran-interfaces=1

After a successful configuration, you should see something similar to the following output in the terminal window:

Configure stage complete. Now build PETSc libraries with (gnumake build): make PETSC DIR=/home/[user]/tarfiles/petsc-3.5.4 PETSC ARCH=arch-linux2-c-debug all

Copy and paste the entire line starting with `make' from your terminal into the command prompt and press Enter. After this stage has completed successfully, you should see something similar to the following output in the terminal window:

Now to install the libraries do: make PETSC DIR=/home/[user]/tarfiles/petsc-3.5.4 PETSC ARCH=arch-linux2-c-debug install

Again, copy and paste the entire line starting with `make' from your terminal into the command prompt, but this time add `sudo' to the beginning of the line before pressing Enter. You should then see something similar to the following output in the terminal window:

Install complete. Now to check if the libraries are working do (in current directory): make PETSC DIR=/usr/local/fluidity/petsc-3.5.4 PETSC ARCH="" test

You can copy-paste the final line from your terminal into the command prompt to make sure that PETSc has been installed successfully. Finally, it is necessary to set the following environment variable (and add it to your .bashrc \_le for future login sessions) so that ATHAM-Fluidity knows where to find the PETSc files during compilation:

$ export PETSC DIR=/usr/local/fluidity/petsc-3.5.4

### ParMETIS and Zoltan

Domain decomposition for parallel runs with ATHAM-Fluidity is performed through the partitioning and load balancing software Zoltan. Zoltan must be configured with the mesh-partitioning library ParMETIS, which should therefore be installed first. Here, we install ParMETIS 3.1.1. The source code can be downloaded from [http://glaros.dtc.umn.edu/gkhome/fsroot/sw/parmetis/OLD](http://glaros.dtc.umn.edu/gkhome/fsroot/sw/parmetis/OLD%20) (ParMetis-3.1.1.tar.gz). Untar this file locally, move into the untarred directory, and prepare an install directory:

$ tar -xzvf ParMetis-3.1.1.tar.gz

$ cd ParMetis-3.1.1

$ sudo mkdir /usr/local/fluidity/ParMetis-3.1.1

ParMETIS is then built by issuing the `make' command, after which the library and header files must be manually copied into the install directory:

$ make

$ sudo cp lib\*.a parmetis.h /usr/local/fluidity/ParMetis-3.1.1/.

Next, download the Zoltan source code from <http://www.cs.sandia.gov/Zoltan/Zoltan_download.html>. Here, we install Zoltan 3.83. Untar the downloaded tar file locally, create a directory called Zoltan-build (Zoltan should be built in a separate directory to the source directory), move into this directory, and prepare an install directory:

$ tar -xzvf zoltan\_distrib\_v3.83.tar.gz

$ mkdir Zoltan-build

$ cd Zoltan-build

$ sudo mkdir /usr/local/fluidity/Zoltan\_v3.83

It is also necessary to specify whether you are installing Zoltan on a 32- or 64-bit system. This can be determined by issuing the following command:

$ uname -i

For a 64-bit system this will return something like `x86\_64', whereas for a 32-bit system it will return something like `i386'. To configure Zoltan, issue the following command (replacing the `x86\_64' to be consistent with your system, if necessary):

env CC=`' CXX=`' CPP=`' FC=`' F90=`' F77=`' \ ../Zoltan\_v3.83/configure x86\_64-linux-gnu \ --prefix=/usr/local/fluidity/Zoltan\_v3.83 \ --enable-mpi --enable-f90interface \ --disable-examples --with-parmetis \ --with-parmetis-libdir=/usr/local/fluidity/ParMetis-3.1.1 \ --with-parmetis-incdir=/usr/local/fluidity/ParMetis-3.1.1

Note that the text before the configure command temporarily `unsets' the compiler environment variables that we set previously - this is required because the configure script would otherwise think that these were the names of the MPI compilers, which is not the case. Next, issue the following two commands to compile and install Zoltan on your system:

$ make

$ sudo make install

Finally, it is necessary to set the following environment variables (and add them to your .bashrc file for future login sessions) so that ATHAM-Fluidity knows where to find the ParMETIS and Zoltan files during compilation:

$ export LDFLAGS=`-L/usr/local/fluidity/ParMetis-3.1.1 \

-L/usr/local/fluidity/Zoltan\_v3.83/lib'

$ export CPPFLAGS=`-I/usr/local/fluidity/ParMetis-3.1.1 \

-I/usr/local/fluidity/Zoltan\_v3.83/include'

### VTK

VTK is required by ATHAM-Fluidity for its data output methods. The VTK install described below requires the following packages to be present on your system, which can be installed using `apt-get' with Ubuntu:

$ sudo apt-get update

$ sudo apt-get install cmake-curses-gui tcl-dev tk-dev

Next, download the VTK source code from [http://www.vtk.org/download/](http://www.vtk.org/download/%20). Here we install VTK 5.10.1 (vtk-5.10.1.tar.gz). Untar the downloaded tar file locally, create a directory called VTK-build (VTK should be built in a separate directory to the source directory), move into this directory, and prepare an install directory:

$ tar -xzvf vtk-5.10.1.tar.gz

$ mkdir VTK-build

$ cd VTK-build

$ sudo mkdir /usr/local/fluidity/VTK5.10.1

It is also necessary to set the following environment variable (and add it to your .bashrc file for future login sessions):

$ export PYTHONPATH= \

/usr/local/fluidity/VTK5.10.1/lib/python2.7/site-packages:$PYTHONPATH

To start the VTK configuration process, issue the following command:

$ ccmake ../VTK5.10.1

This opens up an interactive configure window inside the terminal. Press c to start the initial configure. Once this is complete, press e to be given a list of additional configuration options. Using the arrow keys, Enter key, and keyboard, modify the following options (the rest can be left as they are):

BUILD SHARED LIBS = ON

CMAKE INSTALL PREFIX = /usr/local/fluidity/VTK5.10.1

VTK USE CHARTS = OFF

VTK USE GEOVIS = OFF

VTK USE INFOVIS = OFF

VTK USE N WAY ARRAYS = OFF

VTK USE VIEWS = OFF

VTK WRAP PYTHON = ON

Press c to reconfigure. Once complete, press e, followed by c and e again. You should now have the option to `generate' by pressing g. This will take you back to the standard command line, where you can then build and install VTK by issuing the following commands:

$ make

$ sudo PYTHONPATH=/usr/local/fluidity/VTK5.10.1/lib/python2.7/site-packages \

make install

Note that the `sudo' command does not preserve user environment variables, which is why PYTHONPATH has to be passed in to `make install' despite having been added to the user environment previously. Finally, it is necessary to set the following environment variables (and add them to your .bashrc file for future login sessions) so that ATHAM-Fluidity knows where to find the VTK files during compilation:

$ export VTK\_INCLUDE=/usr/local/fluidity/VTK5.10.1/include/vtk-5.10

$ export LDFLAGS=$LDFLAGS` -L/usr/local/fluidity/VTK5.10.1/lib/vtk-5.10'

$ export \

LD\_LIBRARY\_PATH=$LD\_LIBRARY\_PATH:/usr/local/fluidity/VTK5.10.1/lib/vtk-5.10

## Loading Modules

If you are intending to run ATHAM-Fluidity on a cluster that uses environmental variables then the dependencies required may have already been installed centrally by a system administrator. All that is required to prepare the model is therefore to load the relevant modules and set some environment variables. Check with your system administrator exactly which versions of the dependencies in question were used during compilation of ATHAM-Fluidity. A list of all currently loaded modules can be obtained by typing `module list’ on the command line. If this differs from those used during compilation out of date modules can be unloaded via

$ module unload <MODULE NAME>

Alternatively, modules can be loaded with

$ module load <MMODULE NAME>

It is recommended that you add the correct configuration of modules to your .bashrc profile.

# Installing ATHAM-Fluidity

ATHAM-Fluidity must first be properly configured so that it can be linked to the relevant libraries outlined in Section 2. A minimum configuration is achieved by issuing the following command from inside the main directory of your ATHAM-Fluidity repository, e.g. $HOME/ATHAM-Fluidity:

$ ./configure --enable-2d-adaptivity

For users that have installed the BLAS and LAPACK libraries manually, their location should be passed to the configure command as follows:

$ ./configure --enable-2d-adaptivity \

--with-blas=/usr/local/fluidity/BLAS-3.6.0/libblas.a \

--with-lapack=/usr/local/fluidity/lapack-3.4.2/liblapack.a

This assumes that the BLAS and LAPACK libraries were installed in the locations as specified in Section 2.2; if they were installed elsewhere, modify the paths accordingly. A debug build of ATHAM-Fluidity is obtained by adding the flag --enable-debugging to the configure command. Information about further configure flags can be obtained using the command:

$ ./configure --help

To compile ATHAM-Fluidity after a successful configure, simply type:

$ make

In addition to the standard `make' above, a set of useful tools (including the `flredecomp' executable, required for domain decomposition for parallel runs) should also be compiled by typing:

$ make fltools

If not otherwise specified, the model and tool executables will be placed in the following directory: <A-F install path>/bin, where <A-F install path> is the path to your local ATHAM-Fluidity repository. It can be useful to add this directory to your $PATH environment variable so that the executables can be launched simply by typing their name rather than their entire path. This is done by issuing the following command (and adding it to your .bashrc file for future login sessions):

$ export PATH=<A-F install path>/bin:$PATH

Diamond, the GUI used to generate ATHAM-Fluidity input parameter (.flml) files, is built and then linked to the appropriate options-tree (`schema') file by typing the following two commands:

$ make install-diamond

$ make install-user-schemata

If not specified otherwise, the `diamond' executable will be placed in the following directory: <A-F install path>/libspud/diamond/bin. Again, to be able to launch the executable simply by typing `diamond', you can modify your $PATH environment variable by typing (and adding to your .bashrc file for future login sessions)

$ export PATH=<A-F install path>/libspud/diamond/bin:$PATH

Note that the location of the default .flml can be found in the following directory: $HOME/.diamond/schemata/flml. Finally, local Python scripts should also be made accessible by setting the following environment variable (and adding to your .bashrc file for future login sessions):

$ export PYTHONPATH=$PYTHONPATH:<A-F install path>/python

# Running ATHAM-Fluidity

Once the ATHAM-Fluidity model options have been appropriately set for a given simulation (see Section 5), or if running one of the supplied example test cases, running the model is straight forward. The general command (run from inside a simulation subdirectory that contains the flml configuration file’) reads:

fluidity <input file>.flml

The above command assumes that you have added <A-F install path>/bin to your $PATH environment variable. <input file>.flml should be replaced with the actual name of the .flml file (generated by diamond) for your simulation. Option flags can also be added. For example, -v? (where ? is either 1, 2 or 3) is a verbose option with 3 different levels (from the least to the most verbose), and -l generates log and error files (one per processor). For a parallel run, the numerical domain must first be decomposed using the flredecomp tool:

flredecomp -i X -o Y <serial input file> <parallel input file>

Here, -i is used to specify the initial number of processes (sub-domains) X (typically X=1), and -o is used to specify the output number of processes (sub-domains) Y on which the model will run. <serial input file> is the name of the original .flml file (without the extension) while <parallel input file> is the name of the .flml file (without the extension) generated by flredecomp that will be used as input for the parallel run. After the decomposition is complete, ATHAM-Fluidity is run in the same way as above but specifying the parallel .flml file (with the extension again) rather than the serial file, i.e.:

$ fluidity <parallal input file>.flml

For parallel runs, flredecomp and fluidity need to be executed through the MPI wrapper executable. If this is not done automatically (e.g. through the job submission script that you are using), you should run them in the following way:

mpiexec -np Y flredecomp -i X -o Y <serial input file> <parallel input file>

mpiexec -np Y fluidity <parallel input file>.flml

# ATHAM-Fluidity model options

In this section, you will find a description of all the useful ATHAM-Fluidity model options accessible through the diamond GUI. The options listed below correspond to a generic P1DG -P2 atmospheric simulation (the recommended finite element discretization method, in which pressure and density are solved on a 2nd-order continuous grid while momentum and all other scalars are solved on a 1st-order discontinuous grid) for compressible flow, including turbulence and cloud microphysics parameterizations. Refer to the main Fluidity manual for a more detailed description of all the Fluidity options and capabilities. For any option that does not appear below, it can typically be left turned off, or the default option used. To launch the diamond GUI type:

diamond <filename>.flml

The above command assumes that you have added <A-F install path>/libspud/diamond/bin to your $PATH environment variable. Example .fml files for the test cases described in section 7 can be found under $HOME/ATHAM-Fluidity/tests. If <filename>.flml is omitted, diamond will start with a blank .flml file. Note that when saving the file for the first time, the file extension .flml must be explicitly typed, otherwise the default extension .xml will be added and diamond will complain the next time the file is opened. In the following section options in the diamond interface will appear in **bold.**

## General

The **simulation** name will be used to prefix model output files. The **problem type** must be set to `fluids', whilst the **geometry/dimension** should be set to 2 or 3 depending on whether the test case is a two or three-dimensional problem. Note that once the .flml file has been saved, this number may not be modified later.

## Geometry

**Geometry/mesh (CoordinateMesh)** defines the reference mesh, reads from the mesh file(s) (therefore use select from file). In the Value field of the Attributes section, type the (relative) path to the mesh file(s), e.g. src/MyMesh if the mesh file(s) are called MyMesh and are located within the subdirectory src. It is recommended to use the software package gmsh to generate the initial model mesh, in which case **format (gmsh)** should be selected. **Geometry/mesh (VelocityMesh)** is the default mesh for the velocity (and non-pressure/density scalar) fields, which should be defined from the coordinate mesh. Therefore use **Geometry/mesh (VelocityMesh)/from mesh/mesh** and select (**CoordinateMesh**). **Geometry/mesh (VelocityMesh)/from mesh/** **mesh\_shape/polynomial degree** should be set to 1 and **Geometry/mesh (VelocityMesh)/from mesh/mesh continuity** set to **discontinuous** (i.e. a P1DG configuration). **Geometry/mesh (PressureMesh)** is the pressure and density default mesh which again should be defined from the coordinate mesh, in the same manner as the Velocity mesh above. However in this case **mesh shape/polynomial degree** should be set to 2 and **mesh continuity** set to **continuous** (i.e. a P2 configuration).

Additional derived meshes can be defined following the above procedure. For example, if temperature is to be solved prognostically, a new mesh called, for example, TemperatureMesh should be added, by first selecting and renaming **Geometry/mesh** to **Geometry/TemperatureMesh** and then, similar to before, selecting from **Geometry/TemperatureMesh/mesh/from mesh/mesh** and choosing CoordinateMesh. The .mesh shape/polynomial degree should be set to 1 and mesh continuity set to discontinuous (i.e. a P1DG configuration). **Geometry/quadrature/degree** should be set to at least 2N, where N is the maximum polynomial degree. With the P1DG P2 method, N=2 and **so quadrature/degree** should be set to 4 (or greater).

## I/O (input/output)

Input/Output options can be set, with **io/dump period/constant** specifying the time period (in seconds) between each set of output files generated by the model. For the best quality output **io/output mesh (PressureMesh)** should be selected in order to generate outputs on the 2nd-order pressure/density mesh. To enable checkpointing and produce files for model restarts **io/checkpointing** needs to be selected (these files consist of gridded data files as well as an updated .flml file). Typically a value would be selected for checkpoint period in dumps. For example, if this is set to 4 then restart files will be generated every 4 dump periods.

The time at the start of the simulation can be set using **timestepping/current** **time**. This is typically set to 0, unless restarting from a checkpoint where it is set to the time of the desired checkpoint. The model time step (in seconds) is set using **timestepping/timestep**. This value will depend on the modelled flow-field characteristics and the minimum grid mesh size. If adaptive timestepping is used (often employed with adaptive grid meshing) then this is the initial time-step, as it will change throughout the run. The end time of the simulation can be set using **timestepping/finish time**, which specifies the simulation end-time (in seconds).

## Physical parameters

Gravity must be defined in **physical parameters/gravity/magnitude** (9.81 for acceleration due to Earth's gravity, for example), with the direction it acts in given by **physical parameters/gravity/vector field (GravityDirection).** For a 2D case, the constants 0 and -1 would be input if the 2nd dimension coordinate scheme was positive vertically upwards; for a 3D case, the constants 0, 0 and -1 would be input if the 3rd dimension was positive vertically upwards.

## Material phase

A new material phase must be selected and named. For the purpose of this section we assume the name chosen is “Fluids”.

### Equation of state

A compressible equation of state must be selected from **material\_phase (Fluids)/equation of state/compressible**. **Giraldo** is the default model for ideal gas, although it will eventually be replaced by the ATHAM option (pending future development). **Reference pressure** must be set and is the same as that used in the definition of the Exner function (100000 Pa). **C\_P** and **C\_V** are the default values for the heat capacity of dry air at constant pressure and volume respectively (1004.64 and 717.6 in this case). When enabled, **buoyancy\_from\_pt** allows the user to define buoyancy based on density potential temperature instead of density. The **constant\_cp\_cv**, if enabled, holds constant the heat capacities for the moist atmosphere, and sets them equal to their default dry atmosphere values. If **subtract\_out\_reference\_profile** is enabled then the buoyancy, pressure gradient and scalar diffusion terms are computed by subtracting out the hydrostatic reference profile. These reference profiles MUST be defined beforehand, as described later.

### Pressure

The pressure field is set by enabling **material\_phase (Fluids)/scalar\_field (Pressure).** The mesh should be set to **prognostic/mesh (PressureMesh**), with **spatial\_discretisation/continuous\_galerkin/remove\_stabilisation** also enabled, and **scheme/poisson\_pressure\_solution** set to never. Your preferred solver should be set (**iterative\_ method (gmres)** works fine as a default) with relative error and max iterations for the chosen solver (suggested values are 1.0e-7 and 1000). I**nitial\_conditions** can be specified either via a python script (for idealized cases) or read from a file (non-idealised cases). Boundary conditions are set individually for each boundary with **boundary\_conditions (name)**. Setting Dirichlet boundary conditions on all sides of the model, as well as the top, (chosen via selecting ids to match those of the mesh generated in gmsh) was found to work correctly. The method (**python** or **from\_file**) must again be selected. Time varying boundary conditions can be set with **boundary\_conditions (name)/from\_file/time\_dependent**. The number of input files must then be prescribed (see Section 6 for the required file name formats).

### Density

A density field must be enabled by selecting **material\_phase (Fluids)/scalar\_field (Density).** The mesh should be set to be the same as the pressure mesh with **prognostic/mesh (PressureMesh)**, i.e. the density must be defined on the same continuous mesh as pressure. As the density is diagnosed, **equation** is not required. The **spatial\_discretisation/continuous\_galerkin/stabilisation/no\_stabilisation** option should be selected, whilst **spatial\_discretisation/continuous\_galerkin/conservative advection** is, again, not used as the density is diagnosed. Time advancing is set to **temporal\_discretisation/theta.** It is recommend to choose the same solver as for the pressure solver, setting relative error and max iterations as before (suggested values are 1.0e-7 and 1000, respectively). Initial conditions are specified either via a python script (idealized cases), read from file or from the equation of state (the density is initially diagnosed using pressure, energy and equation of state. The latter is recommended for non-idealized cases for consistency between thermodynamic variables). Boundary conditions are not necessary if pressure boundary conditions are defined (which is recommended). It is not necessary to specify absorption.

### Velocity

Velocity should be set by selecting **vector\_field (Velocity)/prognostic.** The mesh is chosen to be on the **(VelocityMesh).** The **equation** to be used should be specified as **LinearMomentum.** The spatial discretisation should be **spatial\_discretisation/discontinuous\_galerkin** with **viscosity\_scheme/bassi\_ebay** enabled. **Partial\_stress\_form** is recommended for LES or with fixed viscosity. For the advection scheme, **spatial\_discretisation/discontinuous galerkin/advection\_scheme/project\_velocity\_to\_continuous** should be selected. With **spatial\_discretisation/discontinuous\_galerkin/advection\_scheme/integrate\_advection\_by\_parts/twice** also enabled. **Conservative\_advection** should be set to zero (nonconservative). The **temporal\_discretisation/relaxation** should be set to zero whilst **temporal\_discretisation/discontinuous\_galerkin/maximum\_courant\_number\_per\_subcycle** should be specified. For surface boundary conditions either **use surface\_ocean\_COARE3** or **type(dirichilet)/align\_bc\_with\_cartesian** with only the normal velocity component selected and set to zero for a free slip condition. Inlet boundary conditions should be set as appropriate for the normal velocity components. Nothing needs to be set for the other boundaries (with the possible exception of the top boundary condition as a rigid lid with normal velocity set to zero). Time dependent boundary conditions are also available, with values read in from external files (from file option) and the number of input files **prescribed** (see Section 6 for the required file name formats). It is possible to set up a “sponge” layer with **vector\_field (Absorption)/diagnostic/algorithm (atmosphere forcing vector).**

### Potential Temperature

Potential Temperature is the default thermal variable used for ATHAM-Fluidity, although the absolute temperature or internal energy may also be used. It is set with **scalar\_field (PotentialTemperature)** and should set its mesh to be on the velocity mesh with **/prognostic/mesh (VelocityMesh**). Note that the velocity mesh is the default mesh for any scalar, but a different ScalarMesh can also be defined if desired. The default **equation type** is **AdvectionDiffusion,** the default type for any scalar. The **spatial discretisation** should be set to **discontinuous\_galerkin** withan **upwind** advection scheme. **Advection\_ scheme/project\_velocity** should be continuous with **advection\_by\_parts/twice** and **spatial\_discretisation/discontinuous\_galerkin/slope\_limiter: Vertex\_Based.** This is the most diffusive but safest option, **Hermite\_WENO** is less diffusive and works well in most situations, and as such it is the best choice to use if stable. Constant subsidence can be added with **spatial\_discretisation/subsidence** in the form of a large-scale horizontal divergence (with a possibility to apply subsidence to horizontally averaged fields only). **Conservative\_advection** should be set to zero (non-conservative). It is unstable if set to 1 (conservative). Conservation can be achieved with **include\_continuity\_residual** and **temporal\_discretisation/discontinuous\_galerkin** with max CFL. Initial conditions can be set using python (idealised) or from a file **(non-idealised\_ boundary conditions).** For the surface boundary conditions, either use **surface\_ocean\_COARE3, type (dirichlet) (python or from file), or nothing** (zero-gradient). At the inlet, use **Dirichlet** (do not apply weakly). Other boundary conditions should not need to be set. It is possible to use time dependent boundary conditions. Boundary condition values are read from external files (from file option) and the number of input files is prescribed (see section 6). An absorption layer can be set up with **scalar\_field (Absorption)/diagnostic/algorithm** (atmosphere forcing scalar). If doing so **galerkin\_projection/discontinuous** should be selected.

### Water Vapour

Water vapour is represented by **scalar\_field (VapourWaterQ),** the water vapour fraction, recommended for moist processes. Scalar\_field(**TotalWaterQ)**, the total water vapour (concentration multiplied by volume), is also a possible choice. The mesh should be set to the velocity mesh in **scalar\_field (VapourWaterQ)/prognostic/mesh (VelocityMesh**) and the **equation** set to **AdvectionDiffusion.** Spatial discretisation should be **spatial\_discretisation/discontinuous\_galerkin** should be selected with an **upwind\_advection\_scheme. Advection\_ scheme/project\_velocity** should be continuous with **advection\_by\_parts/twice** and **spatial\_discretisation/discontinuous\_galerkin/slope\_limiter: Vertex\_Based.** This is the most diffusive but safest option, **Hermite\_WENO** is less diffusive and works well in most situations. It is the best choice to use if stable. If enabled **spatial\_discretisation/subsidence** adds a constant subsidence under the form of a large-scale horizontal divergence with the possibility to apply subsidence to horizontally averaged field only. **Spatial\_discretisation/discontinuous\_galerkin/conservative\_advection** should be set to zero (non conservative). It is unstable if set to 1 (conservative). Conservation can be achieved with **include\_continuity\_residual**. Initial conditions can be set using python (idealised) or from a file (non-idealised boundary conditions). For the surface boundary conditions, either use **surface\_ocean\_COARE3**, type (dirichlet) (python or from file), or nothing (**zero-gradient**). At the inlet, use **Dirichlet** (do not apply weakly). Other boundary conditions should not need to be set. It is possible to use time dependent boundary conditions. Boundary condition values are read from external files (**from\_file** option) and the number of input files is prescribed (see section 6). An absorption layer can be set up with **scalar\_field (Absorption)/diagnostic/algorithm** (**Atmosphere\_forcing\_scalar**). If doing so **galerkin\_projection/discontinuous** should be selected. If using an optional sponge layer then **galerkin\_projection** should be set to **discontinuous.** Any other prognostic scalar can be defined in the same way as those described above, material phase [name] prescribed fields:

### Hydrostatic reference states

The hydrostatic reference pressure is enabled with **scalar\_field (HydrostaticReferencePressure)** defined on the Pressure Mesh and initialized in the same way as the pressure but without perturbations. It is used in the evaluation of the pressure gradient term. Similarly, the hydrostatic reference density is enabled with **scalar\_field (HydrostaticReferenceDensity)** anddefined on the Pressure Mesh and initialized in the same way as the density but without perturbations. It is used in the buoyancy calculation. The hydrostatic reference potential temperature is enabled with **scalar\_field (HydrostaticReferencePotentialTemperature)** defined on the Velocity Mesh (or ScalarMesh) and initialized in the same way as the potential temperature but without perturbations. It is used in the buoyancy calculation (if selected) and in the turbulent diffusion operator. Finally, the scalar field (HydrostaticReferenceScalarName) defined on VelocityMesh (or ScalarMesh) and initialized in the same way as the scalar but without perturbations. It is used in the turbulent diffusion operator. It may be necessary to choose a solver even for prescribed fields (which have no solver by default) in the case when projections will be performed.

### Cloud microphysics:

The default integration of the cloud microphysics component with the rest of the model is enabled with **cloud\_microphysics/time\_integration (Direct)**. This integrates microphysics source terms directly within the advection step whilst **time\_integration (Splitting)** uses a time-split method for microphysics where microphysics is integrated independently after the main time marching loop. **Time\_integration (Strang)** is another time-split method for microphysics where microphysical variables are advanced by half a time-step before the main integration sequence and half a time-step after. Finally, **time\_integration/limit\_after\_advance** applies a slope limiter after the microphysics step (when computed independently from the rest). The relaxation parameter, **relaxation (optional)** sets the relaxation parameter for the calculation of microphysics sources (when it is zero the values from the previous time-step are used). **Condensation\_evaporation(saturation adjustment)** uses the saturation adjustment procedure to calculate liquid content whilst with **condensation\_evaporation (Simple)** diffusion/evaporation sources are computed and treated implicitly. When using **condensation\_evaporation (Analytic)** diffusion/evaporation sources are computed and treated analytically (this is the recommended setting) whilst with **condensation\_evaporation (Adaptive)** diffusion/evaporation sources are computed with a 2nd order backward difference method with variable step size to guarantee 2nd order accuracy. To prevent unphysical negative concentrations, enable **no\_negative\_concentrations** to apply a strong limit to concentrations. The full microphysics scheme is found within **fortran\_microphysics. Scalar\_field (MicrophysicsSource**) defines options related to the microphysics sources (must be diagnostic and defined on the same mesh as the microphysical quantities, likewise for **scalar field (SinkingVelocity). Two\_moment\_microphysics (Morrison)** is the default microphysical scheme. Five prognostic quantities must be defined as scalar fields **(CCN, Ndrop, Qdrop, Nrain** and **Qrain**). Some can be directly prescribed (CCN and Ndrop in particular, in which case only one moment is computed for droplets. **Cold\_microphysics** switches on ice particles and cold microphysics. Although no proper ice microphysics is implemented, there is already the possibility to define ice particle quantities. **Autoconversion** radius sets the auto conversion radius for the scheme (default is 40 microns), whilst with **simple\_activation** droplets are systematically formed in supersaturated regions and Ndrop is directly set to the prescribed number of CCN (from CCN scalar field). **Detailed\_activation** simulates theactivation of new cloud droplets using a simple model based on Kohler theory **One\_moment\_microphysics (kessler)** is a one moment scheme where only the mass of cloud and rain droplets are prognostic while the number of cloud droplets is prescribed and the number of rain droplets diagnostic. It uses Kessler auto conversion plus parts of Thompson's scheme. **Mass\_threshold** is for auto conversion

## **Flredecomp**

This section contains options related to domain decomposition using flredecomp. If problems related to the ParMETIS library arise (see Section 2), typically observed when executing flredecomp, a different partitioner can be used. In this case, **flredecomp/final\_partitioner/zoltan/method[hypergraph]** will be preferred. If nothing is specified, the ParMETIS graph is used for partitioning.

## Linearised density

To linearise the density used in the momentum equations **material\_phase(Fluids)/linearise** should be enabled. Note that this option has not, as yet, been extensively tested.

# Creating a numerical mesh

The numerical meshes for ATHAM-Fluidity are generated using the external software Gmsh. The Gmsh binaries (or source code) can be downloaded from [http://gmsh.info/#Download](http://gmsh.info/%23Download). If building Gmsh from source, follow the installation instructions within the included README file.

Generating the mesh is a two stage process. The geometry of the modelling domain and mesh resolution parameters (plus any additional options) must first be specified in an ASCII text file with the extension .geo. Guidance on the format of these geometry files, as well as some examples, can be found in the Gmsh reference manual, available here: <http://gmsh.info/doc/texinfo/gmsh.pdf>. Users could also look at the .geo files included with the ATHAM-Fluidity test cases/examples (see Section 7). The modelling domain and mesh can also be visualised within the Gmsh GUI, which is launched by typing:

$ gmsh <mesh file>.geo

Once the geometry file has been created, the Gmsh executable should be invoked to read the contents of this .geo and generate a corresponding .msh file - a much larger file that contains a list of all the mesh elements and node coordinates:

$ gmsh -N <other options> <mesh file>.geo

where N is the dimension of the modelling domain (i.e. 2 or 3). Useful ‘other options’ include -bin, which writes the .msh file in binary rather than ASCII format (thereby saving disc space) and -optimize. This latter option can be very important when generating a fully unstructured mesh within a complex geometry (e.g. above a topographical surface) as it passes over the mesh a second time to ensure that there are no ‘bad’ (i.e. very small) elements that might dramatically reduce a CFL-limited model timestep.

# ATHAM-Fluidity test cases and examples

## Test cases

A number of 2-dimensional test cases have been included with the ATHAM-Fluidity source code (under the ‘tests’ subdirectory, located in $HOME/ATHAM-Fluidity/tests). These comprise a series of benchmark and idealized atmospheric simulations that were originally performed in order to evaluate ATHAM-Fluidity. Full details and results of these simulations can be found in Savre et al. (2016, Monthly Weather Review, 144:4349-4372). Note, however, that due to subsequent code changes and/or tweaks to model parameters, results will be similar but not identical to those presented in this paper. Example results from these cases can be found in the ‘test\_results’ subdirectory of the tests folder. A brief description of each test case, as well as a snapshot image of the result at the end of the simulation using paraview, are also given below:

• **Warm bubble:** A positive Gaussian potential temperature perturbation is initially imposed in an otherwise neutral and static environment in hydrostatic balance. This results in a rising smooth warm bubble with a Kelvin-Helmholtz rotor developing on each side of the bubble. The configuration from Savre et al. (2016) that uses a 10 m spatial resolution is specified.

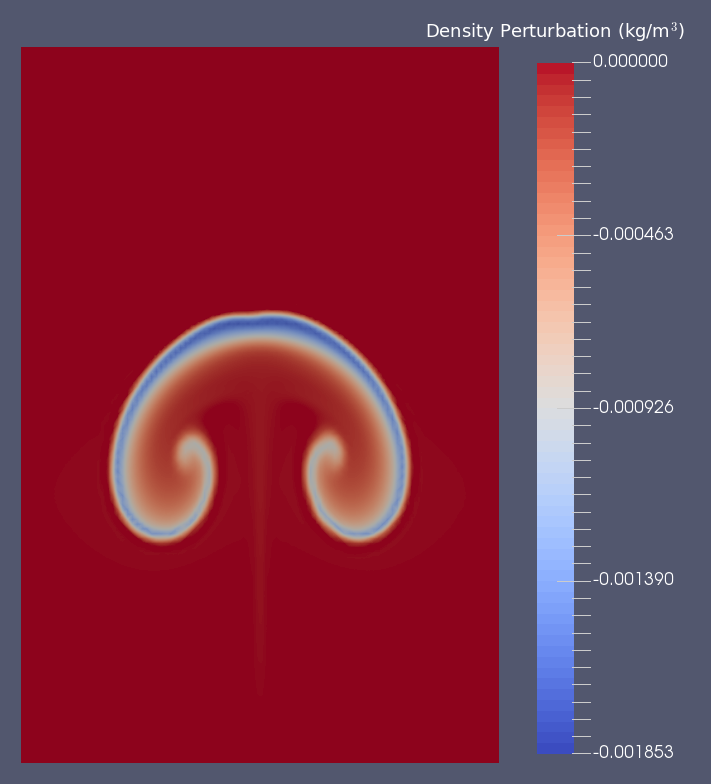


Figure 1: Density perturbation relative to hydrostatic reference density for the warm\_bubble test case. Snapshot is from the end of the simulation.

• **Density current:** A negative Gaussian potential temperature perturbation is initially imposed in an otherwise neutral and static environment in hydrostatic balance. This rapidly sinks, hits the solid surface and spreads out as a cold density current with three rotors on each side. The configuration from Savre et al. (2016) that uses a 200 m spatial resolution is specified.



Figure 2: Density perturbation relative to hydrostatic reference density from the density current test case. Snapshot is from the end of the simulation.

**• Inertial gravity waves:** This case involves a horizontally propagating non-hydrostatic gravity wave in a channel, resulting from an initial potential temperature perturbation in an otherwise uniformly stratified atmosphere with homogeneous horizontal flow. The configuration from Savre et al. (2016) that uses an adaptive timestep based on a CFL number of 0.25 is specified.

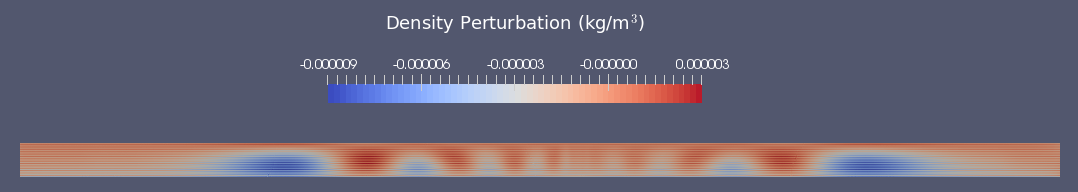


Figure 3: Density perturbation relative to hydrostatic reference density from the inertial gravity waves test case. Snapshot is from the end of the simulation.

• **Schar mountain:** In this case, a dry atmospheric flow is forced over a five-peak mountain range with constant velocity, producing steady-state gravity waves. The configuration differs from Savre et al. (2016) in that the simulation time has been reduced from 8 h to 0.5 h to keep the runtime down (this could be easily changed back in the .flml file).

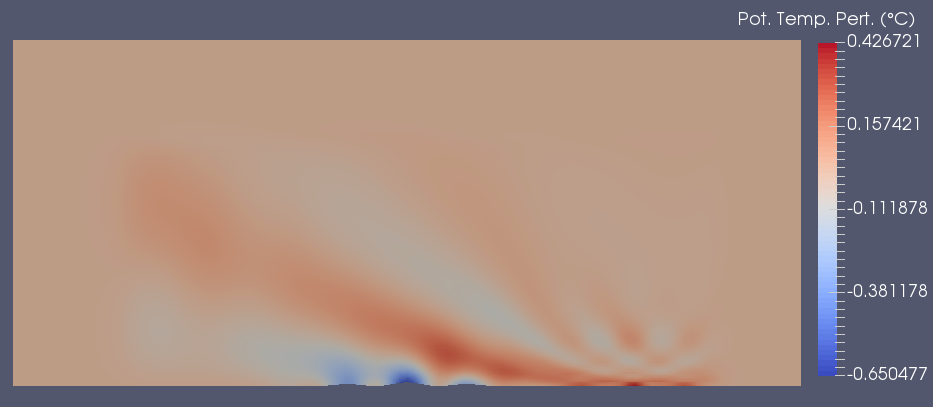


Figure 4: Potential temperature perturbation relative to hydrostatic reference temperature from the single mountain test case. Snapshot is from the end of the simulation.

**• Single mountain:** In this case, a dry atmospheric flow is forced over a single linear mountain profile with constant velocity. Similarly, the configuration differs from Savre et al. (2016) in that the simulation time has been reduced from 5 h to 0.5 h.

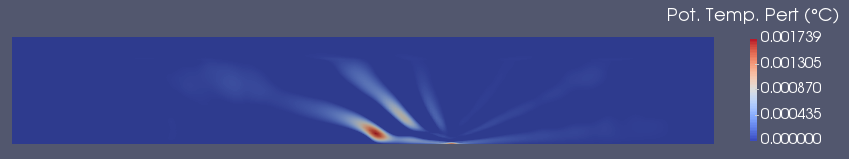


Figure 5: Potential temperature perturbation from the hydrostatic reference temperature for the single mountain test case. Snapshot is from the end of the simulation.

As well as the .flml and mesh geometry files, each of the above test directories also includes an .xml file that can be used to automate the execution of each test case and a subsequent comparison of the model output against stored results (for the benefit of model development testing). To run a particular test case, issue the following command:

$ <A-F install path>/tools/testharness.py -f <test case>.xml

where <test case> should be replaced by one of the test case names above, e.g. warm\_bubble. To run all the test cases in succession, issue the following command:

$ <A-F install path>/tools/testharness.py -t atham -l long

Note that all the above test cases are set up to run in parallel on 24 processes in order to keep runtimes down. If you are using a machine that does not have this many cores (or if you want use more processes), you should open the relevant .xml file(s) in a text editor and modify this value (it appears in two places near the top of each file) as appropriate.

## Example cases

A number of 2- and 3-dimensional examples have also been included with the ATHAM-Fluidity source code (under the ‘examples’ subdirectory). A brief description of each example is given below:

* **Rain**: This 3-d boundary-layer-scale simulation involves a logarithmic velocity profile, a constant potential temperature profile up to 1000 m with an inversion above this, and a moisture profile that gives a stratified layer of saturated air (clouds) just below the inversion. Turbulence is generated at the domain inlet using Fluidity’s synthetic-eddy method. A spatially varying surface boundary condition for potential temperature is defined, where the surface in the last two thirds of the domain is 5K warmer than the upwind third. This generates thermals, leading to convectively-driven cloud and precipitation formation in the downwind half of the domain later in the simulation.

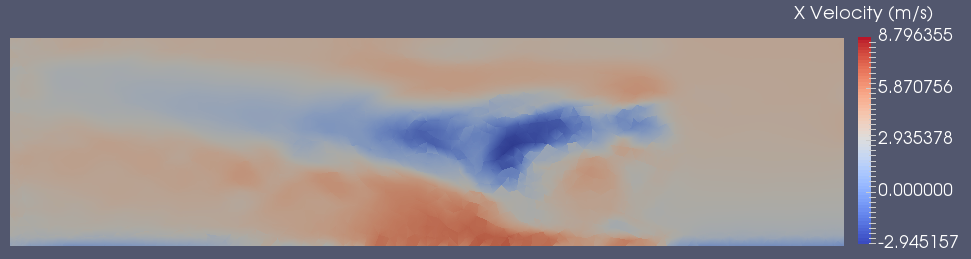


Figure 6: X velocity for the rain example case. Snapshot is from midway through the simulation.

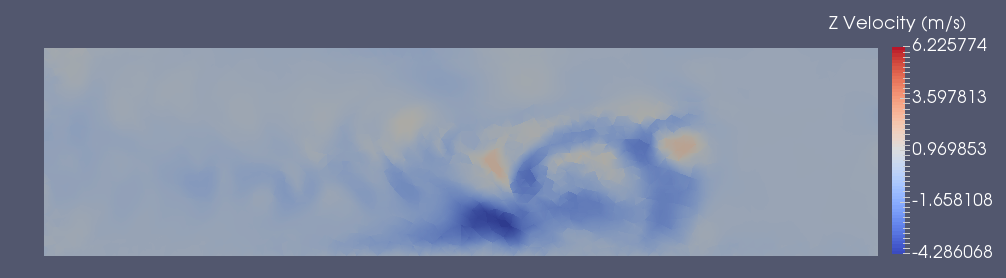


Figure 7: Z velocity for the rain example case. Snapshot is from the middle of the simulation.

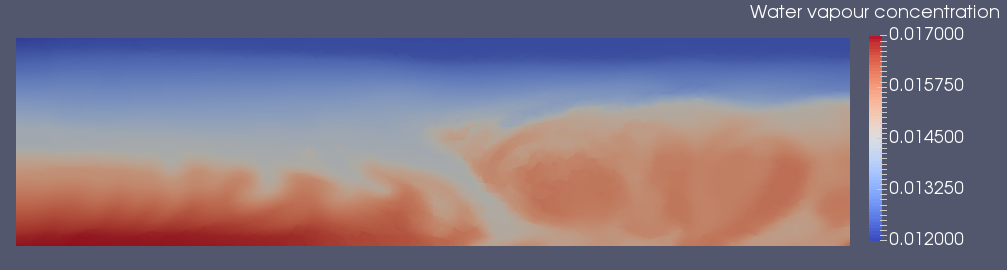


Figure 8: Water vapour concentration for the rain example case. Snapshot is from the end of the model simulation.

* **Precip extreme:** This simulation represents a simplified version of a case study performed as part of the EU PEARL project (Preparing for Extreme And Rare events in coastal regions). An extreme precipitation event, as simulated by a regional climate model, is downscaled close to the region of interest (Greve, Denmark). A simplified numerical mesh without topography or distinct land-sea regions is adopted, with the horizontal domain extent also reduced from 100 km x 100 km to 100 km x 0.6 km to accommodate the use of modest computational resources (the set-up uses 24 cores by default). If the user has access to a larger number of cores, a mesh geometry file with the full horizontal extent of 100 km x 100 km is also supplied. A version of the model input (.flml) file in which the inlet velocity profile is scaled to give a maximum of 10 m s−1 is also included - this reduces the (CFL-limited) timestep for a faster runtime and also allows for the generation of convective clouds closer to the inlet (these clouds form due to the advection of a convectively unstable atmosphere into the domain and the vertical perturbations provided by the inlet turbulence generator).

|  |
| --- |
| Figure 9: Cloud droplet mass concentration for the precip\_extreme example case. Snapshot is from a period of high precipitation. |
| Figure 10: Rain sinking velocity for the precip\_extreme example case. Snapshot is from a period of high precipitation. |

* **Sealevel extreme**: This simulation represents a simplified version of a second case study performed for PEARL. An extreme sea-level event predicted by the regional climate model is downscaled close to Greve. The same simplified numerical mesh (no topography or distinct land-sea regions, reduced horizontal extent) as in the previous example is adopted.

Any one of these examples can be run by navigating to the relevant directory ( $HOME/ATHAM-Fluidity/tests/warm\_bubble, for example) and issuing the following commands:

$ make preprocess

$ make run

To clean the output from a previous run, the following command can be used:

$ make clean

# Input/output files

By default, the main output files are written in .vtu format. These are directly readable by the ParaView free software (available from [https://www.paraview.org/](https://www.paraview.org/%20) ). In parallel runs, as many files as there are processes are produced and stored in a folder. A .pvtu file is also created to unify all the sub-domains in ParaView. A .stat file is also created and updated after each time-step. It contains runtime information on each defined variable (plus others) such as domain averages and min or max values. The file is readable directly using the statplot tool.

In addition to the .flml file required to run ATHAM-Fluidity, several other input files are necessary, in particular initial condition files and mesh files (the necessary files for the cases in section 7 are all located within the repository). In a parallel run, these will be needed by flredecomp only, which will then export .vtu files containing mesh and initial field information. When restarting the parallel run, only these will be needed by ATHAM-Fluidity to restart (this is specified in the modified .flml file). Mesh files are preferably generated using the free GMSH software. GMSH is now the default mesh format for ATHAM-Fluidity. The geometry to be meshed can be defined in a .geo file readable by GMSH.

For non-idealized cases for which it is not possible to initialize the simulations using a built in python script, initial atmospheric soundings can be provided (select the from file/type (sounding) option under initial conditions and/or boundary condition) to homogeneously initialize the domain. These soundings possess a very standard and easy to read structure: the first line contains the values of the surface pressure (hPa), surface potential temperature, surface vapour mixing ratio (kgm-3) and surface velocities. Then, the 1D variables are stored in columns: first the altitude (in m) then the potential temperature, the vapour mixing ratio (kgm-3) and the horizontal velocities (vertical velocities are set to zero).

If time dependent boundary conditions are requested for sponge layers or nudging, the number of input files to be provided must be prescribed. These files all have the same base name (to be specified in diamond), with an extension indicating the time of the sounding (the first one being 0): e.g. SOUNDING.00000 (first one), SOUNDING.07200 (after 2h), SOUNDING.14400 (after 4h). Linear interpolation in time is performed between soundings.

# Licensing

ATHAM-Fluidity can be used under the terms of a GNU Lesser General Public License, the text of which is reproduced below for convenience (as well as being located within the repository).

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Version 2.1, February 1999

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(For example, a function in a library to compute square roots has a purpose that is entirely well-defined independent of the application. Therefore, Subsection 2d requires that any application-supplied function or table used by this function must be optional: if the application does not supply it, the square root function must still compute square roots.)

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This option is useful when you wish to copy part of the code of the Library into a program that is not a library.

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b) Use a suitable shared library mechanism for linking with the Library. A suitable mechanism is one that (1) uses at run time a copy of the library already present on the user's computer system, rather than copying library functions into the executable, and (2) will operate properly with a modified version of the library, if the user installs one, as long as the modified version is interface-compatible with the version that the work was made with.

c) Accompany the work with a written offer, valid for at least three years, to give the same user the materials specified in Subsection 6a, above, for a charge no more than the cost of performing this distribution.

d) If distribution of the work is made by offering access to copy from a designated place, offer equivalent access to copy the above specified materials from the same place.

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